CS304 Operating Systems

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Materials in these slides have been borrowed from textbooks and existing operating systems courses

21 Jan 2021 Inter Process Communication

- Processes do not share any memory with each other
- •Some processes might want to work together for a task, so need to communicate information
- •IPC mechanisms to share information between processes

Virtual Memory View

- During execution, each process can only view its virtual addresses,
- It cannot
 - View another processes virtual address space
 - Determine the physical address mapping

Executing Process

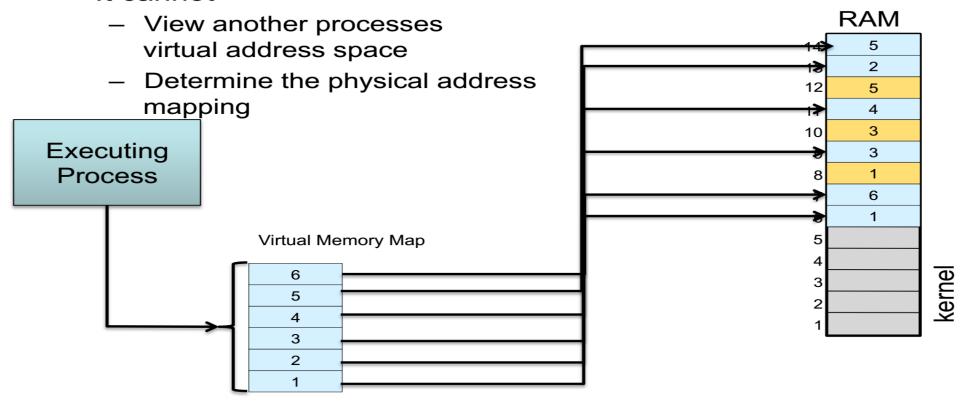
Virtual Memory Map

6
5
4
3
2
1

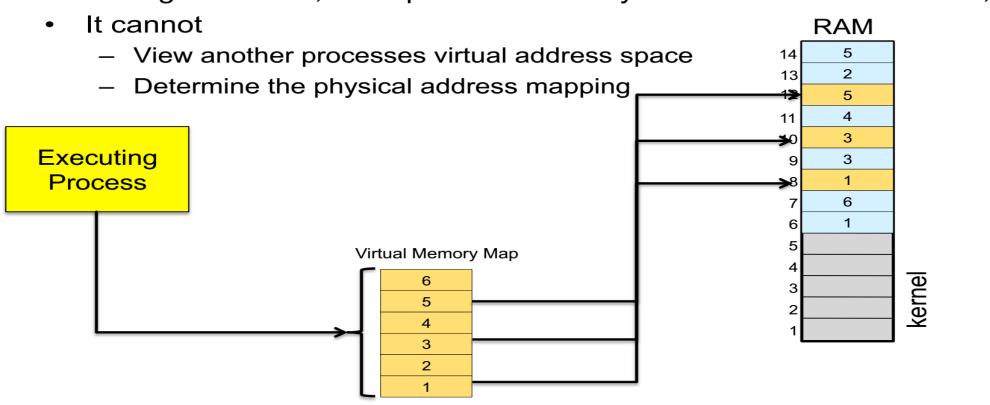
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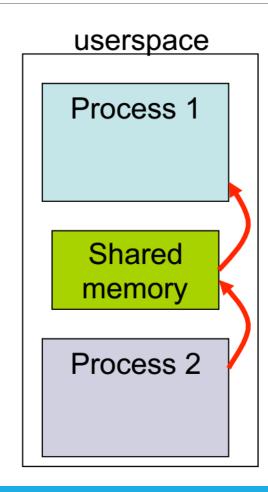


Inter Process Communication

- Advantages of Inter Process Communication (IPC)
 - Information sharing
 - Modularity/Convenience
- 3 ways
 - Shared memory
 - Message Passing
 - Signals

Shared Memory

- One process will create an area in RAM which the other process can access
- Both processes can access shared memory like a regular working memory
 - Reading/writing is like regular reading/writing
 - Fast
- Limitation : Error prone. Needs synchronization between processes



Shared Memory

Processes can both access same region of memory via shmget() system call

- int shmget(key_t key, int size, int shmflg)
- By providing same key, two processes can get same segment of memory
- Can read/write to memory to communicate
- Need to take care that one is not overwriting other's data: how?

