Symmetry of Magnetically Induced Currents

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13th September 2022











Overview

- Symmetry and pseudo-symmetry groups in magnetic fields
- Unitary representation analysis on linear spaces
- Wavefunction and current density symmetries
 - Relationships between wavefunction and current density symmetries
 - Symmetry descent and symmetry breaking in magnetic fields

Groups in magnetic fields

 \odot For an N_o -electron system in a uniform magnetic field $B = \nabla \times A(r)$, consider the Schrödinger-Pauli Hamiltonian in atomic units:

$$\hat{\mathcal{H}} = \frac{1}{2} \sum_{k=1}^{N_{e}} \left| -\hat{\boldsymbol{p}}_{k} + \boldsymbol{A}(\boldsymbol{r}_{k}) \right|^{2} + \sum_{k=1}^{N_{e}} v_{ext}(\boldsymbol{r}_{k}) + \frac{1}{2} \sum_{k\neq l}^{N_{e}} \frac{1}{|\boldsymbol{r}_{k} - \boldsymbol{r}_{l}|} + \frac{g_{s}}{2} \sum_{k=1}^{N_{e}} \boldsymbol{B} \cdot \hat{\boldsymbol{s}}_{k}$$

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kinetic

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external potential

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electron-electron interaction

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spin Zeeman interaction

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Zero-field Hamiltonian, $\hat{\mathcal{H}}_0(v_{\text{ext}})$

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The electronic Hamiltonian

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$$\begin{split} \widehat{\mathcal{H}} &= \frac{1}{2} \sum_{k=1}^{N_{e}} \left| -\hat{\boldsymbol{p}}_{k} + \boldsymbol{A}(\boldsymbol{r}_{k}) \right|^{2} + \sum_{k=1}^{N_{e}} v_{\text{ext}}(\boldsymbol{r}_{k}) + \frac{1}{2} \sum_{k\neq l}^{N_{e}} \frac{1}{|\boldsymbol{r}_{k} - \boldsymbol{r}_{l}|} + \frac{g_{s}}{2} \sum_{k=1}^{N_{e}} \boldsymbol{B} \cdot \hat{\boldsymbol{s}}_{k} \\ &= \frac{1}{2} \sum_{k=1}^{N_{e}} \hat{p}_{k}^{2} + \sum_{k=1}^{N_{e}} v_{\text{ext}}(\boldsymbol{r}_{k}) + \frac{1}{2} \sum_{k\neq l}^{N_{e}} \frac{1}{|\boldsymbol{r}_{k} - \boldsymbol{r}_{l}|} + \boldsymbol{A}(\boldsymbol{r}_{k}) \cdot \hat{\boldsymbol{p}}_{k} + \frac{g_{s}}{2} \sum_{k=1}^{N_{e}} \boldsymbol{B} \cdot \hat{\boldsymbol{s}}_{k} + \frac{1}{2} \boldsymbol{A}^{2}(\boldsymbol{r}_{k}) \\ &= \widehat{\mathcal{H}}_{0}(v_{\text{ext}}) + \boldsymbol{A}(\boldsymbol{r}_{k}) \cdot \hat{\boldsymbol{p}}_{k} + \frac{g_{s}}{2} \sum_{k=1}^{N_{e}} \boldsymbol{B} \cdot \hat{\boldsymbol{s}}_{k} + \frac{1}{2} \boldsymbol{A}^{2}(\boldsymbol{r}_{k}). \end{split}$$

How does each term transform spatially and temporally?

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Let v be a rank-k Cartesian tensor in three dimensions.

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- \bullet Let \mathbf{v} be a rank-k Cartesian tensor in three dimensions.
- Spatially, let $u \in O(3)$ be any proper or improper rotation that acts on an orthogonal basis $\{e_i\}$ spanning \mathbb{R}^3 according to

$$\hat{u}\mathbf{e}_i = \mathbf{e}_j \ U_{ji}.$$

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U: representation matrix for u in $\{e_i\}$

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To consider the *linear* action of u on \mathbf{v} , let $\mathbf{v}' = \hat{u}\mathbf{v}$.

v is a polar tensor if

$$\mathbf{v}_{ab\dots k}' = \mathbf{U}_{ap}\mathbf{U}_{bq}\dots\mathbf{U}_{kz}\,\mathbf{v}_{pq\dots z}.$$

v is an axial tensor if

$$V'_{ab...k} = |U|U_{ap}U_{bq}...U_{kz}V_{pq...z}.$$

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+1 for proper rotations, -1 for improper rotations

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- \bullet Let **v** be a rank-*k* Cartesian tensor in three dimensions.
- **Temporally**, let θ be the **time reversal** that acts on an orthogonal basis $\{\zeta_1, \zeta_2\}$ of a two-component spinor according to

$$\hat{\theta}[\zeta_1 \quad \zeta_2] = [\zeta_2^* \quad -\zeta_1^*].$$

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To consider the *antilinear* action of θ on \mathbf{v} , let $\mathbf{v}'' = \hat{\theta}\mathbf{v}$.

v is a time-even tensor (i-tensor) if

$$\mathbf{v}'' = \mathbf{v}$$
.

v is a time-odd tensor (c-tensor) if

$$\mathbf{v}'' = -\mathbf{v}$$
.

