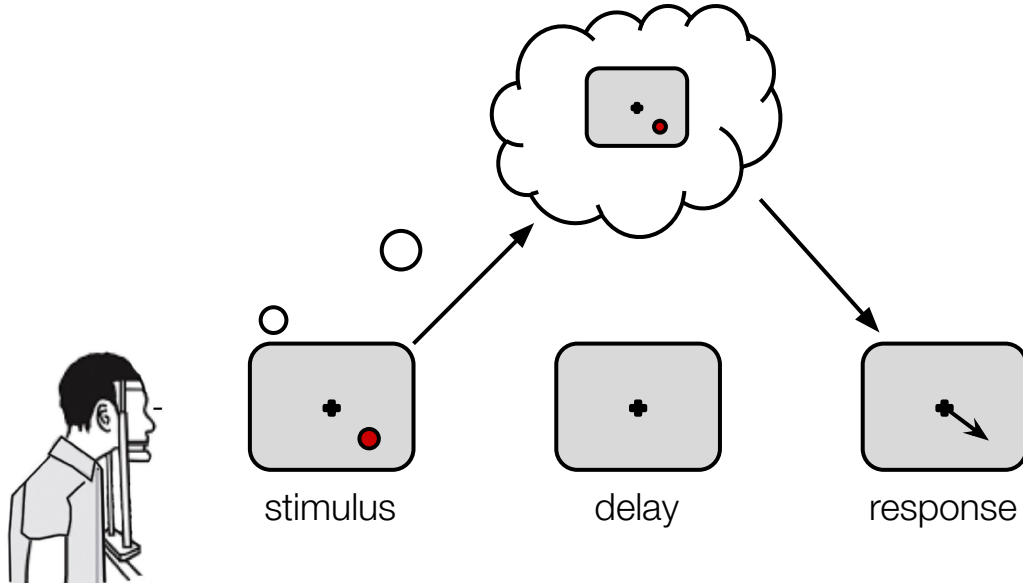
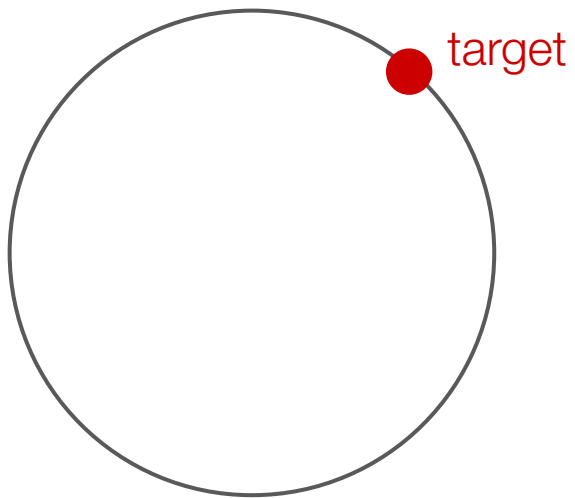


Mixture Models

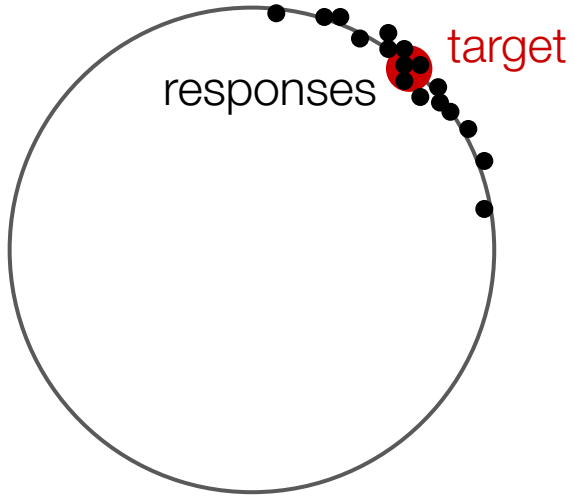
Classic WM task



Response distributions

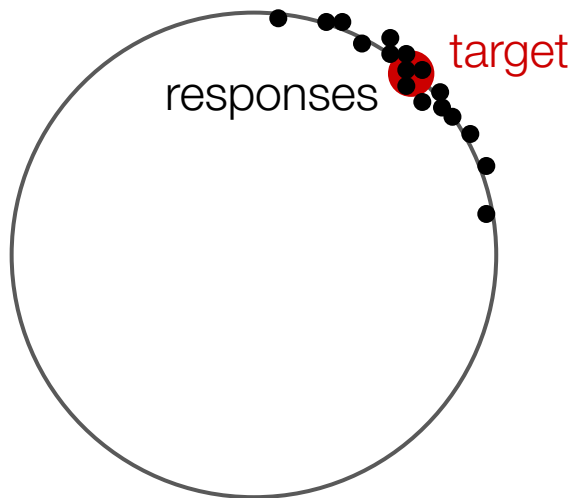


Response distributions

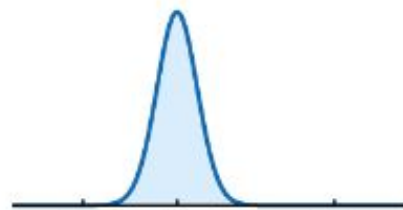


How precise is the working
memory representation?

Response distributions

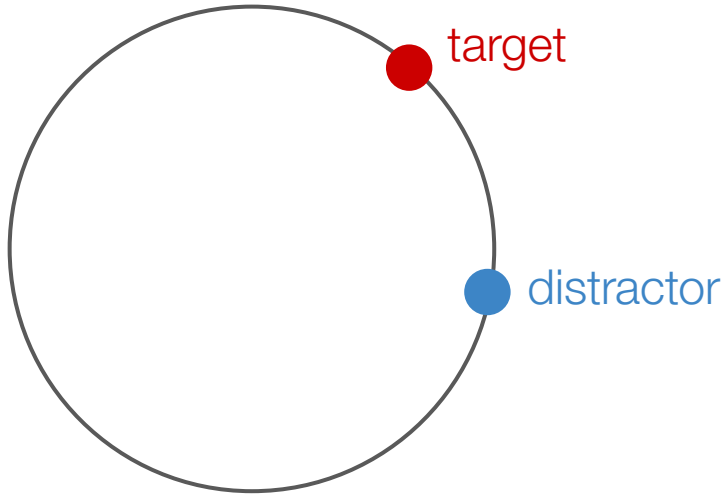


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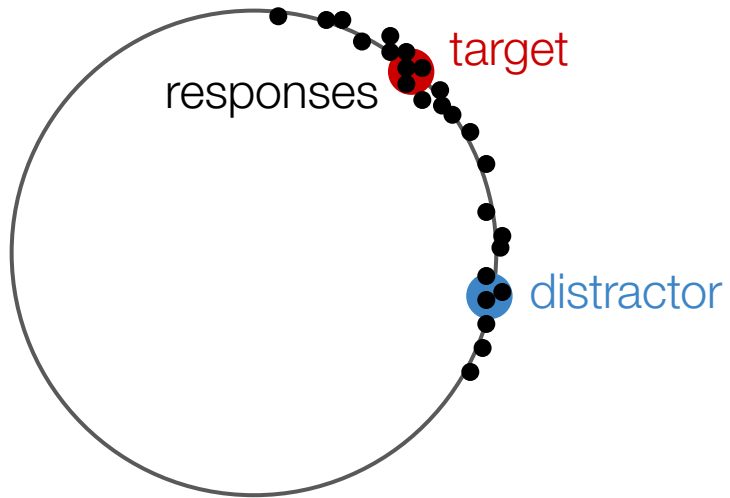


