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Templates of expected measurement uncertainties and machine learning to understand unknown sources of discrepancies

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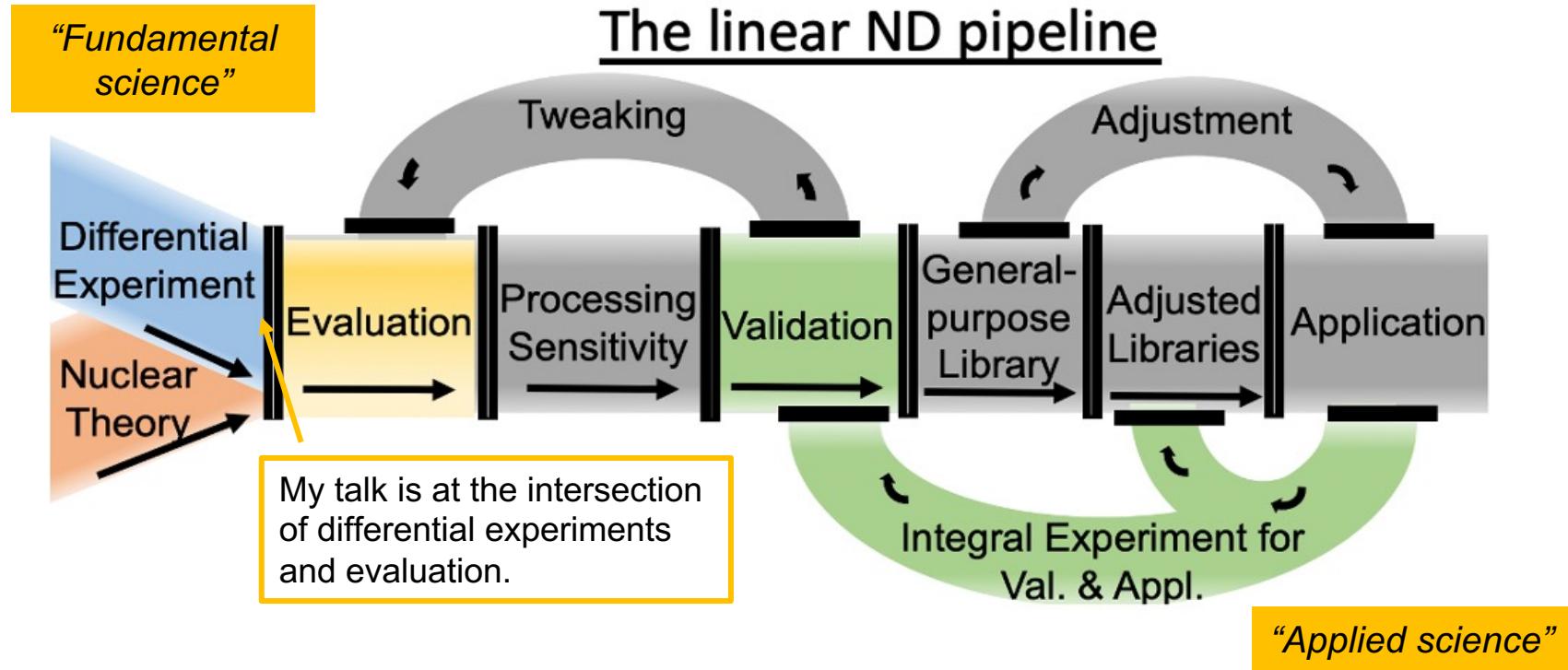
¹LANL, ²BNL, ³NIST, ⁴UTK

BAND Nuclear Data Workshop

Dec. 18, 24

LA-UR-24-

Experimental uncertainty quantification: key piece of creating nuclear data that connect “fundamental” to “applied” science.



EXFOR (<https://www-nds.iaea.org/exfor/exfor.htm>) gives easy access to experimental data for nuclear data evaluations.

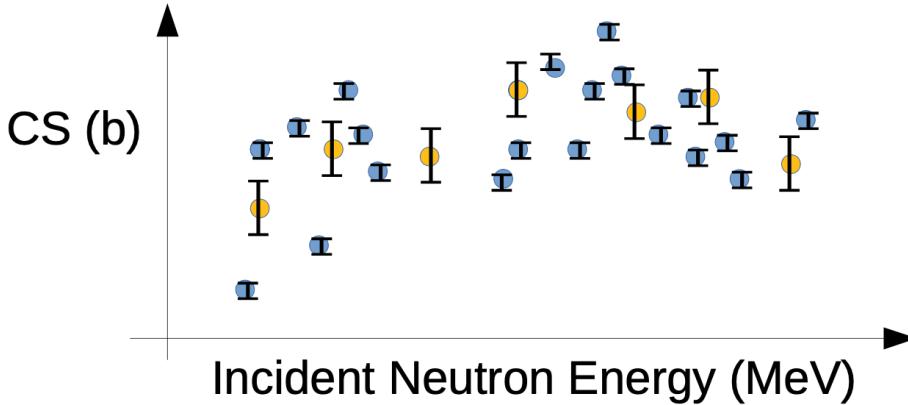
The screenshot shows the EXFOR database search interface. At the top, there's a navigation bar with links like Help, Manual, Lexfor, Output, Plot+, R33, Databases, ENDF, CINDA, IBANDL, EEView, Download, X4Lite, X4Pro, X5Json, Catalog, and Web-API. On the left, there's a sidebar with sections for Request (Target, Reaction, Quantity, Product, Energy range, Author(s), Publication year, Last modified, Accession #), Options (checkboxes for superseded data, reaction combinations, enhanced search, etc.), and Extended, Keywords, Expert, Evaluator tools. The main content area displays the title "Experimental Nuclear Reaction Data (EXFOR) Database Version of 2024-10-30" and a brief description of the library's scope. A yellow callout box in the bottom right corner contains the text: "EXFOR is great, but do NOT blindly adopt experimental data!"

- Note:**
- all criteria are optional (selected by checking)
 - selected criteria are combined for search with logical AND
 - criteria separated in a field by ";" are combined with logical OR
 - criteria starting with "^" will be used as logical NOT
 - wildcards (*) and intervals (..) are available



BUT, one cannot adopt data blindly from EXFOR. One needs to:

- Retrieve data from EXFOR, renormalize data to the newest standard & plot.
- Remove clear outliers from experimental database.
- Review literature and EXFOR entries of each data set.
- Undertake detailed uncertainty quantification ***for each dataset in the database*** using EXFOR data, literature review & templates.
- Critically assess database & study physics causes of discrepancies.



■ Data set with complete UQ
■ Data set with incomplete UQ

We are talking about this here!



