



Upper Bounds For the Correlated Bayesian Information Filtering Problem

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- 1 Motivation
- 2 Problem Formulation
- 3 Main Theoretical Results
- 4 Numerical Experiments
- 5 Conclusion

Information Filtering



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Astrophysics

New submissions

Submissions received from Mon 4 Mar 13 to Tue 5 Mar 13, announced

- [New submissions](#)
- [Cross-lists](#)
- [Replacements](#)

[total of 79 entries: 1-79]
 [showing up to 2000 entries per page: [fewer](#) | [more](#)]

New submissions for Wed, 6 Mar 13

[1] [arXiv:1303.0833](#) [[pdf](#), [ps](#), [other](#)]

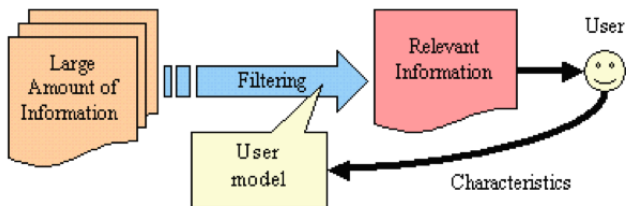
Transverse oscillations in solar spicules induce
[H. Ebadi](#), [M. Hosseinpour](#), [Z. Fazel](#)
 Comments: Accepted for publication in Astrophysics and Space Sciences
 Subjects: Solar and Stellar Astrophysics (astro-ph.SR)

The excitation of Alfvénic waves in the solar spicules due to the sheared magnetic fields is solved. Stratification due to gravity and transition region can penetrate from transition region into the corona.

- There are lots of new papers (roughly 80 new papers/day in astrophysics).
- Problem 1: Browsing this many papers is a lot of work for researchers.
- Problem 2: Researchers still miss important developments.

Information Filtering

- Information filtering systems automatically distinguish relevant from irrelevant items (emails, news articles, intelligence information) in large information streams.



Exploration vs. Exploitation

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- Exploration vs. exploitation tradeoff.

Traditional Approach

- Does not actively explore to get the most useful feedback, such as:
 - Exploration at the beginning followed by exploitation.
 - Exploration and exploitation periodically.

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 - Exploration at the beginning followed by exploitation.
 - Exploration and exploitation periodically.
- We present a Bayesian sequential decision-making formulation of this problem.

Our Results

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- An implementable policy, called Decompose Then Decide (DTD).

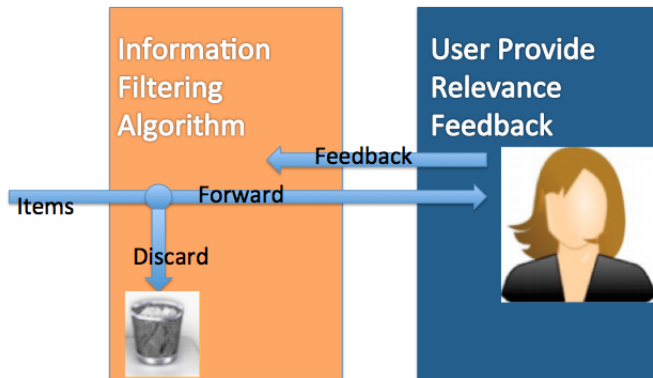
Our Results

- An instance-specific computational upper bound on the value of a Bayes-optimal strategy.
- An implementable policy, called Decompose Then Decide (DTD).
- Prove our upper bound is asymptotically tight.

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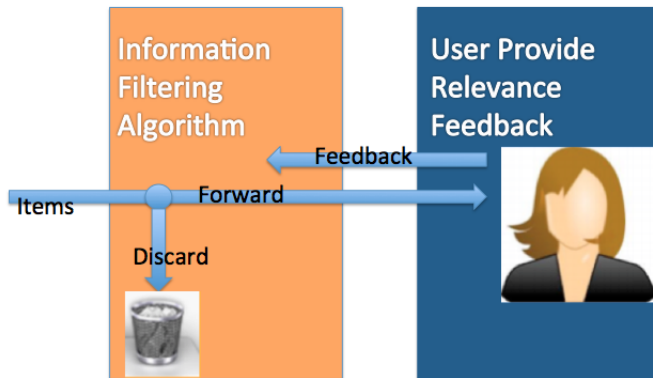
Bayesian Model

- We consider information filtering for a single user.



