

On amortizing convex conjugates for optimal transport

Brandon Amos • Meta AI (FAIR) NYC



<http://github.com/bamos/presentations>
<http://github.com/facebookresearch/w2ot>

Optimal transport connects spaces

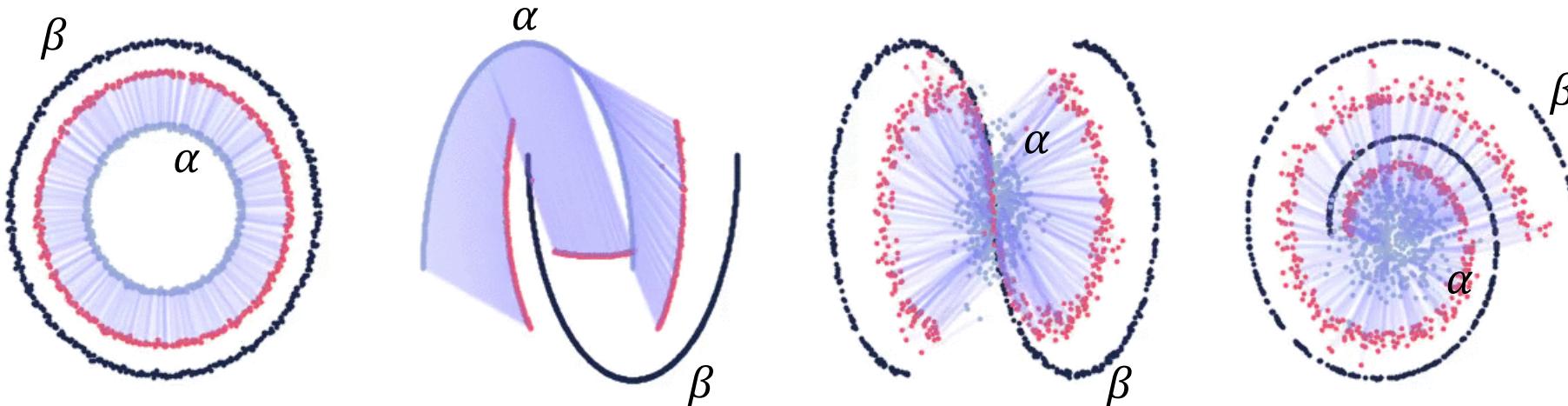
Monge (primal)

$$T^*(\alpha, \beta) \in \operatorname{argmin}_{T \in \mathcal{C}(\alpha, \beta)} \mathbb{E}_{x \sim \alpha} \|x - T(x)\|_2^2$$

α, β are measures

$\mathcal{C}(\alpha, \beta)$ is the set of valid coupling

T is a transport map from α to β



Duality and continuous OT

Monge (primal)

$$T^*(\alpha, \beta) \in \operatorname{argmin}_{T \in \mathcal{C}(\alpha, \beta)} \mathbb{E}_{x \sim \alpha} \|x - T(x)\|_2^2$$



$T^* = \nabla \hat{f}$ (Brenier's Theorem)

Kantorovich (dual)

$$\hat{f} \in \operatorname{argmax}_{f \in \mathcal{L}^1(\alpha)} -\mathbb{E}_{x \sim \alpha}[f(x)] - \mathbb{E}_{y \sim \beta}[f^*(y)]$$

$$f^*(y) := -\inf_{x \in \mathcal{X}} J_f(x; y) \quad \text{with objective} \quad J_f(x; y) := f(x) - \langle x, y \rangle$$

Solving Kantorovich's dual with a neural net

$$\max_{\theta} \mathcal{V}(\theta) \quad \text{where} \quad \mathcal{V}(\theta) := - \mathbb{E}_{x \sim \alpha} [f_\theta(x)] - \mathbb{E}_{y \sim \beta} [f_\theta^*(y)]$$

2-wasserstein approximation via restricted convex potentials. Taghvaei and Jalali, 2019.
Three-Player Wasserstein GAN via Amortised Duality. Nhan Dam et al., IJCAI 2019.
Optimal transport mapping via input convex neural networks. Makkluva et al., ICML 2020.
Wasserstein-2 generative networks. Korotin et al., ICLR 2020.

