Beyond parametric uncertainties in direct reactions and fission

A.E. Lovell, LANL
BAND-Nuclear Data Workshop
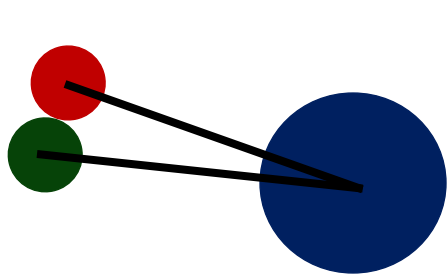
December 18, 2024

LA-UR-24-33200

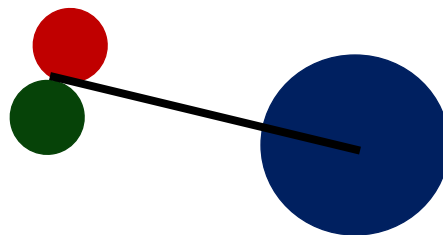# Example 1: few-body approximations, e.g. (d,p)

$$[T_R + H_{\text{int}}(\vec{r}) + V_{pA} + V_{nA} - E]\Psi^{\text{exact}}(\vec{r}, \vec{R}) = 0 \qquad H_{\text{int}} = T_r + V_{np}(r)$$

Adiabatic Wave Approximation (ADWA)

Nucleon-target potentials take into account deuteron break-up

Distorted-Wave Born Approximation (DWBA)
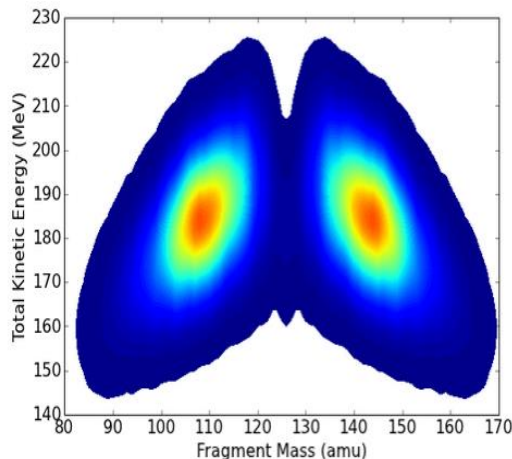
Uses an effective deuteron-target potential

Finite-range, Johnson and Tandy, *Nucl. Phys. A* **235** 56 (1974)

I.J. Thompson and F.M. Nunes, *Nuclear Reactions for Astrophysics*, (Cambridge University Press, Cambridge, 2009)
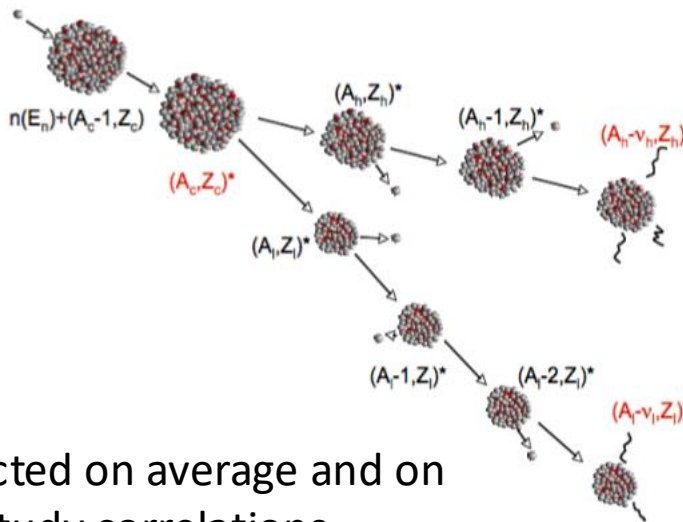
Example 2: event-by-event fission calculations with CGMF
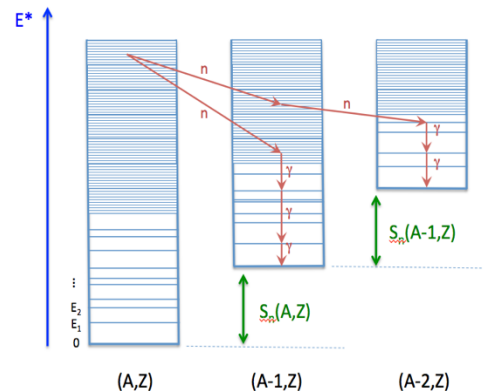
Initial conditions are fragment yields:
Y(A,Z,TKE,J,π)