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Tensor classifications

- There are four types of tensors under spatial-temporal transformations.
 - polar time-even tensors
 - position vectors r
 - axial time-even tensors

- polar time-odd tensors
 - linear momentum vectors p
 - magnetic vector potentials A
 - current densities j
- axial time-odd tensors
 - angular momentum vectors l
 - magnetic field vectors B

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Symmetry and pseudo-symmetry groups

Definition (symmetry group)

All transformations \hat{T} that leave the electronic Hamiltonian $\hat{\mathcal{H}}$ invariant, i.e. $\hat{T}\hat{\mathcal{H}}\hat{T}^{-1} = \hat{\mathcal{H}}$, form the symmetry group of $\hat{\mathcal{H}}$. Such transformations are called symmetry transformations.

\$ Symmetry transformations impose *constraints* on the eigenfunctions of $\hat{\mathcal{H}}$ and properties calculated from them.

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 $\$ Symmetry transformations impose *constraints* on the eigenfunctions of $\hat{\mathcal{H}}$ and properties calculated from them.

Definition (pseudo-symmetry group)

Consider a term $\hat{\mathcal{H}}' \subset \hat{\mathcal{H}}$. All transformations $\hat{\mathcal{T}}$ that leave $\hat{\mathcal{H}}'$ invariant but not the full $\hat{\mathcal{H}}$ form a pseudo-symmetry group of $\hat{\mathcal{H}}$. Such transformations are called pseudo-symmetry transformations.

Pseudo-symmetry transformations provide ways to understand eigenfunctions of $\hat{\mathcal{H}}$ (complicated) from the perspective of $\hat{\mathcal{H}}$ (simpler).

Groups in magnetic fields

Let us revisit the electronic Hamiltonian in a uniform magnetic field:

$$\hat{\mathcal{H}} = \hat{\mathcal{H}}_0(\mathbf{v}_{\text{ext}}) + \mathbf{A}(\mathbf{r}_k) \cdot \hat{\mathbf{p}}_k + \frac{g_s}{2} \sum_{k=1}^{N_e} \mathbf{B} \cdot \hat{\mathbf{s}}_k + \frac{1}{2} A^2(\mathbf{r}_k).$$

Groups in magnetic fields

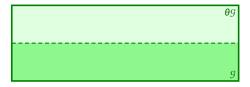
Let us revisit the electronic Hamiltonian in a uniform magnetic field:

$$\hat{\mathcal{H}} = \underbrace{\hat{\mathcal{H}}_0(\mathbf{v}_{\text{ext}})}_{\uparrow} + \mathbf{A}(\mathbf{r}_k) \cdot \hat{\mathbf{p}}_k + \frac{g_s}{2} \sum_{k=1}^{N_e} \mathbf{B} \cdot \hat{\mathbf{s}}_k + \frac{1}{2} A^2(\mathbf{r}_k).$$
polar time-even

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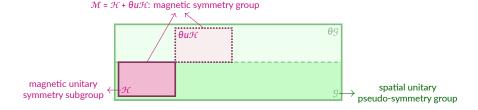


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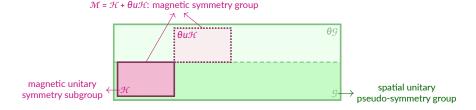
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solution If $\mathcal{M} = \mathcal{H} + \theta u \mathcal{H}$ is isomorphic to a unitary group \mathcal{M}' , we write $\mathcal{M} = \mathcal{M}'(\mathcal{H})$.



Unitary representation analysis

Group unitary representations on linear spaces

- \circ Consider a group g that acts unitarily on a linear space V.
- \bullet Let **v** be an element in V. The unitary action of $\mathcal G$ on **v** generates an **orbit**

$$\mathcal{G} \cdot \mathbf{v} = \{\hat{u}_i \mathbf{v} \mid u_i \in \mathcal{G}\}\$$

which spans a representation subspace $\Gamma \subseteq V$.

For simplicity, we will assume that $\mathcal{G} \cdot \mathbf{v}$ is a linearly independent basis.

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- - \hookrightarrow This quantifies the symmetry of **v** under the action of \mathcal{G} .
- To this end, we pick a reference element $\mathbf{v}_i = \hat{u}_i \mathbf{v}$ in $\mathcal{G} \cdot \mathbf{v}$ and define the representation matrices $\mathbf{D}^{\Gamma}(u_k)$ for all $u_k \in \mathcal{G}$:

$$\hat{u}_k \mathbf{v}_i = \sum_i \mathbf{v}_j D_{ji}^{\Gamma}(u_k).$$

Their traces, $\chi^{\Gamma}(u_k)$, give the characters required for the decomposition of Γ .

