

# Opencv tutorial

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<https://bana-handaga.github.io/opencv>

(opencv using python )

Camera Callibration:

Every camera have distortion:

- Radial Distortion
- Tangential Distortion

Calibration:

1. Download image pattern ( left01.jpg ... left14.jpg ) from opencv source code, link:  
<https://github.com/opencv/opencv/tree/master/samples/data>
2. Save all jpg files inside working folder. Then apply the "kalibrasi.py"