Focus: computing the conjugate

$$\max_{\theta} \mathcal{V}(\theta) \quad \text{where} \quad \mathcal{V}(\theta) := - \mathbb{E}_{x \sim \alpha} [f_{\theta}(x)] - \boxed{\mathbb{E}_{y \sim \beta} [f_{\theta}^*(y)]}$$

$$f^*(y) := - \inf_{x \in \mathcal{X}} J_f(x; y) \quad \text{with objective} \quad J_f(x; y) := f(x) - \langle x, y \rangle$$

Amortization: Approximate the arginf with (another) neural network

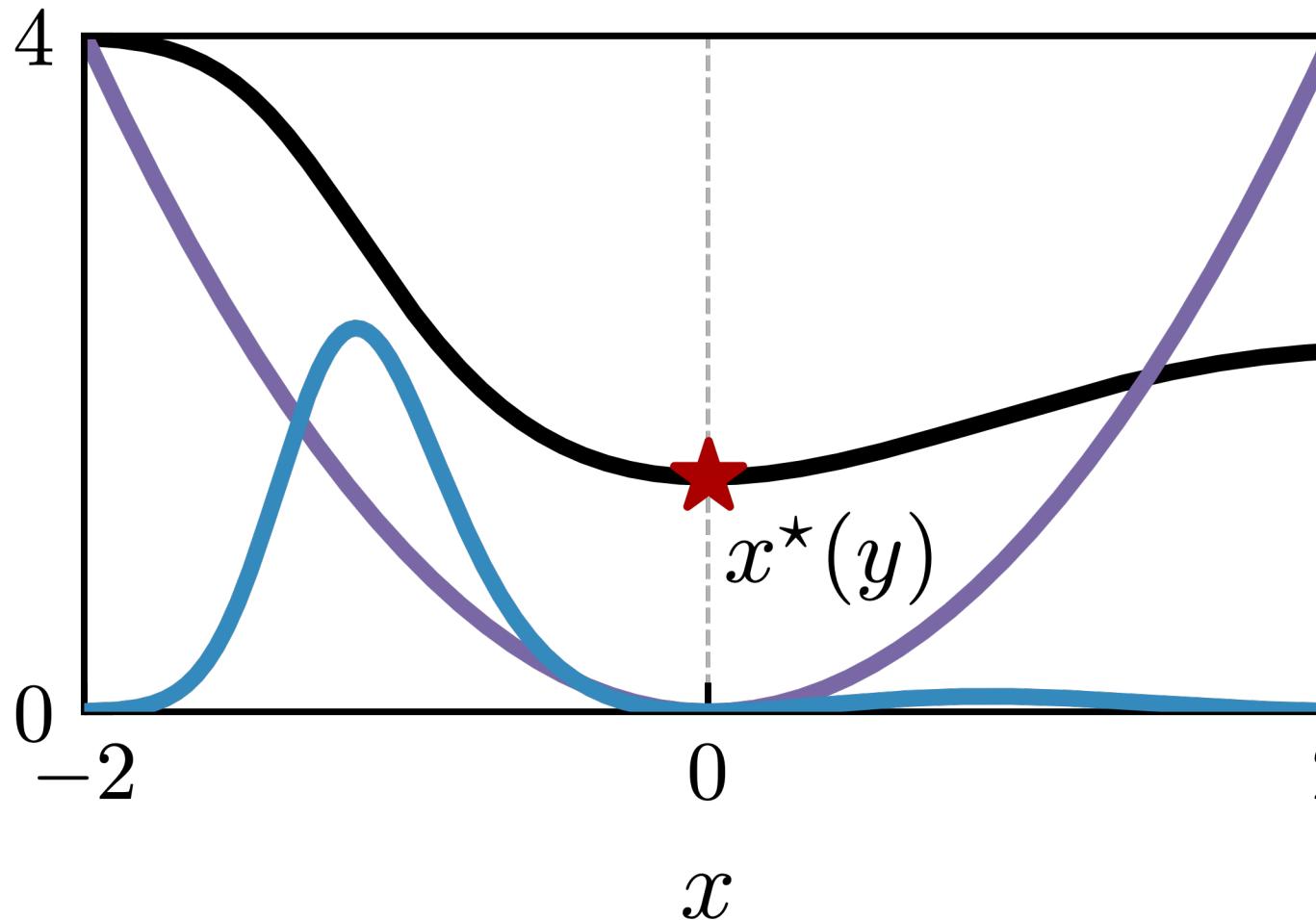
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Conjugate amortization loss choices



$\|x - x^*(y)\|_2^2$
Regression

$J_f(x; y)$
Objective

$\propto \|\nabla J_f(x)\|_2^2$
Cycle

Wasserstein-2 benchmark results

Do Neural Optimal Transport Solvers Work? Korotin et al., NeurIPS 2021.

