

Rethinking the Role of Prompting Strategies in LLM Test-Time Scaling: A Perspective of Probability Theory

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Abstract

Recently, scaling test-time compute on Large Language Models (LLM) has garnered wide attention. However, there has been limited investigation of how various reasoning prompting strategies perform as scaling. In this paper, we focus on a standard and realistic scaling setting: majority voting. We systematically conduct experiments on 6 LLMs \times 8 prompting strategies \times 6 benchmarks. Experiment results consistently show that as the sampling time and computational overhead increase, complicated prompting strategies with superior initial performance gradually fall behind simple Chain-of-Thought. We analyze this phenomenon and provide theoretical proofs. Additionally, we propose a method according to probability theory to quickly and accurately predict the scaling performance and select the best strategy under large sampling times without extra resource-intensive inference in practice. It can serve as the test-time scaling law for majority voting. Furthermore, we introduce two ways derived from our theoretical analysis to significantly improve the scaling performance. We hope that our research can promote to re-examine the role of complicated prompting, unleash the potential of simple prompting strategies, and provide new insights for enhancing test-time scaling performance.

1 Introduction

Over the past few years, how to enhance the reasoning abilities of large language models (LLMs) has been a topic of widespread interest (Dubey et al., 2024; Anil et al., 2023; Touvron et al., 2023; Open AI, 2024a; Team et al., 2024). Researchers have introduced various prompting strategies to improve the reasoning capacity of LLMs, such as Chain of Thought (CoT) (Wei et al., 2022) and so on (Zheng et al., 2024; Yasunaga et al., 2024; Madaan et al., 2023). Recently, many studies have shown that

scaling LLM test-time compute can also effectively improve reasoning (Snell et al., 2025; Open AI, 2024b; Ji et al., 2025; Bi et al., 2024).

However, how different prompting strategies behave when scaling test-time compute is less explored. In this paper, we focus on a standard and effective scaling setting: majority voting. We comprehensively evaluate the performance of 8 mainstream prompting strategies under equivalent sampling time or computation overhead. We test 4 open-sourced and 2 closed-sourced LLMs on 6 reasoning benchmarks, finding that simple CoT consistently performs best on all LLMs across benchmarks with given budgets as scaling increases, even if it falls behind at the beginning. This indicates that current LLMs can achieve remarkable reasoning capabilities by only relying on simple CoT without other complicated prompting strategies. It also reminds us to reflect on the necessity of complicated prompting for scaling and fairly compare different strategies under the same budget.

We systematically analyze this phenomenon and provide theoretical and experimental proofs. We conclude that this is caused by two reasons. One is that there are more easy questions and fewer hard questions for CoT compared to other strategies. Easy questions are more likely to get right solutions, and the error possibility decreases until 0% as scaling. In comparison, hard questions are the opposite. The other is that CoT is less likely to be affected by wrong answers. Although CoT sometimes has lower pass@1 accuracy, its probability of obtaining the correct answer is more prominent in the result distribution. In contrast, other strategies have higher disturbed peaks in the distribution of incorrect answers. These two reasons enable CoT to improve reasoning performance more rapidly and gradually dominate as scaling.

What's more, we propose a method with the complexity $O(1)$ according to probability theory to quickly predict the scaling performance, which

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can serve as the test-time scaling law for majority voting. Experiments show that our method can accurately estimate the scaling performance and select the best strategy with arbitrary sampling time.

Furthermore, we explore two ways to significantly improve scaling performance with our theories. (1) Adaptively scaling according to the question difficulty. (2) Dynamically selecting the optimal prompting strategy. Extensive experiments verify their general effectiveness and superiority, *e.g.*, improving Majority@10 accuracy from 86.0% to 97.4% and 15.2% to 61.0% for LLaMA-3-8B-Instruct (Dubey et al., 2024) on GSM8K (Cobbe et al., 2021) and MATH-500 (Hendrycks et al., 2021b) by combining (1) and (2), respectively.

Our contributions can be summarized as follows:

- We comprehensively study the test-time scaling performance on 6 LLMs \times 8 prompting strategies \times 6 benchmarks. (Section 2)
- We find that CoT consistently performs best under the equivalent sampling time and computation overhead. (Section 3)
- We analyze this phenomenon and provide theoretical and experimental proofs. (Section 4)
- We propose a method to quickly predict the scaling performance and the best strategy under given sampling times. (Section 5)
- Based on the above analysis, we introduce two ways to significantly improve the scaling performance. (Section 6)

2 Scaling System Designs

We focus on a straight and effective setting of test-time scaling, majority voting, *i.e.*, Self-Consistency (Wang et al., 2023b), which selects the most consistent answer among several samples. Our goal is to study what prompting strategy performs best under the equivalent scaling overhead, particularly when largely increasing the scaling extent.

2.1 Models

We conduct experiments on 4 open-sourced LLMs including Qwen2.5-7B-Instruct (Yang et al., 2024a), LLaMA-3-8B-Instruct (Dubey et al., 2024), GLM-4-9B-Chat (GLM et al., 2024) and Phi-3.5-mini-Instruct, and 2 close-sourced LLMs including Gemini-1.5-Flash (Team et al., 2024) and GPT-4o-mini (Open AI, 2024a).

2.2 Prompting Strategies

We mainly focus on generalizable reasoning prompting strategies, excluding those individually designed for specific tasks or involving fine-tuning, training auxiliary models, or incorporating other models, tools, or human assistance. In this setting, the model’s performance is only related to the input prompt, thus making it fairly compare the scaling performance of those prompting strategies. The prompting strategies we test are listed as follows.

Direct Prompting (DiP): Directly input the question to the model, without any additional instruction or restrictions to the output.

Chain-of-Thought (CoT) (Wei et al., 2022; Kojima et al., 2022): Use the prompt “Let’s think step by step.” to solve the problem step by step.

Least-to-Most (L2M) (Zhou et al., 2023): Break down the question into progressive sub-questions. Answer the sub-questions and get the final result according to them and their answers.

Tree-of-Thoughts (ToT) (Yao et al., 2023): Explore multiple reasoning paths to get several solutions, then analyze each solution and decide which one is the most promising.

Self-Refine (S-RF) (Madaan et al., 2023): First, answer the question to get an initial answer. Next, evaluate the previous answer and get feedback. Finally, refine the previous answer according to feedback. This will last for several rounds.

Step-Back Prompting (SBP) (Zheng et al., 2024): First, extract the discipline concepts and principles involved in solving the problem. Then, solve the problem step by step by following the principles.

Analogous Prompting (AnP) (Yasunaga et al., 2024): Recall relevant problems as examples. Afterward, solve the analogous problems and proceed to solve the initial problem according to them.

Multi-Agent Debate (MAD) (Du et al., 2024): Set three model instances as different agents to debate for several rounds, and select the most consistent result among them.

2.3 Benchmarks

We evaluate across 6 reasoning benchmarks used in the original papers of the above prompting strategies, including GSM8K (Cobbe et al., 2021), GSM-Hard (Gao et al., 2023), MATH-500 (Hendrycks

et al., 2021b; Lightman et al., 2024), MMLU-high-school-biology, chemistry and physics (Hendrycks et al., 2021a).

2.4 Formal Expression

We divided the prompting strategies into two groups: iterative methods (S-RF, MAD, and ToT) and the other non-iterative methods. For S-RF and MAD, we run them N rounds and get the final result in the N th round. For ToT, we set the model to explore and evaluate N different reasoning paths to get the best one. For others, we parallel sample N generations and get their most consistent answer with majority voting. For convenience, we refer to all of the above processes as sampling N times. Therefore, we can categorize those iterative strategies that require multiple rounds or reasoning paths as $\mathcal{P}_2 = \{\text{S-RF, MAD, ToT}\}$, and other non-iterative ones as $\mathcal{P}_1 = \{\text{DiP, CoT, L2M, SBP, AnP}\}$.

Formally, assuming that we have n prompting strategies $\{\mathbf{P}_i | i = 1, 2, \dots, n\}$, when using the prompt strategy \mathbf{P}_i to answer a text question x on a model \mathcal{M} , we can get the answered result of one sample with an answer extractor ϕ , which extracts the answer in the output sentence using regular expressions. Then we can formalize the process of getting the final answer when sampling N times as $\phi[\mathcal{M}(x | \mathbf{P}_i); N] =$

$$\begin{cases} \text{mode}\{\phi[\mathcal{M}(x | \mathbf{P}_i)]\}_1^N, \mathbf{P}_i \in \mathcal{P}_1 \\ \phi[\mathcal{M}(x | \mathbf{P}_i; N)], \mathbf{P}_i \in \mathcal{P}_2 \end{cases} \quad (1)$$

With a fixed sampling time N , the best prompting strategy \mathbf{P}_N^* on the dataset \mathfrak{D} is

$$\mathbf{P}_N^* = \underset{\mathbf{P}_i}{\text{argmax}} \mathbb{E}_{x \in \mathfrak{D}} \mathbb{1}\{\phi[\mathcal{M}(x | \mathbf{P}_i); N] = y\}, \quad (2)$$

where y is the ground truth answer for x . However, sampling with distinct \mathbf{P}_i may cause different computation overhead. It would be fairer to compare them with a fixed overhead O . To calculate the overhead of using a model \mathcal{M} to answer a question x by sampling N times with the prompting strategy \mathbf{P}_i , we can consider it as a function of $x, \mathcal{M}, \mathbf{P}_i, N$, noted as $\mathcal{C}(x | \mathcal{M}; \mathbf{P}_i; N)$. Under a fixed overhead O , the best prompting strategy \mathbf{P}_O^* on the dataset \mathfrak{D} is

$$\begin{aligned} \mathbf{P}_O^* = & \underset{\mathbf{P}_i}{\text{argmax}} \max_N \mathbb{E}_{x \in \mathfrak{D}} \mathbb{1}\{\phi[\mathcal{M}(x | \mathbf{P}_i); N] = y\}, \\ & \text{s.t. } \sum_{x \in \mathfrak{D}} \mathcal{C}(x | \mathcal{M}; \mathbf{P}_i; N) \leq O. \end{aligned} \quad (3)$$

Given that completion tokens are more computationally expensive than prompt tokens, we define the overhead as the weighted sum of prompt tokens and completion tokens (Cost). For the models Gemini-1.5-Flash and GPT-4o-mini, we utilize their respective pricing metrics.¹ For other open-sourced models, we adopt the pricing of GPT-4o-mini as a proxy.

3 CoT Dominates as Test-Time Scaling

Under each sampling time N , we test five times to obtain the average performance of majority voting. We evaluate under two kinds of budget constraints: (1) a fixed sampling time budget N , and (2) a fixed inference cost budget O . Figure 1 and 2 summarize the average performances across benchmarks of different \mathbf{P}_i under constrained sampling time N and cost O on each model, and display the best prompting strategy \mathbf{P}_N^* under different values of N and \mathbf{P}_O^* under different values of O , respectively.² We can see that when scaling test-time compute, CoT performs best among all prompting strategies under a constrained N and O most of the time. Although some complicated prompting strategies perform best under lower N and O , CoT dominates without exception on all models when largely scaling. We theoretically and experimentally analyze this phenomenon, whose reasons come from two aspects. We explain these in detail in Section 4.

What's more, we find that about 80% of the results conform to this trend on each model and each benchmark. On certain datasets and LLMs, DiP also performs best as largely scaling. This is particularly evident on powerful models, such as Gemini-1.5-Flash and GPT-4o-mini. More detailed results can be found in Appendix C. These indicate that simple CoT is more efficient and has the potential to surpass other complicated prompting strategies under the same scaling setting. Current LLMs can achieve remarkable reasoning capabilities by only relying on simple prompting strategies. Complicated prompting with superior pass@1 accuracy may not always be better as test-time scaling.

¹The price of Gemini-1.5-Flash: \$0.075/1M prompt tokens, \$0.3/1M completion tokens. The price of GPT-4o-mini: \$0.15/1M prompt tokens, \$0.6/1M completion tokens.

²We don't test the performance with very large N for $\mathbf{P}_i \in \mathcal{P}_2$, as this will lead to extremely long context, large cost and computation time, and marginally increased or even decreased performance, which is no better than Self-Consistency (Smit et al., 2024). S-RF performs poorly even with multiple rounds. This is consistent with the results of (Huang et al., 2024), which points out the limitations of S-RF.

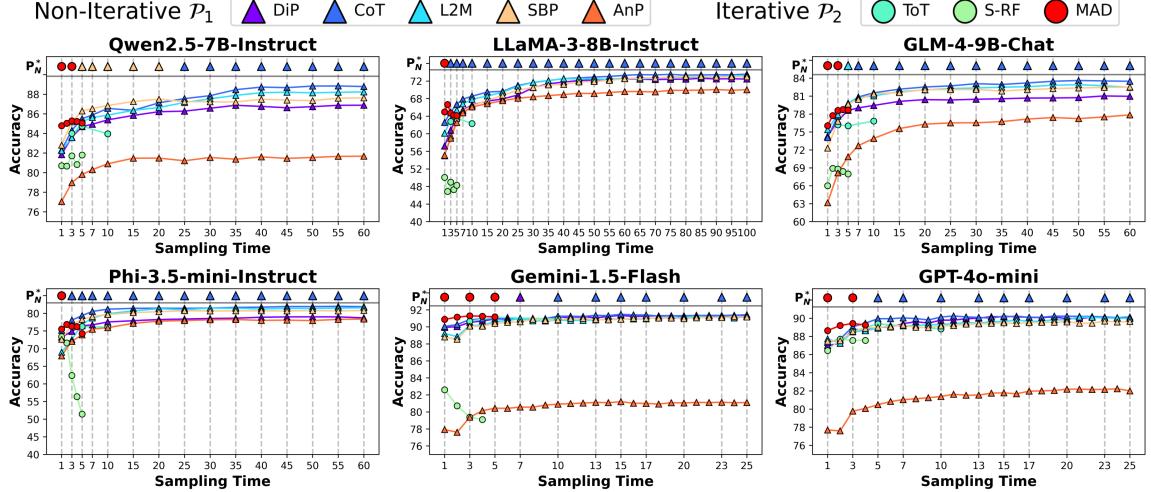


Figure 1: Average performances of distinct prompting strategies and the best one P_N^* across benchmarks on each LLM under constrained sampling time N . As increasing the sample time N , the accuracy of CoT grows rapidly and it dominates on all models when N is large enough.