BUT, one cannot adopt data blindly from EXFOR. One needs to:

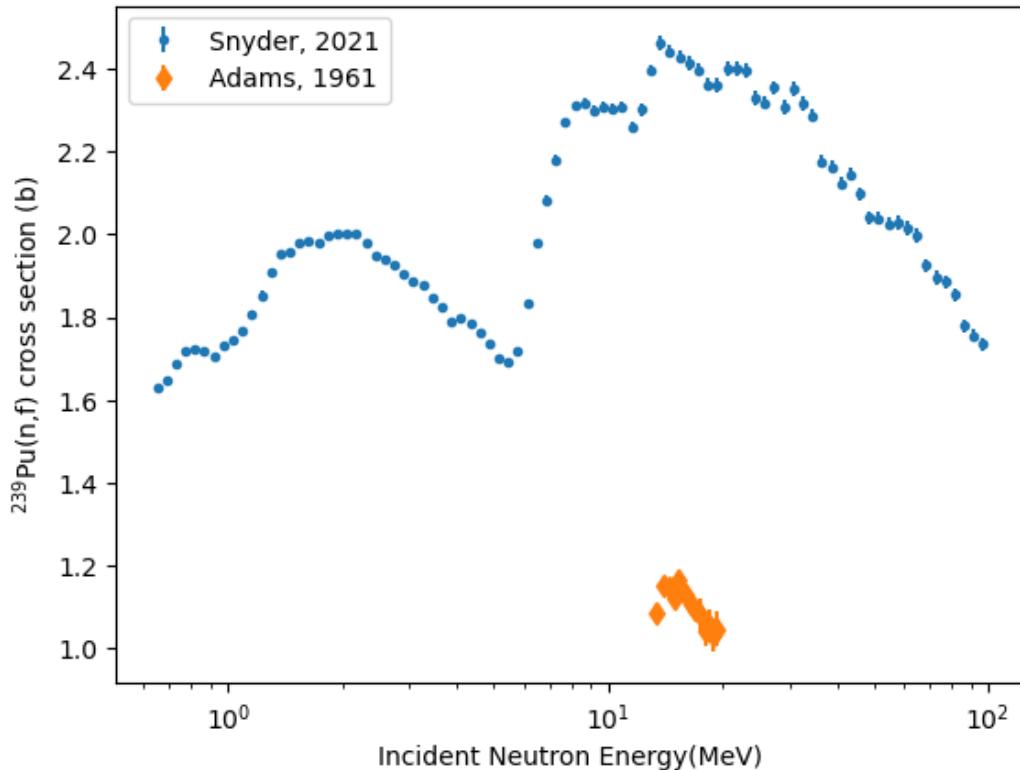
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CS (b)

If one skips these steps, evaluated mean values and uncertainties can be biased impacting in turn application simulations and their bounds!



Example: data of Adams and Snyder read blindly from EXFOR are clearly discrepant!

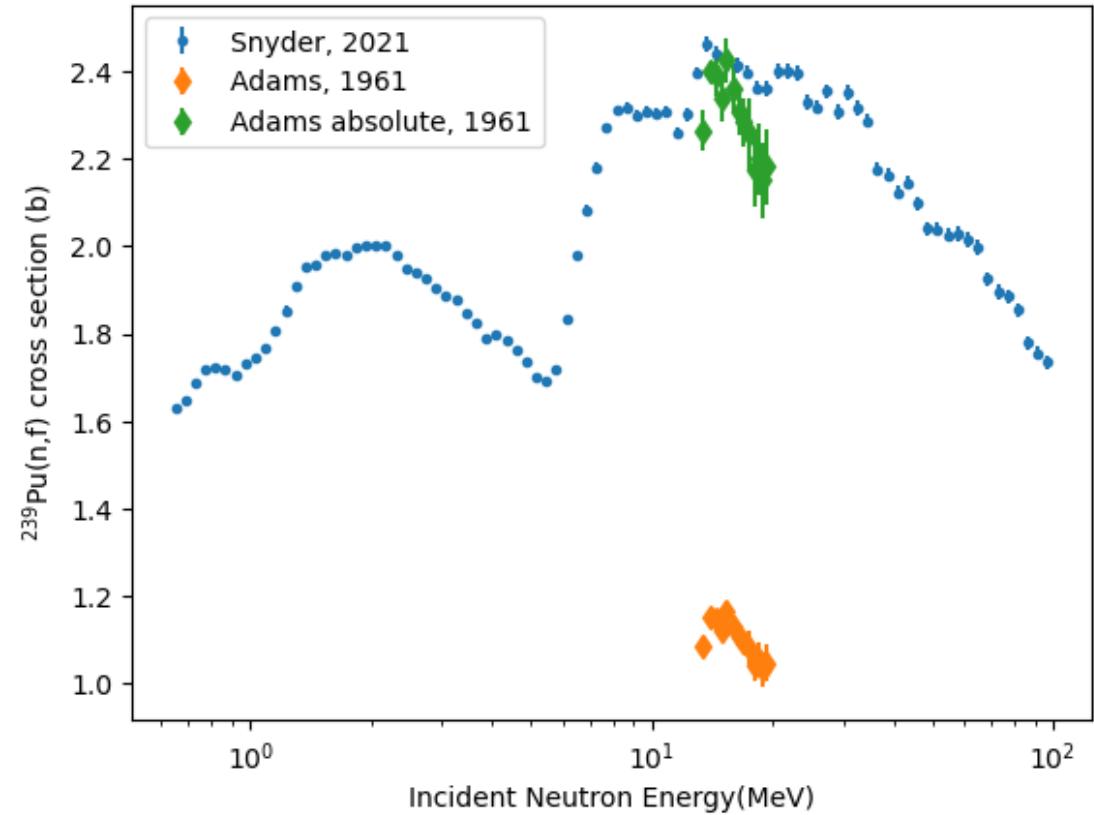


Adams data are shape data and need re-normalization, but only clear if you read the EXFOR entry in detail:

“REACTION 1((94-PU-
239(N,F),,SIG,,REL)/(92-U-
238(N,F),,SIG,,REL))
Normalized to unity at 14 MeV.”

Accession #: 21209004 (Adams)
14721002 (Snyder)

Solution: Adams data are shape data. Ratio data are set to 1.0 at 14.0 MeV. Re-normalize to current evaluation.



- Renormalizing ratio data with factor $2.4/1.151$ as this aligns the cross section with the VIII.1 $^{239}\text{Pu}(n,f)$ cs.
- We still see distinct discrepancies.
- Maybe, some uncertainties are missing?

Templates of expected measurement uncertainties



Templates of expected measurement uncertainties can help complete uncertainties for curated database.

