

12-1 Curves in Space and Their Tangents

師大工教一

When a particle move through space during a time interval I , we think of the particle's coordinates as functions defined on I :

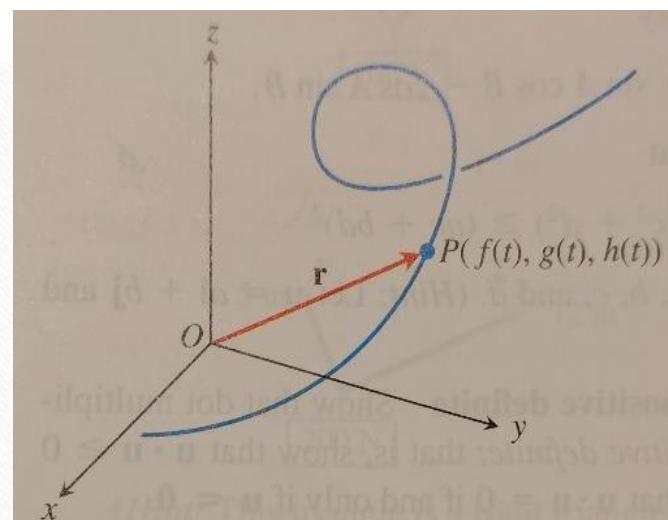
$$x = f(t), \quad y = g(t), \quad z = h(t), \quad t \in I$$

The points $(x, y, z) = (f(t), g(t), h(t))$, $t \in I$, make up the **curve** in space that we call the particle's **path**.

向量
Vector Form

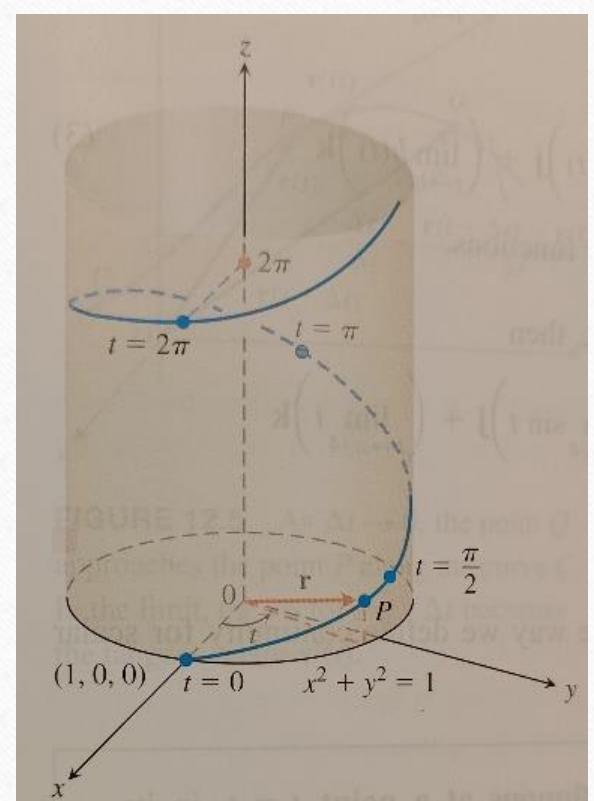
$$\vec{r}(t) = \overrightarrow{OP} = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k} \quad (2)$$

The above equation defines \vec{r} as a **vector-valued function** or **vector function** on a domain set D . D is a rule that assigns a vector in space to each element in D . The functions f, g, h are called the **component functions** (or components) of the position function.



Ex1(p681) Graph the vector function $\vec{r}(t) = (\cos t)\vec{i} + (\sin t)\vec{j} + t\vec{k}$. This graph is called the helix (from the ancient Greek word for “spiral”).

螺旋



Limits and Continuity

Definition Let $\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$ be a vector function with domain D , and let \vec{L} be a vector. We say that \vec{r} has **limit** \vec{L} as t approaches t_0 and write $\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{L}$, if, for every number $\varepsilon > 0$, there exists a corresponding number $\delta > 0$ such that, for all $t \in D$, $|\vec{r}(t) - \vec{L}| < \varepsilon$ whenever $0 < |t - t_0| < \delta$. Or $\lim_{t \rightarrow t_0} \vec{r}(t) = \left(\lim_{t \rightarrow t_0} f(t) \right) \vec{i} + \left(\lim_{t \rightarrow t_0} g(t) \right) \vec{j} + \left(\lim_{t \rightarrow t_0} h(t) \right) \vec{k}$.