Takeaway: amortization choice important, fine-tuning significantly helps

HD benchmarks: Unexplained Variance Percentage (UVP, lower is better)

Baselines from Korotin et al. (2021a)

Amortization loss	Conjugate solver	$n = 2$	$n = 4$	$n = 8$	$n = 16$	$n = 32$	$n = 64$	$n = 128$	$n = 256$	
*[W2]	Cycle	None	0.1	0.7	2.6	3.3	6.0	7.2	2.0	2.7
*[MMv1]	None	Adam	0.2	1.0	1.8	1.4	6.9	8.1	2.2	2.6
*[MMv2]	Objective	None	0.1	0.68	2.2	3.1	5.3	10.1	3.2	2.7
*[MM]	Objective	None	0.1	0.3	0.9	2.2	4.2	3.2	3.1	4.1

Potential model: the input convex neural network described in app. B.3

Amortization loss	Conjugate solver	$n = 2$	$n = 4$	$n = 8$	$n = 16$	$n = 32$	$n = 64$	$n = 128$	$n = 256$
Cycle	None	0.28 ± 0.09	0.90 ± 0.11	2.23 ± 0.20	3.03 ± 0.06	5.32 ± 0.14	8.79 ± 0.16	5.66 ± 0.45	4.34 ± 0.14
Objective	None	0.27 ± 0.09	0.78 ± 0.12	1.78 ± 0.26	2.00 ± 0.11	>100	>100	>100	>100
Cycle	L-BFGS	0.26 ± 0.09	0.77 ± 0.11	1.63 ± 0.28	1.15 ± 0.14	2.02 ± 0.10	4.48 ± 0.89	1.65 ± 0.10	5.93 ± 0.43
Objective	L-BFGS	0.26 ± 0.09	0.79 ± 0.12	1.63 ± 0.30	1.12 ± 0.11	1.92 ± 0.19	4.40 ± 0.79	1.64 ± 0.11	2.24 ± 0.13
Regression	L-BFGS	0.26 ± 0.09	0.78 ± 0.12	1.64 ± 0.29	1.14 ± 0.12	1.93 ± 0.20	4.41 ± 0.74	1.69 ± 0.11	2.21 ± 0.15
Cycle	Adam	0.26 ± 0.09	0.79 ± 0.11	1.62 ± 0.29	1.14 ± 0.12	1.95 ± 0.21	4.55 ± 0.62	1.88 ± 0.26	>100
Objective	Adam	0.26 ± 0.09	0.79 ± 0.14	1.62 ± 0.31	1.08 ± 0.14	1.89 ± 0.19	4.23 ± 0.76	1.59 ± 0.12	1.99 ± 0.15
Regression	Adam	0.35 ± 0.07	0.81 ± 0.12	1.61 ± 0.32	1.09 ± 0.11	1.85 ± 0.20	4.42 ± 0.68	1.63 ± 0.08	1.99 ± 0.16