Templates:

- Document what experiment information and uncertainty sources are needed for evaluators to make most use of experimental data stored in EXFOR.
- Provide stand-in values for uncertainty sources that are not provided by experimenters.

Template's benefit:

- Evaluators can make **more informed choices to fill in missing uncertainty** and correlation information.
- Leads to a **more balanced uncertainty quantification across different data sets.**

Applying templates for UQ leads to more realistic evaluated uncertainties for nuclear data libraries.



Where are templates documented?

| | |
|--|--|
| General introduction | D. Neudecker et al., EPJ N 9, 35 (2023) , https://doi.org/10.1051/epjn/2023014 |
| Fission cross section | D. Neudecker et al., NDS 163, 228 (2020), https://doi.org/10.1016/j.nds.2019.12.005 |
| Total cross section | A. Lewis et al., EPJ N 9, 34 (2023) , https://doi.org/10.1051/epjn/2023018 |
| Capture and charged particle cross section | A. Lewis et al., EPJ N 9, 33 (2023) , https://doi.org/10.1051/epjn/2023015 |
| Scattering cross section | J. Vanhoy et al., EPJ N 9, 31 (2023) , https://doi.org/10.1051/epjn/2023019 |
| Neutron multiplicity | D. Neudecker et al., EPJ N 9, 30 (2023) , https://doi.org/10.1051/epjn/2023016 |
| Prompt fission neutron spectrum | D. Neudecker et al., EPJ N 9, 32 (2023) , https://doi.org/10.1051/epjn/2023013 |
| Fission yields | E. Matthews, <i>Advancements in the nuclear data of fission yields</i> , PhD thesis, Department of Nucl. Engineering, University of California, Berkeley, USA, 2021. |



The example here shows the (n,f) cross section template.

| | |
|--|--|
| General introduction | D. Neudecker et al., EPJ N 9, 35 (2023) , https://doi.org/10.1051/epjn/2023014 |
| Fission cross section | D. Neudecker et al., NDS 163, 228 (2020), https://doi.org/10.1016/j.nds.2019.12.005 |
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And here is the template:

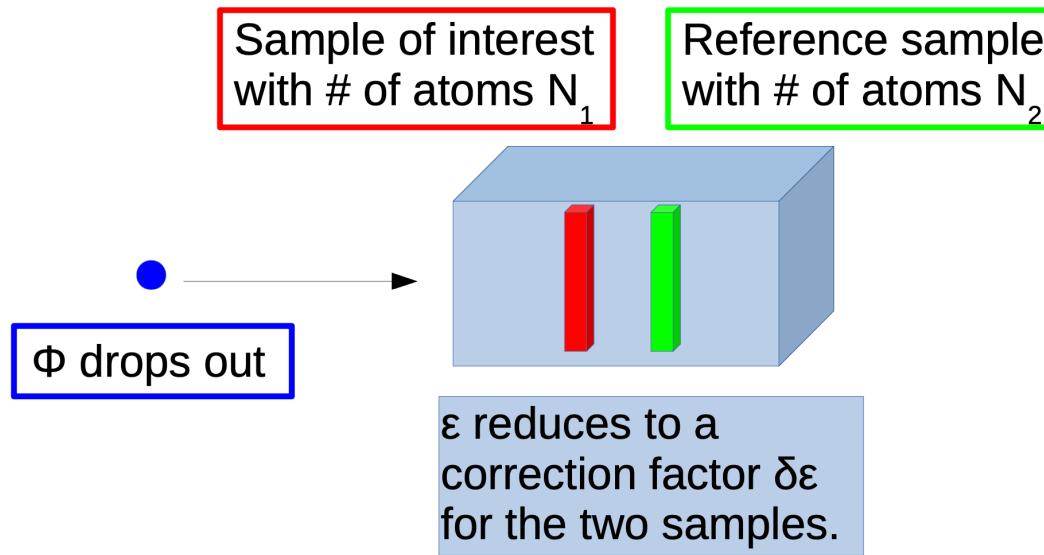
Table 2: Typical uncertainty sources encountered in (n,f) measurements that involve detecting fission fragments are listed dependent on their specific measurement type. The amendments from the preliminary version of the template in Ref. [9] are highlighted in red.

| | Unc. source | Absolute | Absolute clean ratio | Absolute indirect ratio |
|---------------------|--|-------------------------|-------------------------|-------------------------|
| Normalization | $\delta N_{(a/b\&c)}$ | See Table 1 | Both samples | Both samples |
| Counting | δc | Eqs. (3) and (5) | Both, combined | Both, combined |
| Statistics | $\delta\beta$ & δm ; δm | 0.2–2% | 0.02–0.2% | 0.2–2% |
| Multiple scattering | $\delta\beta$ & δm ; $\delta\beta$ | 0.2–1% | Less than absolute | 0.2–1% |
| Efficiency | $\delta\varepsilon$ & $\delta\alpha$; $\delta\varepsilon$ | 1.1–4% | 0.3–4% | 1.1–4%, 0.5–1% |
| Background | $\delta\varepsilon$ & $\delta\alpha$; $\delta\alpha$ | Compare to nuclear data | Compare to nuclear data | Compare to nuclear data |
| Energy | δb | 0.2–>10% | 0.2–>10% | 0.2–>10% |
| Flux | δE | 1%, 1–3 ns | Combined | Both detectors |
| Impurity | $\delta\phi$ | >1% | Cancels or small | Cancels or small |
| Deadtime | $\delta\zeta$ | See Table 3 | See Table 3 | See Table 3 |
| | δd | >0.1% | Both combined | Both detectors |

The example covers
this measurement type.



In clean ratio measurement, the (n,f) cs are measured relative to a reference cross section with the same detector.



$$\sigma(E) = \sigma_R^{ND}(E) \frac{C_1(E) N_2}{C_2(E) N_1} \delta\epsilon(E) \zeta(E)$$

The nuclear data of the reference data σ_R^{ND} is needed to get σ .