Hauser-Feshbach statistical theory used to decay excited fission fragments

Neutrons and γ rays are emitted probabilistically

Observables can be constructed on average and on an event-by-event basis to study correlations

P. Talou, et al., *CPC* **269**, 108087 (2021)
Open source: https://github.com/lanl/CGMF

Most theory/model UQ focus has been on parametric uncertainties but there are clearly other sources

Example: neutron energies from CGMF are systematically too low (comparison to Chi-Nu data)
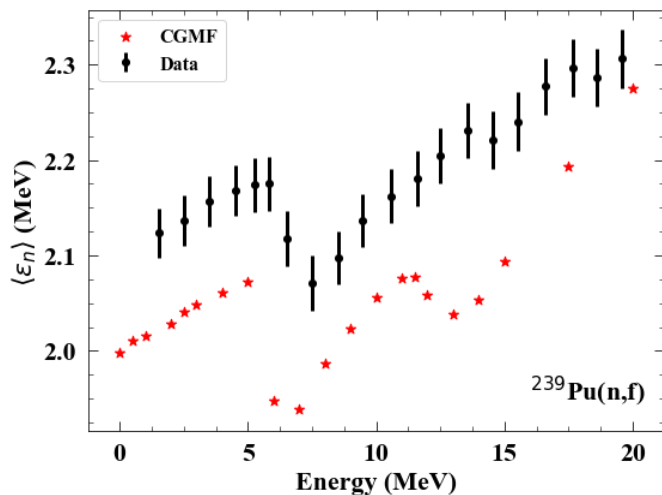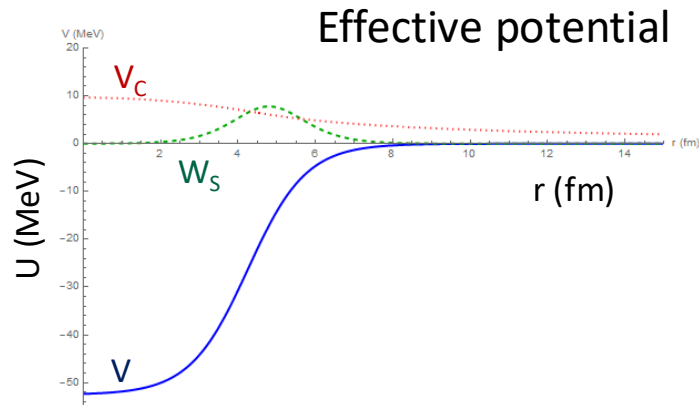

WHY?

- Wrong fission fragment initial conditions?
  - No scission neutrons?
  - Simplified neutron emission?
  - Missing nuclear levels?
  - Incorrect level densities?
  - Other missing physics?

Theory uncertainties largely divide into parametric uncertainties and model uncertainties*
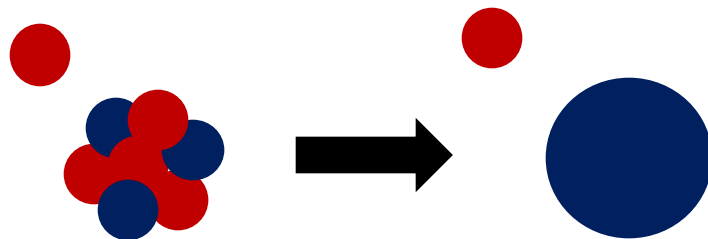
Parametric uncertainties

Effective potential
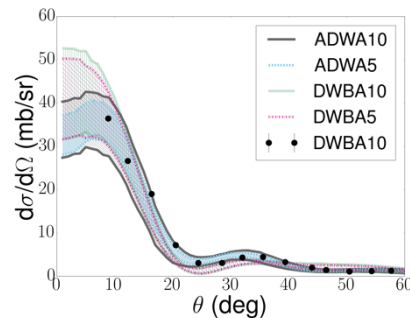

$$f(r; V_o, R_o, a_o) = -\frac{V_o}{1 + e^{(r-R_o)/a_o}}$$

*Plus, numerical uncertainties coming from solving equations, sampling methods, etc.