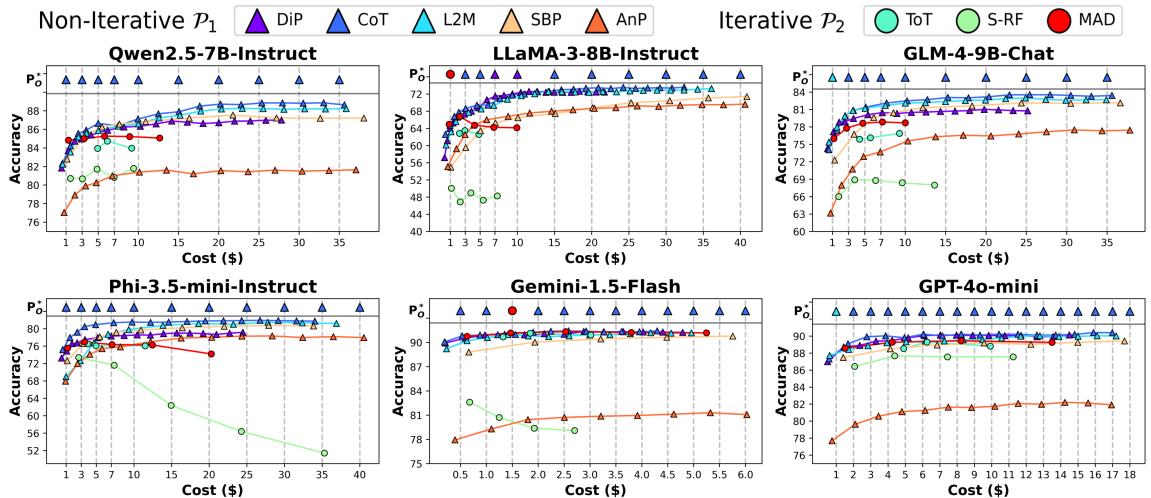


Figure 2: Average performances of distinct prompting strategies and the best one P_O^* across benchmarks on each LLM under constrained cost O . Under the equal cost O , CoT performs best most of the time. When O grows larger, CoT gradually becomes the best prompt strategy P_O^* on all models.

4 Why CoT Performs worse with Lower N while better with Larger N ?

Let us consider a specific input question x , note the answer space $\mathcal{A} = \{a_1, a_2, \dots, a_m\}$ as the set of all probable values of $\phi[\mathcal{M}(x | \mathbf{P}_i)]$ for all \mathbf{P}_i , i.e., $\phi[\mathcal{M}(x | \mathbf{P}_i)] \in \mathcal{A}$ for $\forall \mathbf{P}_i$. We omit $N = 1$ in $\phi[\mathcal{M}(x | \mathbf{P}_i)]$ for brevity. $\{p_{i,1}, p_{i,2}, \dots, p_{i,m}\}$ denotes the corresponding probabilities, i.e., $p_{i,j} = \Pr(\phi[\mathcal{M}(x | \mathbf{P}_i)] = a_j)$. Note a_i^* as the final result of \mathbf{P}_i by scaling sampling N times, i.e., $a_i^* = \phi[\mathcal{M}(x | \mathbf{P}_i); N]$. Then the occurrence number $\mathbf{X}_i = (\mathbf{x}_{i,1}, \dots, \mathbf{x}_{i,m})$ of each probable answer for \mathbf{P}_i follows a multinomial distribution, i.e., $\mathbf{X}_i \sim \text{Mult}(N, p_{i,1}, p_{i,2}, \dots, p_{i,m})$. The process of getting the final result a_i^* of \mathbf{P}_i by sampling N times can be formalized as:

$$\begin{aligned} \mathcal{X}_{ir} &= \{\mathbf{x}_{i,j} \mid \mathbf{x}_{i,j} = \max\{\mathbf{X}_i\}\} \\ k &\sim \text{Uniform}(\mathcal{X}_{ir}), \quad a_i^* = a_k \end{aligned} \tag{4}$$

Next, we will introduce several lemmas and theorems to explain the two reasons why CoT sometimes performs worse with lower N while better with larger N . In the following proof, we omit the input x , assume a_1 is the correct answer, and note the probability of getting a_1 when sampling N times with \mathbf{P}_i as $\Pr(a_1 | \mathbf{P}_i; N)$, which can be regarded as the expectation of the accuracy $\mathbb{E}\{\phi[\mathcal{M}(x | \mathbf{P}_i); N] = y\}$. Details about the proof process can be found in Appendix B.

Definition 1. Note $p_{\max} = \max\{p_{i,1}, \dots, p_{i,m}\}$, $S = \{a_j \mid p_{i,j} = p_{\max}\}$, we can define the difficulty of the input question x for \mathbf{P}_i . If $a_1 \in$

\mathcal{S} and $|\mathcal{S}| = 1$, we call x an easy question for \mathbf{P}_i . If $a_1 \in \mathcal{S}$ and $|\mathcal{S}| > 1$, we call x a moderate question for \mathbf{P}_i . If $a_1 \notin \mathcal{S}$, we call x a hard question for \mathbf{P}_i .

Theorem 1. If x is an easy question for \mathbf{P}_i , $\Pr(a_1|\mathbf{P}_i; N)$ is non-decreasing w.r.t. N , $\lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 1$.

Theorem 2. If x is a moderate question for \mathbf{P}_i , $\Pr(a_1|\mathbf{P}_i; N)$ is non-decreasing w.r.t. N , $\lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 1/|\mathcal{S}|$.

Theorem 3. If x is a hard question for \mathbf{P}_i , $\Pr(a_1|\mathbf{P}_i; N)$ exhibits a general declining trend w.r.t. N , $\lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 0$.

Lemma 1. Consider a specific condition with answer space $|\mathcal{A}| = 3$. For $N = 3$, $\Pr(a_1|\mathbf{P}_i; N) = 3p_{i,1}^2 - 2p_{i,1}^3 + 2p_{i,1}p_{i,2}p_{i,3}$. For $N = 5$, $\Pr(a_1|\mathbf{P}_i; N) = 6p_{i,1}^5 - 15p_{i,1}^4 + 10p_{i,1}^3 + 15p_{i,1}^2p_{i,2}p_{i,3}(p_{i,2} + p_{i,3})$.

Theorem 4. For two prompting strategies \mathbf{P}_i and $\mathbf{P}_{i'}$, note $p_{i,q} = \max\{p_{i,2}, \dots, p_{i,m}\}$, $p_{i',q'} = \max\{p_{i',2}, \dots, p_{i',m}\}$, if $p_{i,1} - p_{i,q} < p_{i',1} - p_{i',q'}$ and $p_{i,1} + p_{i,q} - p_{i,1}^2 - p_{i,q}^2 > p_{i',1} + p_{i',q'} - p_{i',1}^2 - p_{i',q'}^2$, there exists a sufficiently large N_0 such that for $N > N_0$, $\Pr(a_1|\mathbf{P}_i; N) < \Pr(a_1|\mathbf{P}_{i'}; N)$.

4.1 CoT Has More Easy Questions and Fewer Hard Questions

We identify two primary reasons why CoT sometimes performs worse with lower sample sizes (N) but achieves better performance among these prompting approaches with larger N . The first reason relates to the distribution of question difficulty for CoT. CoT has more easy questions and fewer hard questions. When sampling with lower N , \mathbf{P}_i still has a small probability of obtaining the right answer for hard questions, while the probability diminishes to zero as increasing N . This is the opposite of easy questions. The prompting strategy with fewer hard questions and more easy questions will improve performance more rapidly when scaling. According to Theorem 1 to 3, we can calculate the extreme performance of \mathbf{P}_i according to the difficulty proportion of questions, i.e., $\sum_{x \in \mathcal{D}} \lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N)$. Table 1 summarizes the difficulty proportion of the questions and extreme performance for each \mathbf{P}_i on each model. It can be observed that CoT has more easy questions and fewer hard questions, and can reach the best extreme performance on all models, thus making

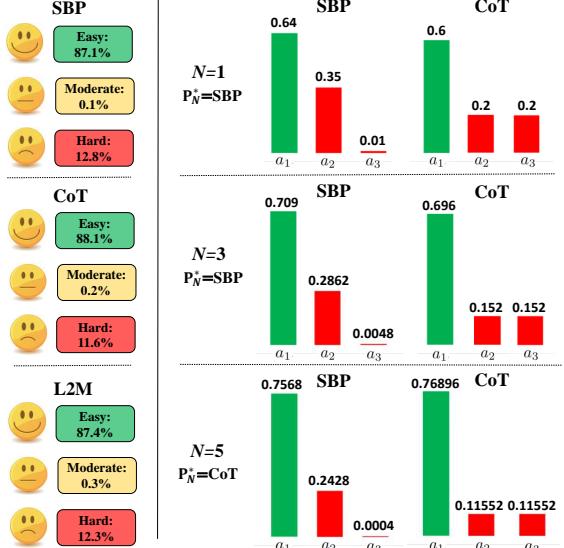


Figure 3: **Illustration of the two reasons why CoT sometimes performs worse with lower N while better with larger N .** **Left:** CoT has more easy questions and fewer hard questions. For example, the probability distribution of L2M is $\{0.4, 0.5, 0.1, 0.0, 0.0\}$ (hard question), and $\{0.3, 0.2, 0.2, 0.2, 0.1\}$ (easy question) for CoT. Although L2M has higher pass@1 accuracy, its accuracy reduces until 0% as scaling while CoT increases until 100%. **Right:** CoT is less likely to be affected by wrong answers due to their relatively uniform distribution. The probability of obtaining the right answer a_1 grows more rapidly as increasing N .

CoT gradually dominate as increasing N even if it has a lower pass@1 accuracy.

4.2 CoT is Less Likely to be Affected by Wrong Answers

The second reason for this phenomenon is that CoT is less likely to be affected by wrong answers. $\Pr(a_1|\mathbf{P}_i; N)$ is not a function of only the probability $p_{i,1}$ of the right answer a_1 , but also related to the probability distribution of other wrong answers. According to Theorem 4, even if $p_{i,1} > p_{i',1}$, i.e., $\Pr(a_1|\mathbf{P}_i; N = 1) > \Pr(a_1|\mathbf{P}_{i'}; N = 1)$, there still may exist an N_0 that $\Pr(a_1|\mathbf{P}_i; N = N_0) > \Pr(a_1|\mathbf{P}_{i'}; N = N_0)$. Considering a question x in GSM8K as an example and a_1 is the correct answer, the result probability distribution of $\mathbf{P}_i = \text{SBP}$ is $\{0.64, 0.35, 0.01\}$, and $\{0.6, 0.2, 0.2\}$ for $\mathbf{P}_{i'} = \text{CoT}$, which satisfies the condition in Theorem 4. According to Lemma 1, $\Pr(a_1|\mathbf{P}_i; N = 1) = 0.640 > \Pr(a_1|\mathbf{P}_{i'}; N = 1) = 0.600$, $\Pr(a_1|\mathbf{P}_i; N = 3) = 0.709 > \Pr(a_1|\mathbf{P}_{i'}; N = 3) = 0.696$, while $\Pr(a_1|\mathbf{P}_i; N = 5) = 0.757 < \Pr(a_1|\mathbf{P}_{i'}; N = 5) = 0.769$. This means, although complicated prompting strategies may have higher

Table 1: **Difficulty proportion of questions and extreme performance (denote by “Acc” for each \mathbf{P}_i and LLM across benchmarks.** CoT has more easy questions and fewer hard questions, and can reach the best extreme performance on all LLMs. More results on other models are shown in Table 4.

\mathbf{P}_i	Easy	Moderate	Hard	Acc	Easy	Moderate	Hard	Acc	Easy	Moderate	Hard	Acc
Qwen2.5-7B-Instruct				LLaMA-3-8B-Instruct				GLM-4-9B-Chat				
DiP	86.3%	0.3%	13.4%	86.4	69.7%	1.0%	29.3%	70.2	79.8%	0.6%	19.6%	80.1
CoT	88.1%	0.2%	11.6%	88.2	70.9%	0.9%	28.2%	71.3	82.8%	0.8%	16.5%	83.1
L2M	87.4%	0.3%	12.3%	87.6	70.3%	1.6%	28.1%	71.0	81.9%	0.4%	17.7%	82.1
SBP	87.1%	0.1%	12.8%	87.2	67.3%	1.3%	31.3%	68.0	81.4%	0.9%	17.6%	81.9
AnP	81.1%	0.5%	18.4%	81.3	67.5%	1.4%	31.1%	68.2	76.4%	1.2%	22.4%	77.0

Table 2: **Quantity of questions described in Section 4.2.** Results are displayed as “x/y”, where x is for Qwen and y for LLaMA. The value v_{ij} in the i th row and j th column represents the quantity of data that satisfies Theorem 4. Results prove that CoT has greater potential to significantly increase performance as scaling.

