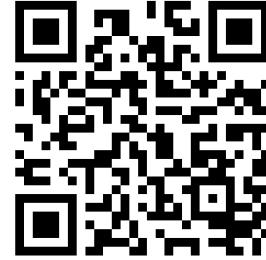


Information Theory With Applications to Data Compression

Robert Bamler · Tutorial at IMPRS-IS Boot Camp 2024

While you're waiting:

If you brought a laptop (optional), please go to <https://bamler-lab.github.io/bootcamp24> and test if you can run the linked Google Colab notebook. You can also find the slides at this link.



Let's Debate

Slides and code available at:
<https://bamler-lab.github.io/bootcamp24>

- 1. Which of the following two messages contains more information?**
 - (a) "The instructor of this tutorial knows how to solve a quadratic equation."
✓ longer; ✗ not much new information (little surprise); ✓ useful to judge my qualification.
 - (b) "The instructor of this tutorial likes roller coasters."
✓ new information; ✗ do you really care?
- 2. Which of the following two pairs of quantities are more strongly correlated?**
 - (a) the volumes and radii of (spherical) glass marbles (of random sizes and colors)
✓ exact correspondence: $V = \frac{4}{3}\pi r^3$, so once we know r , telling us V gives us no new information.
✗ nonlinear relation \Rightarrow lower Pearson's correlation coefficient (see code).
 - (b) the volumes and masses of glass marbles (of random sizes and colors)
✓ linear relation: $m = \rho V$, so m and V essentially convey the same information in different units;
✗ not an exact correspondence: density ρ varies slightly depending on color;
 \Rightarrow even if we know V , we can still learn some new information by measuring m and vice versa.

So, What is Information Theory?

Information theory provides tools to analyze:

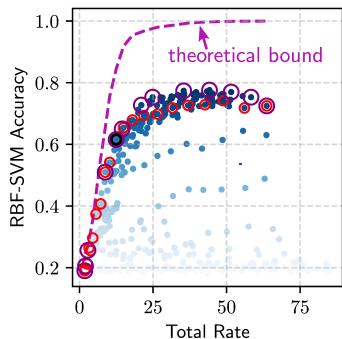
- ▶ the quantity (i.e., amount) of information in some data;
- ▶ more precisely, the amount of novelty/surprisingness of a piece of information w.r.t.:
 - (a) prior beliefs (e.g., an ML researcher probably knows high-school math); or
 - (b) a different piece of information (when quantifying correlations).

Information theory is oblivious to:

- ▶ the quality of a piece of information (e.g., its utility, urgency, or even truthfulness).
- ▶ how a piece of information is represented in the data, e.g.,
 - ▶ the volume and radius of a sphere are different representations of the same piece of information;
 - ▶ for a given neural network with known weights, its output cannot contain more information than its input. *⇒ Inf. theory can provide upper bounds, e.g., on how much useful information an optimal model can extract from some latent representation.*
- ▶ computational costs: compressed representations of the same information are sometimes easier but often harder to process than their uncompressed counterparts.

Where Are These Tools Useful?

Theoretical bounds for model performance



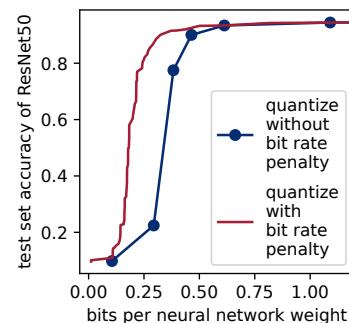
[Tim Xiao, RB, ICLR 2023]

Analyze abstract representation vectors

Metric	Dataset	Baseline
Specificity $MI(s; \ell) \uparrow$	Assist12	8.3
Consistency $^{-1}$ $\mathbb{E}_{\ell_{\text{sub}}} MI(s^{\ell}; \ell_{\text{sub}}) \downarrow$	Assist12	12.1
Disentanglement $D_{\text{KL}}(s \ \ell) \uparrow$	Assist12	2.1
	Assist17	10.1
	Junyi15	13.1
	Assist17	6.4
	Junyi15	7.7
	Assist17	0.6
	Junyi15	5.0

[Hanzi Zhou, RB, C. M. Wu, Á. Tejero-Cantero, ICLR 2024]

Data Compression (“Source Coding”)



[Alexander Conzelmann, RB; coming soon]

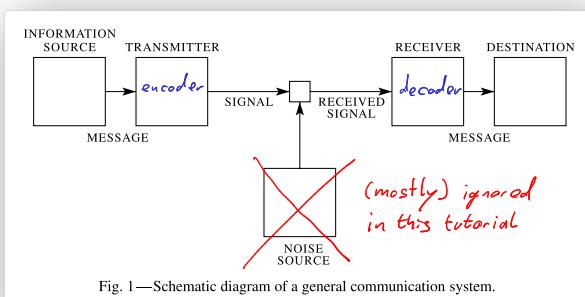
My Promise for This Tutorial

Why?

What for?

Quantifying Information

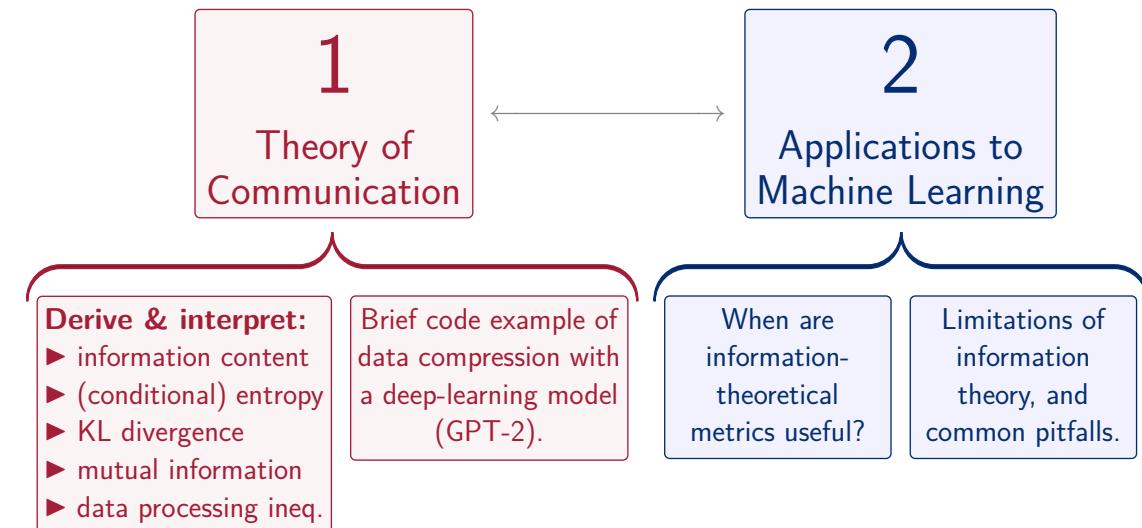
[Shannon, *A Mathematical Theory of Communication*, 1948]



Def. “information content of a message”:

The **minimum number of bits** that you would have to transmit over a noise-free channel in order to communicate the message, **assuming an optimal encoder and decoder**.