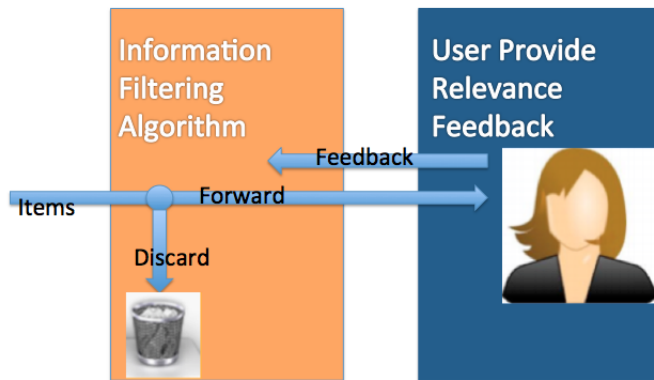
Bayesian Model

- We consider information filtering for a single user.
- The n^{th} arriving item is described by a k -dimensional feature vector $X_n = \{x_{1,n}, \dots, x_{k,n}\}$. We assume that $x_{i,n} \geq 0$ for all i and n and $\sum_{i=1}^k x_{i,n} = 1$.



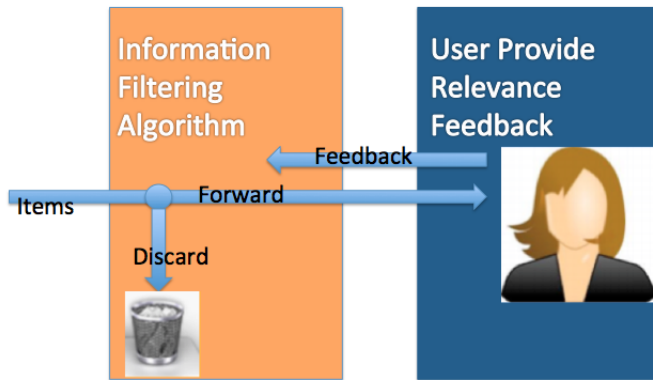
Bayesian Model

- Let $U_n \in \{0, 1\}$ represent this decision for the n^{th} item, where 1 means to forward and 0 means not to forward.



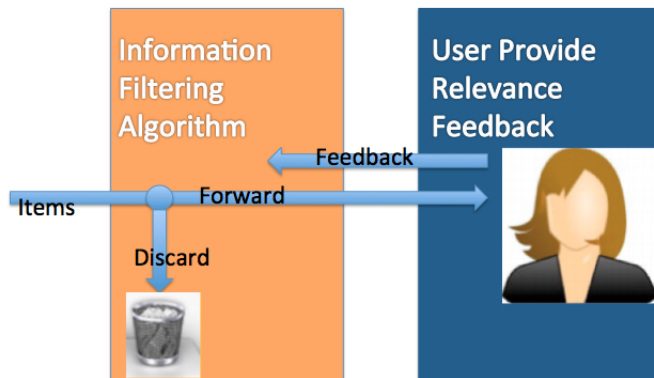
Bayesian Model

- Let $U_n \in \{0, 1\}$ represent this decision for the n^{th} item, where 1 means to forward and 0 means not to forward.
- Each time the system forwards, it pays a constant cost c and receives the item's relevance Y_n as a reward.



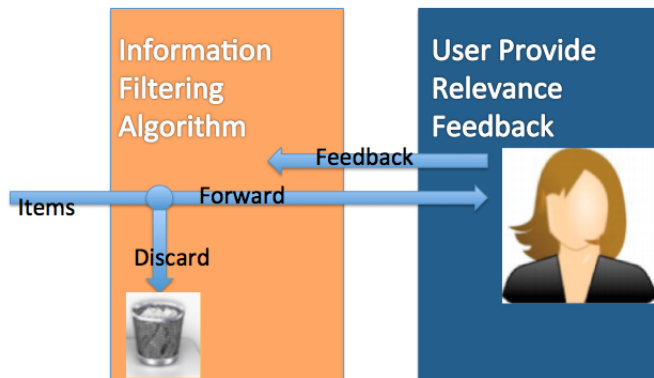
Bayesian Model

- Let $\theta = (\theta_1, \dots, \theta_k)$ denote the single user's latent preference vector for the k different features.