$\mathbf{P}_i \setminus \mathbf{P}_{i'}$	DiP↓	CoT↓	L2M↓	SBP↓	AnP↓	Sum ↓
DiP ↑	-	447/816	414/794	457/459	393/513	1711/2582
CoT ↑	423/620	-	374/646	416/382	361/408	1574/2046
L2M ↑	505/639	510/677	-	494/432	403/393	1912/2141
SBP ↑	599/1316	601/1433	564/1398	-	429/923	2193/5070
AnP ↑	800/1243	817/1381	799/1380	776/871	-	3192/4875
Sum ↑	2327/3818	2375/4307	2151/4218	2143/2144	1586/2237	-

pass@1 accuracy, they are easier to be affected by wrong answers. In contrast, simple CoT has a relatively flat distribution on wrong answers, thus making it focus more on the correct answer, which makes it more rapidly improve performance in easy questions and more slowly reduce accuracy in hard questions as increasing N , as shown in Figure 3. We record the quantity of such questions for each two prompting strategies and display the results of Qwen2.5-7B-Instruct and LLaMA-3-8B-Instruct in Table 2. If CoT is $\mathbf{P}_{i'}$, there are the most data satisfying Theorem 4. If CoT is \mathbf{P}_i , there are the least such questions. These demonstrate that CoT has greater potential to significantly increase scaling performance compared with other strategies.

5 Predicting Scaling Performance and \mathbf{P}_N^*

In practice, evaluating the test-time scaling performance requires significantly intensive resource consumption, especially with very large sampling time N . For pretraining, it is feasible to predict the train-time scaling performance based on the scaling law (Kaplan et al., 2020) through a series of low-cost experiments, while maintaining the model architecture largely unchanged and minimizing the risks associated with large-scale training. Simi-

larly, we can also use the sample results of \mathbf{P}_i with fewer N to approximately get the distribution $\{p_{i,1}, p_{i,2}, \dots, p_{i,m}\}$ to predict the test-time scaling performance with larger N . Directly, one can utilize the multinomial distribution probability calculation formula (Equation 13 and 14) to calculate $\Pr(a_1|\mathbf{P}_i; N)$ with enumeration or leverage numerical simulation to estimate. However, their computational complexities are both $O(N)$, and the former needs to traverse all situations and is difficult to operate. Therefore, we propose a method with the computational complexity $O(1)$ to quickly predict the scaling performance of majority voting for arbitrary \mathbf{P}_i , which can serve as the test-time scaling law. It can also select the best prompting strategy \mathbf{P}_N^* according to the predicted performances of each \mathbf{P}_i .

Here we omit the prompting index i and input question x , and assume a_1 is the correct answer in the following. According to Khinchin’s Law of Large Numbers and Lindeberg-Levy Central Limit Theorem, when N is large enough, each \mathbf{x}_j can be approximated by a normal distribution. Specifically, for \mathbf{x}_1 , we have

$$\mathbf{x}_1 \sim \mathcal{N}(Np_1, Np_1(1 - p_1)), \quad (5)$$

i.e., a normal distribution with mean Np_1 and variance $Np_1(1 - p_1)$. Considering the maximum value among all other \mathbf{x}_j ($j \neq 1$), denoted as $M = \max(\mathbf{x}_2, \dots, \mathbf{x}_m)$, when N is large enough, the distribution of M can be approximated by

$$M \sim \mathcal{N}(Np_{max}, Np_{max}(1 - p_{max})), \quad (6)$$

where p_{max} is the second highest probability excluding p_1 . We now need to calculate $P(\mathbf{x}_1 > M)$, which can be approximated by comparing two normal distributions. Let $Z = \mathbf{x}_1 - M$, then the distribution of Z is

$$Z \sim \mathcal{N}(N(p_1 - p_{max}), N(p_1(1 - p_1) + p_{max}(1 - p_{max}))). \quad (7)$$

Therefore,

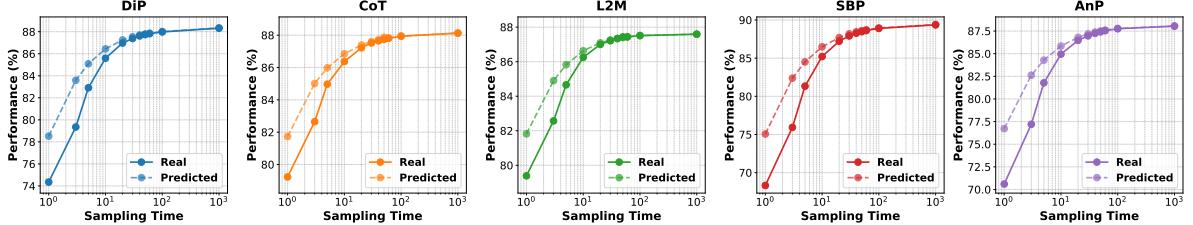


Figure 4: Real and predicted performance using our method of different \mathbf{P}_i under various sampling time constraints. Our method can accurately estimate the scaling performance of arbitrary \mathbf{P}_i , especially with large N .

Table 3: The true best prompting strategy \mathbf{P}_N^* and the predicted \mathbf{P}_N^* using our method under various sampling time constraints. Our method can correctly predict the best prompting strategy under any constraints evaluated.

\mathbf{P}_N^*	Sampling Time N							
	1	3	5	10	20	50	100	1000
Real	L2M	CoT	CoT	CoT	SBP	SBP	SBP	SBP
Predicted	L2M	CoT	CoT	CoT	SBP	SBP	SBP	SBP
Correct	✓	✓	✓	✓	✓	✓	✓	✓

$$\Pr(a^* = a_1) \approx \Pr(Z > 0), \quad (8)$$

where a^* is the final sample result. Using properties of the standard normal distribution, we can write

$$\begin{aligned} \Pr(Z > 0) &= \Pr\left(\frac{Z - E[Z]}{\sqrt{\text{Var}[Z]}} > \frac{-E[Z]}{\sqrt{\text{Var}[Z]}}\right) \\ &= 1 - \Phi\left(\frac{-E[Z]}{\sqrt{\text{Var}[Z]}}\right), \end{aligned} \quad (9)$$

$$E[Z] = N(p_1 - p_{max}),$$

$\text{Var}[Z] = N(p_1(1 - p_1) + p_{max}(1 - p_{max}))$, where Φ is the standard normal cumulative distribution function. Thus, we can quickly predict the scaling performance and select the best prompting strategy \mathbf{P}_N^* with given N by

$$\Pr(a_1 | \mathbf{P}_i; N) \approx 1 - \Phi\left(\frac{-(p_1 - p_{max})}{\sqrt{\frac{p_1(1-p_1)+p_{max}(1-p_{max})}{N}}}\right), \quad (10)$$

$$\text{Accuracy}(\mathbf{P}_i, N) = \mathbb{E}_{x \in \mathcal{D}} \Pr(a_1 | \mathbf{P}_i, N), \quad (11)$$

$$\mathbf{P}_N^* = \underset{\mathbf{P}_i}{\operatorname{argmax}} \text{Accuracy}(\mathbf{P}_i, N). \quad (12)$$

Experiment. We verify our method on LLaMA-3-8B-Instruct on GSM8K, only using 40 samples to estimate $p_{i,j}$. Results are shown in Figure 4. We can see that our method can accurately estimate the scaling performance, and the error decreases until 0% as scaling sampling time. When $N \geq 10$, the error is already less than 1%. This makes sense as our method is based on the assumption that N

is large enough. Although the prediction accuracy is not very high when N is small, the difference in predicted performances between distinct \mathbf{P}_i is similar to that in true performances, so our method can correctly select the best prompting strategy \mathbf{P}_N^* with arbitrary N , as shown in Table 3.

6 Improving Scaling Performance

According to the analysis in Section 4, we can further improve the scaling performance in two ways. Extensive experiments confirm their effectiveness, leading to significant improvements. We will further explore them in the future. All following results are conducted on Qwen-2.5-7B-Instruct on GSM8K. Please refer to Appendix D for more results on other LLMs and benchmarks.

6.1 Adaptively Scaling Based on the Difficulty

According to Theorem 1 to 4, it will lead to decreased performance when scaling sampling time on hard questions. Performances only continuously improve on easy questions. **Therefore, when facing a hard question, we can force LLMs to only answer it once without scaling more. If the question is a moderate or easy question, LLMs scale sampling time as usual.** We evaluate the performance both when forcing the LLM to determine the question difficulty itself (noted as “Adaptive”) and providing the difficulty oracle to the LLM as an upper bound reference (noted as “Oracle”), as shown in Figure 5. “Adaptive” performance is almost equal to the usual scaling performance (noted as “Vanilla”), which is because the LLM is more inclined to believe a question is easy, especially on more complicated \mathbf{P}_i such as SBP and AnP. Nevertheless, all \mathbf{P}_i can significantly improve their scaling performances with question difficulty oracles, proving the potential of this method.

6.2 Dynamically Choosing the Optimal \mathbf{P}_i

For a question x , it may be a hard question for a prompting strategy \mathbf{P}_i with higher accuracy, while

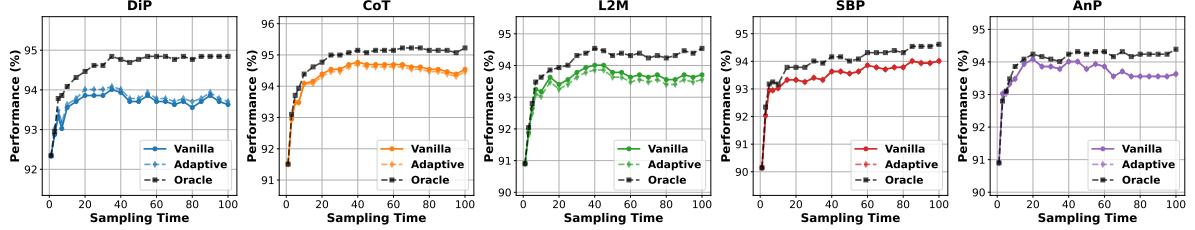


Figure 5: Results of adaptively scaling for each $\mathbf{P}_i \in \mathcal{P}_1$ based on oracle and predicted question difficulty.

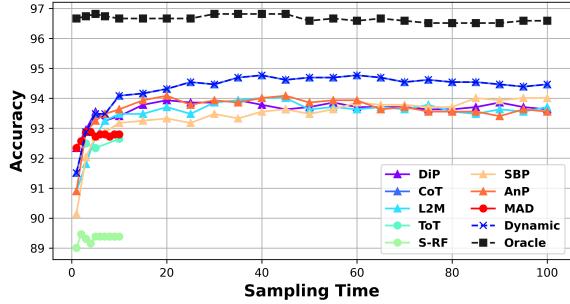


Figure 6: Results of dynamically choosing the optimal \mathbf{P}_i .

an easy question for another strategy $\mathbf{P}_{i'}$ with lower accuracy. **So if we can choose the optimal prompting strategy for each question, it will largely improve the performance.** We test the scaling performance both when forcing the LLM to choose the most suitable \mathbf{P}_i (noted as “Dynamic”) and providing the oracles as an upper bound (noted as “Oracle”), *i.e.*, telling the LLM which \mathbf{P}_i maximizes $\Pr(a_1 | \mathbf{P}_i; N)$, as shown in Figure 6. “Dynamic” performance is almost equal to CoT. This is because Qwen believes CoT is the best \mathbf{P}_i among 8 prompting strategies in 99.7% of the questions. However, it can achieve significant improvement with oracles. This means that selecting the best \mathbf{P}_i for each question is more effective than majority voting, as “Oracle” performance with only $N = 1$ is much higher than $\forall \mathbf{P}_i$ with even $N \rightarrow +\infty$. However, “Oracle” performance does not increase with scaling. This is because there are questions that are hard for all \mathbf{P}_i . Even if we select the best \mathbf{P}_i on a question, its accuracy still reduces with scaling. So if we can combine the two methods in Section 6.1 and 6.2, it would lead to much more improvement.

6.3 Combining Adaptively Scaling and Dynamically Choosing the Optimal \mathbf{P}_i

Figure 7 reports the performance upper bounds of each $\mathbf{P}_i \in \mathcal{P}_1 + \text{“Adaptive”}$, “Dynamic”, and combining “Adaptive” and “Dynamic”. Experiment results demonstrate the powerful potential of the

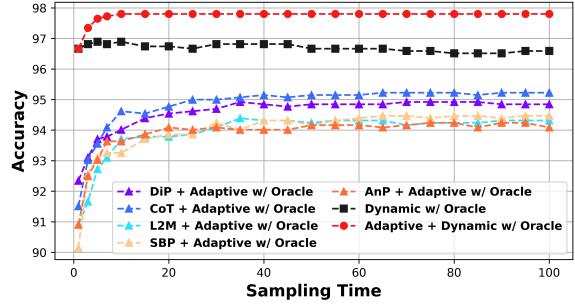


Figure 7: Results of combining adaptively scaling and dynamically choosing the optimal \mathbf{P}_i with oracles.

combined method. We will explore more feasible methods to reach this upper bound in future work.

7 Related Work

Reasoning Prompting Strategies. CoT series carefully design exemplars or 0-shot prompts to unleash the potential of step-by-step solving (Wei et al., 2022; Kojima et al., 2022; Zhang et al., 2023; Fu et al., 2023). (Zhou et al., 2023; Dua et al., 2022; Khot et al., 2023) break down the question into smaller, more manageable subproblems. (Madaan et al., 2023; Kim et al., 2023) force LLMs to self-evaluate and correct. (Du et al., 2024; Liang et al., 2024; Chan et al., 2024; Liu et al., 2025) utilize multi-agent debate to collaborate reasoning. (Yasunaga et al., 2024; Yu et al., 2024) guide LLMs to draw experience from analogous problems. (Zheng et al., 2024; Gao et al., 2025) promote LLMs on abstract reasoning.

Scaling Test-Time Compute. Self-Consistency is a simple but effective scaling method (Wang et al., 2023b). (Li et al., 2023; Hosseini et al., 2024) train a verifier to evaluate samples and select the best solution. Some use iterative refinement (Madaan et al., 2023) or multiple rounds of debate(Du et al., 2024). Others leverage the theory of tree search (Yao et al., 2023; Ding et al., 2024; Zhang et al., 2024a) and graph search (Besta et al., 2024a; Jin et al., 2024a) to expand and aggregate reasoning paths (Besta et al., 2024b).