Ex2(p682) If $\vec{r}(t) = (\cos t)\vec{i} + (\sin t)\vec{j} + t\vec{k}$, find $\lim_{t \rightarrow \frac{\pi}{4}} \vec{r}(t)$.

$$\begin{aligned}\lim_{t \rightarrow \frac{\pi}{4}} \vec{r}(t) &= \left(\lim_{t \rightarrow \frac{\pi}{4}} \cos t \right) \vec{i} + \left(\lim_{t \rightarrow \frac{\pi}{4}} \sin t \right) \vec{j} + \left(\lim_{t \rightarrow \frac{\pi}{4}} t \right) \vec{k} \\ &= \frac{\sqrt{2}}{2} \vec{i} + \frac{\sqrt{2}}{2} \vec{j} + \frac{\pi}{4} \vec{k}\end{aligned}$$

Definition A vector function $\vec{r}(t)$ is **continuous at a point** $t = t_0$ in its

domain if $\lim_{t \rightarrow t_0} \vec{r}(t) = \vec{r}(t_0)$. The function is **continuous** if it is continuous at every point in its domain.

Ex3(p682) (a) If each component function is continuous, then the space curve is also continuous.

(b) The function $\vec{g}(t) = (\cos t)\vec{i} + (\sin t)\vec{j} + [t]\vec{k}$ is discontinuous at every

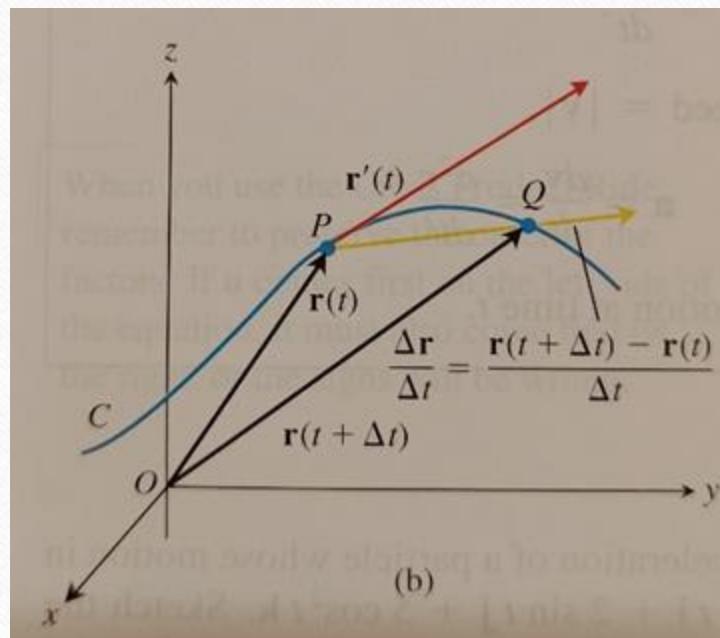
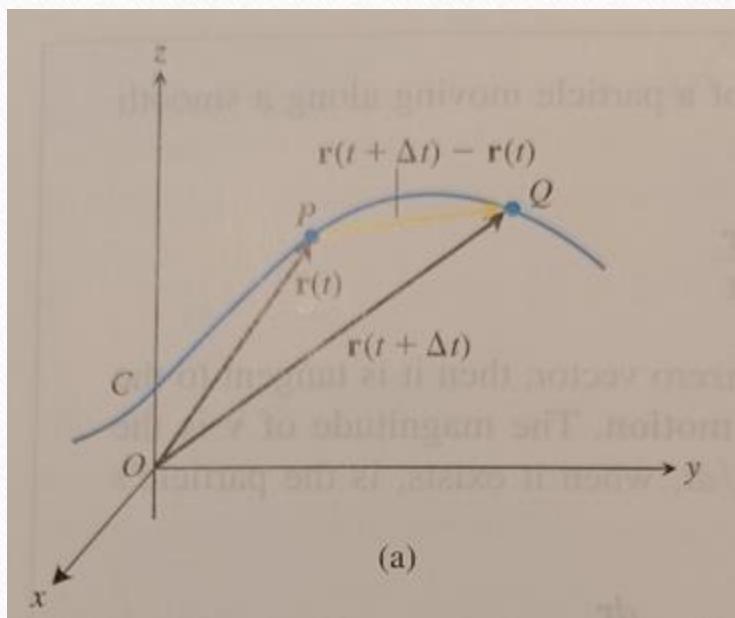
integer, where $[t]$ is the greatest integer function.