Potential model: the non-convex neural network (MLP) described in app. B.4

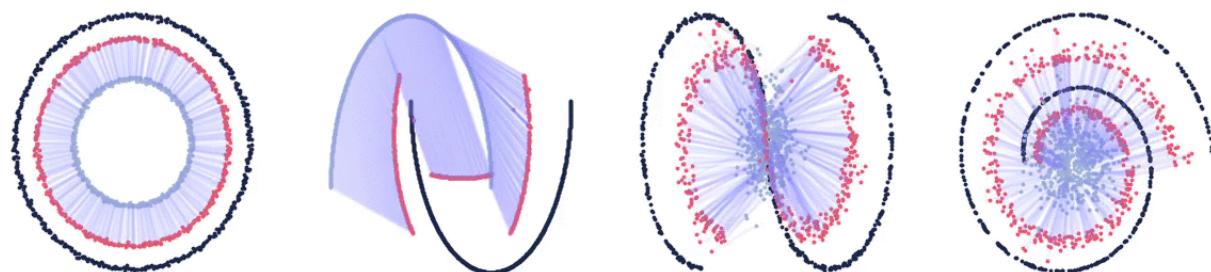
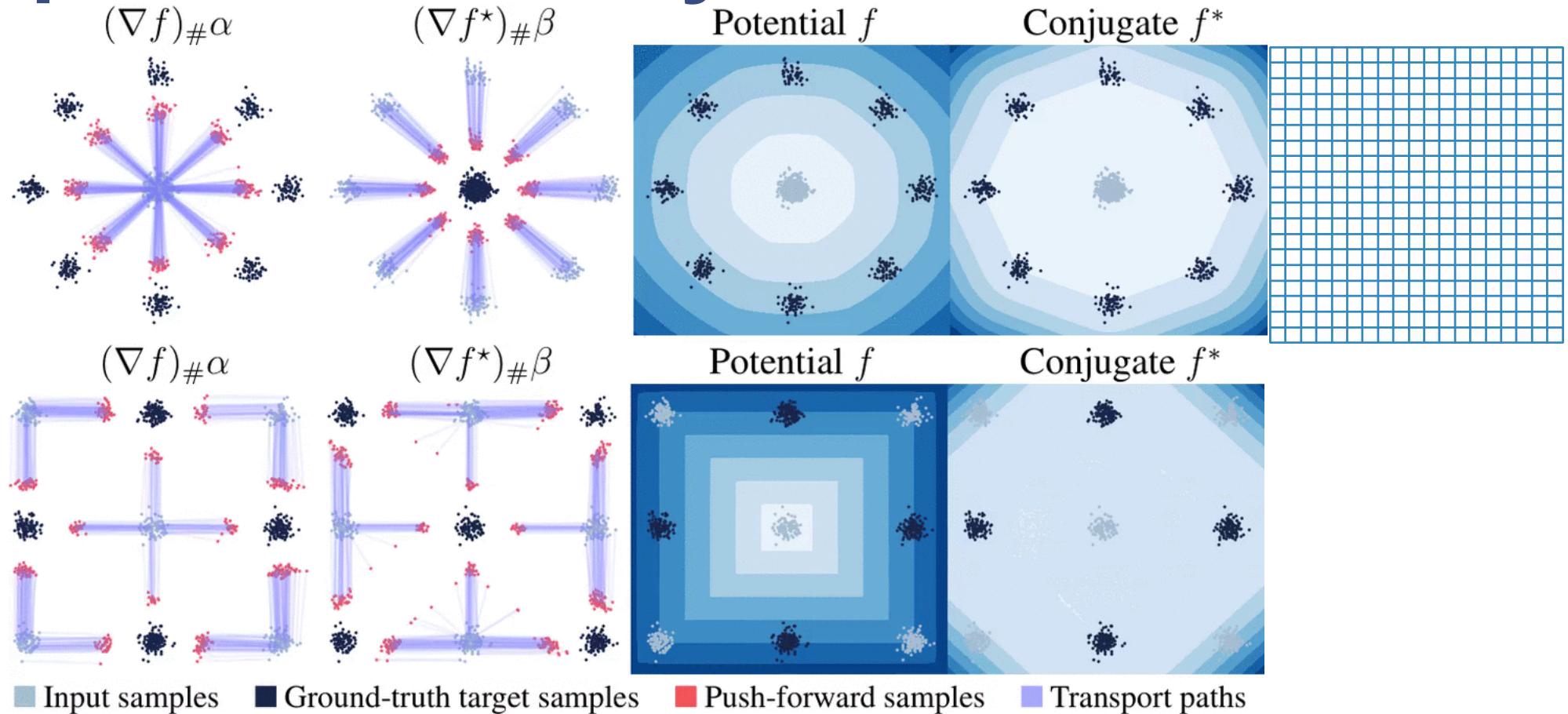
Amortization loss	Conjugate solver	$n = 2$	$n = 4$	$n = 8$	$n = 16$	$n = 32$	$n = 64$	$n = 128$	$n = 256$
Cycle	None	0.05 ± 0.00	0.35 ± 0.01	1.51 ± 0.08	>100	>100	>100	>100	>100
Objective	None	>100	>100	>100	>100	>100	>100	>100	>100
Cycle	L-BFGS	>100	>100	>100	>100	>100	>100	>100	>100
Objective	L-BFGS	0.03 ± 0.00	0.22 ± 0.01	0.60 ± 0.03	0.80 ± 0.11	2.09 ± 0.31	2.08 ± 0.40	0.67 ± 0.05	0.59 ± 0.04
Regression	L-BFGS	0.03 ± 0.00	0.22 ± 0.01	0.61 ± 0.04	0.77 ± 0.10	1.97 ± 0.38	2.08 ± 0.39	0.67 ± 0.05	0.65 ± 0.07
Cycle	Adam	0.18 ± 0.03	0.69 ± 0.56	1.62 ± 2.82	>100	>100	>100	>100	>100
Objective	Adam	0.06 ± 0.01	0.26 ± 0.02	0.63 ± 0.07	0.81 ± 0.10	1.99 ± 0.32	2.21 ± 0.32	0.77 ± 0.05	0.66 ± 0.07
Regression	Adam	0.22 ± 0.01	0.28 ± 0.02	0.61 ± 0.07	0.80 ± 0.10	2.07 ± 0.38	2.37 ± 0.46	0.77 ± 0.06	0.75 ± 0.09
Improvement factor over prior work		3.3	3.1	3.0	1.8	2.7	1.5	3.0	4.4