8 Conclusion

We comprehensively study the behavior of various prompting strategies when scaling majority voting. Our experiments on $6 \text{ LLMs} \times 8 \text{ prompting strategies} \times 6 \text{ benchmarks}$ consistently show that CoT has the potential to perform best as scaling. Theoretical analyses reveal that CoT benefits from fewer hard questions, more easy questions, and less susceptibility to incorrect answers, enabling rapid performance gains with increased sampling. Additionally, our proposed method for predicting scaling performance offers a practical tool to select the optimal prompting strategy under given budgets. What’s more, we introduce two effective methods to further improve scaling performance. We hope our research can provide new insights to understand, predict, and improve LLM test-time scaling performance.

Limitations

In this paper, we mainly focus on majority voting, which is a simple but effective scaling approach. However, we don’t test on other more complex scaling approaches such as Monte Carlo Tree Search. Our finding that CoT dominates as scaling most of the time does not always hold for every LLM on every dataset, *e.g.*, Table 3. Nevertheless, 80% of the results conform to this rule. In fact, it depends on the composition of the dataset. If we specifically collect hard questions for \mathbf{P}_i as a dataset, it will lead to a continuous decline performance of \mathbf{P}_i . Our experiments and analysis indicate that, even though some \mathbf{P}_i may perform poorly with lower sampling time, they hold the potential to exhibit superior performance than other prompting strategies as test-time scaling. We propose two superior methods according to rigorous theories, which can significantly improve scaling performance on each model and each benchmark we test, and we are confident in the universality of our methods. However, our experiment results indicate that LLMs alone cannot readily achieve the intended effects, pushing us to explore more practicable and effective methods in our future work.

Ethical Considerations

There are many potential societal consequences of our work, none which we feel must be specifically highlighted here. The sole potential risk we acknowledge is that scaling compute may result

in substantial electricity consumption and carbon dioxide emissions.

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A Broader Related Work

Efficient Reasoning. Several studies have shown that scaling test-time compute can be more effective than scaling model parameters (Snell et al., 2025; Open AI, 2024b). (Aggarwal et al., 2023; Li et al., 2024; Chen et al., 2024a) improve the reasoning efficiency with majority voting by adjusting the sampling time. (Damani et al., 2025; Zhang et al., 2024b) learn to dynamically allocate resources under limited sampling time budgets. (Chen et al., 2024b; Yue et al., 2024; Šakota et al., 2024) leverage multiple models with different prices to reduce cost while maintaining performance.

Role and Mechanism of CoT and Test-Time Scaling. (Jin et al., 2024b) studies the impact of reasoning step length of CoT. (Wang et al., 2023a) studies what makes CoT prompting effective, indicating that being relevant to the query and correctly ordering the reasoning steps are more important. (Feng et al., 2024; Cui et al., 2024) analyze the mechanism of CoT from a theoretical perspective. (Sprague et al., 2025) points out that CoT helps mainly on math and symbolic reasoning by sorting and analyzing a large number of experimental results. (Chen et al., 2024c) proposes a framework to quantify the reasoning boundary of CoT. (Yang et al., 2024b) provides an in-context learning analysis of CoT. (Chen et al., 2024a) investigates and analyzes the performance changes with more LLM calls. (Chen et al., 2024d) proves that the failure probability of test-time scaling decays to zero exponentially or by a power law.

B Proofs

Theorem 1. If x is an easy question for \mathbf{P}_i , $\Pr(a_1|\mathbf{P}_i; N)$ is non-decreasing w.r.t. N , $\lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 1$.

Theorem 2. If x is a moderate question for \mathbf{P}_i , $\Pr(a_1|\mathbf{P}_i; N)$ is non-decreasing w.r.t. N , $\lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 1/|\mathcal{S}|$.

Theorem 3. If x is a hard question for \mathbf{P}_i , $\Pr(a_1|\mathbf{P}_i; N)$ exhibits a general declining trend w.r.t. N , $\lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 0$.

Proof. The occurrence number $\mathbf{X}_i = (\mathbf{x}_{i,1}, \dots, \mathbf{x}_{i,m})$ of each probable answer for \mathbf{P}_i follows a multinomial distribution, i.e., $\mathbf{X}_i \sim \text{Mult}(N, p_{i,1}, p_{i,2}, \dots, p_{i,m})$. When sampling N times, the specific probability of a certain occurrence number can be calculated with Equation 13. For brevity, we omit the input x , sampling time N , and the prompting index i in $\mathbf{x}_{i,j}$ and $p_{i,j}$ in the following equations.

$$\begin{aligned} \Pr(\mathbf{x}_1 = k_1, \mathbf{x}_2 = k_2, \dots, \mathbf{x}_m = k_m) \\ = \underbrace{\frac{N!}{k_1! k_2! \cdots k_m!}}_{\text{coefficient}} \underbrace{p_1^{k_1} p_2^{k_2} \cdots p_m^{k_m}}_{\text{probability term}} \end{aligned} \quad (13)$$

$$s.t. \quad \sum_{j=1}^m k_j = N, \quad \sum_{j=1}^m p_j = 1$$

Assuming the correct answer is a_1 , $M = \max(k_2, \dots, k_m)$, the probability of obtaining the right answer by sampling N times with \mathbf{P}_i is

$$\Pr(a_1|\mathbf{P}_i) = \Pr(\mathbf{x}_1 > M) + \sum_{|\mathcal{J}|=1}^{m-1}$$

$$\Pr(\mathbf{x}_1 = \mathbf{x}_j > \mathbf{x}_q \text{ for all } j \in \mathcal{J}, q \notin \{1\} \cup \mathcal{J}), \quad |\mathcal{J}|+1 \quad (14)$$

where \mathcal{J} is the set of all indexes j ($j \neq 1$) of \mathbf{x}_j that satisfies $\mathbf{x}_j = \mathbf{x}_1$.

$$\Pr_1 = \Pr(\mathbf{x}_1 > M) =$$

$$\sum_{\substack{m \\ \sum_{j=1}^m k_j = N}} \frac{N!}{k_1! \cdots k_m!} p_1^{k_1} \prod_{j=2}^m p_j \mathbb{1}(k_j < k_1), \quad (15)$$

$$\Pr_2 = \Pr(\mathbf{x}_1 = \mathbf{x}_j > \mathbf{x}_q \text{ for all } j \in \mathcal{J}, q \notin \{1\} \cup \mathcal{J})$$

$$= \sum_{\substack{m \\ \sum_{j=1}^m k_j = N}} \frac{N!}{k_1! \prod_{q \notin \{1\} \cup \mathcal{J}} k_q!} p_1 \prod_{j \in \mathcal{J}} p_j \prod_{q \notin \{1\} \cup \mathcal{J}} p_k \mathbb{1}(k_k < k_1), \quad (16)$$

\Pr_1 represents the probability that \mathbf{x}_1 is the only maximum number in \mathbf{X}_i . \Pr_2 denotes the probability that there exists more than one maximum number and correctly obtains a_1 by randomly choosing from them.

Here we present a generalized representation. As shown in Equation 14, $\Pr(a_1|\mathbf{P}_i)$ only includes the cases where $\mathbf{X}_{i,1}$ is the maximum value (maybe not the only one). Therefore, for a certain occurrence number $\mathbf{X}_i = (\mathbf{x}_1, \dots, \mathbf{x}_m)$ of each probable answer $\{a_1, \dots, a_m\}$, we can reorder a_2, \dots, a_m to obtain $\mathbf{x}_1 = \mathbf{x}_2 = \cdots = \mathbf{x}_l > \mathbf{x}_{l+1}, \mathbf{x}_{l+2}, \dots, \mathbf{x}_m$, where $1 \leq l \leq m$. When $l = 1$, \mathbf{x}_1 is the only maximum value. So each term in $\Pr(a_1|\mathbf{P}_i; N)$ can be written as

$$\frac{1}{l} \cdot \frac{(lk + \sum_{j=l+1}^m k_j)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^{k_2} \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m}, \quad (17)$$

where $k_1 = k_2 = \cdots = k_l = k > k_j$, $j = l+1, \dots, m$ and $lk + \sum_{j=l+1}^m k_j = N$.

Now we prove Theorem 1 and 2. We aim to prove that given the set of answers $\{a_1, a_2, \dots, a_m\}$ with associated probabilities $\{p_1, p_2, \dots, p_m\}$ from \mathbf{P}_i , we have $\Pr(a_1|\mathbf{P}_i; N+1) \geq \Pr(a_1|\mathbf{P}_i; N)$ for any $N \in \mathbb{N}^+$. Due to $\sum_{j=1}^m p_j = 1$, the given proposition can be restated as

$$\Pr(a_1|\mathbf{P}_i; N+1) - \left(\sum_{j=1}^m p_j \right) \cdot \Pr(a_1|\mathbf{P}_i; N) \geq 0. \quad (18)$$

We consider the probability term $p_1^k p_2^{k_2} \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m}$ in each term in $\Pr(a_1|\mathbf{P}_i; N)$, i.e., Equation 17. When it times $\sum_{j=1}^m p_j$, there will be three cases.

Case 1: When it times p_1 , \mathbf{x}_1 is the only maximum value. The probability term becomes

$$p_1^{k+1} p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m},$$

Case 2: When it times p_s , where $s \in \{2, \dots, l\}$, \mathbf{x}_s become the only maximum value. In this situation, its final result would be an incorrect answer. If $l = 1$, case 2 will not exist. The probability term becomes

$$p_1^k p_2^k \cdots p_{s-1}^k p_s^{k+1} p_{s+1}^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m}$$

Case 3: When it times p_t , where $t \in \{l+1, \dots, m\}$, the value of \mathbf{x}_t changes from k_t to $k_t + 1$. If $k_t = k-1$, \mathbf{x}_t becomes a new maximum value. If $l = m$, case 3 will not exist. The probability term becomes

$$p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_t+1} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m}.$$

It can be seen that case 1 and case 3 are also

present in $\Pr(a_1|\mathbf{P}_i; N+1)$, whereas case 2 does not. We begin by considering case 1 and case 2. The terms in $\Pr(a_1|\mathbf{P}_i; N+1)$ corresponding to case 1 $p_1^{k+1} p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m}$ are shown in Equation 19, and no term in $\Pr(a_1|\mathbf{P}_i; N+1)$ involves case 2. The terms in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$ involving case 1 are shown in Equation 20. The terms in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$ involving case 2 $p_1^k p_2^k \cdots p_s^k p_{s-1}^{k_{s-1}} p_s^{k_{s+1}} \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m}$ are shown in Equation 21. Based on the fact of Equation 22, we can establish the inequality Equation 23, *i.e.*, the terms corresponding to case 1 and case 2 in $\Pr(a_1|\mathbf{P}_i; N+1)$ are greater than or equal to those in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$.

Now we consider case 3 $p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_{t+1}} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m}$, which can be analyzed by splitting it into two distinct scenarios: $k_t + 1 < k$ and $k_t + 1 = k$.

For scenario $k_t + 1 < k$, the terms in $\Pr(a_1|\mathbf{P}_i; N+1)$ corresponding to case 3 are shown in Equation 24. The terms in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$ corresponding to case 3 are shown in Equation 25. Evidently, we can obtain Equation 26 similar to Equation 22, and then we can get Equation 27, which proves the terms corresponding to the scenario $k_t + 1 < k$ in $\Pr(a_1|\mathbf{P}_i; N+1)$ are equal to those in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$.

For scenario $k_t + 1 = k$, in a similar manner, according to the Equation 28, we obtain the same result as the above scenario, *i.e.*, the terms corresponding to the scenario $k_t + 1 = k$ in $\Pr(a_1|\mathbf{P}_i; N+1)$ are equal to those in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$.

Thus far, let us revisit the proof steps. In the first step, we expand the expression $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$ and divide it into three cases, where case 1 and case 3 are present in $\Pr(a_1|\mathbf{P}_i; N+1)$ whereas case 2 does not. It has been proven that the coefficients of the terms in $\Pr(a_1|\mathbf{P}_i; N+1)$, where case 3 appears as the probability term part, are identical to those in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$. Consequently, these terms cancel out in the expression $\Pr(a_1|\mathbf{P}_i; N+1) - (\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$. However, case 2 is not present in $\Pr(a_1|\mathbf{P}_i; N+1)$, which implies that the terms in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$, where case 2 appears as the probability term part, cannot be combined with any terms in $\Pr(a_1|\mathbf{P}_i; N+1)$ by extracting the exponent and performing subtraction on the coefficients like the terms containing case 3. It is fortunate that the

terms in $\Pr(a_1|\mathbf{P}_i; N+1)$, where case 1 appears as the probability term part, cancel out with the corresponding terms in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$ which share the same probability terms and the remaining terms have coefficients identical to those of the terms in $(\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N)$, where case 2 appears as the probability terms. Therefore, these terms can be combined by factoring out the shared coefficients and partial probability terms. The remaining part after factoring out the common factor is $\sum_{s=2}^l (p_1 - p_s)$. It is undeniable that $p_1 \geq p_s$ when x is an easy question or moderate question for \mathbf{P}_i , therefore $\Pr(a_1|\mathbf{P}_i; N+1) - (\sum_{j=1}^m p_j) \cdot \Pr(a_1|\mathbf{P}_i; N) \geq 0$. Namely, $\Pr(a_1|\mathbf{P}_i; N)$ is strictly non-decreasing w.r.t. N if x is an easy or moderate question.

For sufficiently large N , the strong law of large numbers implies that $\Pr(\lim_{N \rightarrow +\infty} \mathbf{x}_j/N = p_j) = 1$. When x is an easy question, $p_1 > p_j, \mathbf{x}_1/N > \mathbf{x}_j/N$ for $j = 2, 3, \dots, m$. As N is sufficiently large, it is sure that \mathbf{x}_1 is the only maximum value, making the final result must be the correct answer a_1 . Therefore, if x is an easy question, $N, \lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 1$. If x is a moderate question, there are $|\mathcal{S}|$ equivalent answers in the probability sense, whose probabilities are all the maximum value. Therefore, $\lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 1/|\mathcal{S}|$. Similarly, if x is a hard question, the maximum probability is not p_1 , the final result must be a wrong answer, so $\lim_{N \rightarrow +\infty} \Pr(a_1|\mathbf{P}_i; N) = 0$. Theorem 1 to 3 is proved.

