LEONID GREMYACHIKH

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EDUCATION

National Research University Higher School of Economics

Computer and Information Sciences

Nov 2019 – Sep 2022   Moscow, Russia

- PhD in Applied Mathematics and Informatics
- The dissertation will be related to Machine Learning and Deep Reinforcement Learning

National Research University Higher School of Economics

Data Science

Sep 2016 – Jun 2018   Moscow, Russia

- MS in Applied Mathematics and Informatics
- Grade in Reinforcement Learning = 10
- Grade in Deep Learning = 10
- Thesis theme: "Automation of Satellite Collision Avoidance Maneuvers with Deep Reinforcement Learning"

National Research University Moscow Aviation Institute

Design and Technology of Electronic Equipment

Sep 2009 – Feb 2015   Moscow, Russia

- Specialist in Engineering

EDUCATION / COURSES

Computer Vision

OTUS (2020)

Autumn School on Generative Models

HSE-Yandex (26-29 November 2019)

WORK EXPERIENCE

ADALISK

Senior Machine Learning Engineer

Aug 2021 – currently   Moscow, Russia

Computer Vision – DL, Engineering, Research

`Python` `C++`

Laboratory of Methods for Big Data Analysis

Research Assistant

Apr 2018 – currently   Moscow, Russia

ML, DL, RL, Distributed Learning, Research, Papers

`Python`

Radio Engineering Institute named after academician A. L. Mints

Engineer

Apr 2015 – Apr 2018   Moscow, Russia

Digital signal processing, Signal Analysis, Space Objects Recognition

`C++` `Mathcad`

HARD SKILLS

- Deep Learning
- Computer Vision
- Machine Learning
- Reinforcement Learning

Python ●●●●●
C++ ●●●○○

SOFT SKILLS

- presentation skills
- meeting management skills
- communication
- self-management, self-efficiency
- teamwork skills
- mentoring
- documentation

PUBLICATIONS

- 📄 **Journal Articles**
  - Arzymatov, Kenenbek, Mikhail Hushchyn, Andrey Sapronov, Vladislav Belavin, Leonid Gremyachikh, Maksim Karpov, and Andrey Ustyuzhanin (2021). "Online detection of failures generated by storage simulator". In: *Journal of Physics: Conference Series* 1740, p. 012052.
  - K. Arzymatov, A. Sapronov, V. Belavin, L. Gremyachikh, M. Karpov, A. Ustyuzhanin, I. Tchoub, and A. Ikoev (2020). "SANgo: a storage infrastructure simulator with reinforcement learning support". In: *PeerJ Computer Science*, pp. 1–16.
  - "Space Navigator: a Tool for the Optimization of Collision Avoidance Maneuvers" (2020). In: *Advances in the Astronautical Sciences* 170, pp. 305–319. eprint: 1902.02095.

CONFERENCES & SPEECHES

- SMILES, Moscow, SKOLTECH, international summer school – poster presentation "AI and Satellite Problems" (2020)
- IDAO (International Data Analysts Olympiad) – IDAO Webinar on Data Analysis for Satellite Tracking (2020), webinar
- Space debris: fundamental and practical aspects of the threat, Moscow, Institute of Astronomy RAS and Space Research Institute RAS, Russian conference with international participation – report "Space Navigator" (2019)
- IAA SciTech Forum 2018, Moscow, RUDN, international conference – paper report "SpaceNavigator: a Tool for the Optimization of Collision Avoidance Maneuvers" (2018)

ART PROJECTS

- For All Exists Infinity – VR installation created with the Unreal Engine (2021, exhibition "Game Junction").

TEACHING

- Machine Intelligence, interdisciplinary perspective (2021, HSE University)
- Introduction to Data Analysis (2021, HSE University)
- Python for Data Science (2020-2021, Skillbox)

PROJECTS

Computer Vision for working with teeth (2021)

- Different tasks

Python   DL   CV

Reinforcement Learning for Poker (2021)

- RL: environment, simulator, algorithms, experiments, research

Python   RL

Reinforcement Learning for automatic budget management for advertising campaigns. (2021)

- RL: environment, simulator, algorithms, experiments, research
- Management

Python   RL   Management

Anomaly Prediction in Storage Area Network (2018-2021)

- a publication "SANgo: a storage infrastructure simulator with reinforcement learning support"
- researched methods for improving Digital Twin of Storage Area Network, tested methods on chaotic systems, developed OpenAI Gym wrappers, applied RL methods
- NLP on logs

Python   Docker   DL   RL   NLP

Sixth Machine Learning in High Energy Physics Summer School (2020)

Volunteering, helping students.

Python   DL   Mentoring

International Data Analysis Olympiad (2020)

Participated in the preparation of Higher School of Economics and Yandex the 3rd international data analysts olympiad. The competition task – build a model that would predict the position of space objects using simulation data.

- analyzed the task and SOTA
- prepared and verified data (ephemeris) using GMAT and SGP4
- prepared a baseline (LR)
- checked and analyzed the solutions of the participants
- answered questions from participants

Python   GMAT

Satellite Positioning (2019-2020)

The project task – build a model that would predict the position of space objects using simulation data.

- students mentoring

Python   Management   Mentoring

Distributed Deep Learning (2018-2019)

- developed Distributed Deep Learning pipelines

Python   Docker   Azure   DL

Model Gym (2018)

- developed and debugged a hyperparameter optimization system

Python   ML

Automation of Satellite Collision Avoidance Maneuvers with Deep Reinforcement Learning (2017-2018)

- a publication "Space Navigator: a Tool for the Optimization of Collision Avoidance Maneuvers"
- researched and developed a system for calculating maneuvers for spacecraft based on Machine Learning
- MVP is done
- participated in IAA SciTech Forum 2018

Python   DL   RL

Sex Prediction via Deep Learning (2017)

- researched Sex Prediction via Deep Learning by person's Friends Graph from social network and friends' photos
- used pre-trained VGG from ImageNet, Social Network Analysis
- collected data from "vk.com"
- obtained better score than the baseline

Python   DL   Social Network Analysis