Shared Memory in Linux

- int shmget (key, size, flags)
 - Create a shared memory segment;
 - Returns ID of segment : shmid
 - key: unique identifier of the shared memory segment
 - size: size of the shared memory (rounded up to the PAGE_SIZE)
- int shmat(shmid, addr, flags)
 - Attach shmid shared memory to address space of the calling process
 - addr : pointer to the shared memory address space
- int shmdt(shmid)
 - Detach shared memory

Example

server.c

```
1 #include <sys/types.h>
2 #include <sys/ipc.h>
3 #include <sys/shm.h>
4 #include <stdio.h>
5 #include <stdlib.h>
                       27 /* Size of shared memory */
 7 #define SHMSIZE
9 main()
10 {
11
       char c:
12
       int shmid;
13
       key t key;
14
       char *shm, *s;
15
16
       key = 5678; /* some key to uniquely identifies the shared memory */
17
18
       /* Create the segment. */
19
       if ((shmid = shmget(key, SHMSIZE, IPC_CREAT | 0666)
20
           perror("shmget");
21
22
23
           exit(1);
24
       /* Attach the segment to our data space. */
      if ((shm = shmat(shmid NULL, 0)) == (char *) -1) {
25
26
           perror("shmat );
27
           exit(1);
28
29
30
       /* Now put some things into the shared memory */
31
       s = shm:
32
      for (c = 'a'; c <= 'z'; c++)
33
           *S++ = C;
34
       *s = 0; /* end with a NULL termination */
35
36
       /* Wait until the other process changes the first character
37
       * to '*' the shared memory */
38
       while (*shm != '*')
39
           sleep(1),
40
       exit(0);
41 }
```

client.c

```
#include <sys/types.h>
 2 #include <sys/ipc.h>
 3 #include <sys/shm.h>
 4 #include <stdio.h>
 5 #include <stdlib.h>
 7 #define SHMSIZE
 9 main()
10 {
       int shmid;
       key t key;
       char *shm, *s;
       /* We need to get the segment named "5678", created by the server
       key = 5678;
       /* Locate the segment. */
      if ((shmid = shmget(key, SHMSIZE, 0666)) < 0) {
          perror("shmget");
           exit(1);
       /* Attach the segment to our data space. */
       if ((shm = shmat(shmid, NULL, 0)) == (char *) -1) {
           perror("shmat");
           exit(1);
       /* read what the server put in the memory. */
       for (s = shm; *s != 0; s++)
           putchar(*s);
      putchar('\n');
34
35
       * Finally, change the first character of the
        * segment to '*', indicating we have read
38
        * the segment.
39
       *shm = '*':
       exit(0):
```

Signals

- A certain set of signals supported by OS
- Some signals have fixed meaning (e.g., signal to terminate process)
- Some signals can be user-defined
- Signals can be sent to a process by OS or another process (e.g., if you type Ctrl+C, OS sends SIGINT signal to running process)
- Signal handler: every process has a default code to execute for each signal
- Exit on terminate signal
- Some signal handlers can be overridden to do other things

- Asynchronous unidirectional communication between processes
- Signals are a small integer
 - eg. 9: kill, 11: segmentation fault
- Send a signal to a process
 - kill(pid, signum) >
- Process handler for a signal
 - sighandler_t signal(signum, handler);
 - Default if no handler defined

Sockets

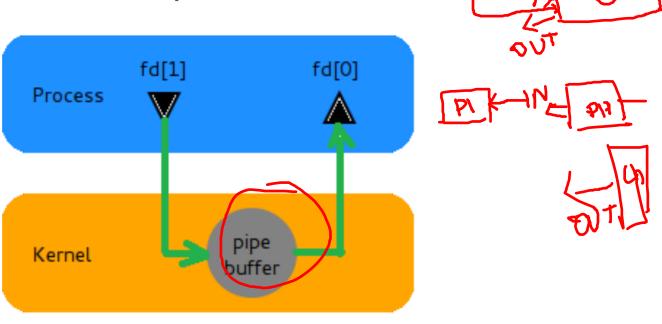
- Sockets can be used for two processes on same machine or different machines to communicate
- TCP/UDP sockets across machines
- Unix sockets in local machine
- Communicating with sockets
- Processes open sockets and connect them to each other
- Messages written into one socket can be read from another
- OS transfers data across socket buffers