Model uncertainties

Missing degrees of freedom

Approximations made

A variety of optimization/UQ methods are in use

χ^2 optimization

- χ^2 metric is minimized

$$\chi^2 = \sum_{i=1}^{n} \left(\frac{m(\mathbf{x}; \theta_i) - d_i}{\sigma_i} \right)^2$$

- Uncertainties are calculated by numerically constructing a parameter covariance matrix and sampling from that distribution

$$\mathcal{N}(\hat{\mathbf{x}}, \mathbb{C}_p) = \frac{1}{\sqrt{2\pi |\mathbb{C}_p|}} e^{-\frac{1}{2}(\mathbf{x}-\hat{\mathbf{x}})^T \mathbb{C}_p^{-1}(\mathbf{x}-\hat{\mathbf{x}})}$$

$$s^2 = \frac{1}{n-p} \sum_{i=1}^{n} \left(\frac{m(\mathbf{x}; \theta_i) - d_i}{\sigma_i} \right)^2 \qquad \mathbb{C}_p \rightarrow s^2 \mathbb{C}_p$$

Bayesian optimization[*]

- Posterior distribution numerically sampled through a Markov Chain Monte Carlo

- Prior incorporates information about what is already known

- Likelihood compares data and model (typically through χ^2)

$$P(\mathcal{H}|\mathcal{D}) = \frac{P(\mathcal{D}|\mathcal{H}) P(\mathcal{H})}{P(\mathcal{D})}$$

Different weights for the χ^2 metric   [*]linear approximation to Bayesian update in the Kalman filter

How the optimization is performed is important (method and inputs)

χ^2 (LM) vs Bayesian (MCMC), using a 1/N scaling factor in the likelihood or not (other weighting discussed by Matt)

C.D. Pruitt, A.E. Lovell, C. Hebborn, and F.M. Nunes, *PRC* **110**, 064606 (2024)
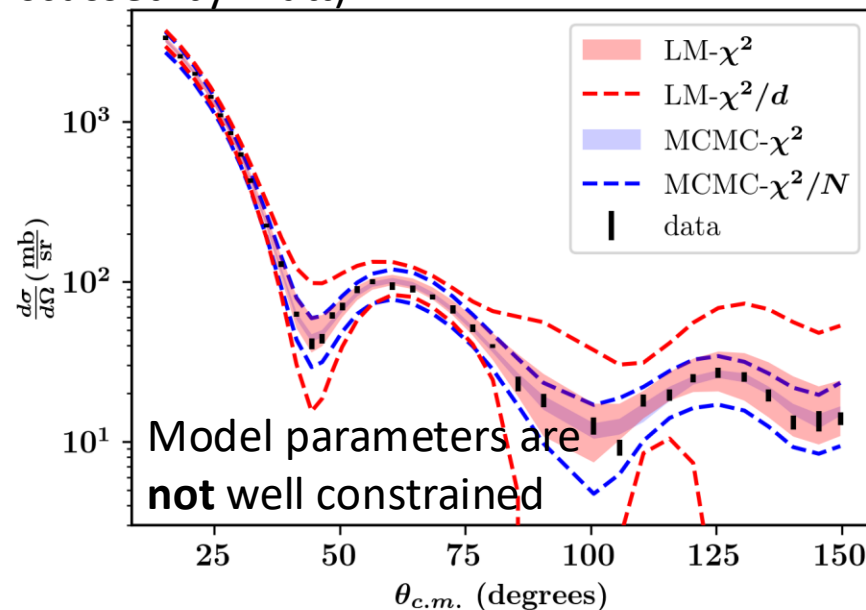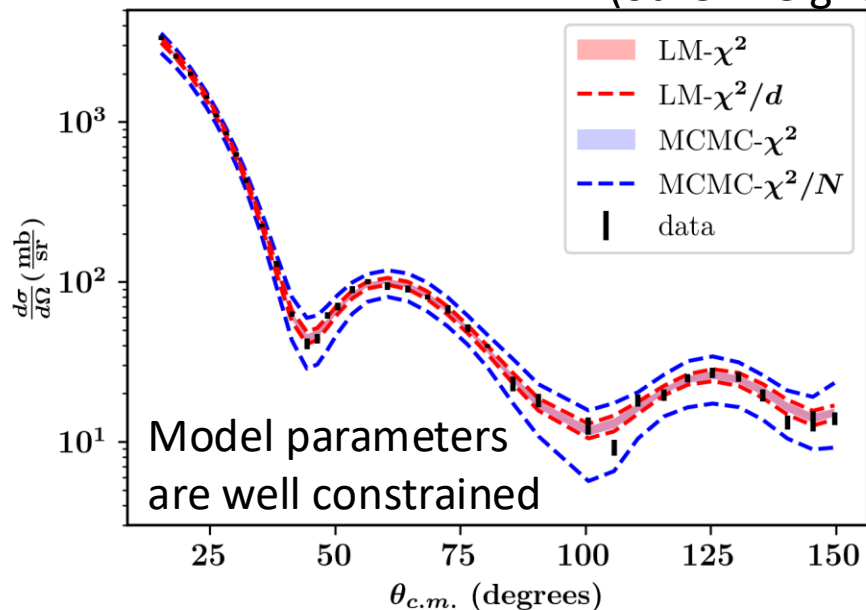
Experimental inputs to the optimization and covariance procedure matter

