

view_frames Result

Recorded at time: 1643595559.679

map

Broadcaster: /amcl
Average rate: 16.517 Hz
Most recent transform: 1643595559.720 (-0.041 sec old)
Buffer length: 5.025 sec

odom

Broadcaster: /robot_pose_ekf
Average rate: 26.844 Hz
Most recent transform: 1643595559.636 (0.043 sec old)
Buffer length: 4.880 sec

base_footprint

Broadcaster: /base_link_broadcaster
Average rate: 10.189 Hz
Most recent transform: 1643595559.759 (-0.080 sec old)
Buffer length: 4.907 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1643595559.679 sec old)
Buffer length: 0.000 sec

base_plate

Broadcaster: /base_laser_broadcaster
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1643595559.679 sec old)
Buffer length: 0.000 sec

laser

Broadcaster: /imu_broadcaster
Average rate: 10.180 Hz
Most recent transform: 1643595559.761 (-0.082 sec old)
Buffer length: 4.912 sec

imu