Pipes

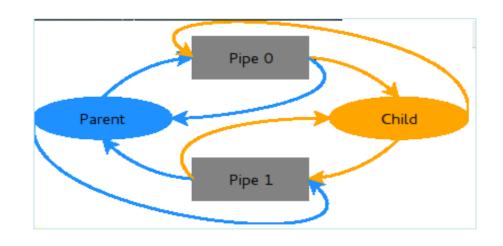
- Pipe system call returns two file descriptors
- Read handle and write handle
- A pipe is a half-duplex communication
- Data written in one file descriptor can be read through another
- Regular pipes: both fd are in same process (how it is useful?)
- Parent and child share fd after fork
- Parent uses one end and child uses other end
- Named pipes: two endpoints of a pipe can be in different processes
- Pipe data buffered in OS buffers between write and read

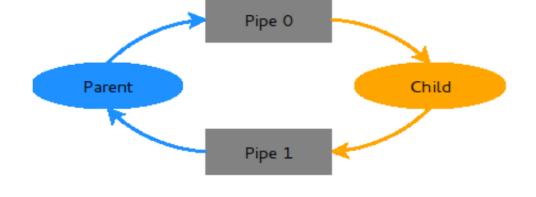
Pipes

- Always between parent and child
- Always unidirectional
- Accessed by two associated file descriptors:
 - fd[0] for reading from pipe
 - fd[1] for writing to the pipe



Two Way Communication





- Two pipes opened pipe0 and pipe1
- Note the unnecessary pipes

 Close the unnecessary pipes

Example [Child process sending a string to Parent]

```
#include <stdio.h>
#include <unistd.h>
#include <stdlib.h>
int main(){
 int pipefd[2];
 int pid;
  char recv[32];
  pipe(pipefd);
  switch(pid=fork()) {
  case (-1: perror("fork");
           exit(1);
                                            /* in child process */
        close(pipefd[0]);
                                            /* close unnecessary pipefd */
        FILE *out = fdopen(pipefd[1], "w"); /* open pipe descriptor as stream */
        fprintf(out, "Hello World\n");
                                            /* write to out stream */
        break:
  default:
                                            /* in parent process */
       close(pipefd[1])
                                            /* close unnecessary pipefd */
       FILE *in = fdopen(pipefd[0], "r"); /* open descriptor as stream */
        fscanf(in, "%s", recv);
                                            /* read from in stream */
        printf("%s", recv);
        break;
```

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Normed FIFOs

Message Queues

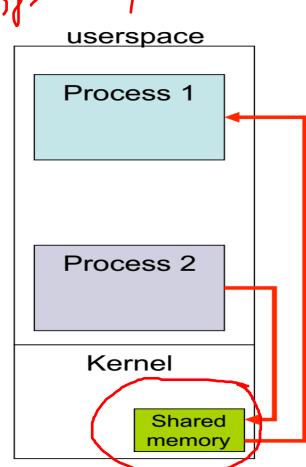
- Mailbox abstraction
- Process can open a mailbox at a specified location
- Processes can send/receive messages from mailbox
- OS buffers messages between send and receive



Message Passing



- Shared memory created in the kernel
- System calls such as send and receive used for communication
 - Cooperating : each send must have a receive
- Advantage : Explicit sharing, less error prone
- Limitation: Slow. Each call involves marshalling / demarshalling of information



Blocking Vs Non-Blocking

- Some IPC actions can block
- Reading from socket/pipe that has no data, or reading from empty message queue
- Writing to a full socket/pipe/message queue
- The system calls to read/write have versions that block or can return with an error code in case of failure
- A socket read can return error indicating no data to be read, instead of blocking