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 - \hookrightarrow This requires V to be <u>endowed</u> with an <u>inner product</u> $\langle \cdot | \cdot \rangle$.
- Define a non-orthogonal projection operator

$$\hat{\mathcal{P}}_{i} = \sum_{j} |\mathbf{v}_{i}\rangle (\mathbf{S}^{-1})_{ij} \langle \mathbf{v}_{j}|$$

where $S_{ij} = \langle \mathbf{v}_i | \mathbf{v}_j \rangle$ such that $\hat{\mathcal{P}}_i | \mathbf{v}_j \rangle = \delta_{ij} | \mathbf{v}_i \rangle$.

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② Closure of $\mathcal{G} \implies T_{ij}(u_k)$ can be mapped to $T_{m1}(e)$ for some $m = 1, ..., |\mathcal{G}|$. $\hookrightarrow T(u_k)$ can be computed with $\mathcal{O}(|\mathcal{G}|)$ time complexity.

Soriano, M. & Palacios, J. J. Phys. Rev. B 90, 075128 (August 2014).

Current density linear space

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- **©** Define an inner product $\langle \cdot | \cdot \rangle$ on V_i as

$$\langle \boldsymbol{j}_m | \boldsymbol{j}_n \rangle = \int \boldsymbol{j}_m(\boldsymbol{r})^{\dagger} \boldsymbol{j}_n(\boldsymbol{r}) d\boldsymbol{r}.$$

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- \circ Given a current density j(r) and a symmetry or pseudo-symmetry unitary group \mathcal{G} , the required overlap matrix elements for the symmetry analysis of j(r) are of the form

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Non-perturbative current densities

Non-perturbative calculations in arbitrarily strong magnetic fields are performed in a basis of London atomic orbitals:

$$\omega_{\mu}(\mathbf{r}; \mathbf{R}_{\mu}) = \varphi_{\mu}(\mathbf{r}; \mathbf{R}_{\mu}) \exp[-i\mathbf{A}(\mathbf{R}_{\mu}) \cdot \mathbf{r}].$$

In this basis, the current density can be partitioned into the diamagnetic and paramagnetic contributions with the non-perturbative forms:

$$\boldsymbol{j}(\boldsymbol{r}) = \boldsymbol{j}_{d}(\boldsymbol{r}) + \boldsymbol{j}_{p}(\boldsymbol{r})$$

$$\mathbf{j}_{\rm d}(\mathbf{r}) = -\mathbf{A}(\mathbf{r}) \sum_{\sigma} \omega_{\mu}^{\star}(\mathbf{r}) \omega_{\nu}(\mathbf{r}) P_{\sigma}^{\nu\mu}, \qquad \mathbf{j}_{\rm p}(\mathbf{r}) = \frac{i}{2} \sum_{\sigma} \nabla \omega_{\mu}^{\star}(\mathbf{r}) \omega_{\nu}(\mathbf{r}) P_{\sigma}^{\nu\mu} + \text{c.c.}$$

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f st This partition depends on the gauge origin m G which manifests itself in

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Ipsocentric DZ

We employ the ipsocentric DZ method which makes use of a continuous set of gauge transformations:

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In addition,

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$$= \varphi_{\mu}(\mathbf{r}; \mathbf{R}_{\mu}) \exp \left[-\frac{i}{2} (\mathbf{B} \times \mathbf{R}_{\mu}) \cdot \mathbf{r} \right],$$

which is the same as keeping **G** at the space-fixed origin.

Keith, T. A. & Bader, R. F. Chem. Phys. Lett. 210, 223-231 (1993). Soncini, A. & Fowler, P. W. Chem. Phys. Lett. 396, 174-181 (2004).

Integrals

 \circ The required overlap matrix elements for the symmetry analysis of j(r) may now be cast in a computable form:

$$\begin{split} T_{m1}(e) &= \int (\hat{u}_{m} \boldsymbol{j}_{p})(\boldsymbol{r})^{\dagger} \, \boldsymbol{j}_{p}(\boldsymbol{r}) \, \mathrm{d}\boldsymbol{r} \\ &= \frac{1}{4} \sum_{\sigma \sigma'} (P_{\sigma}^{v\mu})^{*} P_{\sigma'}^{v'\mu'} \\ &\qquad \int (\hat{u}_{m} \omega_{v}^{*})(\boldsymbol{r}) \, \boldsymbol{\nabla} (\hat{u}_{m} \omega_{\mu})(\boldsymbol{r})^{\top} \big[\boldsymbol{\nabla} \omega_{\mu'}^{*}(\boldsymbol{r}) \, \omega_{v'}(\boldsymbol{r}) - \boldsymbol{\nabla} \omega_{\mu'}(\boldsymbol{r}) \, \omega_{v'}^{*}(\boldsymbol{r}) \big] \, \mathrm{d}\boldsymbol{r} + \mathrm{c.c.} \end{split}$$

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second derivatives of four-centre overlap integrals

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(pseudo-)symmetry-transformed London orbitals