Lemma 1. Consider a specific condition with answer space $|\mathcal{A}| = 3$. For $N = 3$, $\Pr(a_1|\mathbf{P}_i; N) = 3p_{i,1}^2 - 2p_{i,1}^3 + 2p_{i,1}p_{i,2}p_{i,3}$. For $N = 5$, $\Pr(a_1|\mathbf{P}_i; N) = 6p_{i,1}^5 - 15p_{i,1}^4 + 10p_{i,1}^3 + 15p_{i,1}^2p_{i,2}p_{i,3}(p_{i,2} + p_{i,3})$.

Proof. For $N = 3$, we can calculate $\Pr(a_1|\mathbf{P}_i; N)$ with Equation 14 as follows:

$$\begin{aligned} \Pr(a_1|\mathbf{P}_i; N=3) &= \binom{3}{3} p_{i,1}^3 + \binom{3}{2} p_{i,1}^2(1-p_{i,1}) \\ &\quad + A(3, 1) p_{i,1} p_{i,2} p_{i,3} \\ &= 3p_{i,1}^2 - 2p_{i,1}^3 + 2p_{i,1}p_{i,2}p_{i,3}, \end{aligned} \tag{29}$$

where $A(n, k)$ is the permutation number formula

$$\frac{\left(lk + 1 + \sum_{j=l+1}^m k_j\right)!}{(k+1) \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} p_1^{k+1} p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \quad (19)$$

$$\begin{aligned} & p_1 \cdot \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \\ & + \sum_{s=2}^l p_s \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k+1}{k} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} p_1^{k+1} p_2^k \cdots p_{s-1}^k p_s^{k-1} p_{s+1}^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \\ & + \sum_{t=l+1}^m p_t \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k+1}{k_t} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} p_1^{k+1} p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_{t-1}} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m} \end{aligned} \quad (20)$$

$$\sum_{s=2}^l p_s \cdot \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} p_1^k p_2^k \cdots p_{s-1}^k p_s p_{s+1}^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \quad (21)$$

$$\begin{aligned} \frac{\left(lk + 1 + \sum_{j=l+1}^m k_j\right)!}{(k+1) \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} &= \frac{[(k+1) + (l-1)k + \sum_{t=l+1}^m k_t](lk + \sum_{j=l+1}^m k_j)!}{(k+1) \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} \\ &= \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} + (l-1) \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k+1}{k} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} \\ &+ \sum_{t=l+1}^m \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k+1}{k_t} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} + (l-1) \cdot \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j!)^{k_j}} \end{aligned} \quad (22)$$

$A(n, k) = \frac{n!}{(n-k)!}$. For $N = 5$, we can get

$$\begin{aligned} \Pr(a_1 | \mathbf{P}_i; N = 5) &= \binom{5}{5} p_{i,1}^5 + \binom{5}{4} p_{i,1}^4 (1 - p_{i,1}) + \\ &\quad \binom{5}{3} p_{i,1}^3 (1 - p_{i,1})^2 + \binom{5}{2} p_{i,1}^2 \binom{3}{2} (p_{i,2}^2 p_{i,3} + p_{i,3}^2 p_{i,2}) \\ &= 6p_{i,1}^5 - 15p_{i,1}^4 + 10p_{i,1}^3 + 15p_{i,1}^2 p_{i,2} p_{i,3} (p_{i,2} + p_{i,3}) \end{aligned} \quad (30)$$

Lemma 1 is proved.

Theorem 4. For two prompting strategies \mathbf{P}_i and $\mathbf{P}_{i'}$, note $p_{i,q} = \max\{p_{i,2}, \dots, p_{i,m}\}$, $p_{i',q'} = \max\{p_{i',2}, \dots, p_{i',m}\}$, if $p_{i,1} - p_{i,q} < p_{i',1} - p_{i',q'}$ and $p_{i,1} + p_{i,q} - p_{i,1}^2 - p_{i,q}^2 > p_{i',1} + p_{i',q'} - p_{i',1}^2 - p_{i',q'}^2$, there exists a sufficiently large N_0 such that for $N > N_0$, $\Pr(a_1 | \mathbf{P}_i; N) < \Pr(a_1 | \mathbf{P}_{i'}; N)$.

Proof. According to Khinchin's Law of Large Numbers and Lindeberg-Levy Central Limit Theorem, when N is sufficiently large, each X_i can be approximated by a normal distribution. Specifically, for each $\mathbf{x}_{i,j}$, we have $\mathbf{x}_{i,j} \sim \mathcal{N}(Np_{i,j}, Np_{i,j}(1 - p_{i,j}))$. Note $M_i = \max(\mathbf{x}_{i,2}, \dots, \mathbf{x}_{i,m})$ and $p_{i,q} = \max\{p_{i,2}, \dots, p_{i,m}\}$, the distribution of M_i can be approximated by $M_i \sim \mathcal{N}(Np_{i,n}, Np_{i,1}(1 - p_{i,1}))$. So $\mathbf{x}_{i,j} - M_i$ obey the normal distribution $\mathcal{N}(N(p_{i,1} - p_{i,q}), N(p_{i,1}(1 - p_{i,1}) + p_{i,q}(1 - p_{i,q})))$. Thus, we can get Equation 31:

$$\begin{aligned}
& \frac{\left(lk + 1 + \sum_{j=l+1}^m k_j\right)!}{(k+1) \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^{k+1} p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \\
& - p_1 \cdot \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \\
& - \sum_{s=2}^l p_s \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k+1}{k} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^{k+1} p_2^k \cdots p_{s-1}^k p_s^{k-1} p_{s+1}^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \\
& - \sum_{t=l+1}^m p_t \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k+1}{k_t} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^{k+1} p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_t-1} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m} \\
& - \sum_{s=2}^l p_s \cdot \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_{s-1}^k p_s^k p_{s+1}^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \\
& = \sum_{s=2}^l \left[\frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_{s-1}^k p_s^k p_{s+1}^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} \right] \cdot (p_1 - p_s) \geq 0
\end{aligned} \tag{23}$$

$$\frac{1}{l} \cdot \frac{\left(lk + 1 + \sum_{j=l+1}^m k_j\right)!}{(k_t+1) \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_t+1} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m} \tag{24}$$

$$\begin{aligned}
& \sum_{s=2}^l p_s \cdot \frac{1}{l-1} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k_t+1}{k} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_{s-1}^k p_s^{k-1} p_{s+1}^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_{t+1}} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m} \\
& + \sum_{r=l+1, r \neq t}^m p_r \cdot \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k_t+1}{k_r} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{r-1}^{k_{r-1}} p_r^{k_{r+1}} p_{r+1}^{k_{r+1}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_{t+1}} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m} \\
& + p_t \cdot \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m}
\end{aligned} \tag{25}$$

$$\begin{aligned}
& \frac{1}{l} \cdot \frac{\left(lk + 1 + \sum_{j=l+1}^m k_j\right)!}{(k_t+1) \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} = \sum_{s=2}^l \frac{1}{l-1} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k_t+1}{k} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} \\
& + \sum_{r=l+1, r \neq t}^m p_r \cdot \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{\frac{k_t+1}{k_r} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} \\
& + \frac{1}{l} \cdot \frac{\left(lk + \sum_{j=l+1}^m k_j\right)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!}
\end{aligned} \tag{26}$$

$$\begin{aligned}
& \frac{1}{l} \cdot \frac{(lk + 1 + \sum_{j=l+1}^m k_j)!}{(k_t + 1) \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_t+1} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m} \\
& - \sum_{s=2}^l p_s \cdot \frac{1}{l-1} \cdot \frac{(lk + \sum_{j=l+1}^m k_j)!}{\frac{k_t+1}{k} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_{s-1}^k p_s^{k-1} p_{s+1}^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_t+1} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m} \\
& - \sum_{r=l+1, r \neq t}^m p_r \cdot \frac{1}{l} \cdot \frac{(lk + \sum_{j=l+1}^m k_j)!}{\frac{k_t+1}{k_r} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_{r-1}^{k_{r-1}} p_r^{k_{r+1}} p_{r+1}^{k_{r+1}} \cdots p_{t-1}^{k_{t-1}} p_t^{k_t+1} p_{t+1}^{k_{t+1}} \cdots p_m^{k_m} \\
& - p_t \cdot \frac{1}{l} \cdot \frac{(lk + \sum_{j=l+1}^m k_j)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!} p_1^k p_2^k \cdots p_l^k p_{l+1}^{k_{l+1}} p_{l+2}^{k_{l+2}} \cdots p_m^{k_m} = 0
\end{aligned} \tag{27}$$

$$\begin{aligned}
\frac{1}{l+1} \cdot \frac{(lk + 1 + \sum_{j=l+1}^m k_j)!}{(k_t + 1) \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} &= \sum_{s=2}^l \frac{1}{l} \cdot \frac{(lk + \sum_{j=l+1}^m k_j)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!} \\
&+ \sum_{r=l+1, r \neq t}^m p_r \cdot \frac{1}{l+1} \cdot \frac{(lk + \sum_{j=l+1}^m k_j)!}{\frac{k_t+1}{k_r} \cdot (k!)^l \cdot \prod_{j=l+1}^m (k_j)!} \\
&+ \frac{1}{l} \cdot \frac{(lk + \sum_{j=l+1}^m k_j)!}{(k!)^l \cdot \prod_{j=l+1}^m (k_j)!}
\end{aligned} \tag{28}$$

Table 4: **Difficulty proportion of questions and extreme performance (denote by “Acc” for each \mathbf{P}_i and LLM across benchmarks.** CoT has more easy questions and fewer hard questions, and can reach the best extreme performance on all LLMs.

\mathbf{P}_i	Easy	Moderate	Hard	Acc	Easy	Moderate	Hard	Acc	Easy	Moderate	Hard	Acc
Phi-3.5-mini-Instruct				Gemini-1.5-Flash				GPT-4o-mini				
DiP	78.4%	0.6%	21.1%	78.6	91.0%	0.0%	9.0%	91.0	89.7%	0.4%	9.9%	89.9
CoT	81.2%	0.4%	18.4%	81.4	91.2%	0.2%	8.6%	91.3	89.8%	0.3%	9.9%	90.0
L2M	80.2%	0.6%	19.2%	80.5	90.9%	0.2%	89.8%	90.9	89.8%	0.3%	10.0%	89.9
SBP	79.0%	0.6%	20.4%	79.3	90.6%	0.4%	9.0%	90.8	81.4%	0.2%	10.4%	89.5
AnP	77.0%	1.2%	21.8%	77.6	80.5%	0.6%	18.8%	90.9	81.4%	1.1%	17.5%	81.9

$$\begin{aligned}
& \Pr(\mathbf{x}_{i,1} > M_i) \\
&= \Pr(\mathbf{x}_{i,1} - M_i > 0) \\
&= 1 - \Phi(f(p_{i,1}, p_{i,q}, N)), \\
& \Phi(f(p_{i,1}, p_{i,q}, N)) = \\
& \Phi\left(\sqrt{\frac{N}{p_{i,1}(1-p_{i,1}) + p_{i,q}(1-p_{i,q})}}(p_{i,q} - p_{i,1})\right),
\end{aligned} \tag{31}$$

where Φ is the standard normal cumulative distribution function. This also holds for any other $\Pr(\mathbf{x}_{i',1} > M'_i)$. If $p_{i,1} - p_{i,q} <$

$p_{i',1} - p_{i',q'}$ and $p_{i,1} + p_{i,q} - p_{i,1}^2 - p_{i,q}^2 > p_{i',1} + p_{i',q'} - p_{i',1}^2 - p_{i',q'}^2$, we can get $p_{i,q} - p_{i,1} > p_{i',q} - p_{i',1}$ and $p_{i,1}(1-p_{i,1}) + p_{i,q}(1-p_{i,q}) < p_{i',1}(1-p_{i',1}) + p_{i',q'}(1-p_{i',q'})$, and $\Phi(f(p_{i,1}, p_{i,q}, N)) > \Phi(f(p_{i',1}, p_{i',q'}, N))$. So there exists a large N_0 such that for $N > N_0$, $\Pr(\mathbf{x}_{i',1} > M'_i) > \Pr(\mathbf{x}_{i,1} > M_i)$, i.e., $\Pr(a_1 | \mathbf{P}_i; N) > \Pr(a_1 | \mathbf{P}_{i'}; N)$. Theorem 4 is proved.

C Detailed Results

Here we display the scaling performance of different prompting strategies on each LLM and bench-

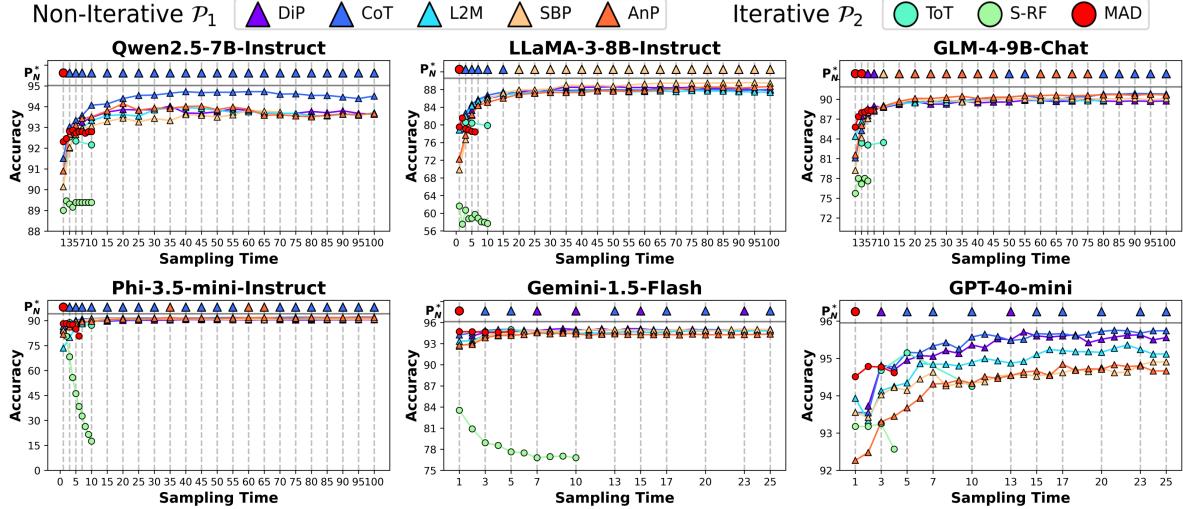


Figure 8: Performance of each prompting strategy under given sampling time N on GSM8K.

