

总成绩 (100%) = 考勤 (10%) + 习题 (30%) + 测验 (60%), 习题每个点至少完成一半  
课程概况:

- 绪论 2h
- 凸集和凸函数 3h
- 凸优化问题 6h
- 拉格朗日乘子 5h
- 凸优化应用 6h
- 无约束凸优化问题求解 5h
- 有约束凸优化问题求解 4h
- 课程测试 2h

## 1 绪论

*Remark 1.1.*  $f$  是凸函数,  $\nabla f_x = 0 \Leftrightarrow$  点  $x$  是最小值点

## 2 凸集和凸函数

*Remark 2.1.* 凸集:  $\forall x, y \in C, \theta \in [0, 1] \implies \theta x + (1 - \theta)y \in C$ 。空集、点、线段都是凸集。

*Remark 2.2.* 凸集的例子:

- 超平面:  $\{x : a^T x = b\}$ ,  $a \in \mathbb{R}^n - \{0\}$  是法向量
- 半平面:  $\{x : a^T x \leq b\}$ ,  $a \in \mathbb{R}^n - \{0\}$
- 欧几里得球:  $B(x_c, r) = \{x : \|x - x_c\| < r\} = \{x_c + ru : \|u\| < 1\}$
- 椭球:  $\{x : (x - x_c)^T P^{-1}(x - x_c) < 1\}$ ,  $P \in S_{++}^n$  或  $\{x_c + Au : \|u\| < 1\}$ ,  $A \in S_{++}^n$
- 多面体:  $\{x : Ax \preceq b, Cx = d\}$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $C \in \mathbb{R}^{p \times n}$ ,  $b \in \mathbb{R}^m$ ,  $d \in \mathbb{R}^p$ , 多面体是半空间和超平面的交集, 任意个数的凸集的交集是凸集。

*Remark 2.3.* 凸集  $S$ : 是  $S$  中所有点的凸组合的最小集合

- 如果  $C$  是一个凸集, 则  $aC + b = \{ax + b : x \in C\}$ ,  $a \in \mathbb{R}$ ,  $b \in \mathbb{R}^n$  也是一个凸集
- 对于仿射函数  $f(x) = Ax + b$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$

– 凸集在  $f$  下的像是凸集

$$S \subset \mathbb{R}^n \text{ convex} \implies f(S) = \{f(x) : x \in S\} \subset \mathbb{R}^m \text{ convex}$$

– 凸集在  $f$  下的逆像是凸集

$$C \subset \mathbb{R}^m \text{ convex} \implies f^{-1}(C) = \{x : f(x) \in C\} \subset \mathbb{R}^n \text{ convex}$$

- 两个凸集可以用一个超平面分离（证明困难）
- 支撑超平面： $\{x : a^t x = a^t x_0\}, a \in \mathbb{R}^n - \{0\}, a^t x \leq a^t x_0, \forall x \in C$ , 其中  $C$  是一个凸集,  $x_0$  是凸集上一边界点
- 支撑超平面定理：如果  $C$  是凸的，则在  $C$  的每个边界点上都存在一个支撑超平面

*Remark 2.4.* 凸函数： $f : \mathbb{R}^n \rightarrow \mathbb{R}$  的定义域  $\text{dom}(f)$  是一个凸集，满足  $\forall x, y \in \text{dom}(f), \theta \in [0, 1]$

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$$

$f$  是一个凸函数，则  $f$  在定义域的任何内点都是连续的，并且  $f$  是局部有界的： $\exists B(x, r) \subset \text{dom}(f)$

$$z = \theta x + (1 - \theta)y \implies \frac{f(z) - f(x)}{1 - \theta} \leq \frac{f(y) - f(z)}{\theta} \implies \frac{f(z) - f(x)}{\|z - x\|} \leq \frac{f(y) - f(z)}{\|y - z\|}$$

*Remark 2.5.* 一些凸函数的例子：

- 仿射函数： $a^t x + b, \forall a \in \mathbb{R}^n, b \in \mathbb{R}$
- 幂函数  $x^\alpha$  on  $\mathbb{R}_{++} = (0, \infty), \alpha \geq 1$  or  $\alpha \leq 0$
- $l^p$  范数： $\|x\|_p = \sum_{i=1}^n (|x_i|^p)^{\frac{1}{p}}$  on  $\mathbb{R}^n$  for  $p \geq 1$

*Remark 2.6.* 凸函数的性质

- $f$  is convex  $\implies \alpha f$  for  $\alpha > 0$  is convex.
- $f_1, \dots, f_m$  are convex  $\implies f_1 + \dots + f_m$  is convex.
- Composition with affine function:  $f$  is convex  $\implies f(Ax + b)$  is convex.
- $f_1, \dots, f_m$  are convex  $\implies f(x) = \max \{f_1(x), \dots, f_m(x)\}$  is convex.