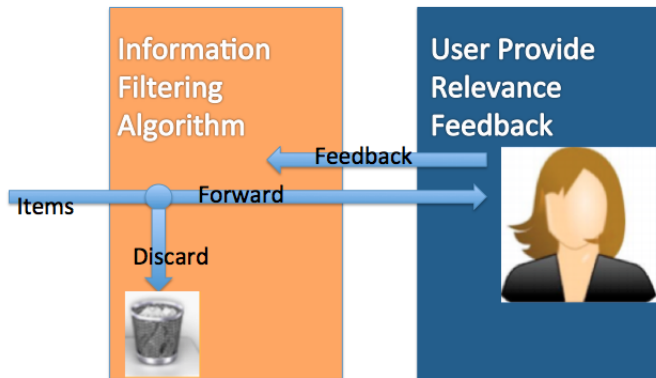
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- We assume $\theta \sim N(\mu_0, \Sigma_0)$.
- This relevance is modeled as $Y_n = \theta \cdot X_n + \epsilon_n$, where $\epsilon_n \sim N(0, \lambda^2)$ (Similar in spirit to Bayesian linear bandit).



Our Goal

- The decision of whether or not to forward the n^{th} item can only depend on our current X_n as well as the previous information $H_{n-1} = (U_m, X_m, U_m Y_m : m \leq n-1)$.

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- The decision of whether or not to forward the n^{th} item can only depend on our current X_n as well as the previous information $H_{n-1} = (U_m, X_m, U_m Y_m : m \leq n-1)$.
- Maximize the following:

$$\sup_{\pi \in \Pi} E^{\pi} \left[\sum_{n=1}^N U_n (Y_n - c) \right] \quad (1)$$

where E^{π} denotes the expected reward using policy π .

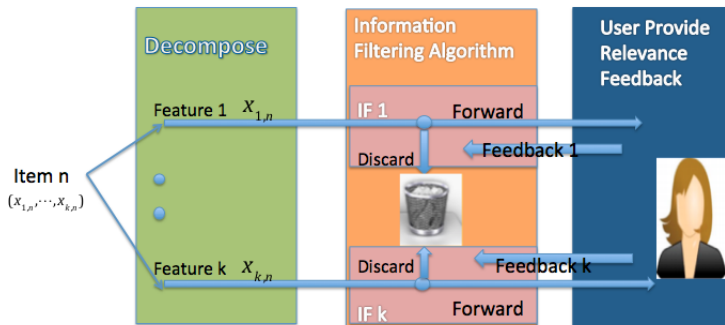
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Upper Bounds

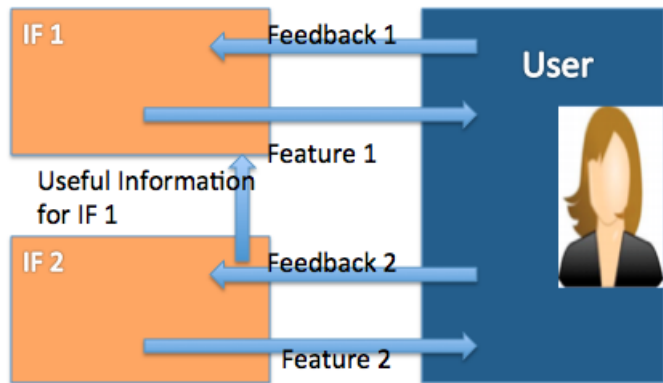
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Upper Bounds

- This problem can be solved using stochastic dynamic programming, but it suffers from curse of dimensionality.
- Our idea is:



Why we need information relaxation?



The maximum information Feedback2 can contain is θ_2 , which corresponds to the user's latent preference vector for the second feature.

Upper Bounds

- Define $Y_{i,n} = \theta_i + \epsilon_n^i$ and $\epsilon_n^i \sim N(0, \lambda^2)$ for $i = 1, 2, \dots, k$.
We may think of $Y_{i,n}$ as the reward that we would have seen if X_n were equal to e_i .