$$\theta = \{\mu, \sigma^2\}$$

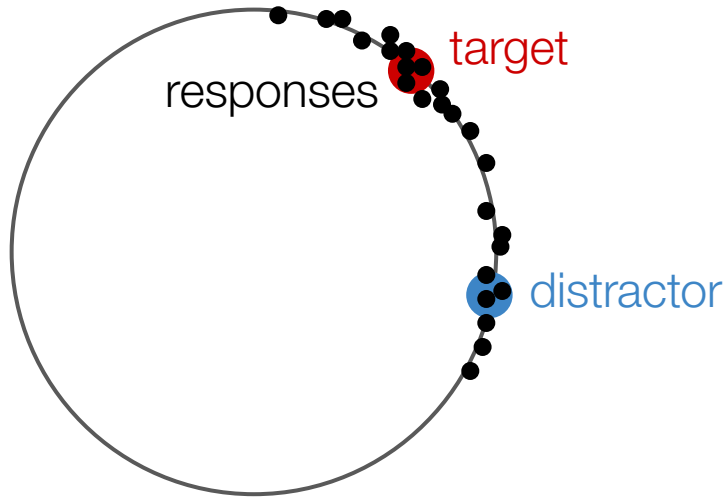
Response distributions



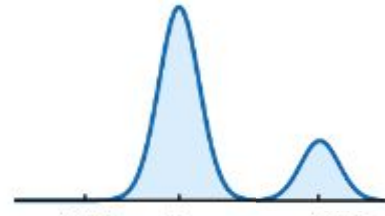
Response distributions



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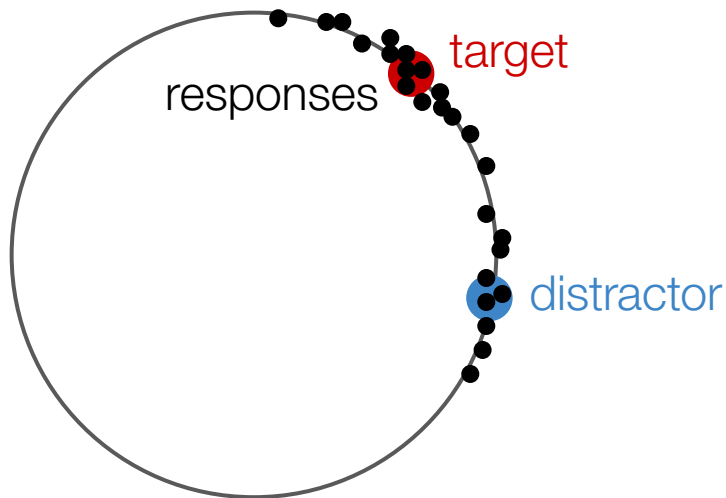


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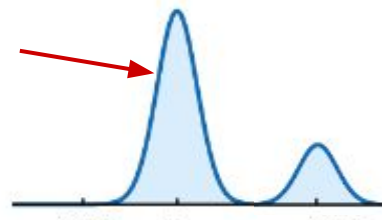


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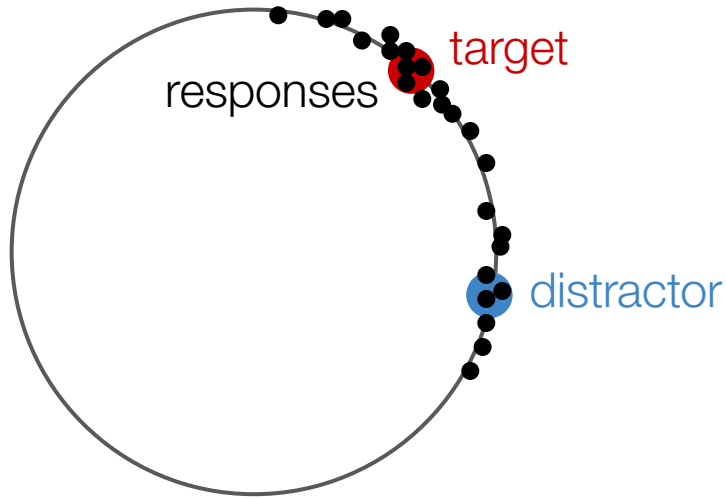


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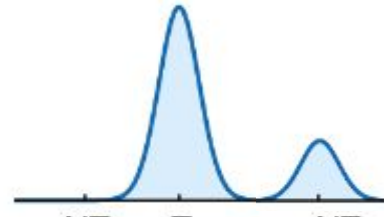


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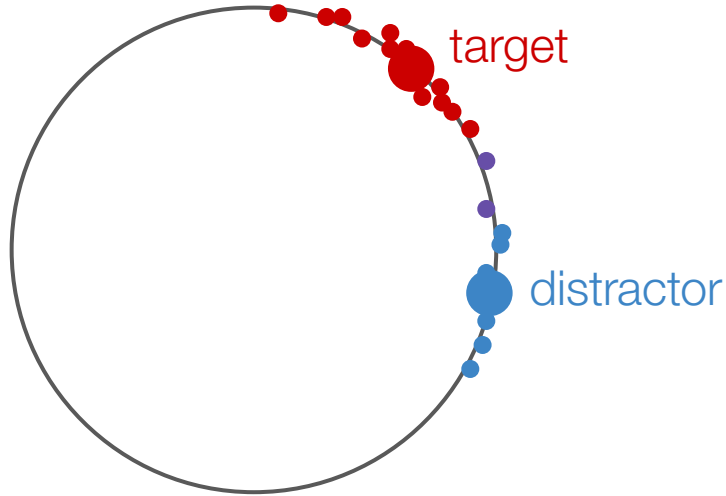


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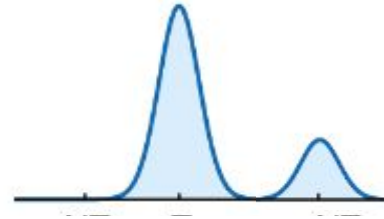


Which stimulus did the subject hold in mind in each trial?