- ▶ What does “optimal” mean?
- ▶ You don’t actually have to construct an optimal encoder & decoder to calculate this number.



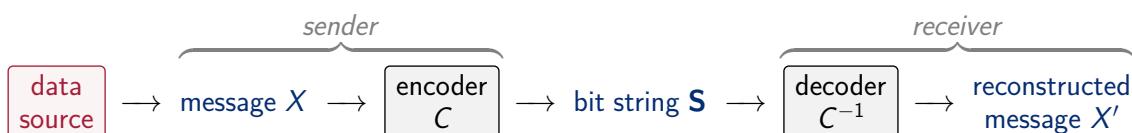
Data Compression: Precise Problem Setup



Assumptions:

- ▶ the bit string S is sent over a *noise free channel* (we won't cover *channel coding*);
- ▶ *lossless* compression: we require that $X' = X$; ($|S| = |C(X)| < \infty \forall x \in \mathcal{X}$, but f.t. $x \mapsto |C(x)|$ may be unbounded)
- ▶ S may have a different length $|S|$ for different messages: $S \in \{0,1\}^* := \bigcup_{n=0}^{\infty} \{0,1\}^n$;
 - ▶ But: the encoder must *not* encode any information in the *length* of S alone (see next slide).
- ▶ Before the sender sees the message, sender and receiver can communicate arbitrarily much for free in order to agree on a *code* C : message space $\mathcal{X} \rightarrow \{0,1\}^*$.
- ▶ **Goal:** find a valid code C that minimizes the *expected bit rate* $\mathbb{E}_{P_{\text{data source}}(X)}[|C(X)|]$.

What's a “Valid Code”? (Unique Decodability)



Recall:

- ▶ The bit string $S = C(X) \in \{0,1\}^*$ can have different lengths for different messages X .
- ▶ We want to interpret its length $|S|$ as the *amount of information* in the message X .
 - ▶ Seems to make sense: if the sender sends, e.g., a bit string of length 3 to the receiver, then they can't communicate more than 3 bits of information ...
 - ▶ ... unless the fact that $|S| = 3$ already communicates some information. **We want to forbid this.**
- ▶ **Add additional requirement:** C must be *uniquely decodable*:
 - ▶ Sender may concatenate the encodings of several messages: $S := C(X_1) \parallel C(X_2) \parallel C(X_3) \parallel \dots$
 - ▶ Upon receiving S , the receiver must still be able to detect where each part ends.

Source Coding Theorem

Theorem (Shannon, 1949): Consider a data source $P(X)$ over a discrete message space \mathcal{X} .

- **The bad news:** in expectation, lossless compression can't beat the entropy:

$$\forall \text{ uniquely decodable codes } C: \mathbb{E}_P[|C(X)|] \geq \mathbb{E}_P[-\log_2 P(X)] =: H_P(X).$$

- **The good news:** but one can get quite close (and not just in expectation):

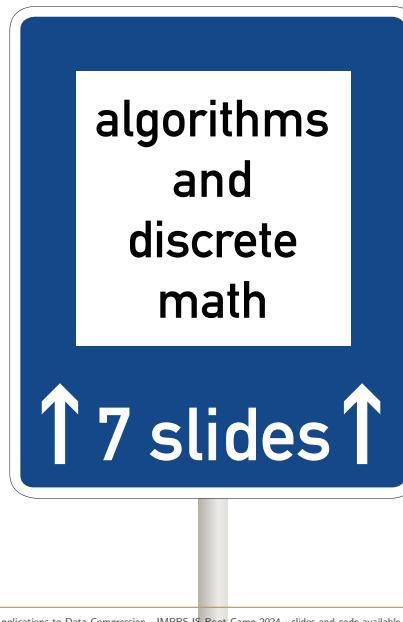
$\exists \text{ uniquely decodable code } C:$

$$\forall \text{ messages } x \in \mathcal{X}: |C(x)| < -\log_2 P(X=x) + 1.$$
$$(\Rightarrow \mathbb{E}_P[|C(X)|] < H_P(X) + 1)$$

Useful because
it allows us to
easily calculate
(and differentiate
through) the bit rate
of an optimal code
without having to
explicitly construct it.

- Also, we can keep the total overhead < 1 bit even when encoding several messages.

⇒ $-\log_2 P(X=x)$ is the contribution of message x to the bit rate of an optimal code
when we amortize over many messages. It is called “**information content of x** ”.



The Kraft-McMillan Theorem [Kraft, 1949; McMillan, 1956]

- (a) $\forall \text{ uniquely decodable codes } C : \mathcal{X} \rightarrow \{0, 1\}^*$ over some message space \mathcal{X} :

$$\underset{\substack{\text{(not an expectation,} \\ \text{just a normal sum)}}}{\sum_{x \in \mathcal{X}}} 2^{-|C(x)|} \leq 1 \quad (\text{"Kraft inequality"}).$$

Interpretation: we have a finite budget of “shortness” for bit strings:

- Interpret $2^{-|C(x)|}$ as the “shortness” of bit string $C(x)$.

- The sum of all “shortnesses” must not exceed 1.

⇒ If we shorten one bit string then we may have to make another bit string longer so that we don't exceed our “shortness budget”.

- (b) $\forall \text{ functions } \ell : \mathcal{X} \rightarrow \mathbb{N} \text{ that satisfy the Kraft inequality (i.e., } \sum_{x \in \mathcal{X}} 2^{-\ell(x)} \leq 1\text{:)}$
 $\exists \text{ uniquely decodable code } C_\ell \text{ with } |C_\ell(x)| = \ell(x) \ \forall x \in \mathcal{X}.$

Why is this theorem useful? ⇒ $\min \mathbb{E}_P[\text{bit rate}] = \min_{\substack{C: \text{unq.} \\ \text{decodable}}} \mathbb{E}_P[|C(X)|] = \min_{\substack{C: \text{satisfies} \\ \text{Kraft ineq.}}} \mathbb{E}_P[|C(X)|]$

Preparations for Proof of KM Theorem

Definition: For a code $C : \mathcal{X} \rightarrow \{0, 1\}^*$, define

$$C^* : \mathcal{X}^* \rightarrow \{0, 1\}^*, \quad C^*((x_1, x_2, \dots, x_k)) := C(x_1) \parallel C(x_2) \parallel \dots \parallel C(x_k).$$

(Thus: C is uniquely decodable $\iff C^*$ is injective)

Lemma:

- let: $\begin{cases} C \text{ be a uniquely decodable code over } \mathcal{X}; \\ n \in \mathbb{N}_0; \\ Y_n := \{x \in \mathcal{X}^* \text{ with } |C^*(x)| = n\}. \end{cases}$

- then: $|Y_n| \leq 2^n$.

