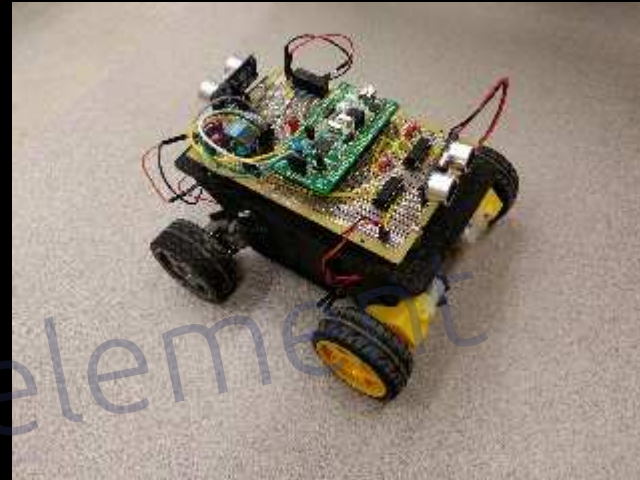


RC Car

ENEL 417 Group Project

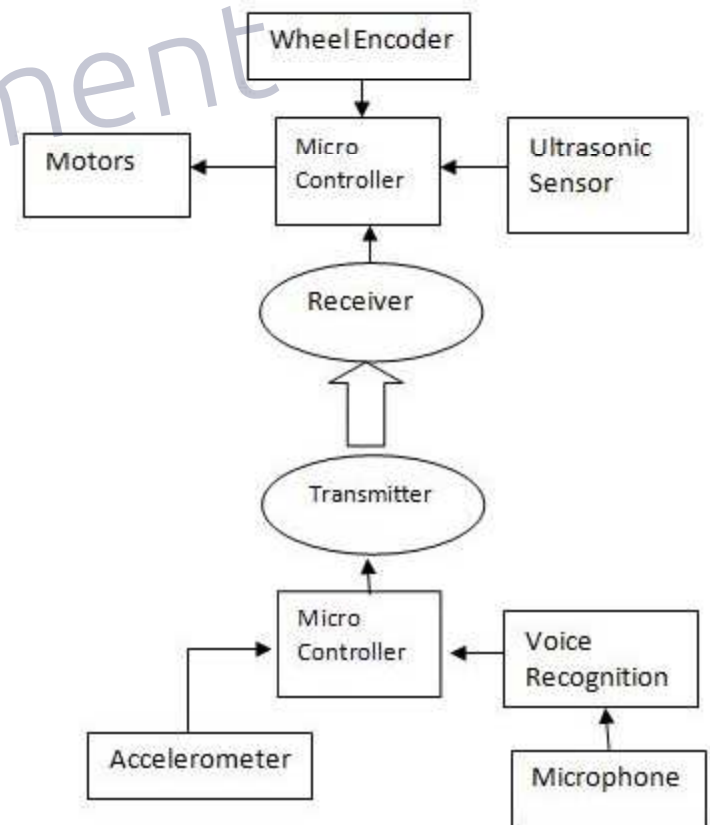
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Mohammed Benhammou
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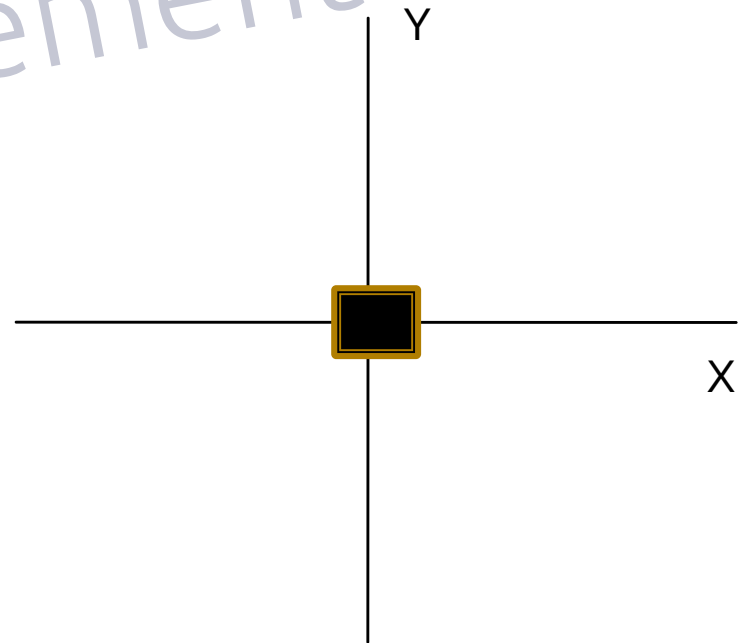
Project Summary

- Create alternative controls and assisted driving systems
- Gesture Based Control
- Voice Based Control
- Obstacle Avoidance
- Speed Regulation
- Wireless Communication



