

LEONID GREMYACHIKH

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📍 Moscow, Russia

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EDUCATION

National Research University Higher School of Economics

Computer and Information Sciences

📅 Nov 2019 – Sep 2022

📍 Moscow, Russia

- PhD in Applied Mathematics and Informatics
- The dissertation will be related to Machine Learning and Deep Reinforcement Learning

National Research University Higher School of Economics

Data Science

📅 Sep 2016 – Jun 2018

📍 Moscow, Russia

- MS in Applied Mathematics and Informatics
- Grade in Reinforcement Learning = 10
- Grade in Deep Learning = 10
- Thesis theme: "Automation of Satellite Collision Avoidance Maneuvers with Deep Reinforcement Learning"

National Research University Moscow Aviation Institute

Design and Technology of Electronic Equipment

📅 Sep 2009 – Feb 2015

📍 Moscow, Russia

- Specialist in Engineering

WORK EXPERIENCE

Laboratory of Methods for Big Data Analysis

Research Assistant

📅 Apr 2018 – currently

📍 Moscow, Russia

ML, DL, RL, Distributed Learning, Research, Papers

Python

Radio Engineering Institute named after academician A. L. Mints

Engineer

📅 Apr 2015 – Apr 2018

📍 Moscow, Russia

Digital signal processing, Signal Analysis, Space Objects Recognition

C++

Mathcad

HARD SKILLS

- Deep Learning
- Computer Vision
- Machine Learning
- Reinforcement Learning

Python

C++



EDUCATION / COURSES

Computer Vision 2

OpenCV (2020) (in process)

Computer Vision 1

OpenCV (2020) (in process)

Computer Vision

OTUS (2020)

Advanced ML Specialization

Coursera (2019-2020) (in process)

C++ Specialization

Coursera (2019-2020) (in process)

Autumn School on Generative Models

HSE-Yandex (26-29 November 2019)

SOFT SKILLS

- presentation skills
- meeting management skills
- communication
- self-management, self-efficiency
- teamwork skills
- mentoring
- documentation

PROJECTS

Anomaly Prediction in Storage Area Network (2018-2020)

- a publication "SANgo: a storage infrastructure simulator with reinforcement learning support"
- researched methods for improving Digital Twin of Storage Area Network, tested methods on chaotic systems, developed OpenAI Gym wrappers, applied RL methods
- NLP on logs

Python Docker DL RL NLP

Sixth Machine Learning in High Energy Physics Summer School (2020)

Volunteering, helping students.

Python DL Mentoring

International Data Analysis Olympiad (2020)

Participated in the preparation of Higher School of Economics and Yandex the 3rd international data analysts olympiad. The competition task – build a model that would predict the position of space objects using simulation data.

- analyzed the task and SOTA
- prepared and verified data (ephemeris) using GMAT and SGP4
- prepared a baseline (LR)
- checked and analyzed the solutions of the participants
- answered questions from participants

Python GMAT

Satellite Positioning (2019-2020)

The project task – build a model that would predict the position of space objects using simulation data.

- students mentoring

Python Management Mentoring

Distributed Deep Learning (2018-2019)

- developed Distributed Deep Learning pipelines

Python Docker Azure DL

Model Gym (2018)

- developed and debugged a hyperparameter optimization system

Python ML

Automation of Satellite Collision Avoidance Maneuvers with Deep Reinforcement Learning (2017-2018)

- a publication "Space Navigator: a Tool for the Optimization of Collision Avoidance Maneuvers"
- researched and developed a system for calculating maneuvers for spacecraft based on Machine Learning
- MVP is done
- participated in IAA SciTech Forum 2018

Python DL RL

Sex Prediction via Deep Learning (2017)

- researched Sex Prediction via Deep Learning by person's Friends Graph from social network and friends' photos
- used pre-trained VGG from ImageNet, Social Network Analysis
- collected data from "vk.com"
- obtained better score than the baseline

Python DL Social Network Analysis

PUBLICATIONS

• Journal Articles

- K. Arzymatov, A. Sapronov, V. Belavin, L. Gremyachikh, M. Karpov, A. Ustyuzhanin, I. Tchoub, and A. Ikoef (2020). "SANgo: a storage infrastructure simulator with reinforcement learning support". In: *PeerJ Computer Science*, pp. 1–16.
- "Space Navigator: a Tool for the Optimization of Collision Avoidance Maneuvers" (2020). In: *CoRR abs/1902.02095*. eprint: 1902.02095.

CONFERENCES & SPEECHES

- SMILES, Moscow, SKOLTECH, international summer school – poster presentation "AI and Satellite Problems" (2020)
- IDAO (international data analysts olympiad) – IDAO Webinar on Data Analysis for Satellite Tracking (2020)
- Space debris: fundamental and practical aspects of the threat, Moscow, Institute of Astronomy RAS and Space Research Institute RAS, Russian conference with international participation – report "Space Navigator" (2019)
- IAA SciTech Forum 2018, Moscow, RUDN, international conference – paper report "Space Navigator: a Tool for the Optimization of Collision Avoidance Maneuvers" (2018)