## P & PI Control

Open serial to Pico data port

Send desired heigth and request for number of samples to Pico

```
desired_height = 10;
s.writeline(num2str(desired_height)) % send desired height to Pico

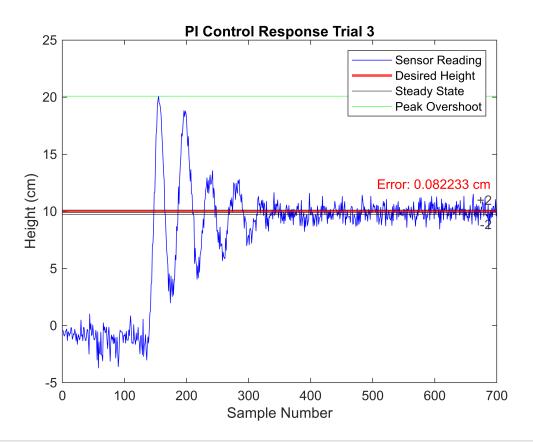
samples = 700;
s.writeline(num2str(samples)) % send number of samples to Pico

height = zeros(1, samples); % create emply row vector for distance collection
voltage = zeros(1, samples); % create emply row vector for voltage collection

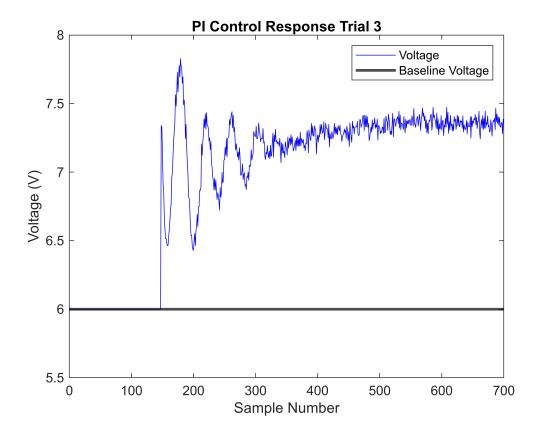
% loop for every sample
for i = 1:samples
    height(i) = s.readline(); % receive distance from serial
    voltage(i) = s.readline(); % receive voltage from serial
end
```

```
save r_data2_04_10_2024.mat height voltage
```

```
ss_min = ss * 0.98;
yline(ss_max, 'k', 'Label', '+2')
yline(ss_min, 'k', 'Label', '-2', 'LabelVerticalAlignment', 'bottom')
hold off
axis([0 700 -5 25]) % set axis limits
title("PI Control Response Trial 3")
xlabel("Sample Number")
ylabel("Height (cm)")
legend("Sensor Reading", "Desired Height", "Steady State", "Peak Overshoot")
```



```
plot(voltage, "b") % plot voltage
hold on
yline(6, 'k', 'LineWidth', 2)
hold off
axis([0 700 5.5 8])
title("PI Control Response Trial 3")
xlabel("Sample Number")
ylabel("Voltage (V)")
legend("Voltage", "Baseline Voltage")
```



## Calculate linear fit parameters to find baseline voltages

```
duty_cycle = [50 55 60 65 70]; % expiremented duty cycles
height = [3.99151 6.907516 9.897944 18.32904 20.30173];

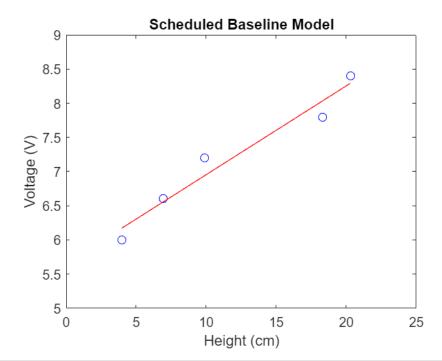
voltage = (duty_cycle ./ 100) .* 12; % convert duty_cycle to fan voltage

plot(height, voltage, 'bo') % plot data points

pfit = polyfit(height,voltage,1); % fit line to data
pval = polyval(pfit, height); % evaluate fitted line

hold on
plot(height, pval, 'r') % plot fitted line
hold off

title("Scheduled Baseline Model")
xlabel("Height (cm)")
ylabel("Voltage (V)")
axis([0 25 5 9])
```



% extract parameters

a = pfit(1)

a = 0.1299

b = pfit(2)

b = 5.6558