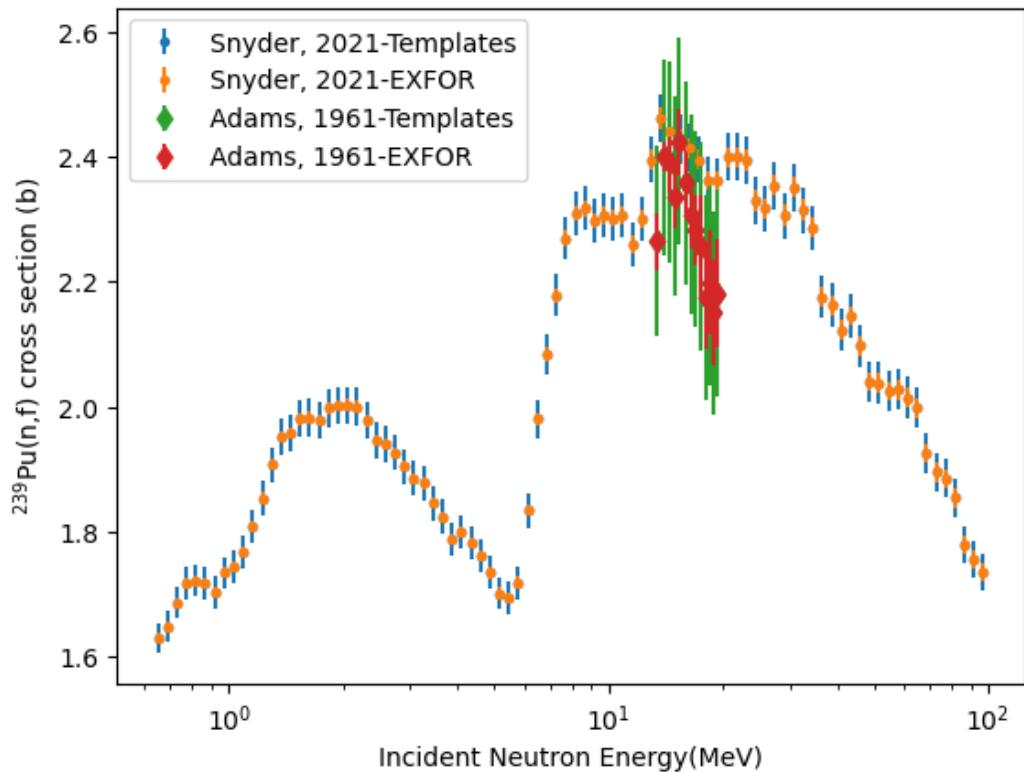
Our example: Adams misses a lot of uncertainty sources in EXFOR, Snyder only one (that is in another article).

| | Unc. source | Absolute | Absolute clean ratio | Adams | Snyder |
|---------------------|--|-------------------------|------------------------------|-------|--------|
| Normalization | $\delta N_{(a/b\&c)}$ | See Table 1 | Both samples | N/A | ✗ |
| Counting Statistics | δc | Eqs. (3) and (5) | Both, combined 0.02–0.2% | ✓ | ✓ |
| Multiple scattering | $\delta\beta$ & δm ; δm | 0.2–2% | Less than absolute 0.3–4% | ✗ | ✓ |
| Efficiency | $\delta\beta$ & δm ; β | 0.2–1% | Compare to nuclear data | ✗ | ✓ |
| Background | $\delta\varepsilon$ & $\delta\alpha$; $\delta\varepsilon$ | 1.1–4% | 0.2–>10% | ✗ | ✓ |
| Energy | $\delta\varepsilon$ & $\delta\alpha$; α | Compare to nuclear data | Combined | ✗ | ✓ |
| Flux | δb | 0.2–>10% | Cancels or small | ✗ | ✓ |
| Impurity | δE | 1%, 1–3 ns | See Table 3 | N/A | ✓ |
| Deadtime | $\delta\phi$ | >1% | See Table 3 | ✗ | ✓ |
| | $\delta\zeta$ | See Table 3 | Both combined | ✗ | ✓ |
| | δd | >0.1% | | | |

Missing uncertainties can be added via templates of uncertainties.



Adding template uncertainties results in data with overlapping uncertainties ...



A word of caution:
While the uncertainties now overlap, I would still think twice before accepting Adams' data.

→ Templates help only report known systematic unc. Here, we need to explore physics root causes of experimental discrepancies.

Using ML to understand what are physics root causes of discrepancies between experimental datasets



We are applying machine learning to accelerate progress in understanding physics underlying nuclear data.

The big questions we are after:

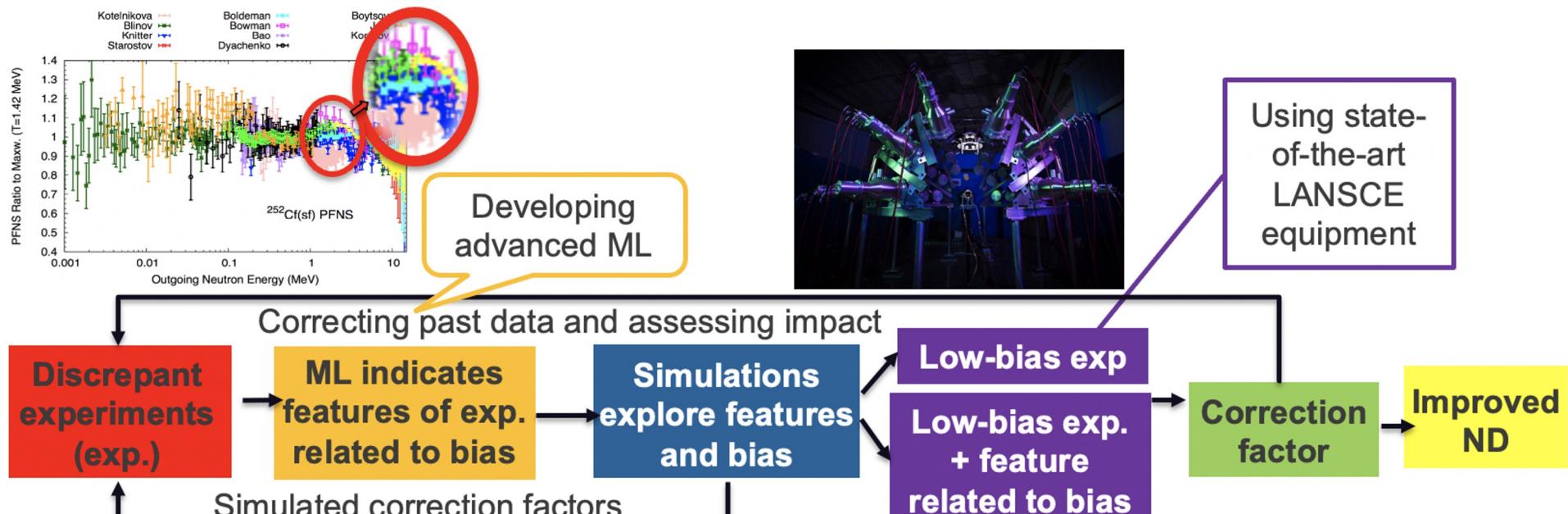
- What is the physical root cause for experimental discrepancies (despite complete experimental UQ)?
- What experiment can we perform to reduce scatter in experimental database?

