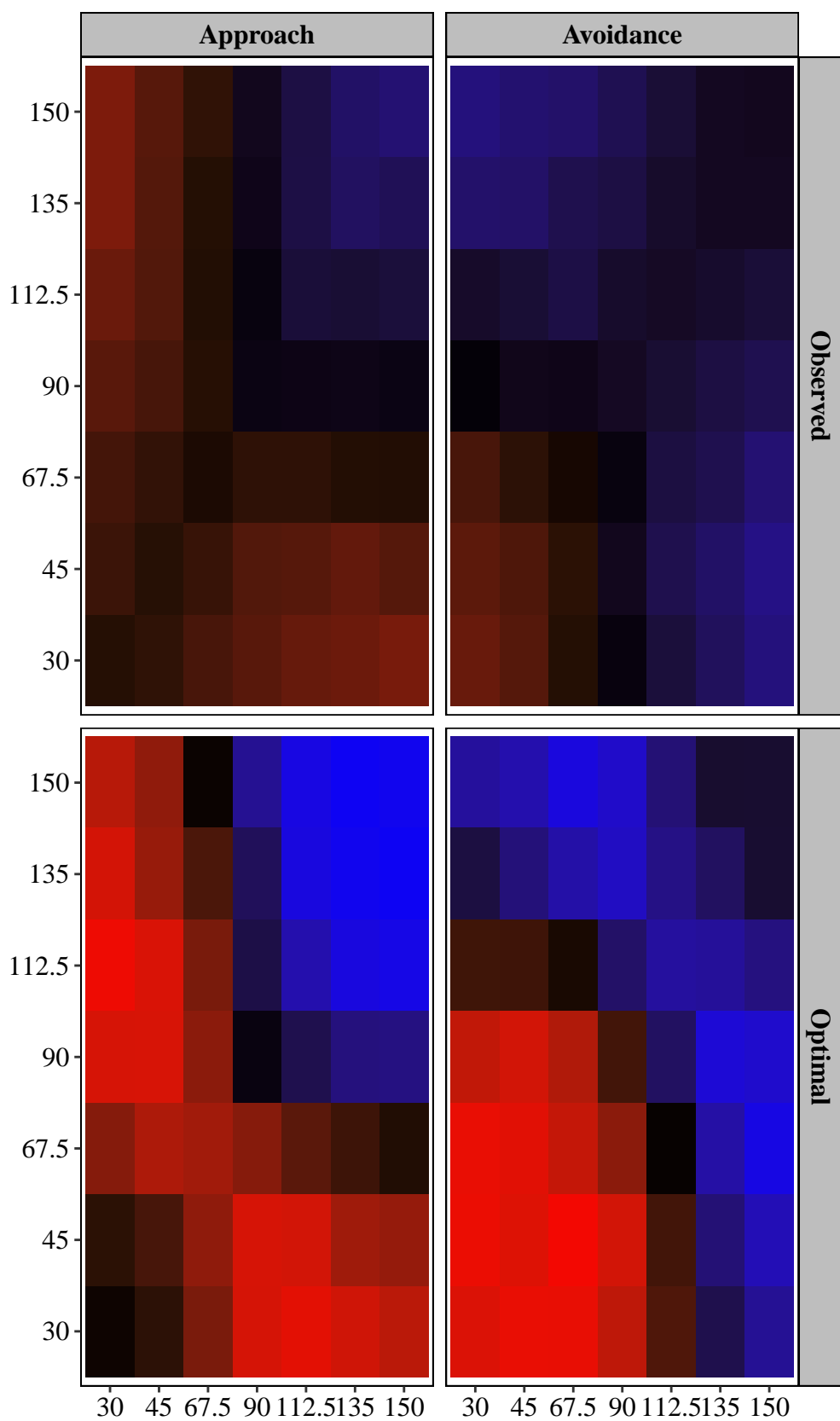


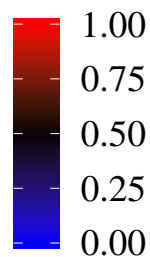
Left Distance to Goal at Start



Observed

Optimal

**Proportion Prioritizing
Farther Goal**



Right Distance to Goal at Start