REGULAR ARTICLE

OPEN ⱥ ACCESS

Templates of expected measurement uncertainties

Denise Neudecker[1,*] [iD], Amanda M. Lewis[2], Eric F. Matthews[3], Jeffrey Vanhoy[4], Robert C. Haight[1], Donald L. Smith[5], Patrick Talou[1], Stephen Croft[6], Allan D. Carlson[7], Bruce Pierson[8], Anton Wallner[9], Ali Al-Adili[10], Lee Bernstein[3,11], Roberto Capote[12], Matthew Devlin[1], Manfred Drosg[13], Dana L. Duke[1], Sean Finch[14,15], Michal W. Herman[1], Keegan J. Kelly[1], Arjan Koning[12], Amy E. Lovell[1], Paola Marini[16,17], Kristina Montoya[1], Gustavo P.A. Nobre[18], Mark Paris[1], Boris Pritychenko[18], Henrik Sjöstrand[10], Lucas Snyder[19], Vladimir Sobes[20], Andreas Solders[10] and Julien Taieb[16,21]
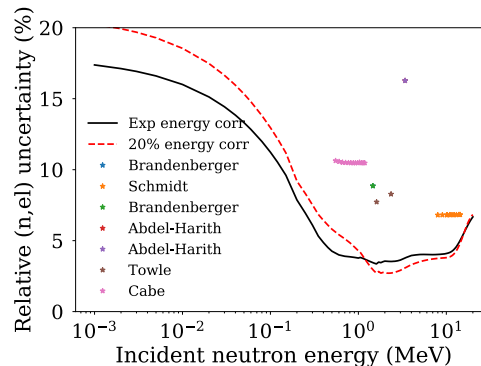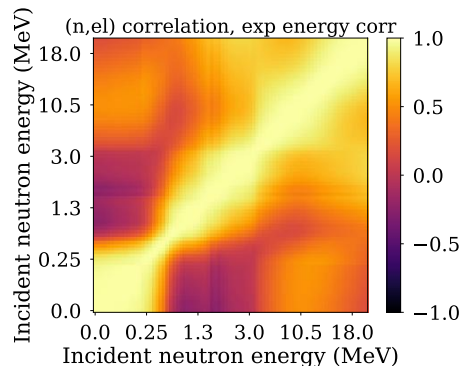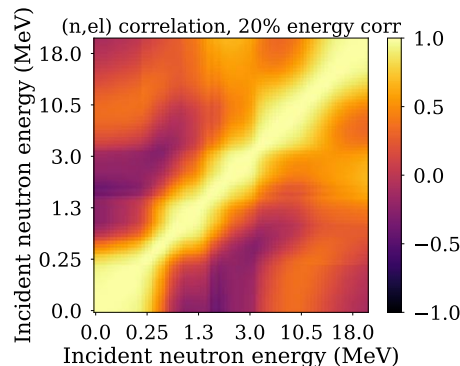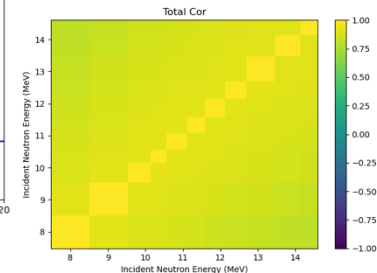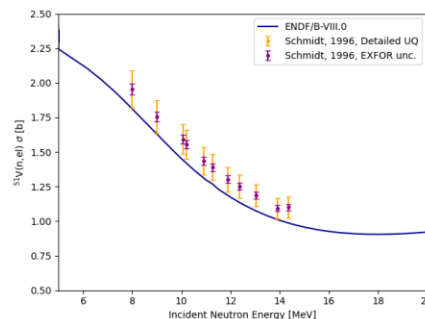
Example of ^{51}V total and elastic cross sections