CelebA benchmarks: UVP

Amortization loss	Conjugate solver	Potential Model	Early Generator	Mid Generator	Late Generator	
*[W2]	Cycle	None	ConvICNN64	1.7	0.5	0.25
*[MM]	Objective	None	ResNet	2.2	0.9	0.53
*[MM-R [†]]	Objective	None	ResNet	1.4	0.4	0.22
	Cycle	None	ConvNet	>100	26.50 ± 60.14	0.29 ± 0.59
	Objective	None	ConvNet	>100	0.29 ± 0.15	0.69 ± 0.90
	Cycle	Adam	ConvNet	0.65 ± 0.02	0.21 ± 0.00	0.11 ± 0.04
	Cycle	L-BFGS	ConvNet	0.62 ± 0.01	0.20 ± 0.00	0.09 ± 0.00
	Objective	Adam	ConvNet	0.65 ± 0.02	0.21 ± 0.00	0.11 ± 0.05
	Objective	L-BFGS	ConvNet	0.61 ± 0.01	0.20 ± 0.00	0.09 ± 0.00
	Regression	Adam	ConvNet	0.66 ± 0.01	0.21 ± 0.00	0.12 ± 0.00
	Regression	L-BFGS	ConvNet	0.62 ± 0.01	0.20 ± 0.00	0.09 ± 0.01
Improvement factor over prior work			2.3	2.0	2.4	

[†]the reversed direction from Korotin et al. (2021a), i.e. the potential model is associated with the β measure

Transport between synthetic measures

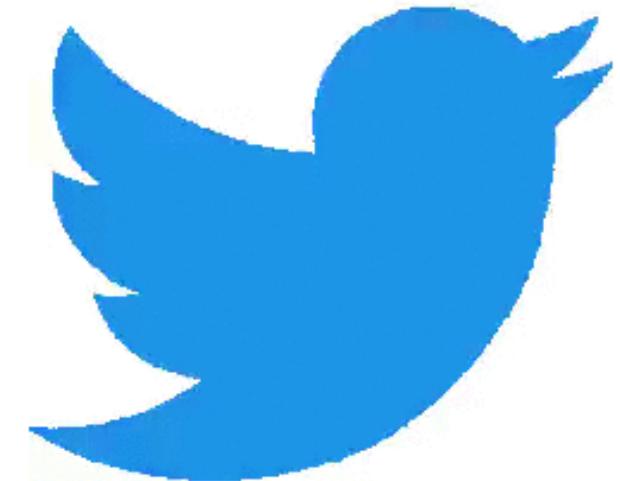
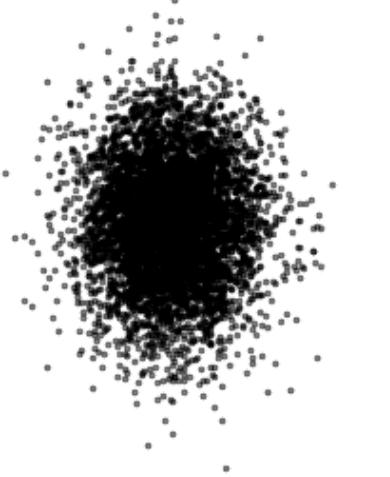