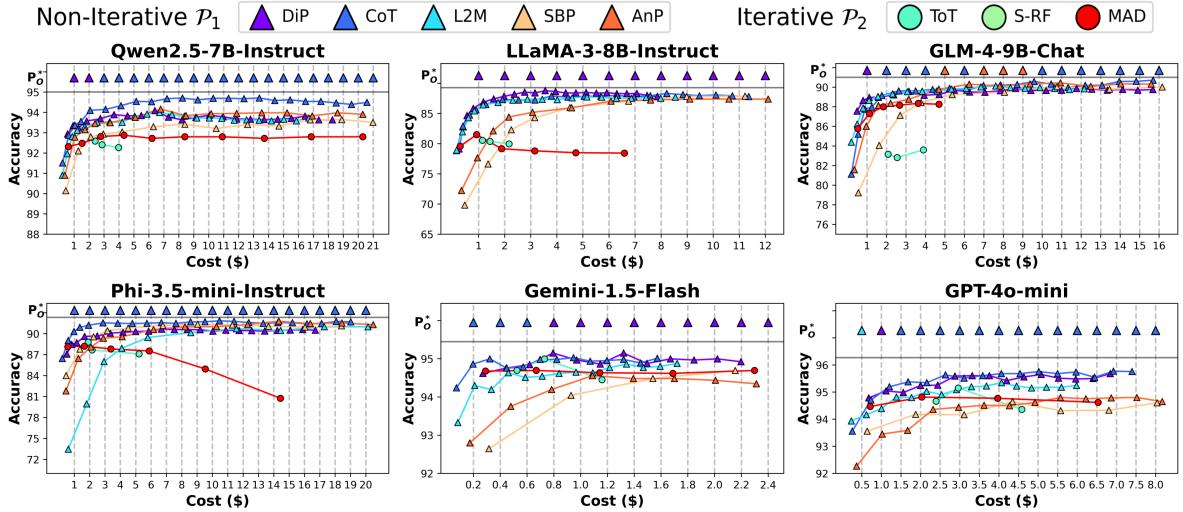


Figure 9: Performance of each prompting strategy under given cost O on GSM8K.

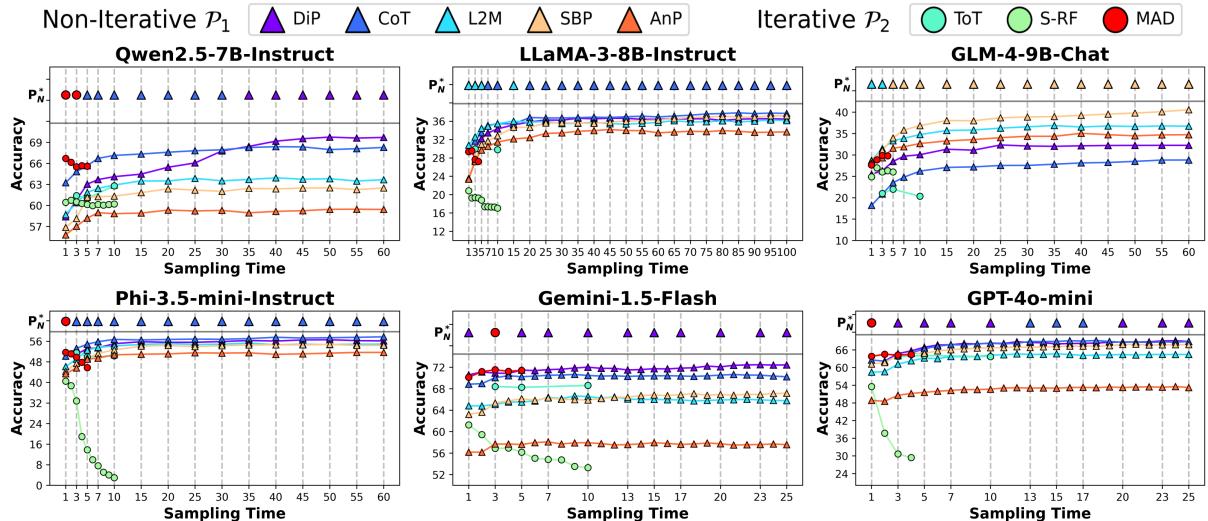


Figure 10: Performance of each prompting strategy under given sampling time N on GSM-Hard.

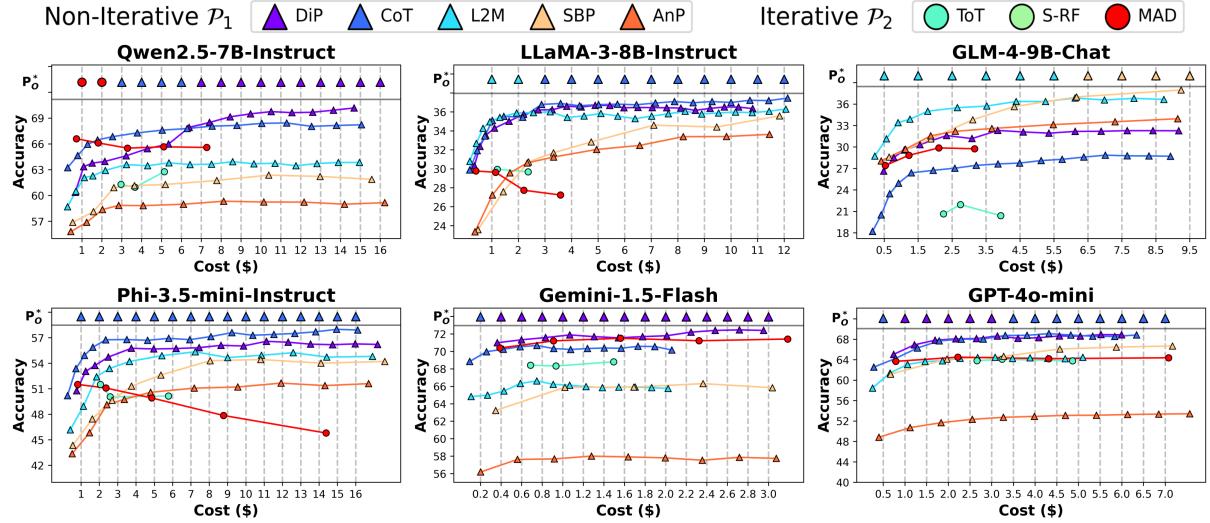


Figure 11: Performance of each prompting strategy under given cost O on GSM-Hard.

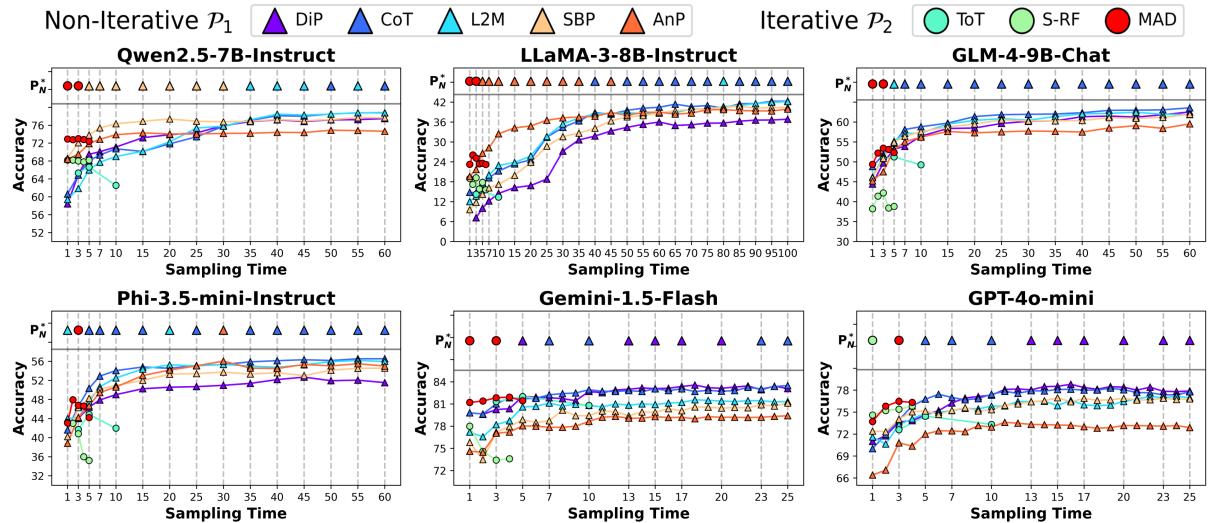


Figure 12: Performance of each prompting strategy under given sampling time N on MATH.

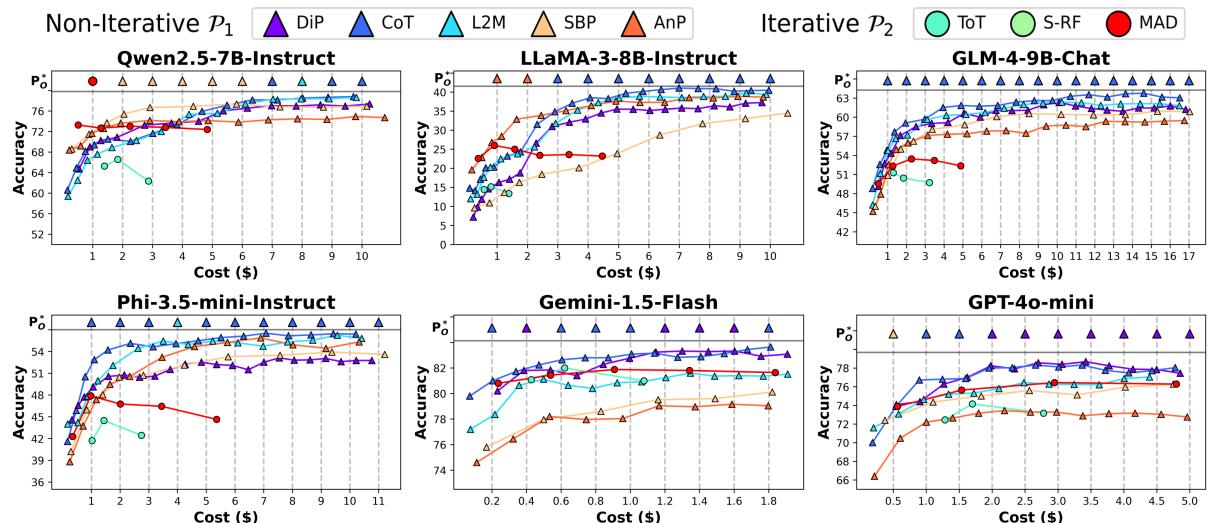


Figure 13: Performance of each prompting strategy under given cost O on MATH.

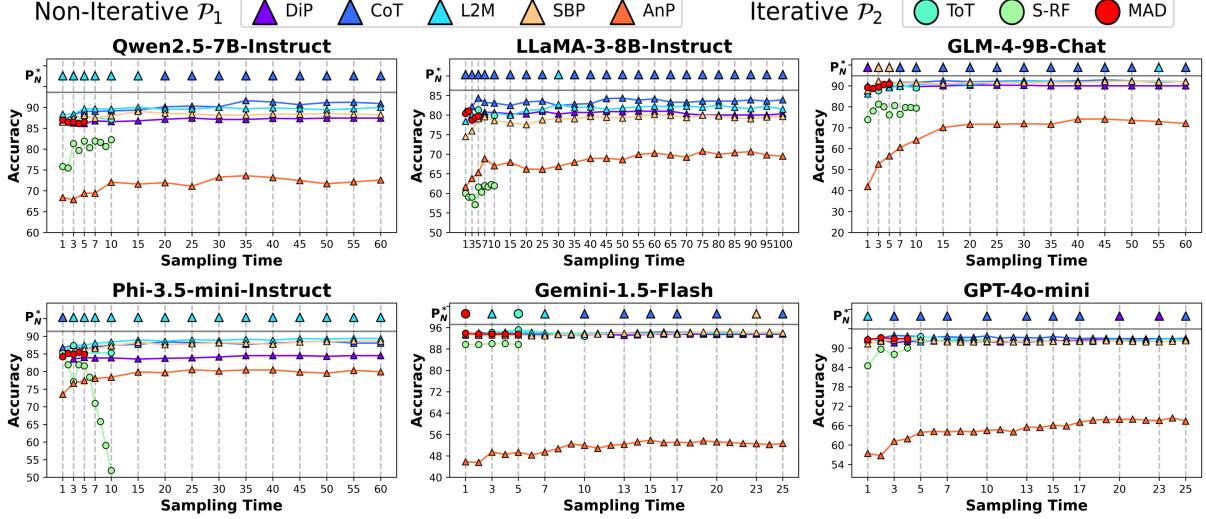


Figure 14: Performance of each prompting strategy under given sampling time N on MMLU.