Benefit of answering questions:

- More targeted experiments reducing spread in an experimental data. This accelerates progress in understanding fission physics.
- Reduced uncertainties and better means for nuclear data that in turns lead to more reliable application simulation and better model fitting.



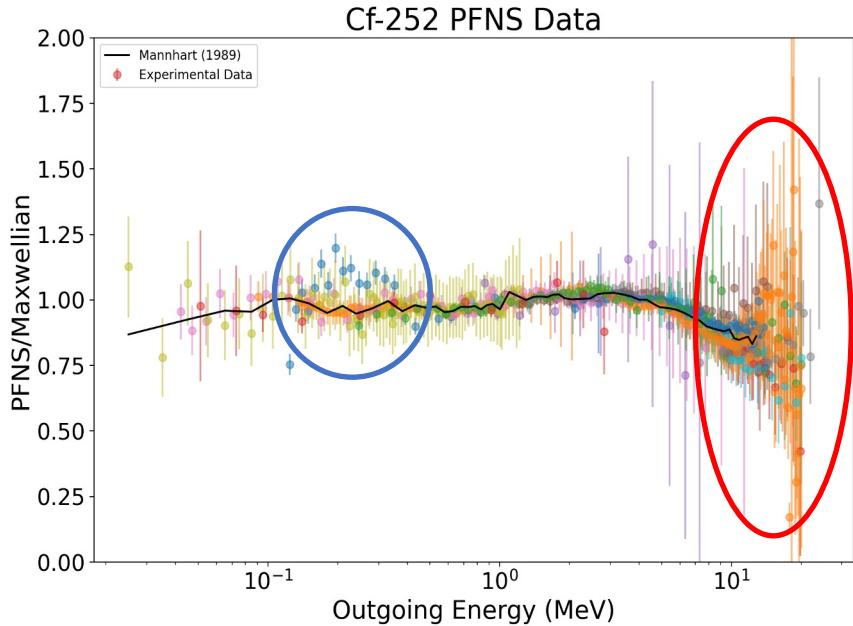
AIACHNE created a ML capability to explore discrepancies in past $^{252}\text{Cf(sf)}$ PFNS exp. & measures new data.



To that end, we used a ML capability to pin-point measurement features likely related to bias and choose most impactful experiments based on MCNP studies.



The problem at hand: Experimental ^{252}Cf PFNS have a wide systematic scatter of data at low and high energies AFTER DETAILED EXPERIMENTAL UQ WITH TEMPLATES.



Discrepancies at low E_{out} understood:

caused by incorrect resolution of ${}^6\text{Li}$ resonance for detector response.

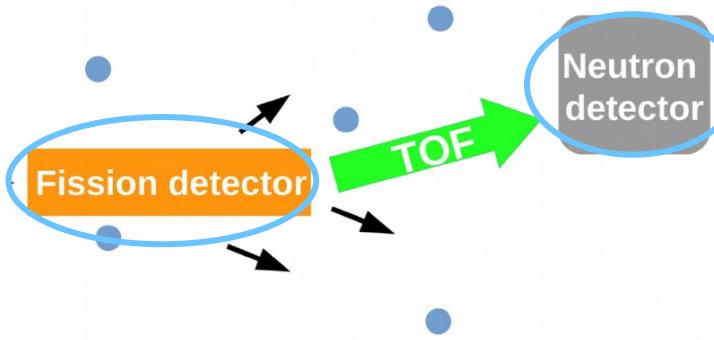
Discrepancies at high E_{out} not understood:

- Background?
- Time resolution?
- Fission fragment issues?
- Neutron detector response?



Root cause of discrepancies must be tied to set-up issue or analysis technique encoded in measurement features.

Here, we analyze features related to neutron and fission detectors.



| | Correction Features | Hardware Features | Method Features |
|----|--|-------------------------------------|---------------------------------------|
| 0 | ShadowBarBackground | FissionDetector1_raw | RandomCoincidence |
| 1 | BackgroundCorrected | FissionDetector1_caseA | BackgroundGeneral |
| 2 | RandomCoincidenceBackground | FissionDetector1_caseB | BackgroundAlpha |
| 3 | GammaBackground | FissionDetector1_caseC | GammaBackground |
| 4 | AlphaBackground | FissionParticleDetected | MSinSample |
| 5 | WrapAroundBackground | FissionFragmentDetectorEfficiency | MSinSurrounding |
| 6 | MultipleScatteringSampleBackingCorrected | FissionDetectorGas_raw | FissionDetectorEfficiencyMethod |
| 7 | MultipleScatteringSurroundingCorrected | FissionDetectorGas_caseA | FFAbsorptionAngularDistributionMethod |
| 8 | AttenuationSampleBackingCorrected | AngularAcceptanceofFFDetector | NeturonDetectorResponseMethod |
| 9 | AttenuationSurroundingCorrected | NeutronDetector_raw | NeturonDetectorEfficiencyMethod |
| 10 | FissionDetectionEfficiencyCorrected | NeutronDetector_caseA | DeadtimeDeterminationMethod |
| 11 | NeutronDetectionEfficiencyCorrected | AngularCoverageofNeutronDetector | |
| 12 | NeutronDetectionResponseCorrected | NeutronDetectorSizeCM | |
| 13 | SampleDecayCorrected | NeutronDetectorStructuralMaterialAu | |
| 14 | FissionFragmentAbsorptioninSampleCorrected | NeutronDetectorStructuralMaterialAl | |
| 15 | SignalPulsePileupCorrected | | |
| 16 | DeadtimeCorrected | | |
| 17 | AngularDistributionFissionFragmentsCorrected | | |
| 18 | ImpuritiesCorrected | | |

This is a *filtered* list of feature categories!!!



These metadata are retrieved from EXFOR in a by-hand process.

AIACHNE is using a sparse Bayesian model to identify potential sources of bias in ^{252}Cf PFNS data.

We are extending the Bayesian model with an energy-dependent, multiplicative bias. Sparsity ensures no bias for most energies but the term is active when the data indicate the need. A horseshoe prior reduces the number of potential biases.