Proof: C^* is injective $\Rightarrow |Y_n| = |C^*(Y_n)|$
 $C^*(Y_n) \subseteq \{0, 1\}^n \Rightarrow |C^*(Y_n)| \leq |\{0, 1\}^n| = 2^n \Rightarrow |Y_n| \leq 2^n \quad \square$

Proof of Part (a) of KM Theorem

Lemma (reminder): $|Y_n| \leq 2^n$ where $Y_n := \{x \in \mathcal{X}^* \text{ with } |C^*(x)| = n\}$, C uniq. dec.

Claim (reminder): C is uniquely decodable $\Rightarrow \sum_{x \in \mathcal{X}} 2^{-|C(x)|} \leq 1$.

Let $k \in \mathbb{N}$;

$$r^k = \left(\sum_{x \in \mathcal{X}} 2^{-|C(x)|} \right) \left(\sum_{x \in \mathcal{X}} 2^{-|C(x)|} \right) \dots \left(\sum_{x \in \mathcal{X}} 2^{-|C(x)|} \right) = \sum_{x \in \mathcal{X}^k} 2^{-\sum_{i=1}^k |C(x_i)|} = |C^*(x)|$$

- (i) if \mathcal{X} is finite:

$$\text{Let } \gamma := \max_{x \in \mathcal{X}} |C(x)| < \infty \Rightarrow \forall x \in \mathcal{X}^k: |C^*(x)| \leq k\gamma \Rightarrow \mathcal{X}^k \subseteq \bigcup_{n=0}^{k\gamma} Y_n$$

$$\Rightarrow r^k \leq \sum_{n=0}^{k\gamma} \sum_{x \in Y_n} 2^{-|C^*(x)|} = \sum_{n=0}^{k\gamma} |Y_n| 2^{-n} \leq k\gamma + 1 \Rightarrow \forall k \in \mathbb{N}: \frac{r^k}{k} \leq \gamma + \frac{1}{k}$$

- (ii) if \mathcal{X} is countably infinite:

$$\text{w.r.t. } \mathcal{X} = \mathbb{N} \Rightarrow \sum_{x \in \mathcal{X}} 2^{-|C(x)|} = \sum_{x=1}^{\infty} 2^{-|C(x)|} \stackrel{\text{all terms} \geq 0}{=} \lim_{N \rightarrow \infty} \sum_{x=1}^N 2^{-|C(x)|} \stackrel{\leq 1 \text{ by (i)}}{\leq} 1$$

Proof of Part (b) of KM Theorem

Note: computationally efficient variants of this idea:
driftmetrie coding and range coding

Claim (reminder): $\sum_{x \in \mathcal{X}} 2^{-\ell(x)} \leq 1 \Rightarrow \exists \text{ uniq. dec. code } C_\ell \text{ with } |C_\ell(x)| = \ell(x) \forall x \in \mathcal{X}$.

Algorithm 1: Construction of C_ℓ .

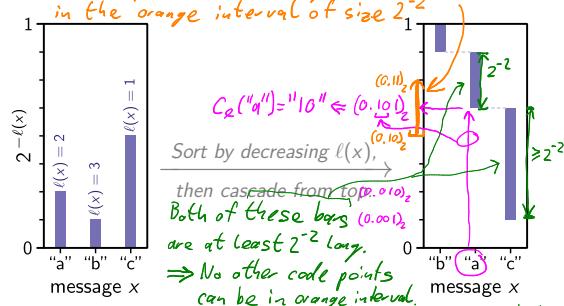
Initialize $\xi \leftarrow 1$;

for $x \in \mathcal{X}$ in order of nonincreasing $\ell(x)$ do

 Update $\xi \leftarrow \xi - 2^{-\ell(x)}$;

 Write $\xi \in [0, 1)$ in binary: $\xi = (0.??? \dots)_2$;

 Set $C_\ell(x)$ to the first $\ell(x)$ bits after the "0."
 (pad with trailing zeros if necessary);



Claim: the resulting code C_ℓ is uniquely decodable.

- We even show: C_ℓ is prefix free: $\forall x \in \mathcal{X}: C_\ell(x)$ is not the beginning of any $C_\ell(x')$, $x' \neq x$.
- Formalization of this proof: see solutions to Problem 2.1 on this problem set:
<https://robamler.github.io/teaching/compress23/problem-set-02-solutions.zip>

algorithms and discrete math

Ende

Quantifying Uncertainty in Bits (for Discrete Data)



- ▶ **Information content:** $-\log_2 P(X=x)$: The (amortized) bit rate for encoding the given message x with a code that is optimal (in expectation) for the data source P .
- ▶ **Entropy:** $H_P(X) = \mathbb{E}_P[-\log_2 P(X)] \equiv H[P(X)] \equiv H[P]$: The expected bit rate for encoding a (random) message from data source P with a code that is optimal for P .
= How many bits does receiver need (in expectation) to reconstruct X ?
= How many bits does receiver need (in expectation) to resolve any *uncertainty* about X ?
- ▶ **Cross entropy:** $H[P, Q] = \mathbb{E}_P[-\log_2 Q(X)] \geq H[P]$:
The expected bit rate when encoding a message from data source P with a code that is optimal for a model Q of the data source (\Rightarrow practically achievable expected bit rate).
 \rightarrow We'd want to minimize this over the model Q . \rightarrow Maximum likelihood estimation.
- ▶ **Kullback-Leibler divergence:** $D_{KL}(P \parallel Q) = H[P, Q] - H[P] = \mathbb{E}_P\left[-\log_2 \frac{Q(X)}{P(X)}\right] \geq 0$:
Overhead (in expected bit rate) due to a mismatch between the true data source P and its model Q (also called "relative entropy").
 D_{KL} can be ∞ (if $\exists x_0$ where $P(x=x_0) > 0$ but $Q(x=x_0) = 0$).
 \Rightarrow Interpretation: optimal code for model Q could not encode x_0 .