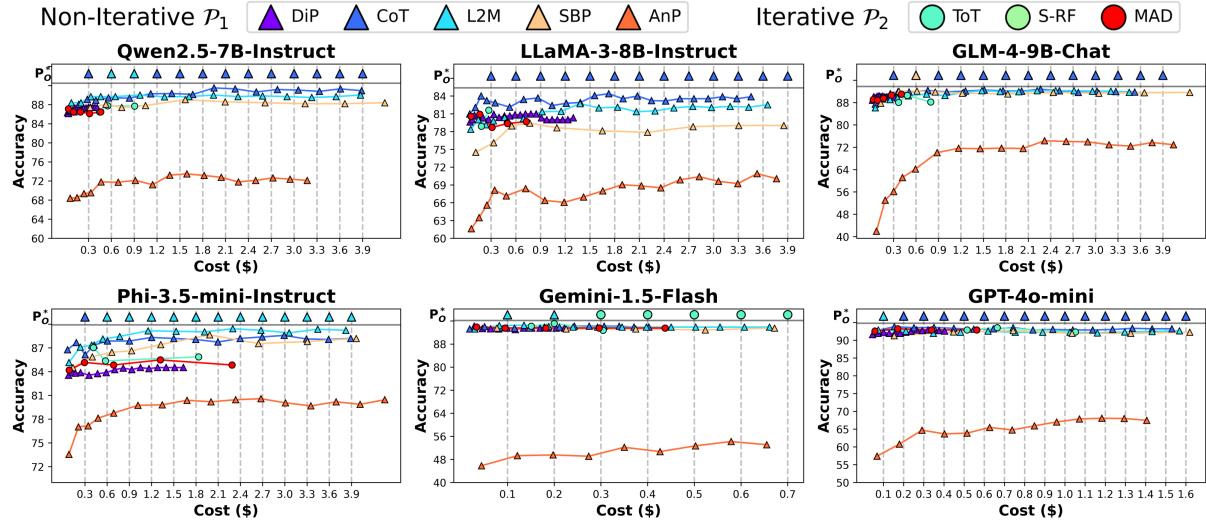


Figure 15: Performance of each prompting strategy under given cost O on MMLU.

mark under given sampling time N and cost O , as shown in Figures 8 to 15. We find that, aside from CoT, DiP also exhibits superior performance compared to other complex prompting strategies on certain models and datasets, *e.g.*, Gemini-1.5-Flash on MATH. This also comes from the two reasons, *i.e.*, DiP has more hard questions and easy questions and a flat probability distribution of wrong answers on the specific dataset. This phenomenon is particularly prominent on powerful LLMs such as Gemini-1.5-Flash on GSM8K and GSM-Hard, where DiP and CoT exhibit comparable performance. Almost 83% of results satisfy that CoT or DiP performs best as significantly scaling. Besides, this trend is also observed on other prompting strategies on few datasets and models. This encourages us to fully unleash the potential of simple prompting strate-

gies, and indicates that the scaling performance does not only depend on the prompting strategies' pass@1 accuracy.

D More Discussions on Improving the Scaling Performance

In this section, we will discuss more about our further exploration on the two ways to improve the scaling performance. We display more results of (1) adaptively scaling based on the question difficulty, (2) dynamically choosing the optimal P_i and (3) combining adaptively scaling and dynamically choosing the optimal P_i in Section D.1, D.2 and D.3, respectively.

D.1 Adaptively Scaling Based on the Difficulty

We use the following prompt to force the LLM to determine if the question is hard for given P_i .

Question:
{question}

Using the method #{method}# to solve the question:
{description}

If the method is more likely to get the right answer, the question is easy. Otherwise, if the method is more likely to get the wrong answer, the question is hard. Please determine the difficulty of the question for the used method, and answer in the following JSON format.

{"Difficulty": "Easy or Hard", "Reason": ""}

Figures 16 to 20 report the results of each prompting strategy when adaptively scaling based on the question difficulty. Our experiment results show that LLMs cannot accurately judge the difficulty of the input question most of the time, thus even leading to reduced performance. Nevertheless, this method is theoretically capable of enhancing the scaling performance, thereby motivating us to explore other approaches to accurately assess the question difficulty.

D.2 Dynamically Choosing the Optimal P_i

Figures 21 to 25 display the results on GSM8K on LLaMA-3-8B-Instruct, GLM-4-9B-Chat, Phi-3.5-mini-Instruct, Gemini-1.5-Flash and GPT-4o-mini, respectively. It can be observed that all LLMs tend to believe that CoT is the best prompting strategy, while CoT does not excel at every question. With oracles to provide the optimal P_i labels, all LLMs demonstrate significant performance improvements, even only with one sampling time, proving the enormous potential of this method. we will explore how to approach this upper bound in the future.

D.3 Combining Adaptively Scaling and Dynamically Choosing the Optimal P_i

Figures 26 to 30 display the results of combining adaptively scaling and dynamically choosing the optimal P_i on GSM8K on LLaMA-3-8B-Instruct, GLM-4-9B-Chat, Phi-3.5-mini-Instruct, Gemini-1.5-Flash, and GPT-4o-mini, respectively. Figures 31 to 36 show the results on each LLM on MATH,

respectively. Extensive experiments demonstrate the general effectiveness and superiority of this method, which has an extremely high upper bound.

E Implementation Details and Prompts

We use vllm (Kwon et al., 2023) to deploy open-sourced LLMs, with top-p = 0.9 and temperature = 0.7. For close-sourced LLMs, we use their APIs with default settings. We set the content safety detection threshold of Gemini-1.5-Flash to zero to prevent erroneous judgments that may result in null outputs.

Following (Wang et al., 2024; Lightman et al., 2024; Qi et al., 2025), we use MATH-500, a subset of representative problems from the MATH dataset to speed up the evaluation. We use the test split of each dataset. The license for all datasets is CC-BY 4.0 or others for open academic research. The number of samples on each dataset is shown in Table 5. We ensure our use of existing artifacts is aligned with their intended purposes. All of them are public English datasets for academic research. On GSM8K and GSM-Hard, we use the same 1-shot prompt in the original paper of Least-to-Most (Zhou et al., 2023) shown in Figure 39 and Figure 40. On other datasets, we use the 0-shot prompt shown in Figure 41. We use the same prompt in Analogous Prompting (Yasunaga et al., 2024), and guide the LLM to recall one analogous problem. We use the same 1-shot prompt in Step-Back Prompting (Zheng et al., 2024) on MMLU, and apply their prompt designed for reasoning tasks on other datasets. We use the same prompt in 0-shot Chain-of-Thought (Kojima et al., 2022), Multi-Agent Debate (Du et al., 2024) and Self-Refine (Huang et al., 2024) on all datasets. The prompts are shown in Figures 37 to 46.

Table 5: The number of samples in each dataset.

Dataset	Samples
GSM8K	1318
GSM-Hard	1318
MATH-500	500
MMLU-Biology	310
MMLU-Chemistry	203
MMLU-Physics	151

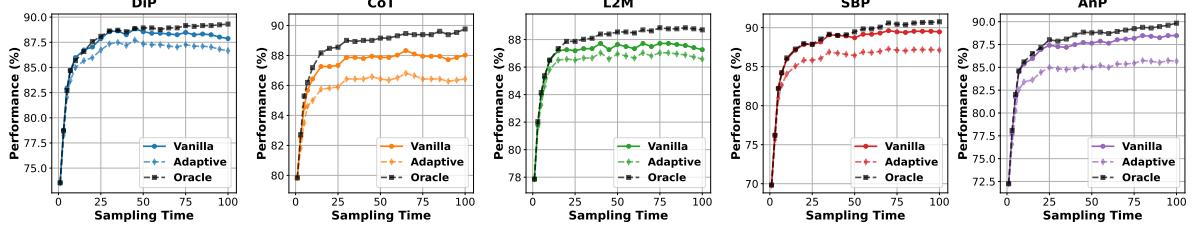


Figure 16: Results of adaptively scaling based on the question difficulty on Llama-3-8B-Instruct on GSM8K.

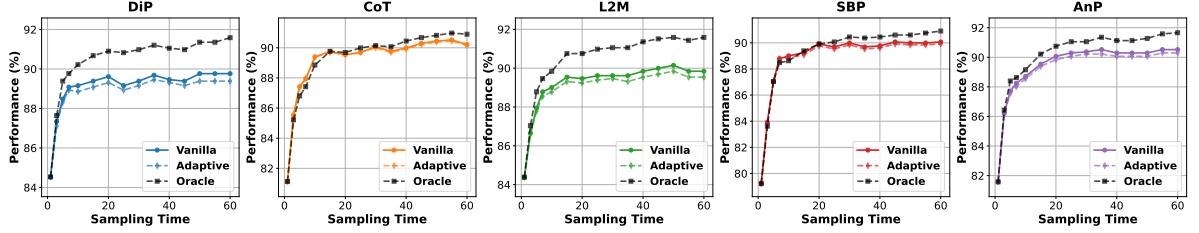


Figure 17: Results of adaptively scaling based on the question difficulty on GLM-4-9B-Chat on GSM8K.

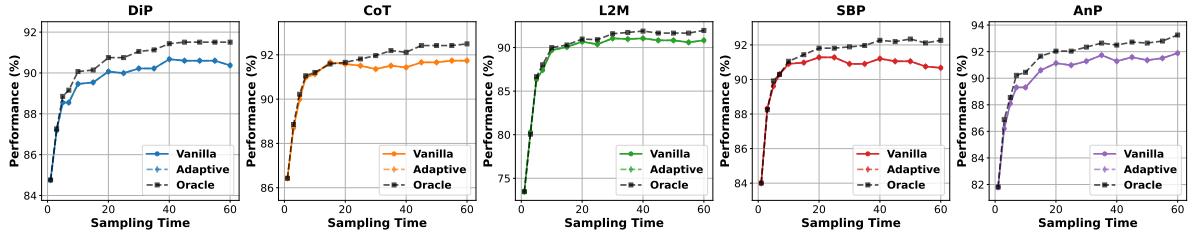


Figure 18: Results of adaptively scaling based on the question difficulty on Phi-3.5-mini-Instruct on GSM8K.

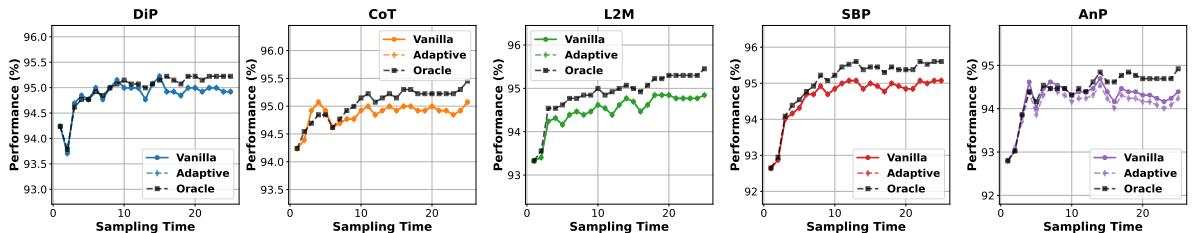


Figure 19: Results of adaptively scaling based on the question difficulty on Gemini-1.5-Flash on GSM8K.

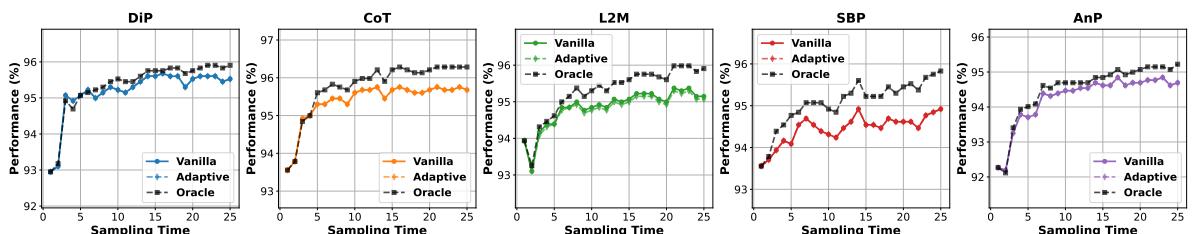


Figure 20: Results of adaptively scaling based on the question difficulty on GPT-4o-mini on GSM8K.

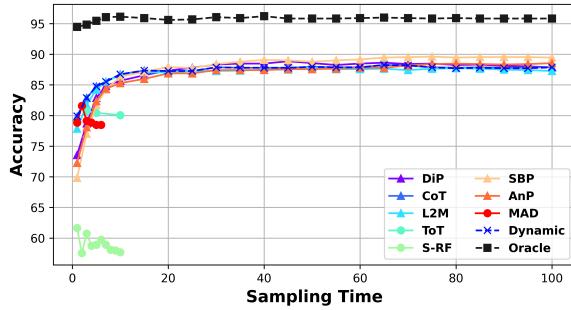


Figure 21: Results of dynamically choosing the optimal P_i on LLaMA-3-8B-Instruct on GSM8K.

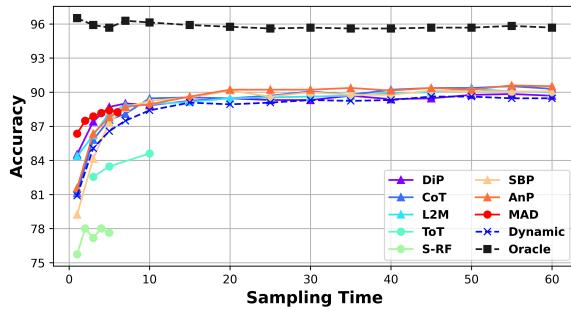


Figure 22: Results of dynamically choosing the optimal P_i on GLM-9B-Chat on GSM8K.