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We may think of $Y_{i,n}$ as the reward that we would have seen if X_n were equal to e_i .
- Rewrite
$$Y_n = \sum_{i=1}^k x_i \theta_i + \epsilon_n = \sum_{i=1}^k x_i (\theta_i + \epsilon_n^i) = \sum_{i=1}^k x_i Y_{i,n}.$$

Upper Bounds

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- Define $U_{j,n}$ to be decision made for the j^{th} feature of the n^{th} item.
- For each feature j , we now introduce a new set of policies Π_j and the decision in Π_j may depend on $\theta \cdot e_i$ for $\forall i \neq j$.

Upper Bounds

Theorem 1

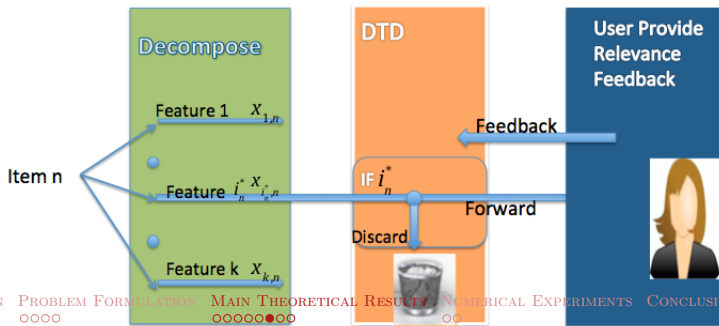
$$\sup_{\pi \in \Pi} E^{\pi} \left[\sum_{n=1}^N U_n(Y_n - c) \right] \leq \sum_{j=1}^k \sup_{\pi'' \in \Pi_j} E^{\pi''} \left[\sum_{n=1}^N U_{j,n}(x_{j,n} Y_{j,n} - x_{j,n} c) \right].$$

Decompose Then Decide (DTD)

DTD

Let π_i^* denote the optimal policy for the i^{th} single-feature subproblem. Then, DTD is defined as follows:

1. Find $i_n^* \in \arg \max \{X_n e_i, i = 1, \dots, k\}$.
2. Set $U_n = \pi_{i_n^*}^*(\mu_{i_n^*}, \sigma_{i_n^*})$.
3. Update μ, Σ respectively.



Asymptotic optimality

Let $(\mathbb{P}^l : l = 1, 2, \dots)$ be a sequence of probability distribution on R^k with $\mathbb{P}^l \rightarrow \mathbb{P}_*$ in distribution, where \mathbb{P}_* has support on the unit vectors.

- Let $U(\mathbb{P})$ denote the upper bound from Theorem 1 in which $X_n \sim \mathbb{P}$.
- Let $V(\mathbb{P})$ denote the value of an optimal policy (i.e., the value function), and $V^{DTD}(\mathbb{P})$ as the value of the DTD policy, for this same problem instance.

Asymptotic optimality

Theorem 2

Suppose that Σ_0 is a diagonal matrix. Then

$$\lim_{l \rightarrow \infty} (U(\mathbb{P}^l) - V(\mathbb{P}^l)) = 0,$$

$$\lim_{l \rightarrow \infty} V(\mathbb{P}^l) - V^{DTD}(\mathbb{P}^l) = 0,$$

$$\lim_{l \rightarrow \infty} V(\mathbb{P}^l) = U(\mathbb{P}_*) = V(\mathbb{P}_*).$$

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Numerical Experiments

- Simulated Data.
- Yelp Academic Dataset.

Numerical Experiments

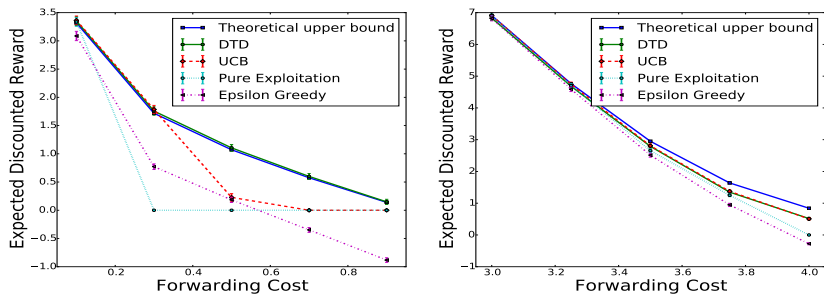


Figure : The left plot compares performance on simulated data and the right plot compares performance on the Yelp academic dataset.

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Conclusion

- An instance-specific computational upper bound.
- An implementable policy (DTD).
- Prove asymptotically optimality.

Question?

Thanks for your time!