– 分段线性函数 (piecewise-linear function):  $f(x) = \max_{1 \leq i \leq m} \{a_i^t x + b_i\}$

*Remark 2.7.* 严格凸函数 strictly convex function,  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

- $\text{dom}(f)$  is convex set
- $\forall x \neq y \in \text{dom}(f), \theta \in (0, 1)$

$$f(\theta x + (1 - \theta)y) < \theta f(x) + (1 - \theta)f(y)$$

$l^p$ -norm and  $l^\infty$ -norm are not strictly convex.

*Remark 2.8.* 强凸函数 strongly convex function,  $f: \mathbb{R}^n \rightarrow \mathbb{R}$

- $\text{dom}(f)$  is convex set
- $\exists m > 0$ , satisfy  $f(x) - \frac{m}{2}\|x\|^2$  is convex.
- 判定方法:  $\nabla^2 f \succ 0$
- 谱分解:  $A = P^t Q P$ , 其中  $Q$  的对角线是  $A$  的特征值
- $\nabla^2 f - mI \succeq 0 \implies u^t(\nabla^2 f - mI)u \geq 0 \implies u^t \nabla^2 f u \geq m\|u\|^2 \implies u^t P^t Q P u \geq m\|u\|^2 \implies \forall \lambda \geq m, \lambda$  是  $\nabla^2 f(x)$  的特征值
- $f(x)$  is convex  $\implies f(x) + \frac{m}{2}\|x\|^2$  is strictly convex.

strongly convex  $\implies$  strictly convex  $\implies$  convex

*Remark 2.9.* 凸函数判定:

- First-order condition: **differentiable**  $f$  with **convex domain** is convex iff  $\forall x, y \in \text{dom}(f)$

$$f(y) \geq f(x) + \nabla f(x)^t(y - x)$$

- *Proof.* \*  $f$  is convex  $\iff \frac{f(z)-f(x)}{z-x} \leq \frac{f(y)-f(z)}{y-z} \implies$  with  $z \rightarrow x, \frac{f(y)-f(x)}{y-x} \geq f'(x) \implies f(y) \geq f(x) + f'(x)(y - x)$
- \*  $f(y) \geq f(x) + f'(x)(y - x) \implies \frac{f(y)-f(z)}{y-z} \geq f'(z) \geq \frac{f(x)-f(z)}{x-z} \implies$  by  $z = \theta x + (1 - \theta)y, f$  is convex

$$f(x^*) = 0 \iff x^* \text{ is global minimum of } f.$$

$$f \text{ is strictly convex} \iff \forall x \neq y \in \text{dom}(f), f(y) > f(x) + \nabla f(x)^t(y - x)$$

- Second-order conditions: for **twice differentiable**  $f$  with **convex domain** is convex iff  $x \in \text{dom}(f)$

$$\nabla^2 f(x) \succeq 0$$

- if  $\nabla^2 f(x) \succ 0$  for  $\forall x \in \text{dom}(f) \implies f$  is strictly convex.

–  $\exists m > 0$ , satisfy  $\nabla^2 f(x) \succeq mI$  for  $\forall x \in \text{dom}(f) \iff f$  is strongly convex.