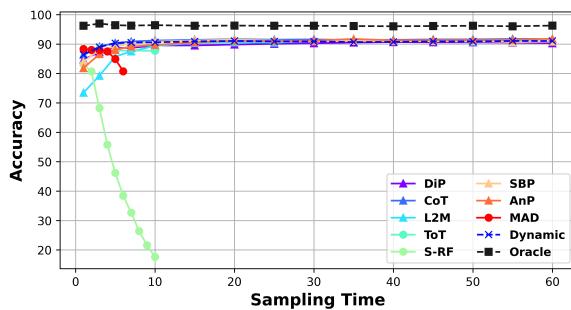


Figure 23: Results of dynamically choosing the optimal P_i on Phi-3.5-mini-Instruct on GSM8K.

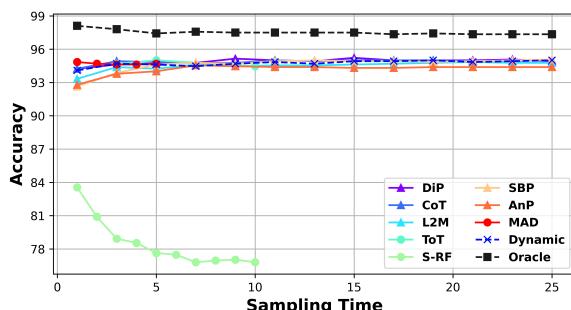


Figure 24: Results of dynamically choosing the optimal P_i on Gemini-1.5-Flash on GSM8K.

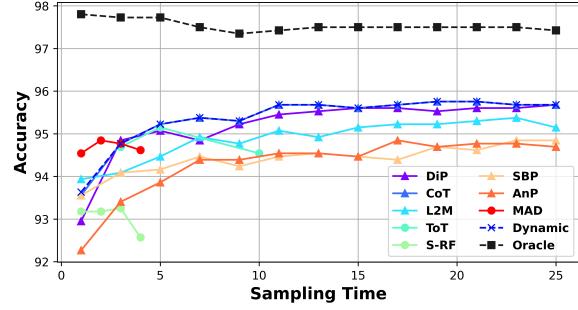


Figure 25: Results of dynamically choosing the optimal P_i on GPT-4o-mini on GSM8K.

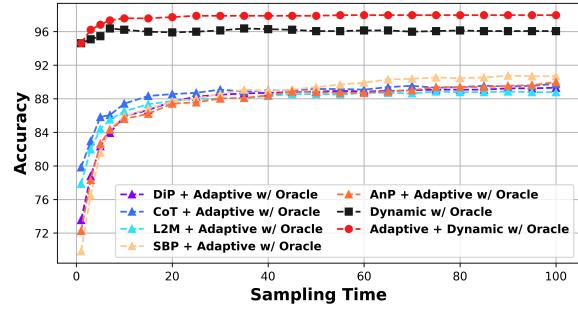


Figure 26: Results of combining adaptively scaling and dynamically choosing the optimal P_i on LLaMA-3-8B-Instruct on GSM8K.

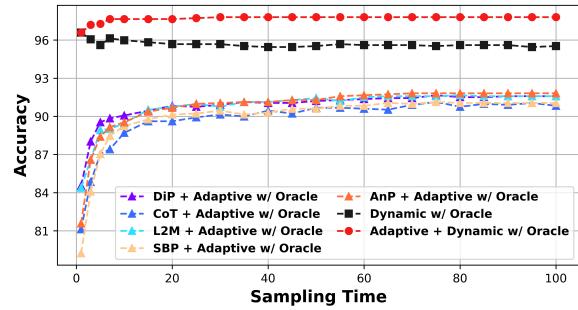


Figure 27: Results of combining adaptively scaling and dynamically choosing the optimal P_i on GLM4-9B-Chat on GSM8K.

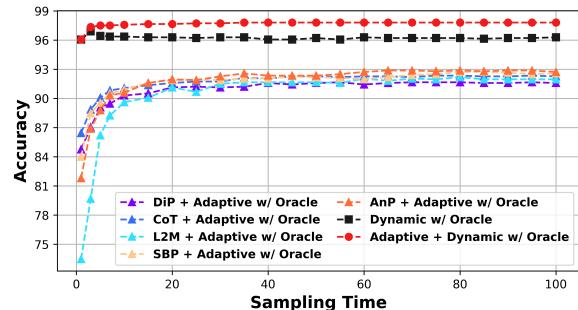


Figure 28: Results of combining adaptively scaling and dynamically choosing the optimal P_i on Phi-3.5-mini-Instruct on GSM8K.

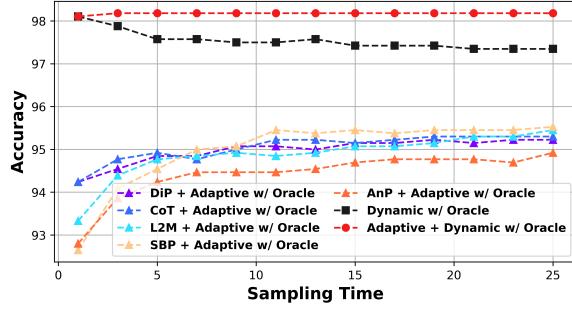


Figure 29: Results of combining adaptively scaling and dynamically choosing the optimal P_i on Gemini-1.5-Flash on GSM8K.

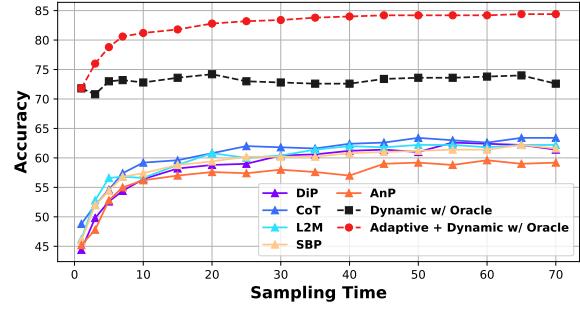


Figure 33: Results of combining adaptively scaling and dynamically choosing the optimal P_i on GLM-4-9B-Instruct on MATH.

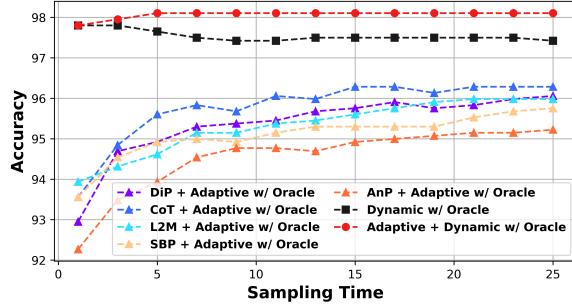


Figure 30: Results of combining adaptively scaling and dynamically choosing the optimal P_i on GPT-4o-mini on GSM8K.

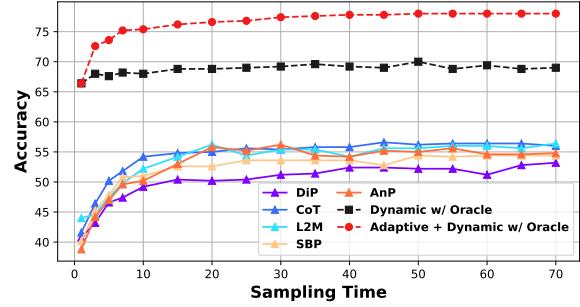


Figure 34: Results of combining adaptively scaling and dynamically choosing the optimal P_i on Phi-3.5-mini-Instruct on MATH.

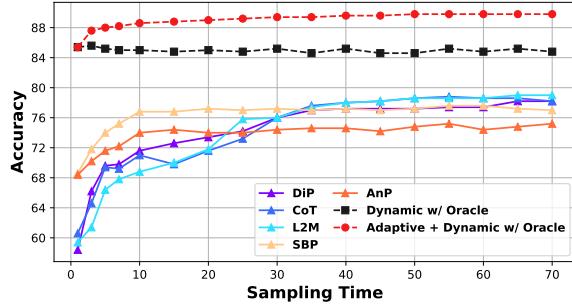


Figure 31: Results of combining adaptively scaling and dynamically choosing the optimal P_i on Qwen2.5-7B-Instruct on MATH.

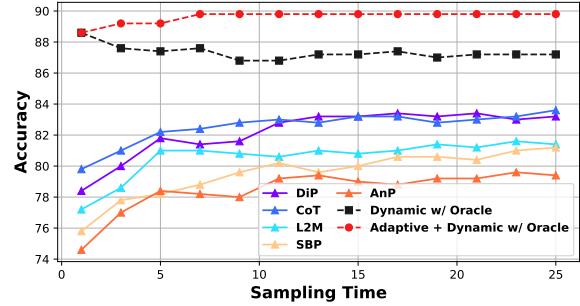


Figure 35: Results of combining adaptively scaling and dynamically choosing the optimal P_i on Gemini-1.5-Flash on MATH.

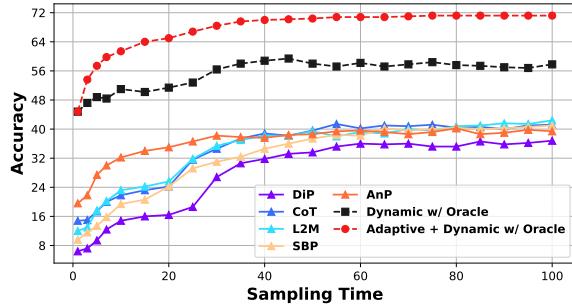


Figure 32: Results of combining adaptively scaling and dynamically choosing the optimal P_i on LLaMA-3-8B-Instruct on MATH.

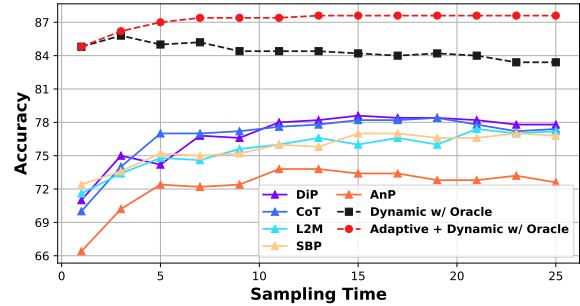


Figure 36: Results of combining adaptively scaling and dynamically choosing the optimal P_i on GPT-4o-mini on MATH.

Direct Prompting

User:

<question>

Assistant:

<answer>

Figure 37: Prompt of DiP.

Chain-of-Thought prompt

User:

Question:

<question>

Answer:

Let's think step by step.

Assistant:

<answer>

Figure 38: Prompt of CoT.

Least-to-Most prompt on GSM8K

User:

Question: Elsa has 5 apples. Anna has 2 more apples than Elsa. How many apples do they have together?

Answer: Let's break down this problem: 1. How many apples does Anna have? 2. How many apples do they have together?

1. Anna has 2 more apples than Elsa. So Anna has $2 + 5 = 7$ apples.

2. Elsa and Anna have $5 + 7 = 12$ apples together.

The answer is: \boxed{12}.

Question:

<question>

Answer:

Assistant:

<answer>

Figure 39: Prompt of L2M on GSM8K.

Least-to-Most prompt on GSM-Hard

User:

Question: Elsa has 524866 apples. Anna has 432343 more apples than Elsa. How many apples do they have together?

Answer: Let's break down this problem: 1. How many apples does Anna have? 2. How many apples do they have together?

1. Anna has 432343 more apples than Elsa. So Anna has $524866 + 432343 = 957209$ apples.

2. Elsa and Anna have $524866 + 957209 = 1482075$ apples together.

The answer is: \boxed{1482075}.

Question:

<question>

Answer:

Assistant:

<answer>

Figure 40: Prompt of L2M on GSM-Hard.

Least-to-Most prompt

User:

In order to solve the question more conveniently and efficiently, break down the question into progressive sub-questions. Answer the sub-questions and get the final result according to sub-questions and their answers.

Question:

<question>

Answer:

Assistant:

<answer>

Figure 41: Prompt of L2M on MATH and MMLU.

Tree-of-Thoughts prompt

User:

Question:

<question>

Answer:

Let's think step by step.

Assistant:

<answer>

User:

Given the question and several solutions, decide which solution is the most promising. Analyze each solution in detail, then conclude in the last line "The index of the best solution is x", where x is the index number of the solution.

<Solution 1>

<Solution 2>

.....

Figure 42: Prompt of ToT.

Self-Refine Prompt

User:

<question>

Assistant:

<previous answer>

User:

Review your previous answer and find problems with your answer.

Assistant:

<feedback>

User:

Based on the problems of your previous answer, improve your answer.

Assistant:

<revised answer>

Figure 43: Prompt of S-RF.

Step-Back Prompting

User:

You are an expert at <subject>. Your task is to extract the mathematics concepts and principles involved in solving the problem.

Question:

<question>

*Principles involved:***Assistant:**

<answer>

User:

You are an expert at <subject>. You are given a <subject> problem and a set of principles involved in solving the problem. Solve the problem step by step by following the principles.

Question:

<question>

Principles:

{principles}

*Answer:***Assistant:**

<answer>

Figure 44: Prompt of SBP.

Analogous Prompting

User:

Your task is to tackle mathematical problems. When presented with a math problem, recall relevant problems as examples. Afterward, proceed to solve the initial problem.

Initial Problem:

{question}

Instructions:

Relevant Problems:

Recall an example of the math problem that is relevant to the initial problem. Your problem should be distinct from the initial problem (e.g., involving different numbers and names). For the example problem:

- After "Q: ", describe the problem.

- After "A: ", explain the solution and enclose the ultimate answer in \boxed{ }.

Solve the Initial Problem:

Q: Copy and paste the initial problem here.

A: Explain the solution and enclose the ultimate answer in \boxed{ } here.

Assistant:

<answer>

Figure 45: Prompt of AnP.

Multi-Agent Debate

User:

<question>

Assistant:

<solving process>

<answer>

User:

These are the answers to the question from other agents:

One agent answer: ...

One agent answer: ...

...

Using the answers from other agents as additional information, can you provide your answer to the question?

<question>

Assistant:

<answer>

User:

...

Assistant:

...

Figure 46: Prompt of MAD.