Denise will discuss more about experimental templates

Work with D. Neudecker and A. Khatiwada (LANL)

Larger sources of uncertainty likely come from model simplifications/missing degrees of freedom

^{90}Zr(d,p)^{91}Zr(g.s) @ 22.7 MeV
χ^2 minimization
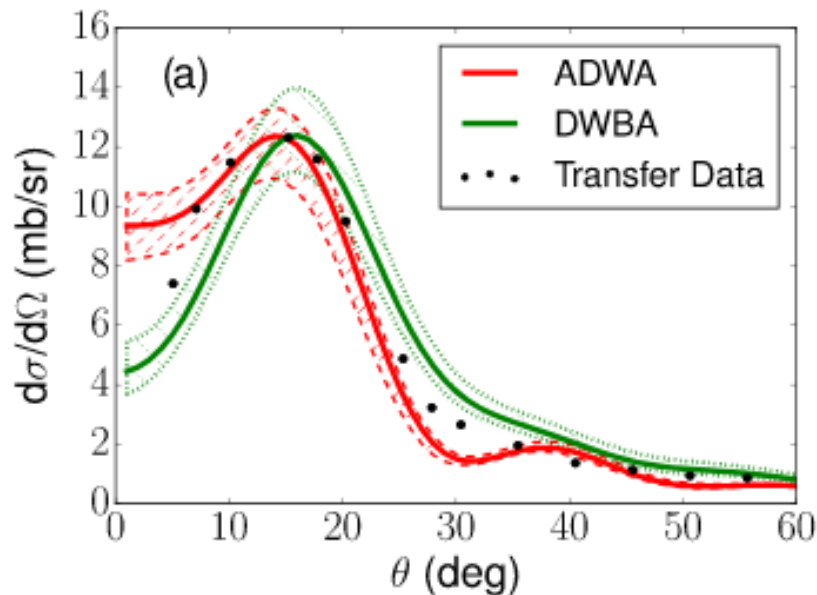
^{90}Zr(d,p)^{91}Zr(g.s) @ 22.0 MeV
Bayesian
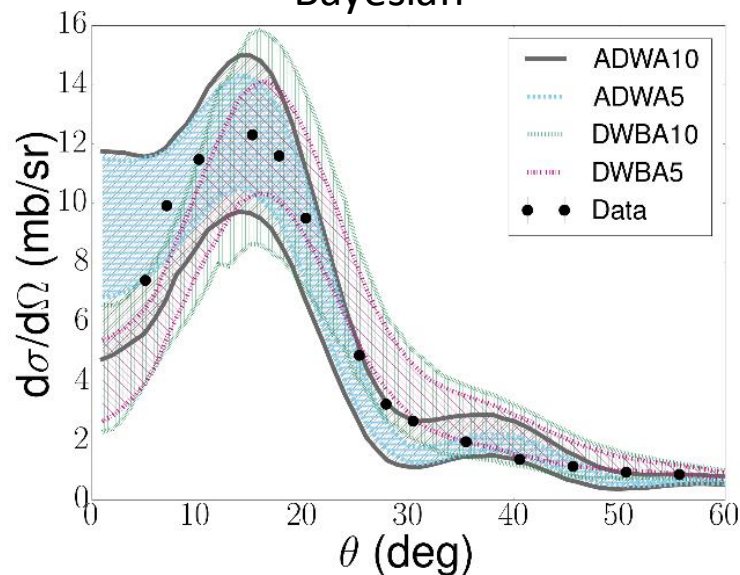
G.B. King, A.E. Lovell, F.M. Nunes,
PRC **98**, 044623 (2018)