- Restriction of a convex function to a line:

–  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is convex iff the function  $g : \mathbb{R} \rightarrow \mathbb{R}$

$$g(t) = f(x + tv), \quad \text{dom}(g) = \{t : x + tv \in \text{dom}(f)\}$$

is convex for any  $x \in \text{dom}(f)$  and  $v \in \mathbb{R}^n$

– *Proof.*  $g(t) = f(x + t(y - x))$  is convex  $\iff g(\theta) \leq \theta g(0) + (1 - \theta)g(1) \iff f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y) \iff f$  is convex.  $\square$

*Remark 2.10.*  $X \in \mathbb{S}_{++}^n \implies X = P^t Q P = P^t \text{diag}(q_1, \dots, q_n) P \implies X^\alpha \triangleq P^t \text{diag}(q_1^\alpha, \dots, q_n^\alpha) P$ , satisfy  $X^\alpha X^\beta = X^{\alpha+\beta}$ ,  $X^0 = I$ .

*Remark 2.11.*

- sublevel set(下水平集) of  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

$$C_\alpha = \{x \text{ in } \text{dom}(f) : f(x) \leq \alpha\}$$

sublevel set of convex functions are convex.

- Epigraph(上境图) set of  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

$$\text{epi}(f) = \{(x, t) \in \mathbb{R}^{n+1} : x \in \text{dom}(f), t \geq f(x)\}$$

$f$  is convex iff epi is convex set.

### 3 凸优化问题

*Remark 3.1.* Optimization problem:

$$\begin{cases} \text{minimize} & f(x) \\ \text{subject to} & f_i(x) \leq 0, \quad 1 \leq i \leq m \\ & h_i(x) = 0, \quad 1 \leq i \leq p \end{cases}$$

- feasible set  $X \subset \mathcal{D}$

$$\mathcal{D} = \text{dom}(f) \cap (\cap_{i=1}^m \text{dom}(f_i)) \cap (\cap_{i=1}^p \text{dom}(h_i))$$

- optimal value:  $p^* = \inf \{f(x) : x \text{ is feasible}\}$

- a feasible  $x$  is an optimal solution(minimizer) if  $f(x) = p^*$

*Remark 3.2.* Convex optimization problem(COP):

$$\begin{cases} \text{minimize} & f(x) \\ \text{subject to} & f_i(x) \leq 0, \quad 1 \leq i \leq m \\ & Ax = b \end{cases}$$

- objective function  $f$  is convex
- inequality constraints  $f_1, \dots, f_m$  are convex
- equality constraints are affine:  $A \in \mathbb{R}^{p \times n}, b \in \mathbb{R}^p$
- the feasible set  $X$  of COP is convex
  - $X = \text{dom}(f) \cap (\cap_{i=1}^m X_i) \cap \text{hyperplanes}$ 
    - \*  $X_i = \{x \in \text{dom}(f_i) : f_i(x) \leq 0\}$
  - so a COP is actually an unconstrained COP defined on a convex set.
- any local minimum of a COP is globally optimal.
  - $x^*$  is a local minimum: a solution of the COP in  $B(x^*, r) \cap X$
  - $\forall y \in X$ , take  $\theta \rightarrow 0$ , satisfy  $z = \theta x^* + (1 - \theta)y \in B(x^*, r)$ , by convexity,  $\theta f(x^*) + (1 - \theta)f(y) \geq f(z) \geq f(x^*)$ , thus  $f(y) \geq f(x^*)$ .
- the set of optimal solutions is convex.

*Remark 3.3.* Important examples:

- Linear program(LP):

$$\begin{cases} \text{minimize} & c^t x \\ \text{subject to} & Gx \preceq h \\ & Ax = b \end{cases}$$

- convex problem with affine object over a polyhedron
- standard form

$$\begin{cases} \text{minimize} & c^t x \\ \text{subject to} & x \succeq 0 \\ & Ax = b \end{cases}$$

- Quadratic program(QP):

$$\begin{cases} \text{minimize} & \frac{1}{2}x^tPx + q^tx + r \\ \text{subject to} & Gx \preceq h \\ & Ax = b \end{cases}$$

$P \in \mathcal{S}_+^n$ , convex problem with quadratic object over a polyhedron.

- Quadratically constrained quadratic program(QCQP)

$$\begin{cases} \text{minimize} & \frac{1}{2}x^tPx + q^tx + r \\ \text{subject to} & \frac{1}{2}x^tP_i x + q_i^tx + r \preceq 0, \quad 1 \leq i \leq m \\ & Ax = b \end{cases}$$

- $P, P_i \in \mathcal{S}_+^n$ , objective and constraints are convex quadratic.
- if  $P_1, \dots, P_m \in \mathcal{S}_{++}^n$ , feasible region is intersection of  $m$  ellipsoids and an affine set.