Response distributions

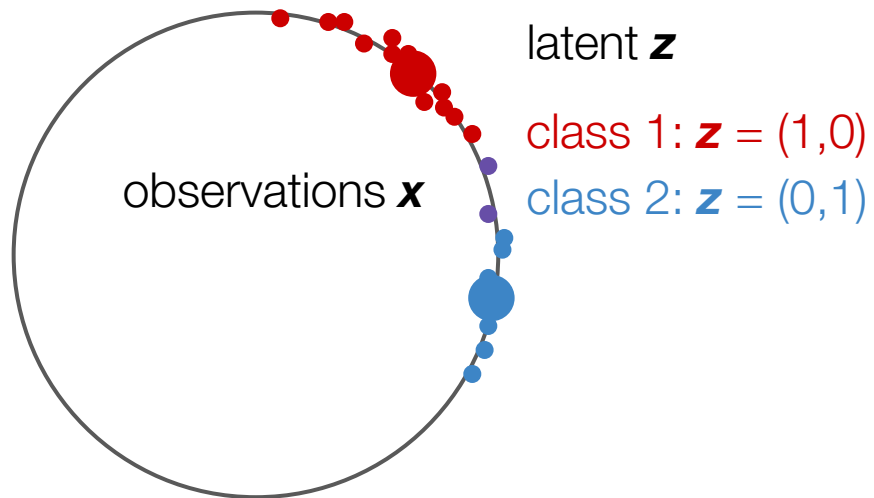


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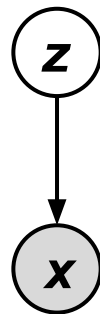
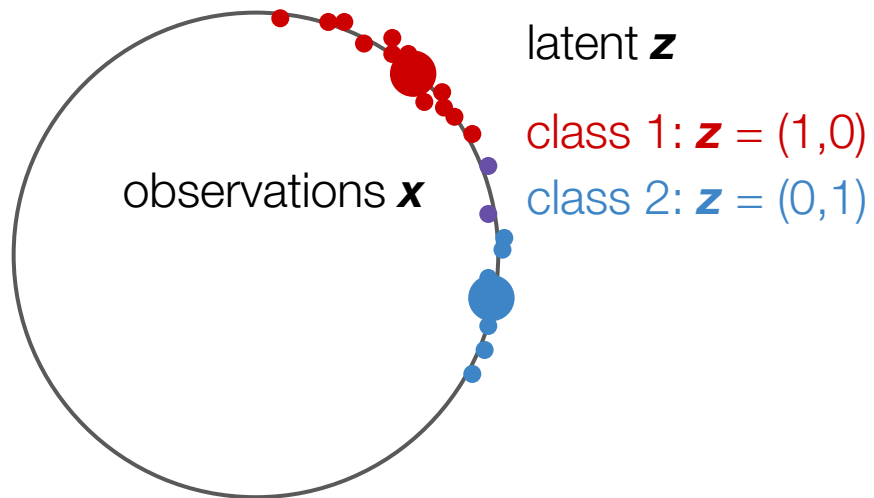


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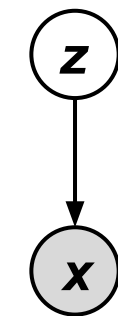
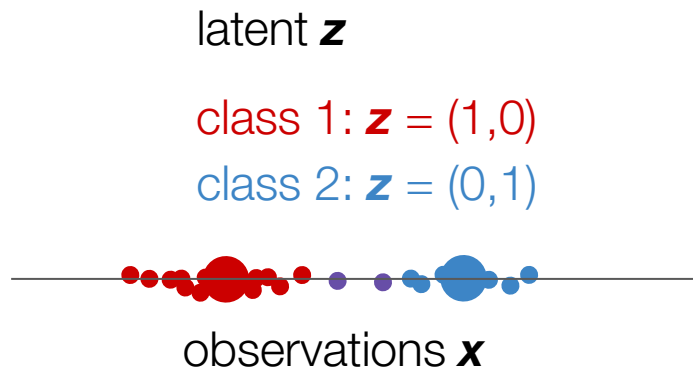
Mixture models



Mixture models



Mixture models



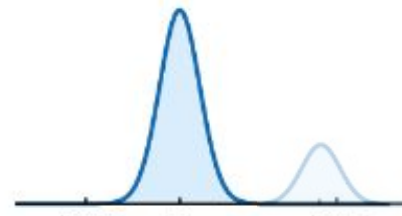
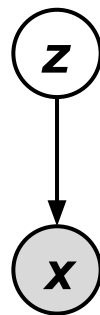
$$p(\mathbf{x} | \mathbf{z}_k = 1) = \mathcal{N}(\mu_k, \sigma_k^2)$$

Mixture models

latent \mathbf{z}

class 1: $\mathbf{z} = (1, 0)$

class 2: $\mathbf{z} = (0, 1)$



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Mixture models

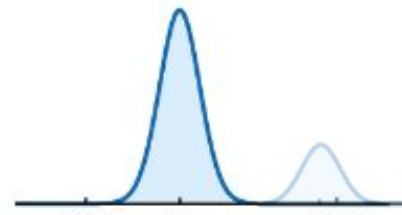
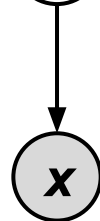
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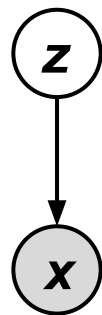
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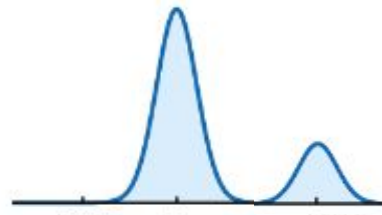
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But: We don't know
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$$p(\mathbf{x}) = \sum_z p(\mathbf{x}, \mathbf{z}) = \sum_z p(\mathbf{x}|\mathbf{z})p(\mathbf{z})$$

marginalization

 $= \sum_k \pi_k \mathcal{N}(\mu_k, \sigma_k^2)$

Expectation maximization (EM)

EM tackles two problems:

- 1) Determine which data point belongs to which class
- 2) Fit class-specific parameters

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EM tackles two problems:

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→ Inference of the **posterior** over the latent indicator variable \mathbf{z}

$$\begin{aligned} p(\mathbf{z}|\mathbf{x}) &= \frac{p(\mathbf{z})p(\mathbf{x}|\mathbf{z})}{p(\mathbf{x})} \\ &= \frac{\pi_k \mathcal{N}(\mu_k, \sigma_k)}{\sum_k \pi_k \mathcal{N}(\mu_k, \sigma_k)} \end{aligned}$$

Expectation maximization (EM)

EM tackles two problems:

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→ Inference of the **posterior** $p(\mathbf{z}|\mathbf{x}, \theta)$ over the latent indicator variable \mathbf{z}

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ML solution: Optimize $\ln p(\mathbf{x}) = \ln \sum_z p(\mathbf{x}, \mathbf{z}|\theta)$, but high computational cost

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Solution: Optimize expected value $\mathbb{E}_{\mathbf{z}} [\ln p(\mathbf{x}, \mathbf{z}|\theta')] = \sum_z p(\mathbf{z}|\mathbf{x}, \theta) \ln p(\mathbf{x}, \mathbf{z}|\theta')$

Expectation maximization (EM)

EM tackles two problems:

- 1) Determine which data point belongs to which class
→ Inference of the **posterior** $p(\mathbf{z}|\mathbf{x}, \theta)$ over the latent indicator variable \mathbf{z}
- 2) Fit class-specific parameters
→ Find parameters that optimize expected complete-data log likelihood

$$\mathbb{E}_{\mathbf{z}} [\ln p(\mathbf{x}, \mathbf{z}|\theta')] = \sum_{\mathbf{z}} p(\mathbf{z}|\mathbf{x}, \theta) \ln p(\mathbf{x}, \mathbf{z}|\theta')$$