A.E. Lovell, MSU/NSCL Thesis (2018)

Larger sources of uncertainty likely come from model simplifications/missing degrees of freedom
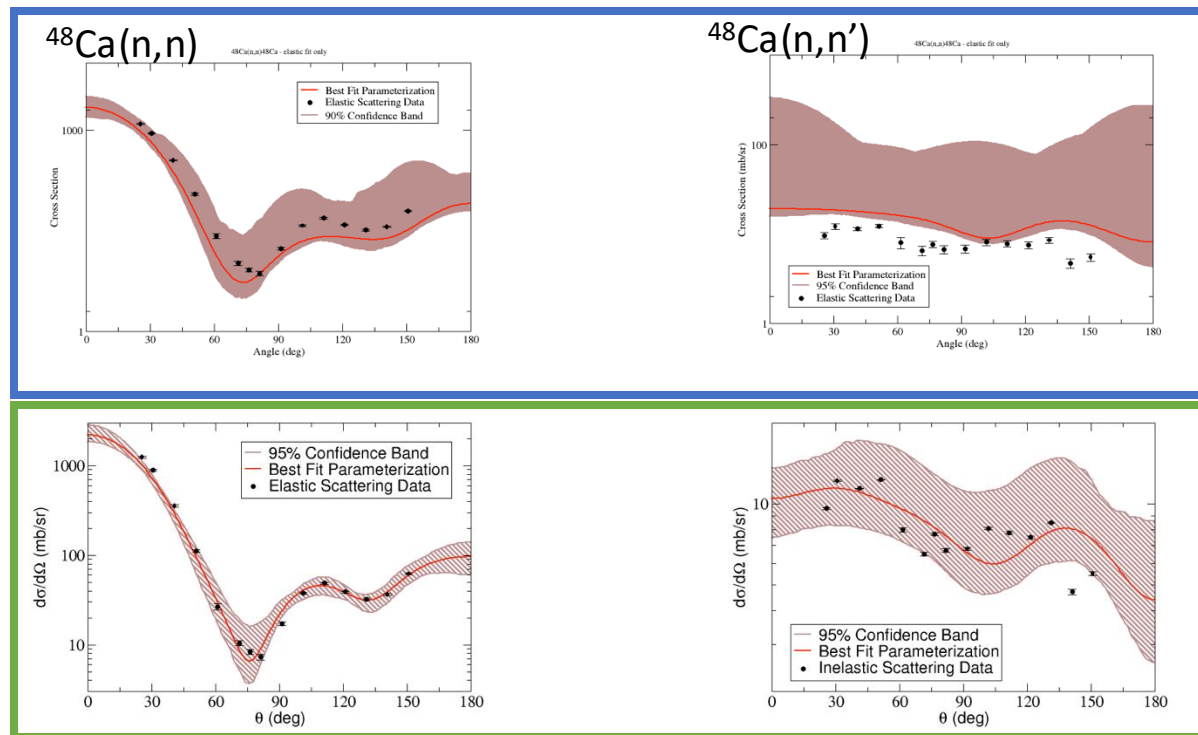
χ^2 minimization

