

Alarm

Timeset.ino

```
#include <Arduino_FreeRTOS.h>
#include "Timealert.h"

int hour;
int minute;
int second;
boolean Run;

Timealert Times(0, 1, 0);//set alarm

void setup() {
  Serial.begin(9600);
  while (!Serial) {
    ;
  }
  hour = 0; // set start hour
  minute = 0; // set start minute
  second = 0; // set start second

  xTaskCreate(
    TaskRuntime
    , (const portCHAR *)
    "AnalogRead"
    , 128 // Stack size
    , NULL
    , 2 // Priority
    , NULL );

  xTaskCreate(
    Taskalert
    , (const portCHAR *)
    "stepmotor"
    , 128 // Stack size
    , NULL
    , 1 // Priority
```

```
    , NULL );
  }

  void loop()
  {

  }

  void TaskRuntime(void
    *pvParameters) // This is a task.
  {
    (void) pvParameters;
    for (;;)
    {
      second++;
      if (second>59){
        second=0;
        minute++;
      }
      else if (minute>59){
        minute=0;
        hour++;
      }
      else if (hour>24){
        hour=0;
      }

      Times.showtime(hour, minute,
        second);

      vTaskDelay(1000 /
        portTICK_PERIOD_MS);
    }
  }

  void Taskalert(void
    *pvParameters) // This is a task.
  {
    (void) pvParameters;
```

```
    for (;;)
    {
      if (hour==Times.getHour())&&
        minute==Times.getMinute()){
        Times.alert();
      }

      vTaskDelay(500 /
        portTICK_PERIOD_MS);
    }
  }
```

Timealert.cpp

```
#include "Arduino.h"
#include "Timealert.h"

Timealert::Timealert(int Hour, int Minute, int Second){
    Serial.print("SetHour =");
    Serial.println(Hour);
    Serial.print("SetMinute =");
    Serial.println(Minute);
    Serial.print("SetSecond =");
    Serial.println(Second);
    H = Hour;
    M = Minute;
    S = Second;
}

void Timealert::showtime(int hour, int minute, int second){
    Serial.print("H:");
    if(hour < 10){
        Serial.print("0");}
    Serial.print(hour);
    Serial.print(" M:");
    if(minute < 10){
        Serial.print("0");}
    Serial.print(minute);
    Serial.print(" S:");
    if(second < 10){
        Serial.print("0");}
    Serial.println(second);
}

void Timealert::alert(){
    Serial.println("alert alert alert alert");
```

```
}

int Timealert::getHour(){
    return H;
}

int Timealert::getMinute(){
    return M;
}

int Timealert::getSecond(){
    return S;
}
```

Timealert.h

```
#include "Arduino.h"

class Timealert
{
public:
    Timealert(int Hour, int Minute, int Second);

    void showtime(int hour, int minute, int second);
    void alert();

    int getHour();
    int getMinute();
    int getSecond();

private:
    int H;
    int M;
    int S;
};
```