Iterate

Tutorial

- Simulate observations from a generative model



Data is two-dimensional!

$$\mu = (\mu_x, \mu_y)$$

$$\Sigma = \begin{pmatrix} \sigma_x^2 & \sigma_x \sigma_y \\ \sigma_y \sigma_x & \sigma_y^2 \end{pmatrix} \quad \text{for each class}$$

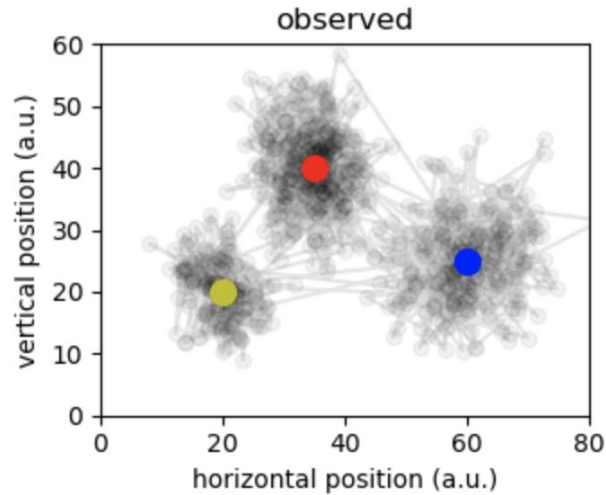
- Use EM to fit a Gaussian mixture model to simulated data

Mixture models

Hidden Markov Models

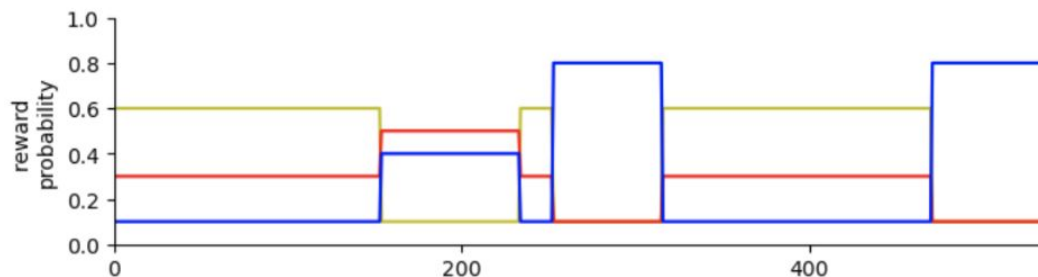
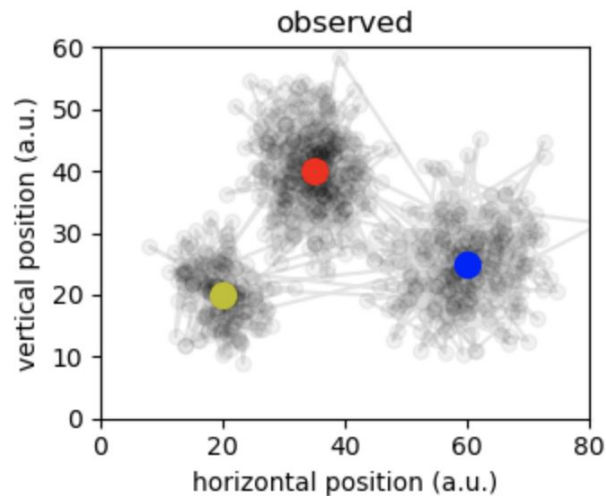
Hidden Markov Models

Same setup as before, but with sequential dependencies between data points



Hidden Markov Models

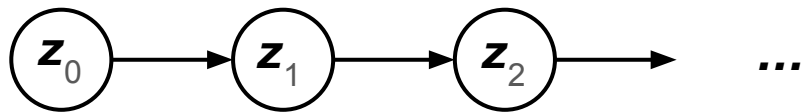
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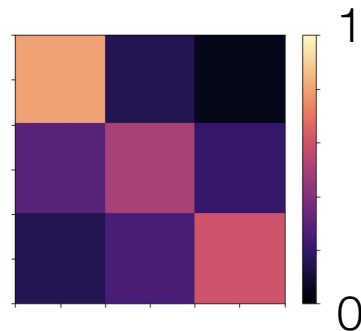
(e.g. because reward probabilities fluctuate in a block structure)

Hidden Markov Models

To capture sequential dependencies in choice behavior, we need an explicit model of transition structure of a latent variable, $p(\mathbf{z}_n | \mathbf{z}_{n-1})$



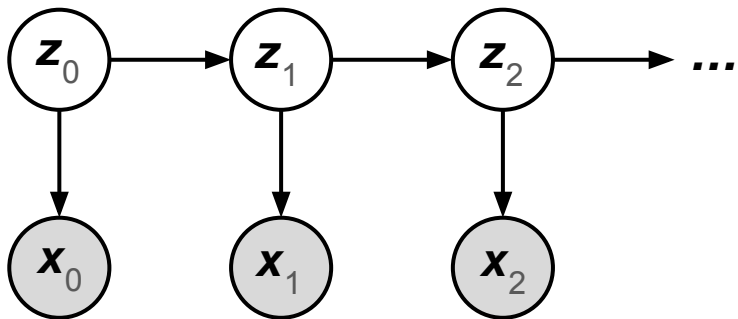
→ Transition matrix **A**



Hidden Markov Models

To capture sequential dependencies in choice behavior, we need an explicit model of transition structure of a latent variable, $p(\mathbf{z}_n | \mathbf{z}_{n-1})$

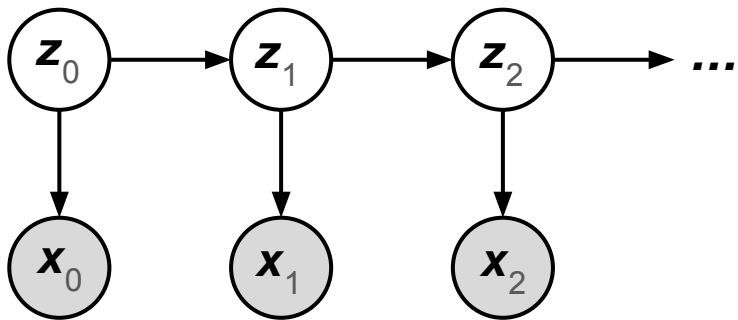
Saccades \mathbf{x} are an “emission” of the latent choice variable