Agenda



1

Theory of
Communication

2

Applications to
Machine Learning

Derive & interpret:

- ▶ information content
- ▶ (conditional) entropy
- ▶ KL divergence
- ▶ mutual information
- ▶ data processing ineq.

Brief code example of
data compression with
a deep-learning model
(GPT-2).

When are
information-
theoretical
metrics useful?

Limitations of
information
theory, and
common pitfalls.

Example 1: Text Compression With GPT-2



Autoregressive language model:

- ▶ Message \mathbf{x} is a sequence of tokens: $\mathbf{x} = (x_1, x_2, \dots, x_n)$.
- ▶ $P(\mathbf{X}) = P(X_1) P(X_2 | X_1) P(X_3 | X_1, X_2) P(X_4 | X_1, X_2, X_3) \dots P(X_n | X_1, X_2, \dots, X_{n-1})$.

We take expectation over our model P here rather than over the true (cultural) data gen. process, so there's an additional overhead due to model mismatch that we don't discuss here.)

Compression strategy:

1. Encode x_1 with an optimal code for $P(X_1)$. $\rightarrow \mathbb{E}[C\# \text{bits}] < H[P(X_1)] + 1$
2. Encode x_2 with an optimal code for $P(X_2 | X_1=x_1)$. $\rightarrow \mathbb{E}[C\# \text{bits}] < H[P(X_2 | X_1=x_1)] + 1$
3. And so forth ... *(decoder operates in same order as encoder)*

Technicalities: <https://bamler-lab.github.io/bootcamp24> → Colab notebook

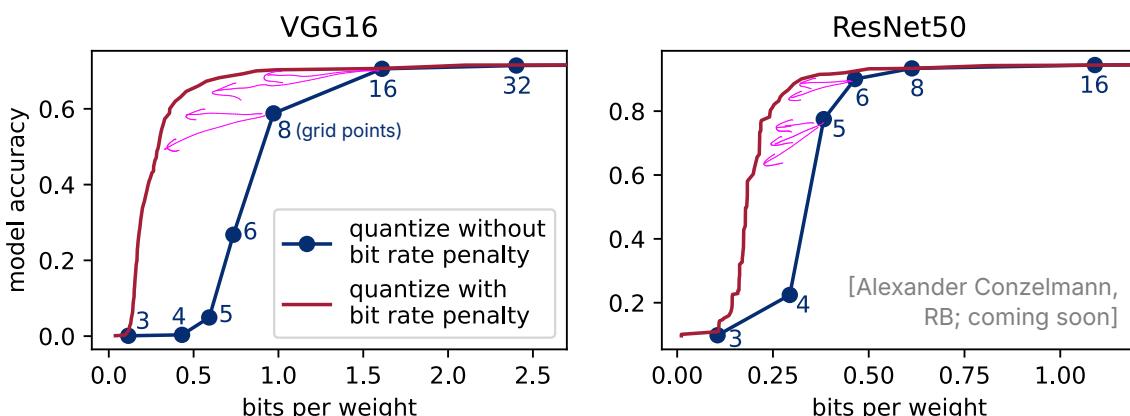
- ▶ Up to 1 bit of overhead *per token?* → Use a *stream code*: amortizes over tokens.
- ▶ The model expects that $x_1 = \langle \text{beginning of sequence} \rangle$. → Redundant, don't encode.
- ▶ How does the *decoder* know when to stop? → Use an *$\langle \text{end of sequence} \rangle$ token*.

Takeaways From Our Code Example

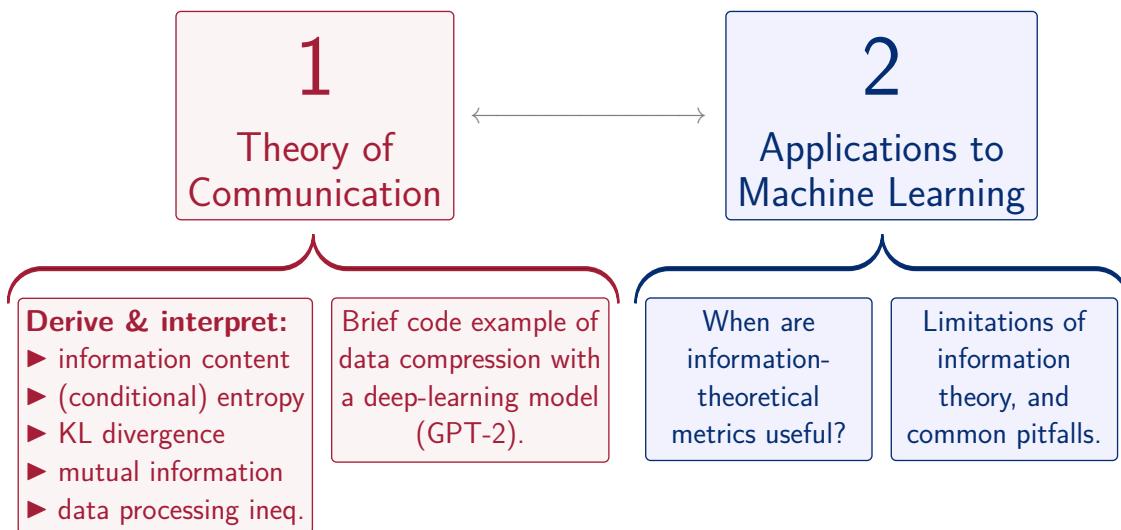


- ▶ Near-optimal compression performance is achievable *in practice*.
⇒ Information content accurately estimates #bits needed *in practice* (even if it's fractional).
- ▶ Data compression is intimately tied to *probabilistic generative modeling*.
 - ▶ "Don't transmit what you can predict." ⇒ generative modeling
 - ▶ But still allow communicating things we wouldn't have predicted. ⇒ probabilistic modeling
- ▶ Decoding ≈ generation (= sampling from a probabilistic generative model P):
 - ▶ To *sample* a token x_i , one injects *randomness* into $P(X_i | \mathbf{X}_{1:i-1}=\mathbf{x}_{1:i-1})$.
 - ▶ To *decode* a token x_i , one injects *compressed bits* into (a code for) $P(X_i | \mathbf{X}_{1:i-1}=\mathbf{x}_{1:i-1})$.
 - ▶ Decoding from a *random* bit string would be exactly equivalent to sampling from P .
- ▶ Data compression is highly sensitive to tiny model changes (e.g., inconsistent rounding).
 - ▶ Compression codes C are "very non-continuous" (because they *remove redundancies* by design).
- ⇒ True data compression usually makes it *harder* to process information.

Example 2: Compression ~~With~~ of Neural Networks



- ▶ **Method:** quantize network weights (\approx round to a discrete grid), then compress losslessly.
- ▶ **Observation:** information content remains meaningful *even in the regime* $\ll 1$ bit.