*Remark 3.4.* For **differentiable**  $f$ ,  $x \in X$  is optimal iff

$$\nabla f(x)^t(y - x) \geq 0, \quad \forall y \in X$$

- if  $x$  is optimal, let  $g(\theta) = f(x + \theta(y - x))$

$$0 \leq \lim_{\theta \downarrow 0} \frac{f(x + \theta(y - x)) - f(x)}{\theta} = g'(0) = \nabla f(x)^t(y - x)$$

- conversely, by convexity(First order condition)

$$f(y) \geq f(x) + \nabla f(x)^t(y - x) \implies \nabla f(x)^t(y - x) \geq 0$$

**Important**, for COP:

$$x \text{ optimal} \iff \nabla f(x)^t(y - x) \geq 0, \forall y \in X$$

*Remark 3.5.* Unconstrained COP, with differentiable  $f$

$$\text{minimize } f(x)$$

- $x \in \text{dom}(f)$  (open set!) is optimal iff  $\nabla f(x) = 0$ 
  - if  $x$  is optimal,  $\nabla f(x)^t(y - x) \geq 0$  for any feasible  $y$ , take  $y = x - \lambda \nabla f(x)$  for sufficient small  $\lambda > 0$ , thus  $\nabla f(x) = 0$
  - conversely,  $\nabla f(x)^t(y - x) = 0$

- Intuitive interpretation:  $x$  is optimal, then  $\langle \nabla f(x), y - x \rangle \geq 0$ . if  $\nabla f(x) \neq 0$ ,  $\exists y$  satisfy  $\langle \nabla f(x), y - x \rangle < 0$ , so  $\nabla f(x) = 0$ .

*Remark 3.6.* Equality constrained COP, with differentiable  $f$ ,  $A \in \mathbb{R}^{p \times n}$ ,  $b \in \mathbb{R}^p$

$$\begin{cases} \text{minimize} & f(x) \\ \text{subject to} & Ax = b \end{cases}$$

- $x \in \text{dom}(f)$  is optimal iff:

$$Ax = b, \text{ and there exists } v \in \mathbb{R}^p, \text{ s.t. } \nabla f(x) = A^t v, \nabla f(x) \in \mathcal{R}(A^t)$$

*Proof.*  $x$  optimal  $\iff Ax = b, \nabla f(x) = A^t v$ .

- " $\Leftarrow$ ":  $\forall y \in X, Ay = b \implies (\nabla f(x))^t(y - x) = v^t A(y - x) = v^t(b - b) = 0 \implies, x$  is optimal.
- $\mathcal{N}(A) = \mathcal{R}(A^t)^\perp, \mathcal{N}(A)^\perp = \mathcal{R}(A^t)$
- " $\implies$ ":  $\forall u \in \mathcal{N}(A), x + \theta u \in \text{dom}(f)$  for  $\theta \rightarrow 0$ . make  $y = x + \theta u, \nabla f(x)(y - x) \geq 0 \implies \theta \langle \nabla f(x), u \rangle \geq 0$  satisfy for all  $\theta \rightarrow 0$ , so  $\langle \nabla f(x), u \rangle = 0$ . As a result,  $\nabla f(x)^t \in \mathcal{N}(A)^\perp$ , then  $\exists v \in \mathbb{R}^p$  s.t.  $\nabla f(x) = A^t v$ .

□

*Remark 3.7.* Equality constrained QP:  $P \in \mathbb{S}_+^n, q \in \mathbb{R}^n, r \in \mathbb{R}, A \in \mathbb{R}^{p \times n}$  with  $\text{rank}(A) = p, b \in \mathbb{R}^p$

$$\begin{cases} \text{minimize} & \frac{1}{2}x^t P x + q^t x + r \\ \text{subject to} & Ax = b \end{cases}$$

- $x^*$  is optimal  $\iff \exists v^* \in \mathbb{R}^p$  s.t.

$$\begin{bmatrix} P & A^t \\ A & 0 \end{bmatrix} \begin{bmatrix} x^* \\ v^* \end{bmatrix} = \begin{bmatrix} -q \\ b \end{bmatrix}$$