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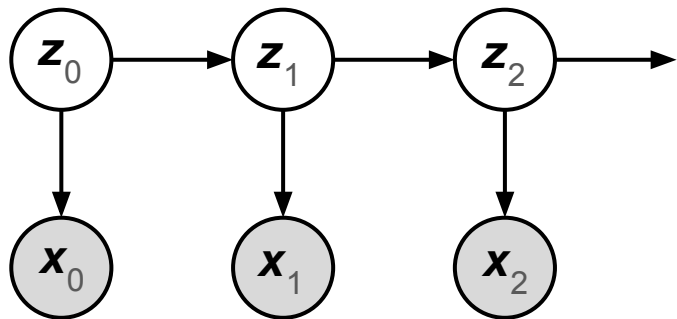
Joint distribution:

$$p(\mathbf{x}, \mathbf{z} | \theta) \\ = p(\mathbf{z}_0) \prod_{n=1}^N p(\mathbf{z}_n | \mathbf{z}_{n-1}) \prod_{n=0}^N p(\mathbf{x}_n | \mathbf{z}_n, \theta)$$

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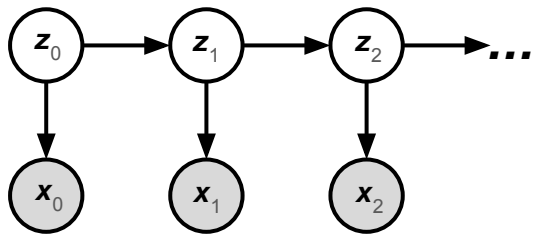
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Joint distribution:

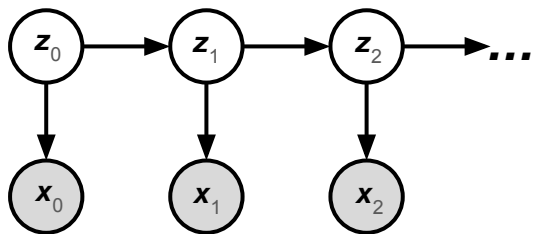
$$\begin{aligned} & \dots p(\mathbf{x}, \mathbf{z} | \theta) \\ &= \underbrace{p(\mathbf{z}_0)}_{\substack{\text{initial} \\ \text{state} \\ \pi}} \underbrace{\prod_{n=1}^N p(\mathbf{z}_n | \mathbf{z}_{n-1})}_{\substack{\text{state} \\ \text{transitions} \\ A}} \underbrace{\prod_{n=0}^N p(\mathbf{x}_n | \mathbf{z}_n, \theta)}_{\substack{\text{likelihoods} \\ \mathcal{N}(\mathbf{x}_n; \mu_k, \Sigma_k)}} \end{aligned}$$

EM for Hidden Markov Models



$$p(\mathbf{x}, \mathbf{z} | \theta) = p(z_0) \prod_{n=1}^N p(z_n | z_{n-1}) \prod_{n=0}^N p(x_n | z_n, \theta)$$

EM for Hidden Markov Models

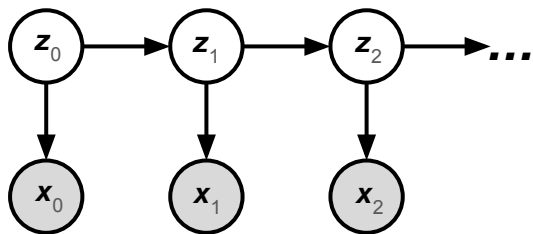


$$p(\mathbf{x}, \mathbf{z}|\theta) = p(\mathbf{z}_0) \prod_{n=1}^N p(\mathbf{z}_n|\mathbf{z}_{n-1}) \prod_{n=0}^N p(\mathbf{x}_n|\mathbf{z}_n, \theta)$$

We want to infer the latent states \mathbf{z} , and estimate parameters $\theta = \{\boldsymbol{\pi}, \mathbf{A}, \boldsymbol{\mu}, \boldsymbol{\Sigma}\}$

E-Step: infer posteriors and calculate initial state and state transition probabilities $\boldsymbol{\pi}, \mathbf{A}$

EM for Hidden Markov Models



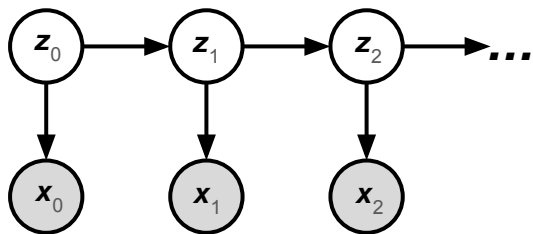
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EM for Hidden Markov Models



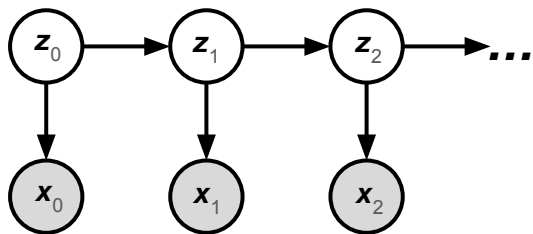
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→ **easy!**

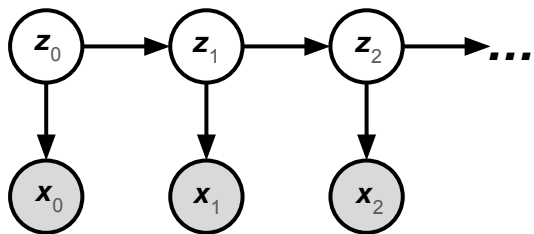
EM for Hidden Markov Models



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EM for Hidden Markov Models



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E-Step: infer posteriors

→ In HMMs, there are two posteriors over \mathbf{z} :

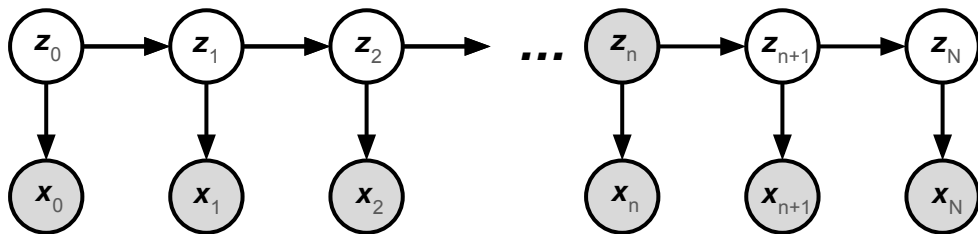
$$p(\mathbf{z}_n|\mathbf{x}, \theta)$$

probability of each latent state value

$$p(\mathbf{z}_n, \mathbf{z}_{n-1}|\mathbf{x}, \theta)$$

probability of observing a pair of subsequent states

EM for Hidden Markov Models

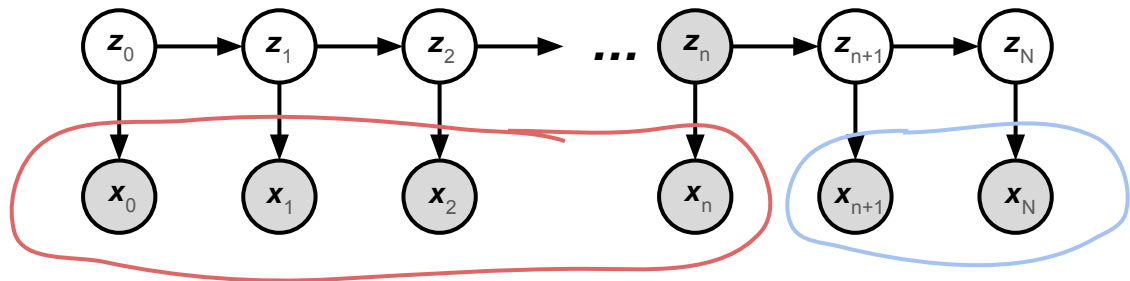


E-Step: infer posteriors

For this, again we use Bayes theorem
$$p(z_n | \mathbf{x}_{0:N}, \theta) = \frac{p(\mathbf{x}_{0:N} | z_n, \theta) p(z_n)}{p(\mathbf{x}_{0:N})}$$