Joint, Marginal, and Conditional Entropy

Consider a data source $P(X, Y)$ that generates pairs $(x, y) \sim P$:

$$P(X, Y) = P(X) P(Y | X) = P(Y) P(X | Y).$$

- ▶ **Joint information content**, i.e., information content of the entire message (x, y) :

$$-\log_2 P(X=x, Y=y) = -\log_2 P(X=x) - \log_2 P(Y=y | X=x).$$

- ▶ **Joint entropy:**

$$\begin{aligned} H_P((X, Y)) &= \mathbb{E}_{P(X, Y)}[-\log_2 P(X, Y)] = \mathbb{E}_{P(X) P(Y|X)}[-\log_2 P(X) - \log_2 P(Y|X)] \\ &= \underbrace{\mathbb{E}_{P(X)}[-\log_2 P(X)]}_{\text{(marginal) entropy } H_P(X)} + \underbrace{\mathbb{E}_{x \sim P(X)} \left[\mathbb{E}_{P(Y|X=x)}[-\log_2 P(Y | X=x)] \right]}_{=: H_P(Y | X=x) = \text{entropy of the conditional distribution } P(Y | X=x)} \\ &\qquad\qquad\qquad \underbrace{=: \text{conditional entropy } H_P(Y | X)}_{=: \text{conditional entropy } H_P(Y | X)} \end{aligned}$$

▶ $H_P((X, Y)) = H_P(X) + H_P(Y | X) = H_P(Y) + H_P(X | Y)$

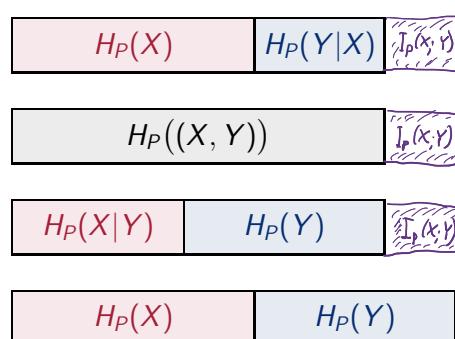
Mutual Information

Reminder: $H_P(Y | X) := \mathbb{E}_P[-\log_2 P(Y | X)] = \mathbb{E}_{x \sim P(X)} \left[\mathbb{E}_{P(Y|X=x)}[-\log_2 P(Y | X=x)] \right];$
 $H_P((X, Y)) = H_P(X) + H_P(Y | X).$

Let's encode a given message (x, y) :

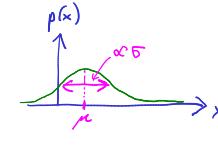
- encode x with optimal code for $P(X)$; then encode y with optimal code for $P(Y | X=x)$;
- encode (x, y) using an optimal code for the data source $P(X, Y)$;
- encode x with optimal code for $P(X | Y=y)$; then encode y with optimal code for $P(Y)$.
- encode x with optimal code for $P(X)$; then encode y with optimal code for $P(Y)$;

Expected bit rate:



Examples of Differential Entropies

- **Uniform distribution:** $P(X) = \mathcal{U}(\mathcal{X})$
- **Density:** $p(x) = \frac{1}{\text{Vol}(\mathcal{X})} \quad \forall x \in \mathcal{X}$
- **Differential entropy:** $h_P(X) = \mathbb{E}_P[-\log_2 p(X)] = \mathbb{E}_P\left[-\log_2 \frac{1}{\text{Vol}(\mathcal{X})}\right] = \log_2(\text{Vol}(\mathcal{X}))$
- **Note:** if $\text{Vol}(\mathcal{X}) < 1$ then $h_P(X) < 0$. (c.f., acidic solution with pH < 0: not special)
→ Nothing to see here, h_P is only meaningful up to an infinite additive constant.
- **Normal distribution:** $P(X) = \mathcal{N}(\mu, \Sigma)$ (with $X, \mu \in \mathbb{R}^n$ and $\Sigma \in \mathbb{R}^{n \times n}$)
- **Density:** $p(x) = \mathcal{N}(x; \mu, \Sigma) = \frac{1}{\sqrt{\det(2\pi\Sigma)}} \exp\left[-\frac{1}{2}(x - \mu)^\top \Sigma^{-1} (x - \mu)\right]$
- **Differential entropy:** $h_P(X) = \mathbb{E}_P[-\log_2 p(X)] = \frac{1}{2} \log_2(\det \Sigma) + \underbrace{\frac{n}{2} \log_2(2\pi e)}_{\text{const.}}$
(plausibility check: large variance \Leftrightarrow large entropy ✓)



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| 30

KL-Divergence Between Continuous Distributions

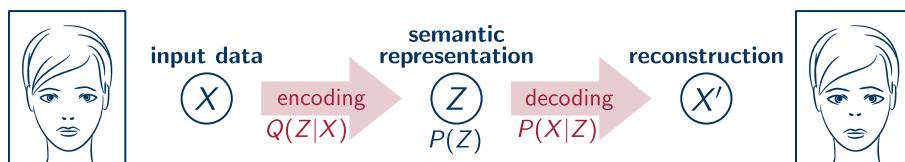
- **Differential entropy** (reminder): $h_P(X) = \mathbb{E}_P[-\log_2 p(X)]$
→ Relation to entropy of discretization \hat{X} : $H_P(\hat{X}) \approx h_P(X) + n \log_2(1/\delta) \xrightarrow{\delta \rightarrow 0} \infty$
- **Differential cross entropy** (less common): $h[P(X), Q(X)] = \mathbb{E}_P[-\log_2 q(X)]$
→ Relation to discretization: $H[P(\hat{X}), Q(\hat{X})] \approx h[P(X), Q(X)] + n \log_2(1/\delta) \xrightarrow{\delta \rightarrow 0} \infty$
- **Kullback-Leibler divergence** between discretized distributions $P(\hat{X})$ and $Q(\hat{X})$:
$$D_{\text{KL}}(P(\hat{X}) \| Q(\hat{X})) = H[P(\hat{X}), Q(\hat{X})] - H_P(\hat{X}) \\ \approx h[P(X), Q(X)] + n \log_2(1/\delta) - (h_P(X) + n \log_2(1/\delta)) \\ = \mathbb{E}_P\left[-\log_2 \frac{q(X)}{p(X)}\right] =: D_{\text{KL}}(P(X) \| Q(X)) \xrightarrow{\text{(possibly)}} < \infty$$
- ⇒ **Interpretation:** $D_{\text{KL}}(P \| Q)$ = modeling overhead, in the limit of infinitely fine quantization.
- **Generalization (density-free):** $D_{\text{KL}}(P \| Q) = - \int \log_2 \left(\frac{dQ}{dP} \right) dP$

