

Autonomoboro

Lab05: Line Following

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Abstract

A dicussion of a robot designed to follow a line and then return home when called for.

1 Robot Design

1.1 Hardware Configuration

Some other text.



Figure 1: A bad robot.

1.2 Software Design

2 Implementation Problems and Their Solutions

3 Unsolved Problems

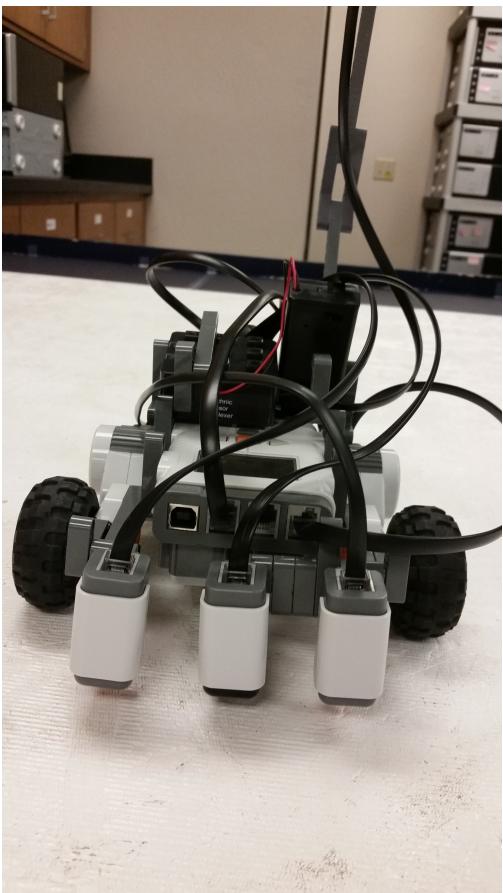


Figure 2: A bad robot as seen from the front.

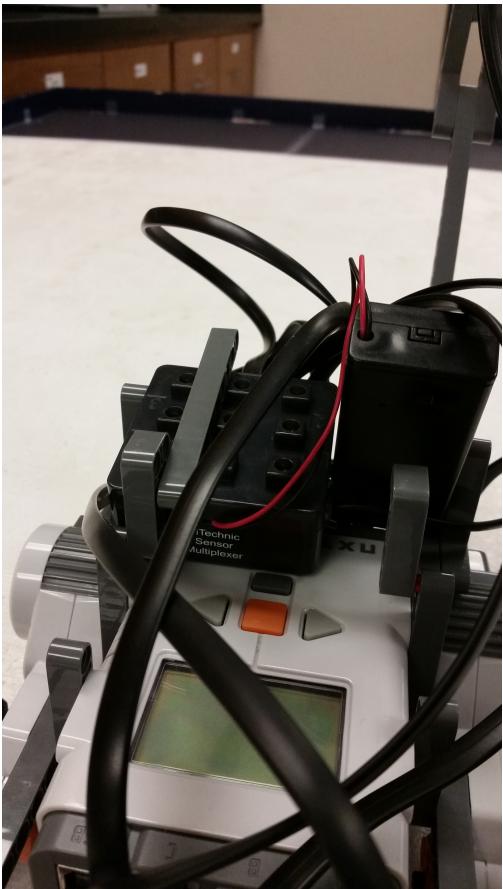


Figure 3: A bad robot.