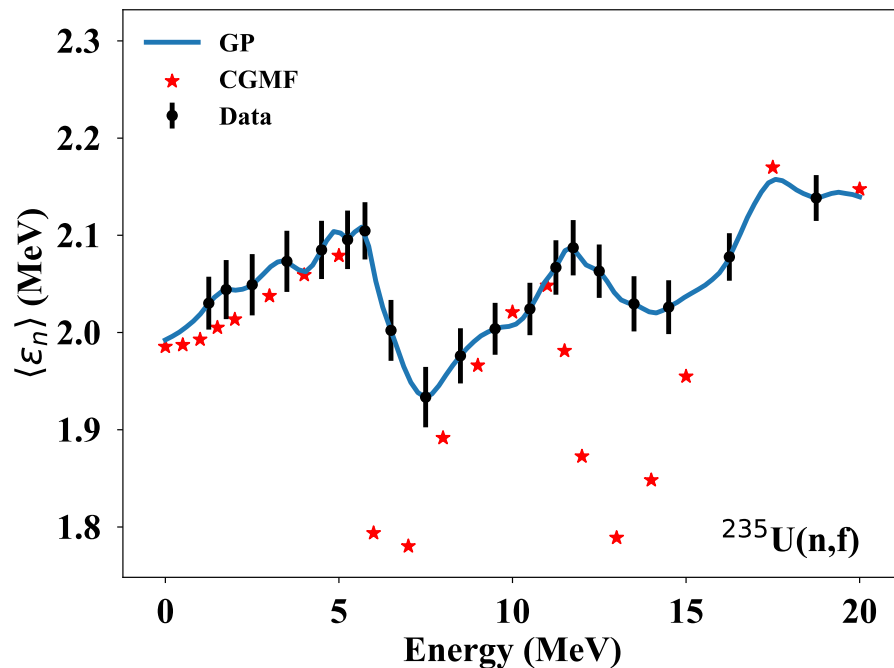Only elastic scattering fitted

Elastic and inelastic fitted with coupled channel calculation

How can we quantify what is missing from our models if we don't have the ground truth from theory?

Gaussian processes (and other methods) can be used to systematically "correct" between theory and experiment

Preliminary GP studies: 2020 XCP Computational Workshop (S. Blade and S. Ozier) emulated the discrepancy between CGMF and experimental data for the average neutron energy (with I. Stetcu and M. Grosskopf)

But can we get enough trends to make predictions? Does this type of correction give us any insight into better modeling or how to include more physics?

Bayesian evidence can give a measure of the impact of different data or models

$$p(\mathcal{D}|\mathcal{M}) = \int_{\Omega_{\mathcal{M}}} p(\mathcal{D}|\alpha, \mathcal{M})p(\alpha|\mathcal{M})d\alpha_{\mathcal{M}}$$

TABLE I. Bayesian evidence (multiplied by 10^{-3}) for the surface model (second row) and the volume model (third row) for both beam energies considered (first row). The ratio between the Bayesian evidence of the volume model over that with the surface model is in the fourth row (the Bayes' factor).
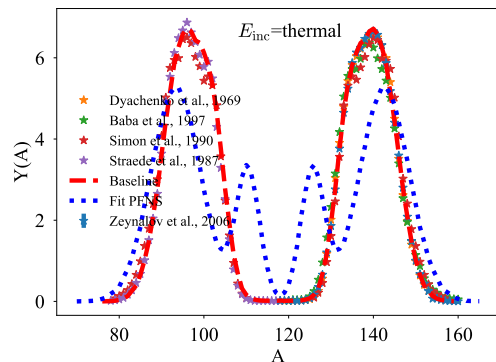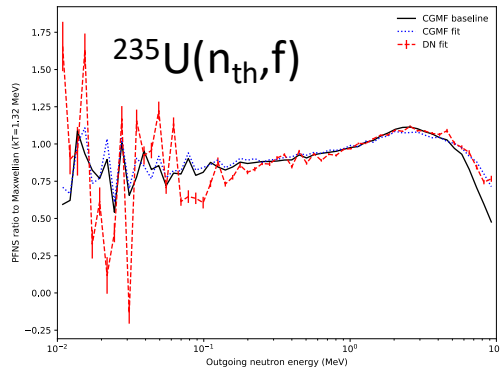
Energy	9 MeV	65 MeV
Evidence (surface)	1.06	0.02
Evidence (volume)	0.65	0.13
Bayes' factor	0.6	6.9