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| 31

(Variational) Information Bottleneck

- **Example:** β -variational autoencoder (similar for supervised models (Alemi et al., ICLR 2017))



- **Loss function:** $\mathbb{E}_{x \sim \text{data}} \left[\mathbb{E}_{Q(Z|X=x)} [-\log P(X=x | Z)] + \beta D_{\text{KL}}(Q(Z | X=x) \| P(Z)) \right]$

$$\begin{aligned} D_{\text{KL}}(\dots \| \dots) &= \begin{cases} \text{information in } z \sim Q(Z | X=x) \\ \text{for someone who doesn't know } x \\ (\text{i.e., they only know } P(Z)) \end{cases} - \begin{cases} \text{information in } z \sim Q(Z | X=x) \\ \text{for someone who knows } x \\ (\text{i.e., they know } Q(Z | X=x)) \end{cases} \end{aligned}$$

⇒ { Capture as much (x -independent) information about z in the prior $P(Z)$ as possible.
Encode as little (unnecessary) information in $Q(Z | X=x)$ as possible. }

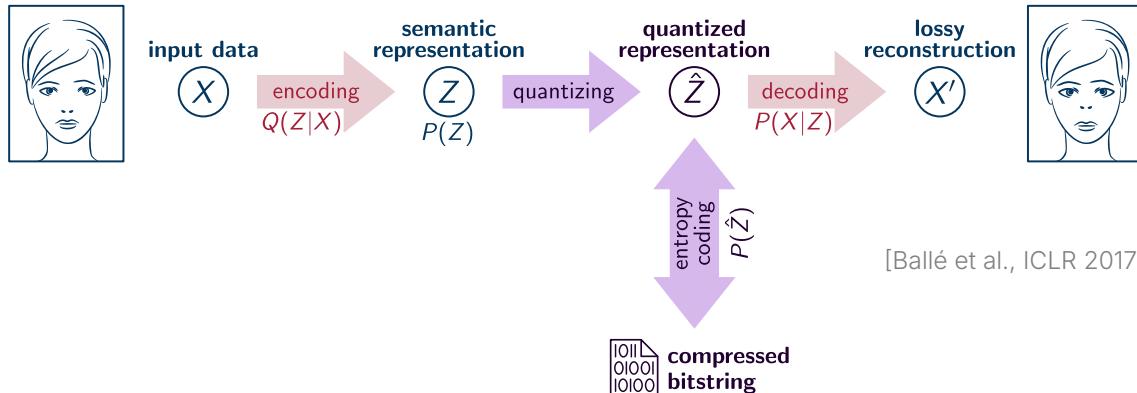
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| 32

Remark: Data Compression With VAEs



- So far, no compression: Z still takes up lots of memory (even if its inf. content is low).
- Real compression has to actually reduce Z to its information content: *entropy coding*



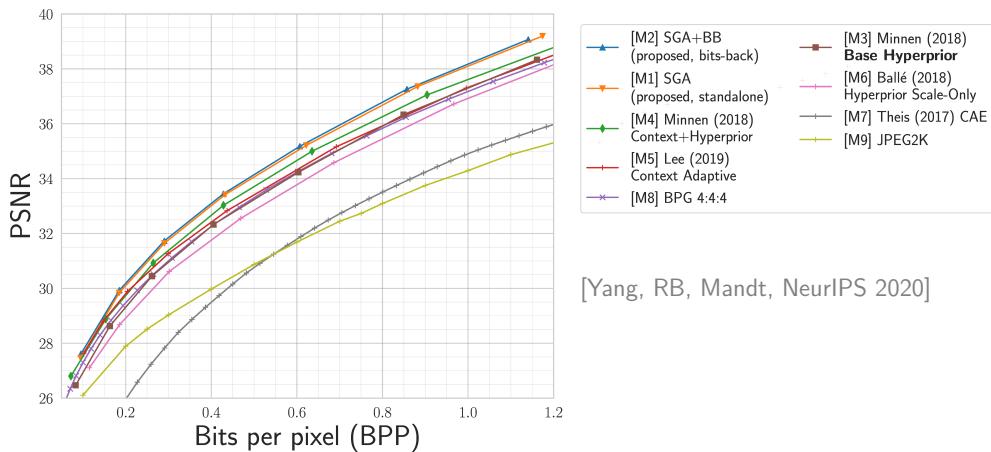
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| 33

Rate/Distortion Trade-off



- Tuning β allows us to trade off *bit rate* against *distortion*.



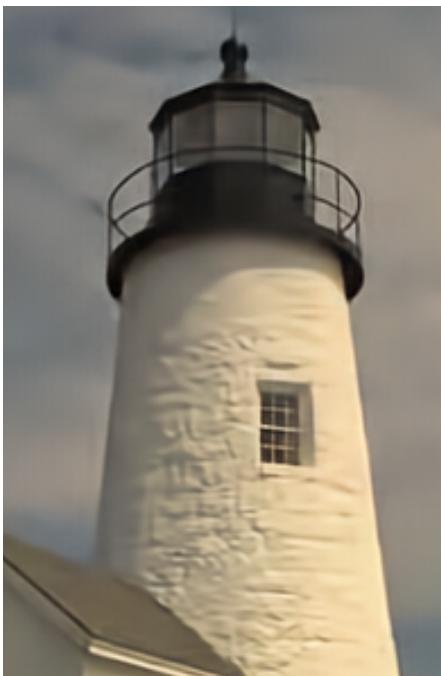
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| 34





BPG 4:4:4
left: 0.143 bit/pixel
right: 0.14 bit/pixel



VAE-based
left: 0.142 bit/pixel
right: 0.13 bit/pixel
[Yang, RB, Mandt,
NeurIPS 2020]



JPEG
left: 0.142 bit/pixel
right: 0.14 bit/pixel



1

Theory of Communication

2

Applications to Machine Learning

Derive & interpret:

- ▶ information content
- ▶ (conditional) entropy
- ▶ KL divergence
- ▶ mutual information
- ▶ data processing ineq.

Brief code example of data compression with a deep-learning model (GPT-2).

When are information-theoretical metrics useful?

Limitations of information theory, and common pitfalls.

