

$$a) \quad \frac{dv}{dt} = -v + wv, \quad \frac{dw}{dt} = r(1-r)v, \quad r > 0$$

The v means the input in the neuro population and the w is the weight vector or weighted sum of inputs. As v increase our weighted sum will also increase, increasing the weights and inputs current.

b) For v decreasing the opposite will occur

1) Find Nullclines:

$$0 = -v + wv, \quad 0 = r(1-r)v$$

$$v = wv$$

$$v = 1$$

2) Find equilibrium: $v = wv = 0$

$$1 = w, \quad v = 1$$

or

$$w = 0$$

$$v = 0$$

3) Find stability $\begin{pmatrix} F_v & F_w \\ G_v & G_w \end{pmatrix}$ eigen values

$$\begin{pmatrix} F_v & F_w \\ G_v & G_w \end{pmatrix} = \begin{pmatrix} w-1 & r \\ r-2v & 0 \end{pmatrix}$$

$$J(1,1) = \begin{pmatrix} 0 & 1 \\ r-2 & 0 \end{pmatrix}$$

$$|\lambda I - J| = \begin{vmatrix} \lambda & -1 \\ 2-r & \lambda \end{vmatrix} = 0$$

$$= \lambda^2 - (r-2) = \lambda^2 - r + 2$$

$$\lambda_1 = \lambda - i\sqrt{2-r}, \quad \lambda_2 = \lambda + i\sqrt{2-r}$$

For a positive λ , the real part will be unstable however the imaginary is unstable and stable hence we will still have an unstable node.

For a negative λ , the real part will be stable and we will have similar imaginary parts from the previous statement, so we will have a saddle.

For $J(0,0)$:

$$J(0,0) = \begin{pmatrix} -1 & 0 \\ r & 0 \end{pmatrix}$$

$$\det(\lambda I - J) = \begin{pmatrix} \lambda + 1 & 0 \\ -r & \lambda \end{pmatrix} = 0$$

$$= \lambda^2 + \lambda = 0$$

$$\lambda = 0, -1$$

From $f(0,0)$ we have a stable saddle since the real part is $0, -1$.

c) Sketch phase plane: $f(1,1)$ $\lambda = 0$