(and equivalent for $p(z_n, z_{n-1} | \mathbf{x}, \theta)$)

EM for Hidden Markov Models



For a given state \mathbf{z}_n in trial n , we can split the likelihood in two terms:

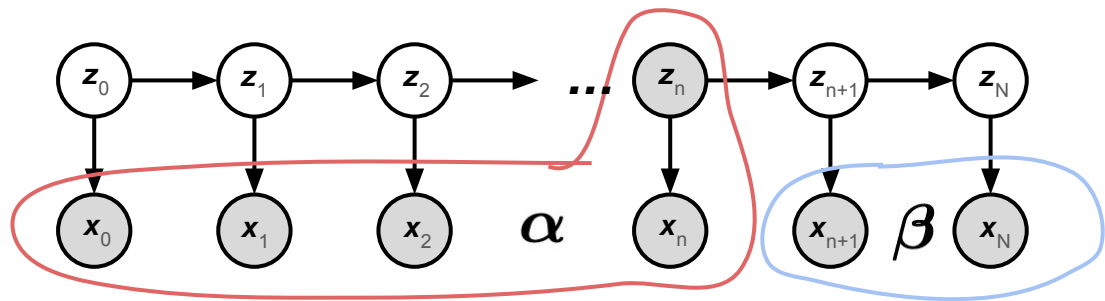
$$p(\mathbf{x}_{0:n} | \mathbf{z}_n, \theta), \quad p(\mathbf{x}_{n+1:N} | \mathbf{z}_n, \theta)$$

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EM for Hidden Markov Models



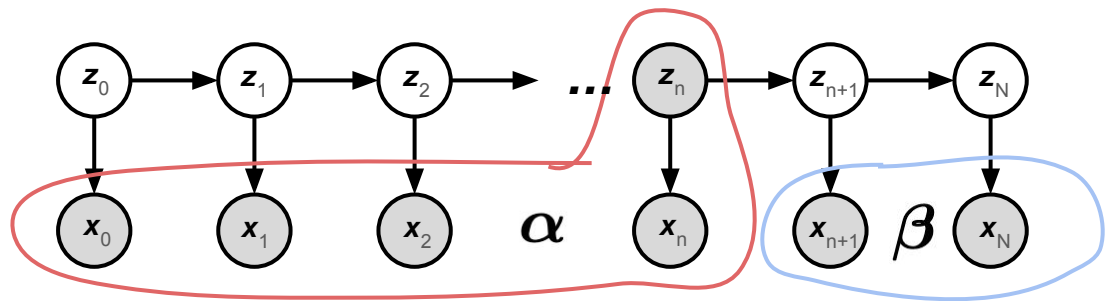
We include $p(z_n)$:

$$\underbrace{p(\mathbf{x}_{0:n}, z_n | \theta)}_{\alpha}, \underbrace{p(\mathbf{x}_{n+1:N} | z_n, \theta)}_{\beta}$$

E-Step: infer posteriors

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EM for Hidden Markov Models



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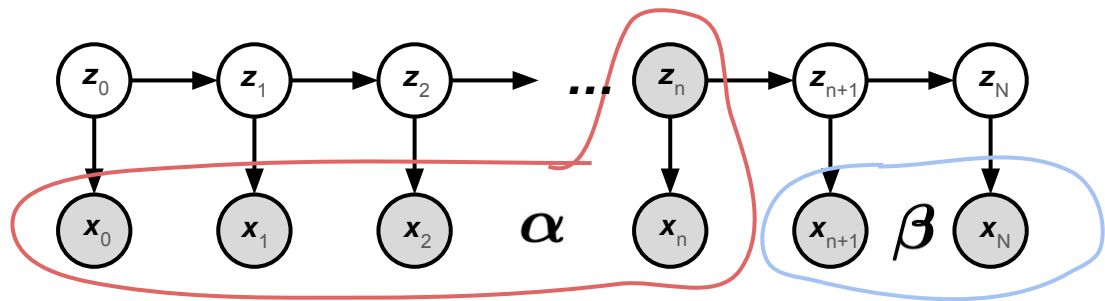
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Then the posterior becomes

$$p(\mathbf{z}_n | \mathbf{x}_{0:N}, \theta) = \frac{\alpha(\mathbf{z}_n) \beta(\mathbf{z}_n)}{p(\mathbf{x}_{0:N})}$$

EM for Hidden Markov Models



We include $p(z_n)$:

$$p(x_{0:n}, z_n | \theta), \quad p(x_{n+1:N} | z_n, \theta)$$

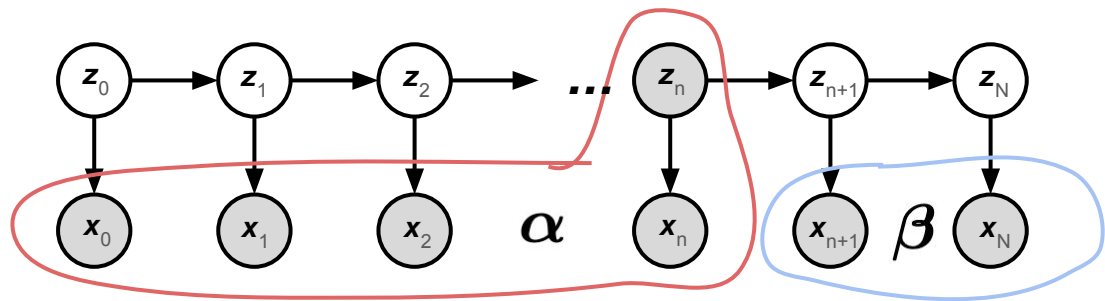
α

β

→ **Good news:**

1. There is an efficient algorithm for calculating α and β (the Baum-Welch / forward-backward algorithm)

EM for Hidden Markov Models



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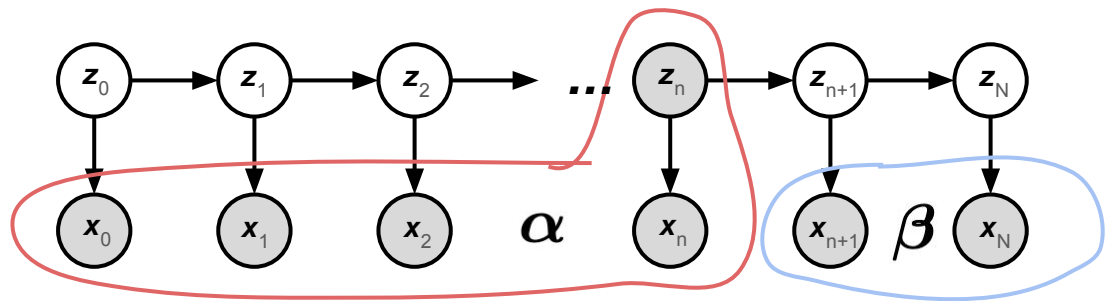
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2. Both posteriors can be calculated from α and β