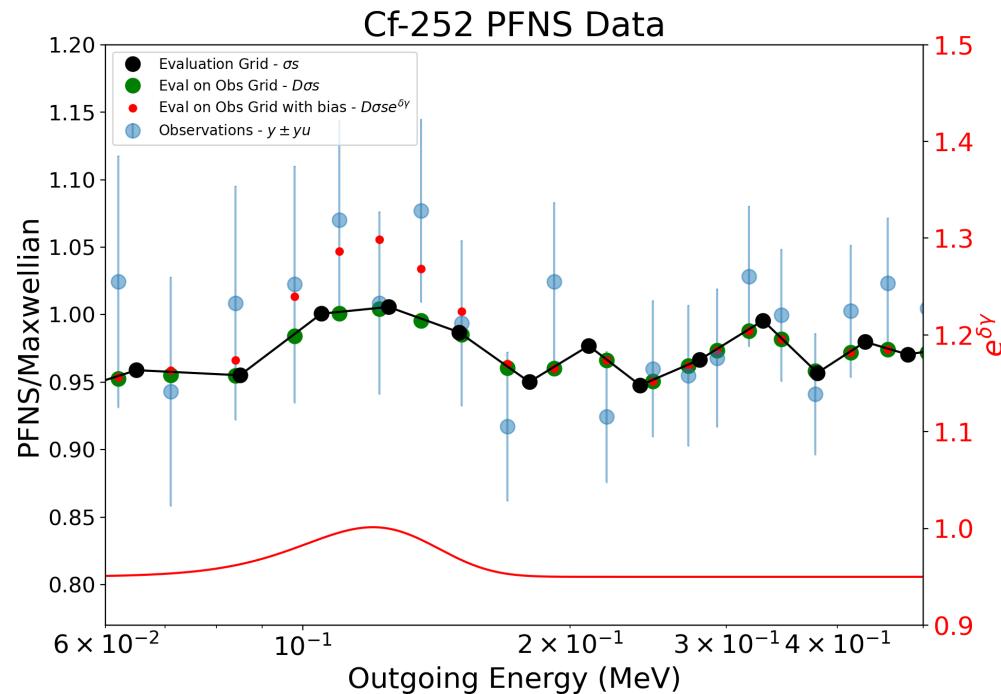
$$y = D\sigma \cdot e^{\delta} + \varepsilon$$

$\delta = B\gamma$ = relative bias

B = bias basis matrix

γ = bias coefficients

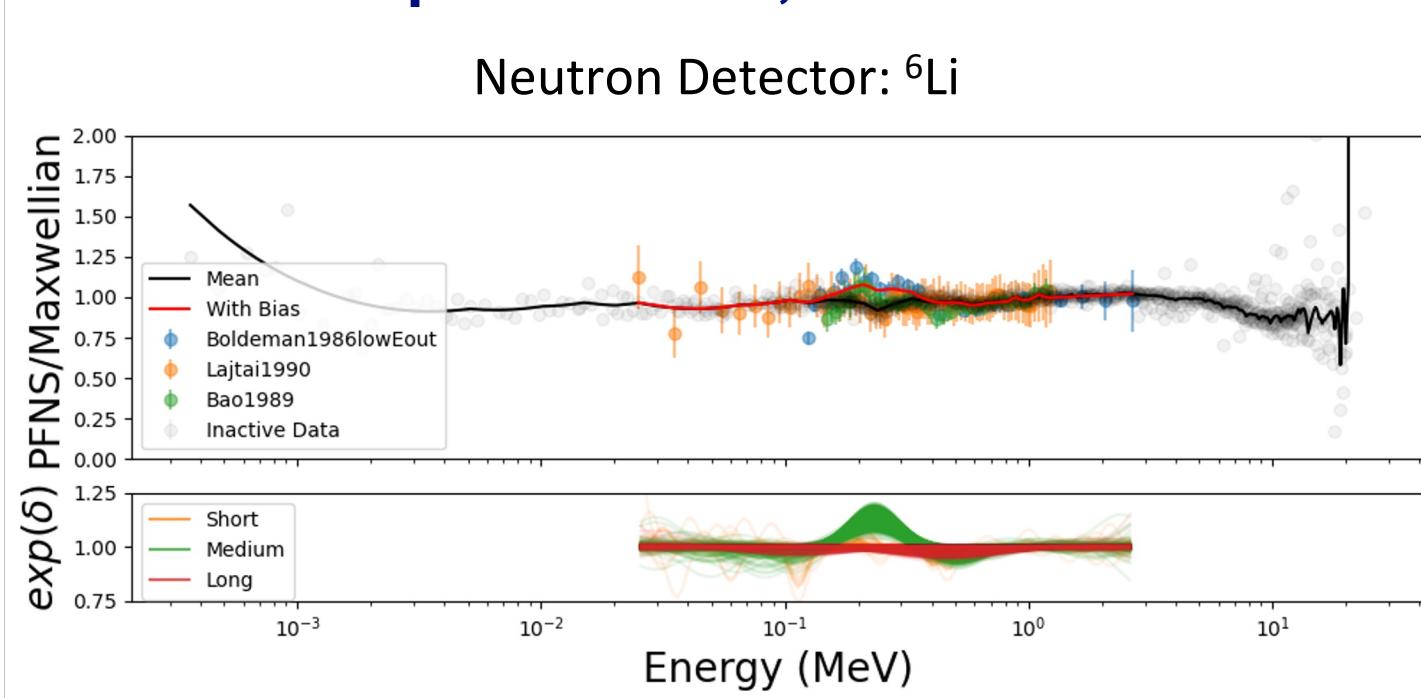
\cdot = element-wise product



The algorithm deals well with a large number of correlated features compared to experimental data.

Validation example: does the algorithm correctly identify expected bias due to ${}^6\text{Li}$ peak? – Yes, it does!

Study is documented in paper: N. Walton, LA-UR-24-29607 (2024), submitted.



Advantage of algorithm: Enables to more quantitatively identify bias in exp. data as a function of energy to be included in evaluation algorithm.

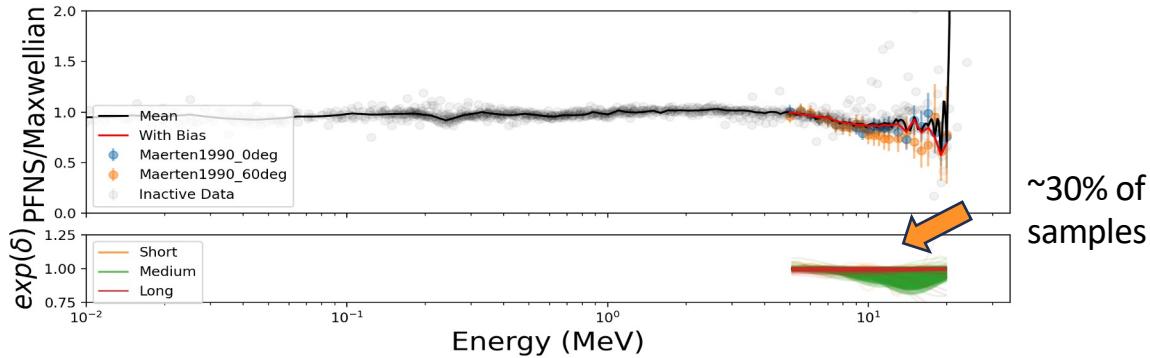


Another example: High-E bias identified across several feature groups, less obvious but experimentally explainable.