Gesture Based Control

Accelerometer measures the force in X Y Z planes



Gestrure Based Control

Gestures

Forward/left	Forward	Forward/right
Left	Flat	right
Backwards/left	Backwards	Backwards/right

Motion 1

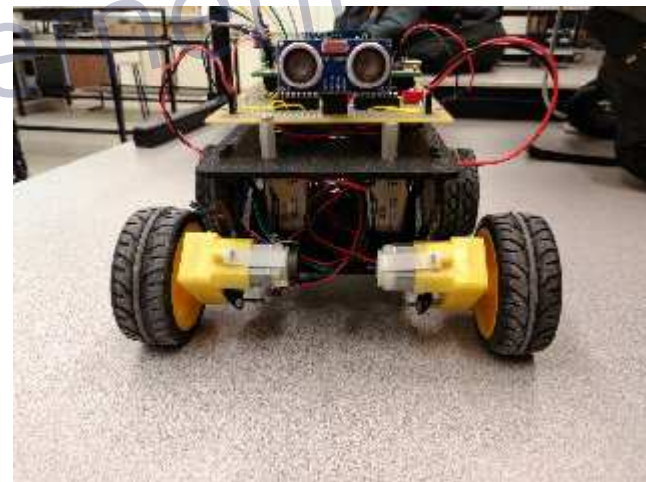
Turn left	Forward	Turn right
Pivot Left	Stop	Pivot right
Turn left	Backwards	Turn right

Voice Based Control

- Voice Recognition Module V3
- Train/Record your own signatures
- Stores up to 80 signatures
- Only 7 signatures effective at one time







Obstacle Avoidance

- Ultrasonic Sensors
- Non-contact
- Transmits 40 kHz signals
- Measure time to receive signals back
- 2 cm to 4 m range



Obstacle Avoidance

Motion 1

Turn left 	Forward 	Turn right 
Pivot Left	Stop	Pivot right
Turn left 	Backwards 	Turn right 

- If an obstacle is detected, the vehicle automatically changes into a different state based on what the users input.

Speed Regulation

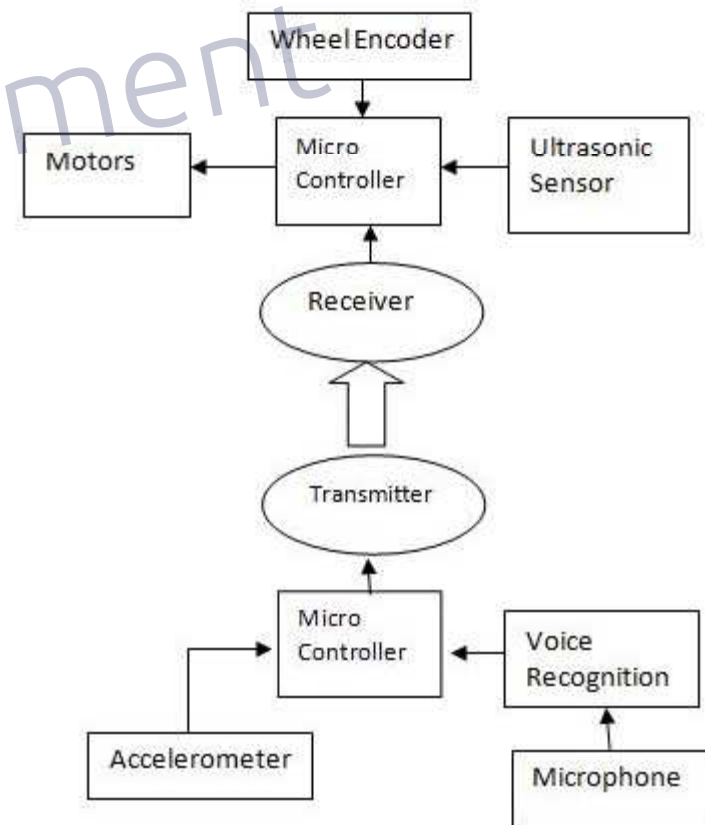
- Wheel Encoder
- Detects wheel rotation
- Count number rotations over period of time
- Use this information as feedback to adjust the output signal to the motors

Wireless Communication

- 433 MHz Radio Frequency signals
- ASK (amplitude shift keying) modulation
- 20-200 meters range
- Communication is one way (controller to car)
- Communication is not obstructed by obstacles such as tables or walls.

Project Summary

- Create alternative controls and assisted driving systems
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Project Summary

- We are presenting this project as a proof of concept
- These alternative techniques of control can be extrapolated into more specific applications
- The goal is to provide adequate control for people who are unable to use conventional controls

Project Summary

- We are re-inventing the steering wheel
- We are integrating autonomous and assisted control systems with user control systems
- We have designed, built and tested a prototype

Questions