EM for Hidden Markov Models



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$$p(x_{0:n}, z_n | \theta), \quad p(x_{n+1:N} | z_n, \theta)$$

α

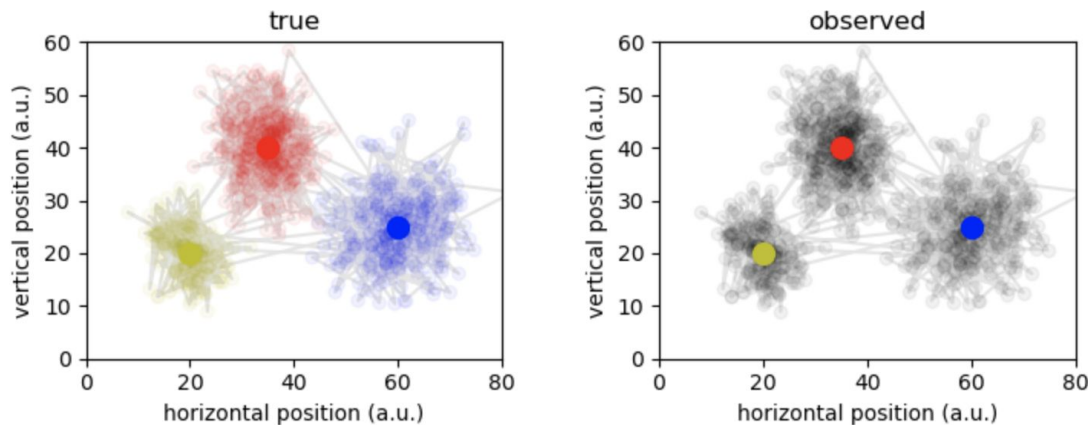
β

→ **Good news:**

1. There is an efficient algorithm for calculating α and β (the Baum-Welch / forward-backward algorithm)
2. Both posteriors can be calculated from α and β
3. M-Step is straightforward

Tutorial

- Simulate observations from a generative model



- Use EM with forward-backward algorithm to fit an HMM to simulated data

Closing remarks

Mixture Models

More flexible models are possible! e.g. when target positions change from trial to trial

$$x^{(1)} = x_{\text{saccade}} - x_{\text{target}}$$

$$x^{(2)} = x_{\text{saccade}} - x_{\text{distractor}}$$

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$$x^{(2)} = x_{\text{saccade}} - x_{\text{distractor}}$$

Mixtures of different distributions (e.g. Gaussian, uniform, Student t... → last exercise)

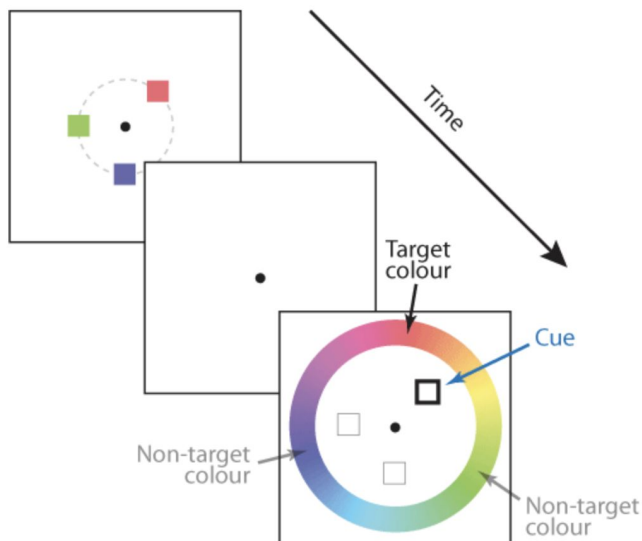
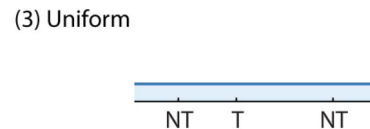
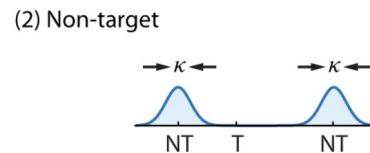
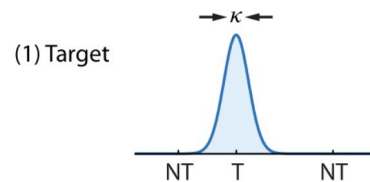


Figure 1 | The colour report task.



Bays, Catalao &
Husain, *J Vis* (2009);
Schneegans & Bays,
Cortex (2016)

Remarks on emission models

Gaussian emission models: $p(\mathbf{x}|z_k = 1, \theta_k) = \mathcal{N}(\mathbf{x}|\mu_k, \Sigma_k)$

Other (including more complex) emission models are possible:

- Student t (see tutorial), Poisson, etc... (continuous observations \mathbf{x})
- Categorical emissions (discrete observations \mathbf{x})

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- Combine them, you get switching DDMs
-

Remarks on emission models

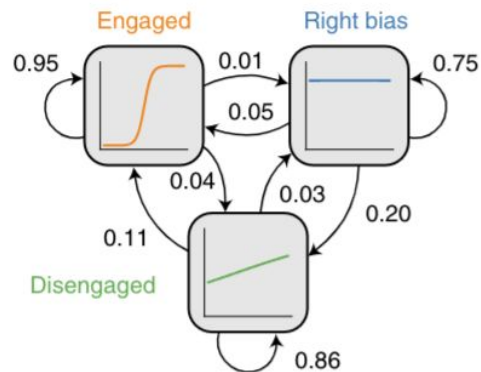
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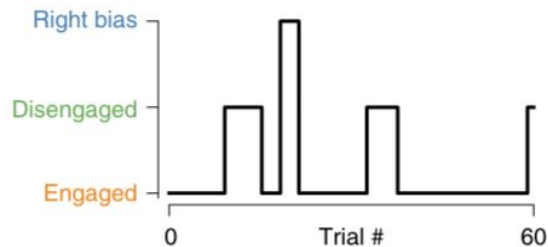
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- Combine them, you get switching DDMs
- Switching factor analysis (if you include an extra set of continuous latents that depend on the state)