Mutual Information for Continuous Random Vars



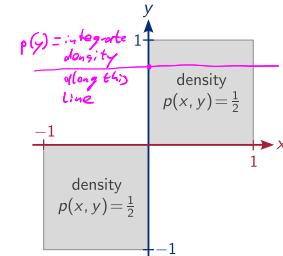
$$I_P(X; Y) = D_{\text{KL}}(P(X, Y) \parallel P(X) P(Y)) = \mathbb{E}_P \left[-\log_2 \frac{p(X) p(Y)}{p(X, Y)} \right] \quad (\text{if densities } p \text{ exist})$$

(we'll discuss non-injective later)

- ▶ **Exercise:** let $X' = f(X)$, $Y' = g(Y)$, where f and g are differentiable *(injective functions)*. Convince yourself that I_P is independent of representation, i.e., $I_P(X'; Y') = I_P(X; Y)$.

Example 1a:

- ▶ $P(X) = P(Y) = \mathcal{U}([-1, 1]) \implies h_P(X) = h_P(Y) = \log_2(2) = 1$.
- ▶ $P(Y|X) = \begin{cases} \mathcal{U}([-1, 0)) & \text{if } X < 0; \\ \mathcal{U}(0, 1)) & \text{if } X \geq 0. \end{cases}$
- ▶ $\implies h_P(Y|X) = \mathbb{E}_{x \sim P(X)} [h_P(Y|X=x)] = \log_2(1) = 0$.
- ▶ **Mutual information:** $I_P(X; Y) = h_P(Y) - h_P(Y|X) = 1 - 0 = 1$ bit.
- ▶ **Interpretation:** observing X tells us (only) the sign of Y . $\implies 1$ bit of information.

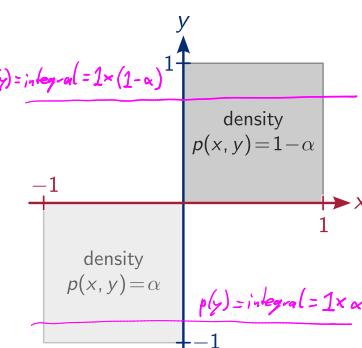


Mutual Information for Continuous Random Vars



Example 1b: non-uniform $P(X)$.

- ▶ $p(y) = \begin{cases} \alpha & \text{if } y \in [-1, 0); \\ 1 - \alpha & \text{if } y \in [0, 1]. \end{cases} \quad (\text{for } \alpha \in [0, 1])$
- ▶ $\implies h_P(Y) = - \int_{-1}^1 p(y) \log_2 p(y) dy$
 $= -\alpha \log_2(\alpha) - (1 - \alpha) \log_2(1 - \alpha) =: H_2(\alpha)$
- ▶ $P(Y|X) = \begin{cases} \mathcal{U}([-1, 0)) & \text{if } X < 0; \\ \mathcal{U}(0, 1)) & \text{if } X \geq 0. \end{cases} \quad (\text{as before})$
- ▶ $\implies h_P(Y|X) = 0 \quad (\text{as before})$
- ▶ **Mutual information:** $I_P(X; Y) = h_P(Y) - h_P(Y|X) = H_2(\alpha) - 0 = H_2(\alpha) \leq 1$ bit.
- ▶ **Interpretation:** observing X still tells us sign(Y) with certainty, but sign(Y) now carries less than one bit of information (in expectation) if $\alpha \neq \frac{1}{2}$.



Mutual Information for Continuous Random Vars



Example 1c: back to uniform $P(X)$, but different $P(Y | X)$:

- $P(X) = \mathcal{U}([-1, 1])$;

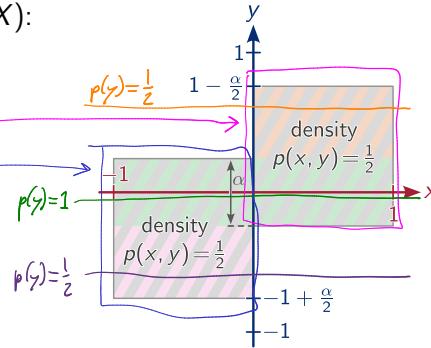
$$P(Y | X) = \begin{cases} \mathcal{U}\left([- \frac{\alpha}{2}, 1 - \frac{\alpha}{2}]\right) & \text{if } X \geq 0; \\ \mathcal{U}\left([-1 + \frac{\alpha}{2}, \frac{\alpha}{2}]\right) & \text{if } X < 0. \end{cases}$$

Method 1: $I_P(X; Y) = h_P(Y) - h_P(Y | X)$

- $h_P(Y | X) = 0$ as before.

$$\begin{aligned} \text{► } p(y) &= \begin{cases} \frac{1}{2} & \text{if } y \in [\frac{\alpha}{2}, 1 - \frac{\alpha}{2}] \cup [-1 + \frac{\alpha}{2}, -\frac{\alpha}{2}]; \\ 1 & \text{if } y \in [-\frac{\alpha}{2}, \frac{\alpha}{2}]. \end{cases} \\ \implies h_P(Y) &= - \int_{\frac{\alpha}{2}}^{1 - \frac{\alpha}{2}} \frac{1}{2} \log_2(\frac{1}{2}) dy - \int_{-1 + \frac{\alpha}{2}}^{-\frac{\alpha}{2}} \frac{1}{2} \log_2(\frac{1}{2}) dy - \int_{-\frac{\alpha}{2}}^{\frac{\alpha}{2}} 1 \log_2(1) dy = 1 - \alpha. \end{aligned}$$

- **Interpretation:** sign(Y) has one bit of entropy again, but knowing X no longer tells us sign(Y) with certainty, it only improves our odds of predicting it.



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| 42

Mutual Information for Continuous Random Vars



Example 1c: back to uniform $P(X)$, but different $P(Y | X)$:

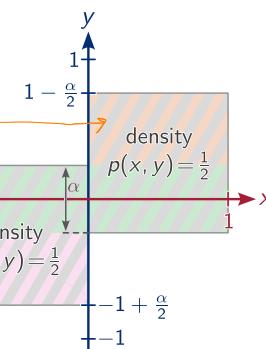
- $P(X) = \mathcal{U}([-1, 1])$;

$$P(Y | X) = \begin{cases} \mathcal{U}\left([- \frac{\alpha}{2}, 1 - \frac{\alpha}{2}]\right) & \text{if } X \geq 0; \\ \mathcal{U}\left([-1 + \frac{\alpha}{2}, \frac{\alpha}{2}]\right) & \text{if } X < 0. \end{cases}$$

Method 2: $I_P(X; Y) = h_P(X) - h_P(X | Y)$

$$\begin{aligned} \text{► } P(X | Y) &= \begin{cases} \mathcal{U}(0, 1) & \text{if } Y \in [\frac{\alpha}{2}, 1 - \frac{\alpha}{2}]; \\ \mathcal{U}(-1, 1) & \text{if } Y \in [-\frac{\alpha}{2}, \frac{\alpha}{2}]; \\ \mathcal{U}(-1, 0) & \text{if } Y \in [\frac{\alpha}{2} - 1, -\frac{\alpha}{2}]. \end{cases} \\ \Rightarrow h_P(X | Y) &= \mathbb{E}_{y \sim P(Y)} [h_P(X | Y=y)] = \frac{1}{2}(1-\alpha)\log_2(1) + \alpha\log_2(2) + \frac{1}{2}(1-\alpha)\log_2(1) = \alpha. \end{aligned}$$

- **Interpretation:** sign(X) has one bit of entropy, but a fraction α of possible observations of Y won't tell us sign(X) at all (while the other observations of Y tell it with certainty).