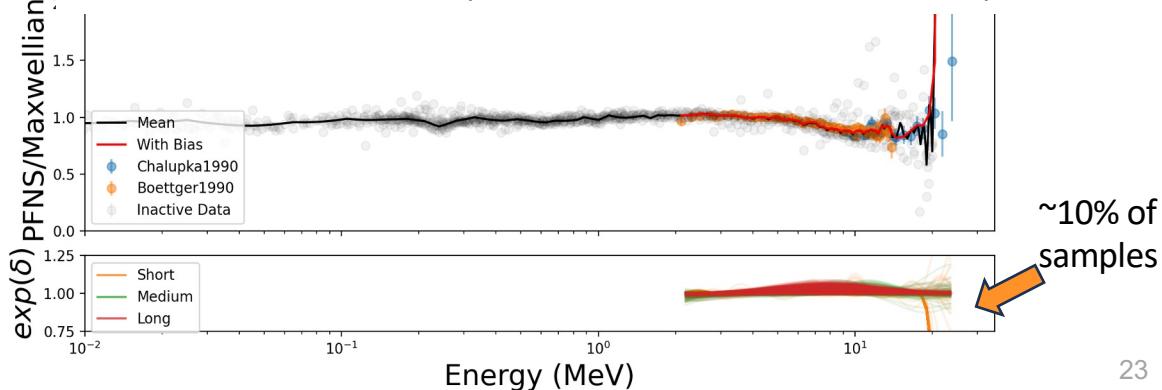
Effect at high energies was attributed to many features. Detailed expert discussion and analysis of data pointed to fission detection (angular dependence of fission fragments).

The algorithm finds features related to bias experts might have otherwise overlooked. The algorithm results require expert interpretation.

Fission Detection Efficiency Correction Method: Calculated/Measured



Fission Detection Efficiency Correction Method: Calculated/Stapre

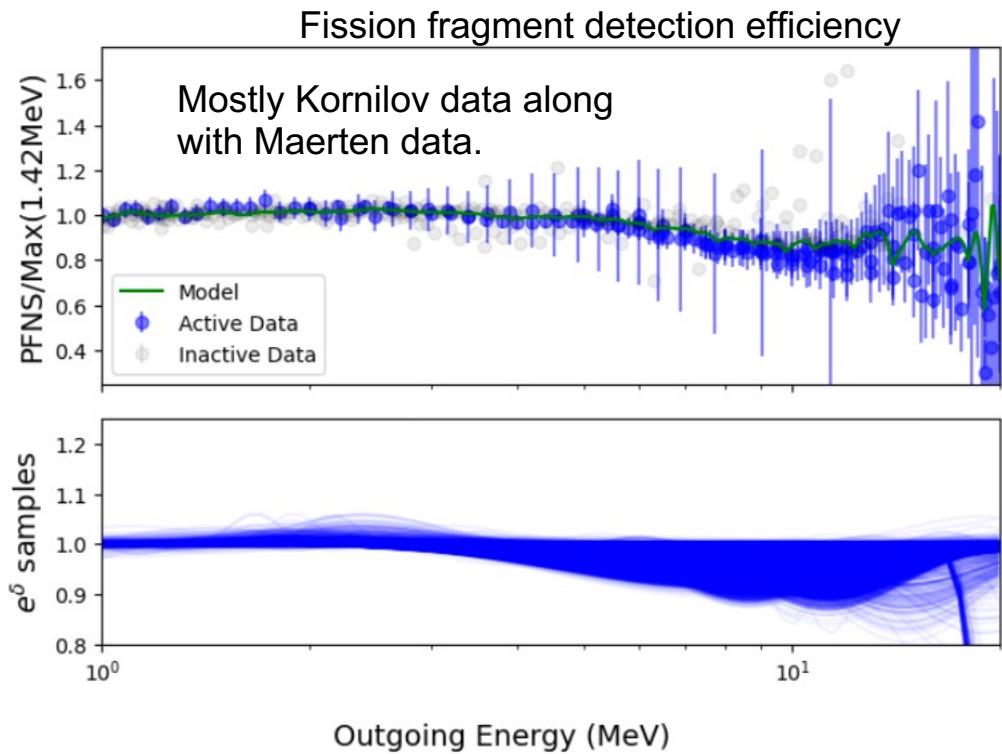


ML results also list in several categories Kornilov data.

Bias in Kornilov data related to:

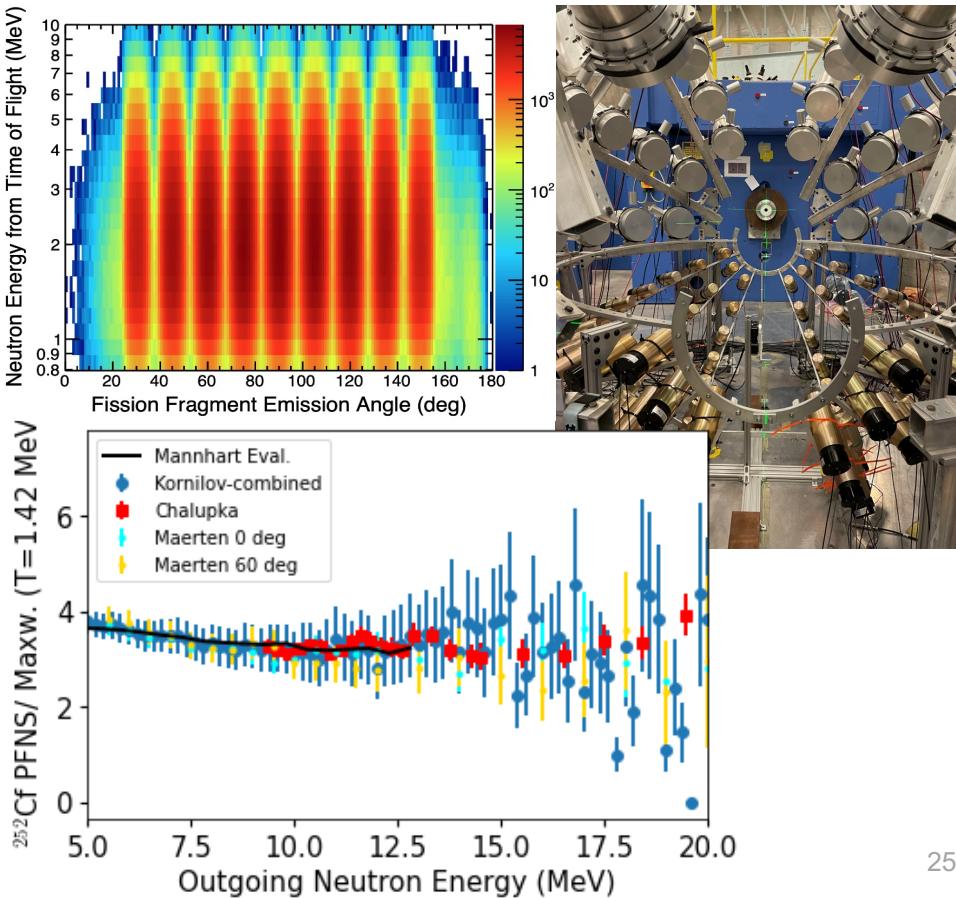
- Fission fragment efficiency,
- Various uncorrected background,
- Neutron detector components,
- ...