Learning flows via continuous OT

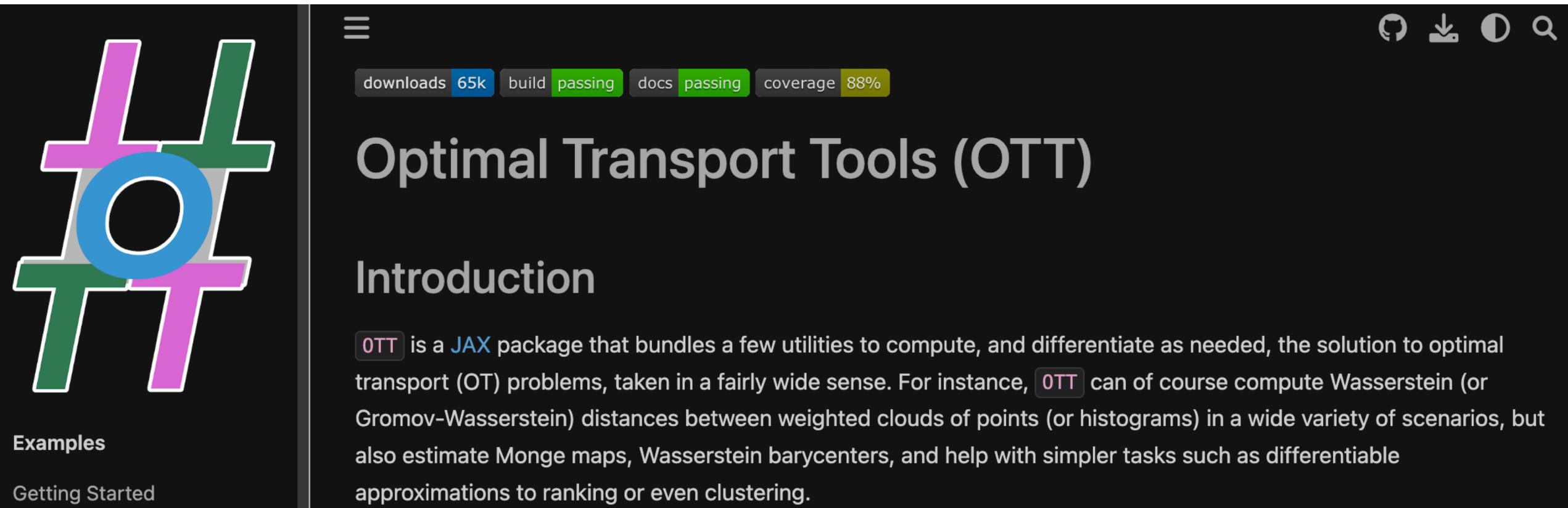
Continuous OT for flows:

1. Works **only from samples** (no likelihoods needed)
2. No need to explicitly enforce invertibility
3. No need to compute the log-det of the Jacobian

$$p_Y(y) = p_X(f^{-1}(y)) \left| \frac{\partial f^{-1}(y)}{\partial y} \right|$$



github.com/ott-jax/ott



The screenshot shows the GitHub repository page for `ott-jax/ott`. On the left, there's a sidebar with a large logo composed of overlapping colored letters ('O', 'T', 'T') in pink, blue, and green. Below the logo are two links: 'Examples' and 'Getting Started'. The main content area has a dark background. At the top, there are navigation icons (three horizontal lines, a magnifying glass, a download arrow, a profile icon, and a search icon). Below these are four status indicators: 'downloads 65k', 'build passing', 'docs passing', and 'coverage 88%'. The title 'Optimal Transport Tools (OTT)' is centered in a large, light-colored font. Underneath the title is a section titled 'Introduction'. The introduction text is as follows:

`OTT` is a `JAX` package that bundles a few utilities to compute, and differentiate as needed, the solution to optimal transport (OT) problems, taken in a fairly wide sense. For instance, `OTT` can of course compute Wasserstein (or Gromov-Wasserstein) distances between weighted clouds of points (or histograms) in a wide variety of scenarios, but also estimate Monge maps, Wasserstein barycenters, and help with simpler tasks such as differentiable approximations to ranking or even clustering.

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