Examples of HMMs in neuroscience

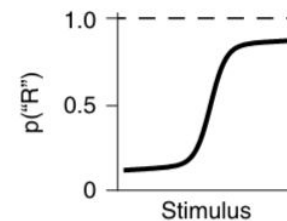
d Three-state GLM-HMM



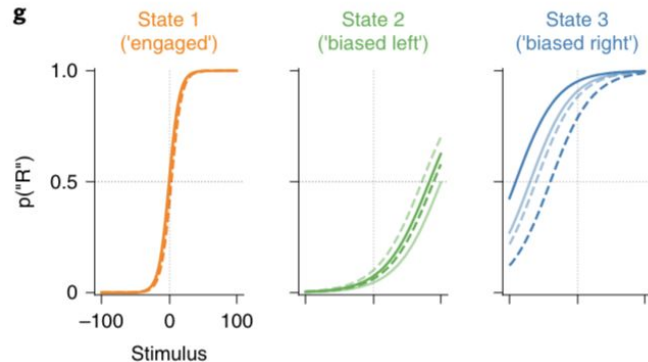
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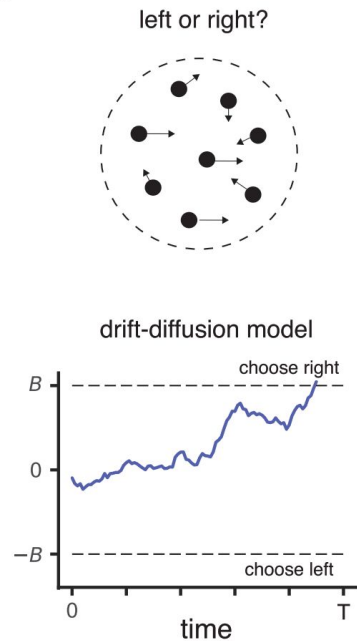


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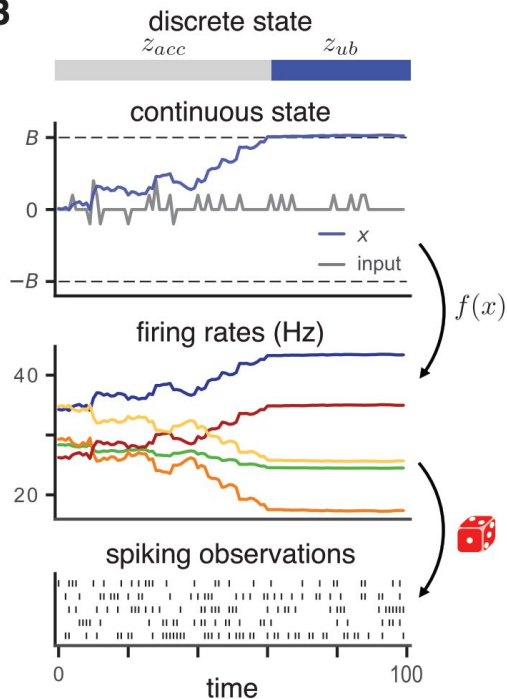


Examples of HMMs in neuroscience

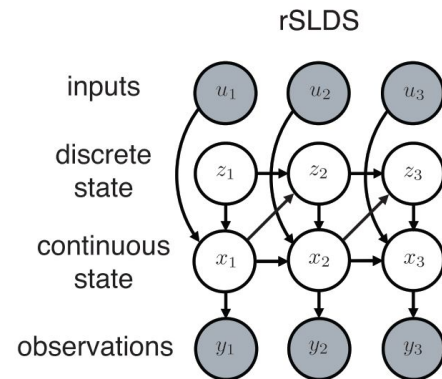
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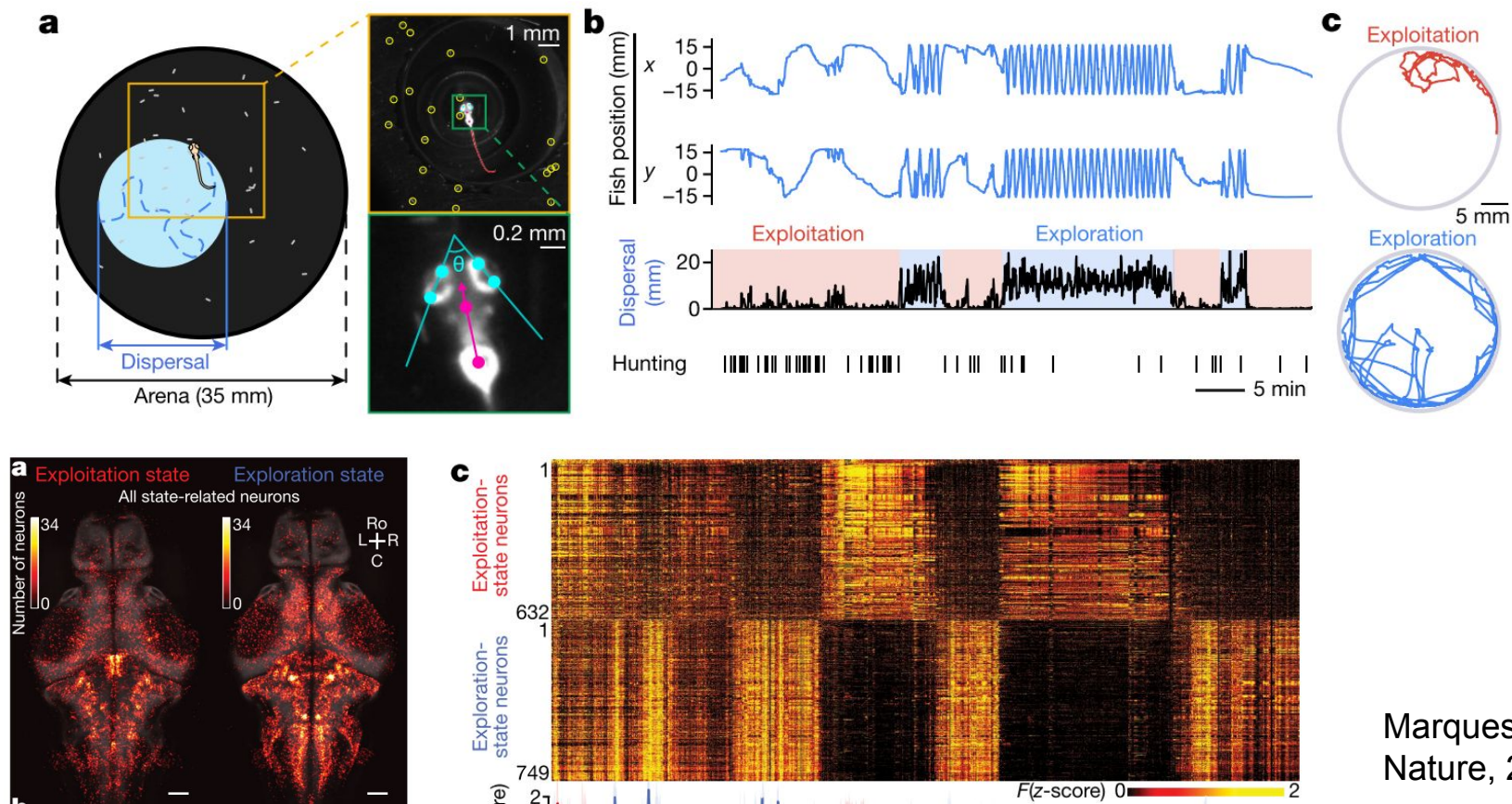
B



C



Examples of HMMs in neuroscience



Marques et al.,
Nature, 2019

Examples of HMMs in neuroscience

Wiltchko et al.,
Neuron, 2015