In essence, the algorithm told us to go and look more at the data. ☺

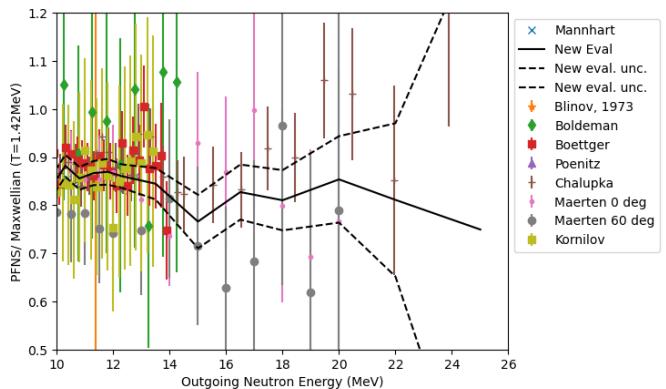
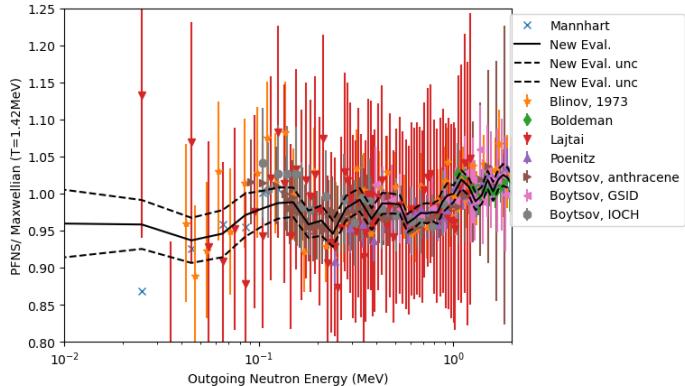
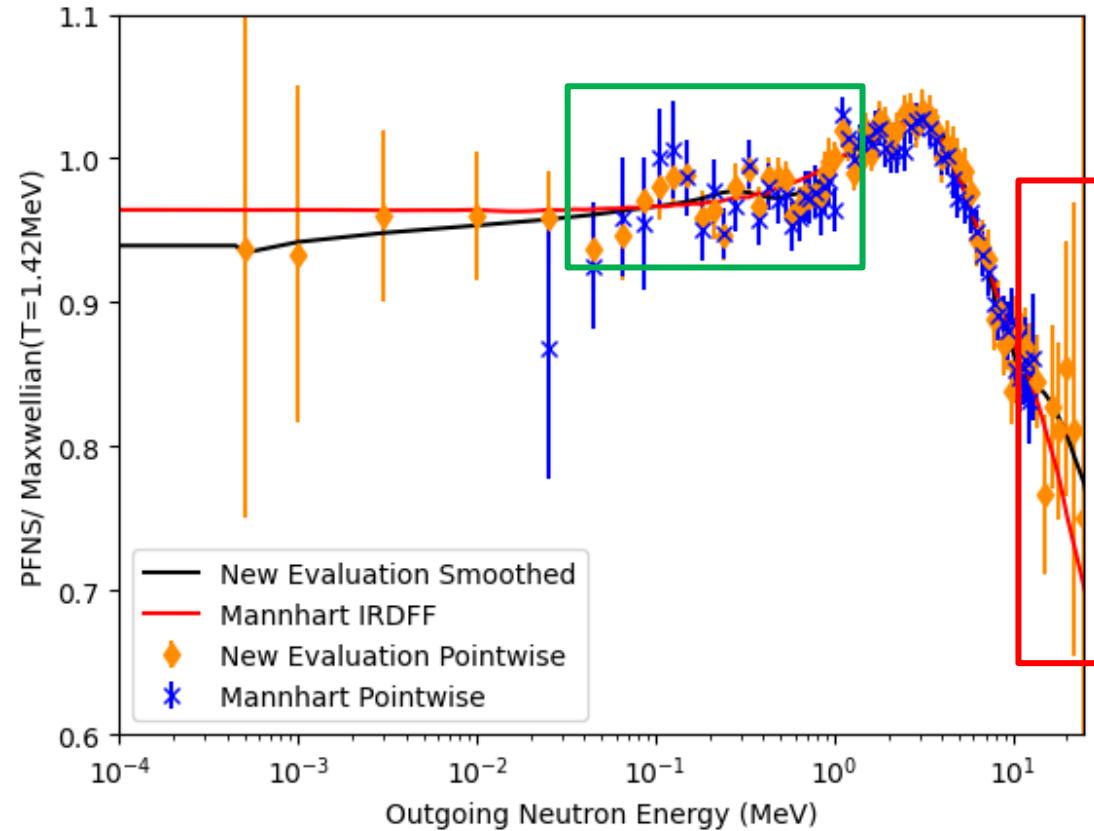


It is key for experts to take a second look at ML results. We are doing that via exp. and simulations.

- Boldeman ${}^6\text{Li}$ bias: will be explored via CoGNAC ${}^{252}\text{Cf}$ PFNS experiment by K. Kelly.
- Kornilov bias: AIACHNE team worked with Tom Massey to identify issue (neutron detector response extrapolation) and removed biased run from data set.
- Maerten bias: will simulate fission fragment angular distribution for correction.



New evaluation reduces ${}^6\text{Li}$ peak but more work needed at high outgoing energies correcting data.



Conclusions

- o Don't use data straight from EXFOR but do detailed experimental UQ & review of data,
- o Templates help us give realistic uncertainty estimates where uncertainties were missing.
- o If, despite good exp. UQ, one still observes discrepancies, question what is the physics root cause!
- o Interplay between expert judgment and ML results can be key to tease out more understanding of physics information than each on their own.



Thank you for listening!

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