Derivatives and Motion

$$\begin{aligned}\Delta \vec{r} &= \vec{r}(t + \Delta t) - \vec{r}(t) \\&= [f(t + \Delta t)\vec{i} + g(t + \Delta t)\vec{j} + h(t + \Delta t)\vec{k}] - [f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}] \\&= [f(t + \Delta t) - f(t)]\vec{i} + [g(t + \Delta t) - g(t)]\vec{j} + [h(t + \Delta t) - h(t)]\vec{k}\end{aligned}$$

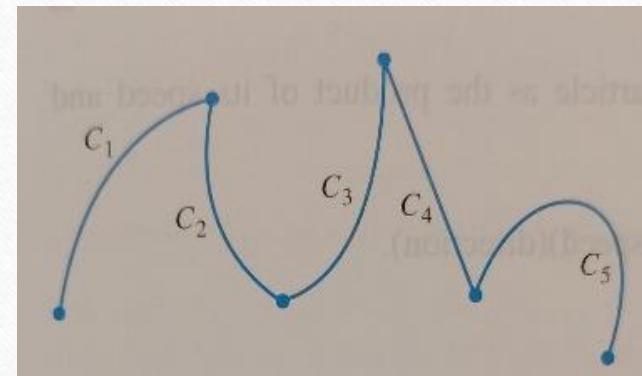
$$\begin{aligned}\lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} &= \left[\lim_{\Delta t \rightarrow 0} \frac{f(t + \Delta t) - f(t)}{\Delta t} \right] \vec{i} + \left[\lim_{\Delta t \rightarrow 0} \frac{g(t + \Delta t) - g(t)}{\Delta t} \right] \vec{j} + \left[\lim_{\Delta t \rightarrow 0} \frac{h(t + \Delta t) - h(t)}{\Delta t} \right] \vec{k} \\&= \left[\frac{df}{dt} \right] \vec{i} + \left[\frac{dg}{dt} \right] \vec{j} + \left[\frac{dh}{dt} \right] \vec{k}\end{aligned}$$

Definition The vector function $\vec{r}(t) = f(t)\vec{i} + g(t)\vec{j} + h(t)\vec{k}$ has a **derivative** (**is differentiable**) at t if f, g, h have derivatives at t . The derivative is the vector function $\vec{r}'(t) = \frac{d\vec{r}}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\vec{r}(t + \Delta t) - \vec{r}(t)}{\Delta t} = \frac{df}{dt}\vec{i} + \frac{dg}{dt}\vec{j} + \frac{dh}{dt}\vec{k}$.



A vector function \vec{r} is **differentiable** if it is differentiable at every point in its domain. The curve traced by \vec{r} is **smooth** if $\frac{d\vec{r}}{dt}$ is continuous and never $\vec{0}$, that is, if f, g, h have continuous first derivatives that are not simultaneously 0 . A curve that is made up of a finite number of smooth curves pieced together in a continuous fashion is called **piecewise smooth**.

分段 光滑



Definition If \vec{r} is the position vector of a particle along a smooth curve in space, then $\vec{v}(t) = \frac{d\vec{r}}{dt}$ is the particle's **velocity vector**. If \vec{v} is a nonzero vector, then it is tangent to the curve, and its direction is the **direction of motion**. The magnitude of \vec{v} is the particle's **speed**, and the derivative $\vec{a} = \frac{d\vec{v}}{dt}$, when it exists, is the particle's **acceleration vector**. In summary,

1. Velocity is the derivative of position: $\vec{v} = \frac{d\vec{r}}{dt}$.
2. Speed is the magnitude of velocity: Speed = $|\vec{v}|$.
3. Acceleration is the derivative of velocity: $\vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2\vec{r}}{dt^2}$.
4. The unit vector $\frac{\vec{v}}{|\vec{v}|}$ is the direction of motion at time t .

Ex4(p684) Find the velocity, speed, and acceleration of a particle whose motion in space is given by the motion vector $\vec{r}(t) = 2\cos t \vec{i} + 2\sin t \vec{j} + 5\cos^2 t \vec{k}$.