- coefficient matrix is called KKT matrix.
- KKT matrix is nonsingular  $\iff "Ax = 0, x \neq 0 \implies x^t P x > 0"$

*Remark 3.8.* Inequality constrained COP, with differentiable  $f, f_1, \dots, f_m$

$$\begin{cases} \text{minimize} & f(x) \\ \text{subject to} & f_i(x) \leq 0, \quad , 1 \leq i \leq m \end{cases}$$

- sufficient condition: for a feasible  $x$ , if  $\lambda_i \geq 0$  for  $i \in [1, m]$  and  $\nabla f(x) + \sum_{i=1}^m \lambda_i \nabla f_i(x) = 0$ ,  $\lambda_1 f_1(x) = \dots = \lambda_m f_m(x) = 0$ ,  $x$  is optimal if the following is established
  - $f_i(x) \neq 0 \implies \lambda_i = 0$
  - $f_i(x) = 0 \implies \nabla f_i(x)^t(y - x) \leq 0$  for any feasible  $y$
  - for any feasible  $y$ ,  $\nabla f(x)^t(y - x) = -\sum_{i=1}^m \lambda_i \nabla f_i(x)^t(y - x) \geq 0$
- the converse is false.

*Remark 3.9.* COP over nonnegative orthant, with differentiable  $f$

$$\begin{cases} \text{minimize} & f(x) \\ \text{subject to} & x \succeq 0 \end{cases}$$

- $x \in \text{dom}(f)$  is optimal iff

$$x \succeq 0, \quad \begin{cases} \nabla f(x)_i \geq 0 & \text{if } x_i = 0 \\ \nabla f(x)_i = 0 & \text{if } x_i > 0 \end{cases}$$

- *Proof.* by observe
  - $x$  is optimal  $\implies \nabla f(x)^t(y - x) \geq 0$  holds **for all feasible**  $y$
  - for  $x_i > 0 \implies y_i - x_i$  can be positive or negative, so  $\nabla f(x)_i = 0$
  - for  $x_i = 0 \implies y_i - x_i \geq 0, \nabla f(x)_i \geq 0$

□

*Remark 3.10.*

$$\lim_{\varepsilon \rightarrow 0} \frac{f(x + a\varepsilon) - f(x)}{\varepsilon} = \langle \nabla f(x), a \rangle, \quad \varepsilon \rightarrow x + a\varepsilon \rightarrow f(x + a\varepsilon)$$

*Remark 3.11.* COP over a simplex, with differentiable  $f$

$$\begin{cases} \text{minimize} & f(x) \\ \text{subject to} & x \succeq 0, \sum_{i=1}^n x_i = 1 \end{cases}$$

- $x \in \text{dom}(f)$  is optimal iff

$$\partial_j f(x) \geq \partial_i f(x) \text{ for all } 1 \leq j \leq n \text{ when } x_i > 0$$

- *Proof.* by observe



- if  $x$  is optimal,  $\nabla f(x)^t(y - x) \geq 0$  holds for all feasible  $y$
- for  $x_i > 0 \implies y_i - x_i$  can be positive or negative, so  $\partial_j f(x) \geq \partial_i f(x) = 0$  for any  $j$
- the converse is obvious

$$\nabla f(x)^t(y - x) = \sum_{x_i > 0} \partial_i f(x)(y_i - x_i) + \sum_{x_i = 0} \partial_i f(x)(y_i - x_i) \geq C \sum_{i=1}^n (y_i - x_i) = 0$$

□

## 4 拉格朗日乘子

*Remark 4.1.* Standard form optimization problem (not necessarily convex)

$$\begin{cases} \text{minimize} & f(x) \\ \text{subject to} & f_i(x) \leq 0, \quad 1 \leq i \leq m \\ & h_i(x) = 0, \quad 1 \leq i \leq p \end{cases}$$

$x \in \mathcal{D} = \text{dom}(f) \cap (\cap_{i=1}^m \text{dom}(f_i)) \cap (\cap_{i=1}^p \text{dom}(h_i))$ , optimal value denoted  $p^*$ .  $x \in \mathcal{D}$  **do not need to satisfy constraints.**