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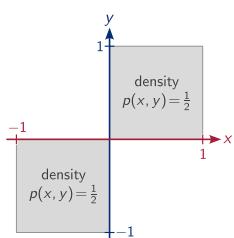
| 43

Summary of Example 1

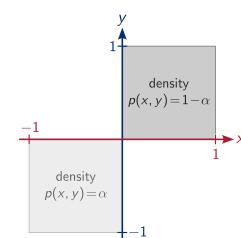


The mutual information $I_P(X; Y)$ takes into account:

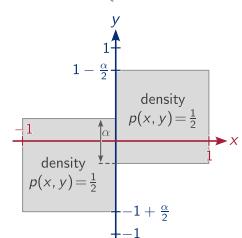
Example 1a:



Example 1b:



Example 1c (Methods 1 & 2):



- how much new information an observation of X reveals about Y (and vice versa) ...

- ... in comparison to how much we'd know about Y anyway;

- with what *certainty* the new information is revealed; and
- how *probable* it is to make an informative observation.

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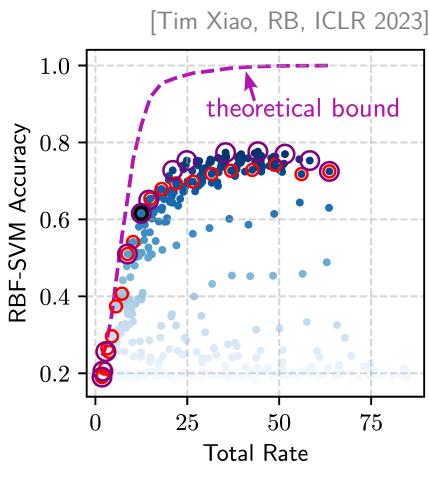
| 44

Inf.-Theoretical Bounds on Model Performance

Consider a classification task: assign label Y to input data X : learn $P(Y|X)$

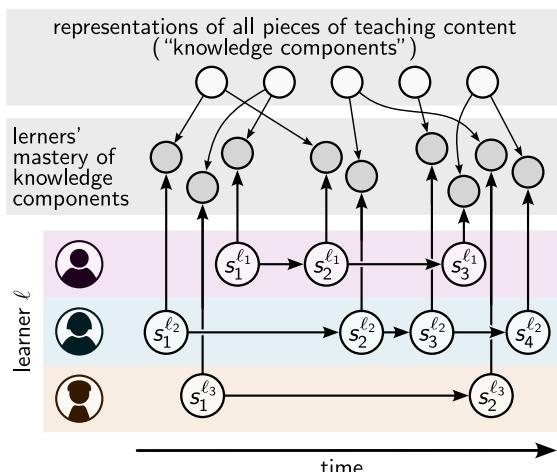
- ▶ Data generative distribution: $P(X, Y_{\text{g.t.}}) = P(Y_{\text{g.t.}})P(X|Y_{\text{g.t.}})$
- ⇒ Markov chain: $Y_{\text{g.t.}} \xrightarrow{\text{data gen.}} X \xrightarrow{\text{classifier}} Y$ *maximally possible mut. inf.
if the data source is fixed*
- ▶ Perfect classification would mean $Y = Y_{\text{g.t.}} \Rightarrow I_P(Y_{\text{g.t.}}; Y) = H_P(Y_{\text{g.t.}}) - \underbrace{H_P(Y_{\text{g.t.}}|Y)}_{=0}$
- ▶ More generally: high accuracy \Rightarrow high $I_P(Y_{\text{g.t.}}; Y) \Rightarrow$ high $I_P(Y_{\text{g.t.}}; X) \geq I_P(Y_{\text{g.t.}}; Y)$:
Bound: accuracy $\leq f^{-1}(I_P(Y_{\text{g.t.}}; X))$ where $f(\alpha) = H_P(Y_{\text{g.t.}}) + \alpha \log_2 \alpha + (1-\alpha) \log_2 \frac{1-\alpha}{\# \text{classes}-1}$
[Meyen, 2016 (MSc thesis advised by U. von Luxburg)]
- ▶ Now introduce a preprocessing step: $Y_{\text{g.t.}} \xrightarrow{\text{data gen.}} X \xrightarrow{\text{preprocessing}} Z \xrightarrow{\text{classifier}} Y$
- ▶ Theoretical bound now: accuracy $\leq f^{-1}(I_P(Y_{\text{g.t.}}; Z)) \leq f^{-1}(I_P(Y_{\text{g.t.}}; X))$
(by information processing inequality and monotonicity of f).
- ⇒ Information theory suggests: preprocessing can only hurt (bound on) downstream performance.

Limitations of Information Theory



- ▶ **Observation:** classification accuracy *decreases* for very large rate (= bound on mutual information).
- ▶ **Explanation:** information theory doesn't consider (computational/modeling) *complexity*.
 - ▶ Forcing the encoder to throw away some of the (least relevant) information can make downstream tasks *easier in practice*.
 - ▶ **Note:** it's the *information* bottleneck that can make downstream processing easier, not any (possible) dimensionality reduction.
(In fact, many downstream tasks become *easier in higher dimensions* → kernel trick.)

Be Creative! You Now Have the Tools for It.



[Hanqi Zhou, RB, CM Wu, Á Tejero-Cantero, ICLR 2024]

We want to quantify:

- ▶ How **specific** are learner representations s for their learner ℓ ?
 $I_P(s; \ell) = H_P(\ell) - H_P(\ell | s)$
- ▶ How **consistent** are representations for a fixed learner if we train on different subsets of time steps?
 $\mathbb{E}_{\ell_{\text{sub}}} [I_P(s^\ell; \ell_{\text{sub}})]$
- ▶ **Disentanglement**, i.e., how informative is each *component* of $s \in \mathbb{R}^n$ about learner identity ℓ ?
 $H_P(s) - H_P(s | \ell)_{\text{diag}}$