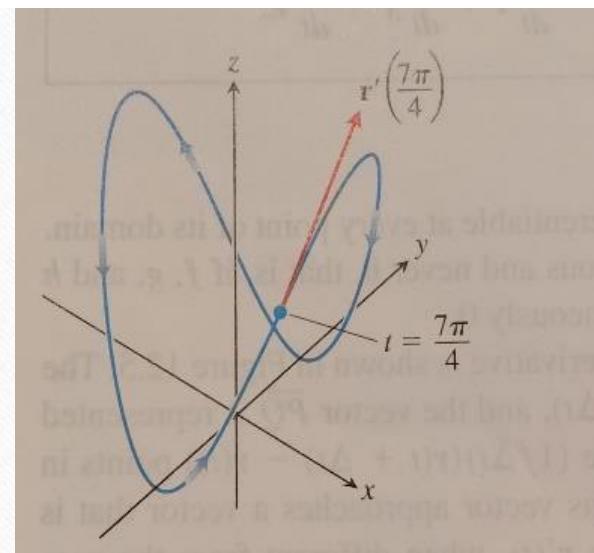
Sketch the velocity vector $\vec{v}\left(\frac{7\pi}{4}\right)$.

$$\vec{r}(t)$$

$$\vec{v}(t) = \vec{r}'(t) = -\sin t \vec{i} + 2\cos t \vec{j} - 10\cos t \sin t \vec{k}$$

$$|\vec{v}(t)| = \sqrt{4\sin^2 t + 4\cos^2 t + 100\cos^2 t \sin^2 t} = \sqrt{4 + 100\sin^2 t \cos^2 t}$$

$$\begin{aligned}\vec{a}(t) &= \vec{v}'(t) = -2\cos t \vec{i} - 2\sin t \vec{j} - 10(-\sin t + \cos t) \vec{k} \\ &= -2\cos t \vec{i} - 2\sin t \vec{j} + (10\sin^2 t - 10\cos^2 t) \vec{k} \\ &= -2\cos t \vec{i} - 2\sin t \vec{j} + 10\cos 2t \vec{k}\end{aligned}$$



1. *Constant Function Rule*: $\frac{d}{dt} \bar{C} = \bar{0}$.

2. *Scalar Multiple Rule*: $\frac{d}{dt} [\bar{c}\bar{u}(t)] = \bar{c}\bar{u}'(t)$,

$$\frac{d}{dt} [f(t)\bar{u}(t)] = f'(t)\bar{u}(t) + f(t)\bar{u}'(t)$$

3. *Dot Product Rule*: $\frac{d}{dt} [\bar{u}(t) \cdot \bar{v}(t)] = \bar{u}'(t) \cdot \bar{v}(t) + \bar{u}(t) \cdot \bar{v}'(t)$

4. *Cross Product Rule*: $\frac{d}{dt} [\bar{u}(t) \times \bar{v}(t)] = \bar{u}'(t) \times \bar{v}(t) + \bar{u}(t) \times \bar{v}'(t)$

5. *Chain Rule*: $\frac{d}{dt} [\bar{u}(f(t))] = f'(t)\bar{u}'(f(t))$

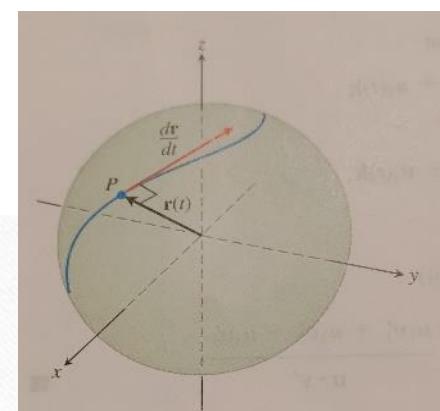
When a particle moves on a sphere centered at the origin, the position vector has a constant length equal to the radius of the sphere.

$$\vec{r}(t) \cdot \vec{r}(t) = |\vec{r}(t)|^2 = c^2$$

$$\frac{d}{dt} [\vec{r}(t) \cdot \vec{r}(t)] = \vec{r}'(t) \cdot \vec{r}(t) + \vec{r}(t) \cdot \vec{r}'(t) = 2\vec{r}'(t) \cdot \vec{r}(t) = 0$$

If \vec{r} is differentiable vector function of t and the length of $\vec{r}(t)$ is constant,

$$\text{then } \vec{r} \cdot \frac{d\vec{r}}{dt} = 0 .$$



HW12-1

- HW: 1,4,9,12,16,18