- Lagrange function,  $L : \mathcal{D} \times \mathbb{R}^m \times \mathbb{R}^p \mapsto \mathbb{R}$

$$L(x, \lambda, \mu) = f(x) + \sum_{i=1}^m \lambda_i f_i(x) + \sum_{i=1}^p \mu_i h_i(x)$$

- Lagrange dual function,  $g : \mathbb{R}^m \times \mathbb{R}^p \mapsto \mathbb{R}$

$$g(\lambda, \mu) = \inf_{x \in \mathcal{D}} L(x, \lambda, \mu)$$

- $g$  is concave, can be  $-\infty$  for some  $(\lambda, \mu)$
- lower bound property: if  $\lambda \succeq 0$ , then  $g(\lambda, \mu) \leq p^*$

*Remark 4.2.* Standard form LP:

$$\begin{cases} \text{minimize} & c^t x \\ \text{subject to} & x \succeq 0 \\ & Ax = b \end{cases}$$

- Lagrangian:

$$L(x, \lambda, \mu) = c^t x - \lambda^t x + \mu^t (Ax - b) = -\mu^t b + (c + A^t \mu - \lambda)^t x$$

- dual function:

$$\begin{aligned} g(\lambda, \mu) &= \inf_x (-\mu^t b + (c + A^t \mu - \lambda)^t x) \\ &= \begin{cases} -\mu^t b, & \text{if } c + A^t \mu - \lambda = 0 \\ -\infty, & \text{otherwise} \end{cases} \end{aligned}$$

- lower bound property:  $p^* \geq -\mu^t b$  if  $c + A^t \mu \succeq 0$ .

*Remark 4.3.* Tow-way partitioning, for  $W \in \mathbb{S}^n$

$$\begin{cases} \text{minimize} & x^t W x \\ \text{subject to} & x_i^2 = 1, \quad i = 1, \dots, n \end{cases}$$

- a nonconvex problem, feasible set contains  $2^n$  discrete points
- Lagrangian:  $L(x, \mu) = f(x) + \sum_{i=1}^n \mu_i (x_i^2 - 1)$
- dual function:

$$\begin{aligned} g(\mu) &= \inf_x (x^t W x + \sum_{i=1}^n \mu_i (x_i^2 - 1)) \\ &= \inf_x x^t (W + \text{diag}(\mu)) x - \sum_{i=1}^n \mu_i \\ &= \begin{cases} -\sum_{i=1}^n \mu_i, & \text{if } W + \text{diag}(\mu) \succeq 0 \\ -\infty, & \text{otherwise} \end{cases} \end{aligned}$$

- lower bound property:  $p^* \geq -\sum_{i=1}^n \mu_i$  if  $W + \text{diag}(\mu) \succeq 0$ .
  - $p^* \geq n\lambda_{\min}(W)$ , where  $\lambda_{\min}(W)$  is the smallest eigenvalue of  $W$ .
  - *Proof.*  $W + \text{diag}(\mu) = P^t Q P + \theta I = P^t (Q + \theta I) P \succeq 0$ , let  $\text{diag}(\mu) = \theta I$ , so  $\lambda_i + \theta \geq 0, \theta = -\lambda_{\min}(W), p^* \geq n\lambda_{\min}(W)$ .  $\square$

*Remark 4.4.* Lagrange dual problem

$$\begin{cases} \text{maximize} & g(\lambda, \mu) \\ \text{subject to} & \lambda \succeq 0 \end{cases}$$

- COP, optimal value denoted  $d^*$
- finds best lower bound on  $p^*$ , obtained from Lagrange dual function.
- weak duality:  $d^* \leq p^*$

- always holds (for both convex and nonconvex problems)
- can be used to find nontrivial lower bounds for difficult problems
- strong duality:  $d^* = p^*$ 
  - does not hold in general, but usually holds for COP
  - an example that the strong duality does not hold

$$\begin{cases} \text{minimize} & e^{-x} \\ \text{subject to} & x^2/y \leq 0 \end{cases}$$

$$* \mathcal{D} = \{(x, y) : x \in \mathbb{R}, y > 0\}, g(\lambda) = 0 \implies d^* = 0 < p^* = 1$$

## 5 凸优化应用

## 6 无约束凸优化问题求解

## 7 有约束凸优化问题求解