Here, we looked at the difference between the imaginary surface and volume terms in the optical potential for two scattering energies, where volume OR surface absorption should dominate
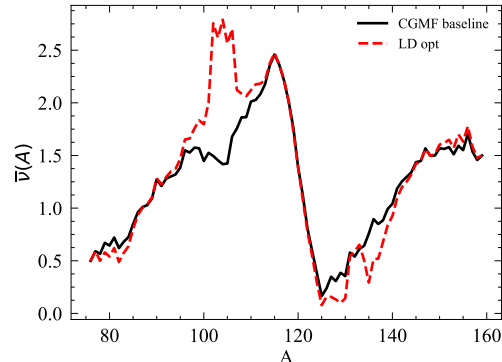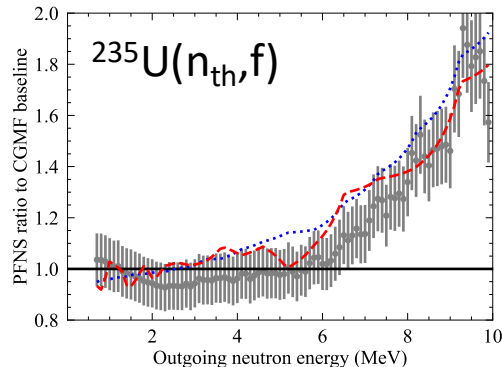The differences in Bayesian evidence reflects those model differences

WARNING: Parameters can try to compensate for model deficiencies

Mass distributions

^{235}U(n$_{th}$,f)

E_{inc}=thermal

Lovell and Neudecker, LA-UR-21-30882

Level densities

^{235}U(n$_{th}$,f)

Lovell, 20220532ECR

Discrete levels

^{235}U(n,f)
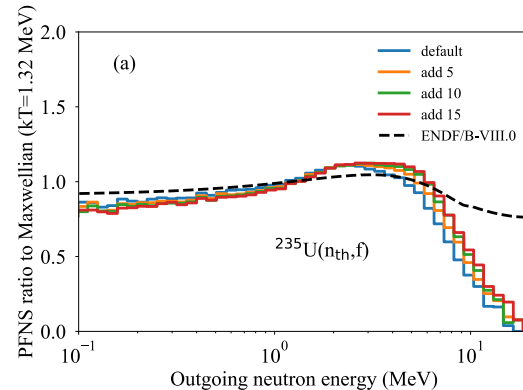
Discrete nuclear levels have not been measured for all of the neutron-rich nuclei that are produced by fission; we can use some model to include more

Conclusions and outlook

- Uncertainty quantification is important for a variety of applications and basic science

- Most UQ focus has been on parametric uncertainties, but these are only part of the total model uncertainty, which should be taken into account

- Quantifying model uncertainties is hard, especially when missing physics might not be easily described or a simplified model is not a subset of a more accurate model

- Tools are being developed to begin to investigate some of these challenges

- Model uncertainty should not be ignored just because it's difficult

Acknowledgements

- F.M. Nunes, M. Catacora-Rios, C. Hebborn (MSU/FRIB)

- S.M. Wild, J. Sarich (formerly ANL)

- G.B. King (LANL, formerly WUStL, MSU)

- C.D. Pruitt (LLNL)

- I. Stetcu, P. Talou, T. Kawano, M.R. Mumpower, D. Neudecker, A. Khatiwada, K.J. Kelly, M. Grosskopf (LANL)

- S. Blade, S. Ozier (LANL XCP Computational Workshop 2020)

Thank you!

Questions?