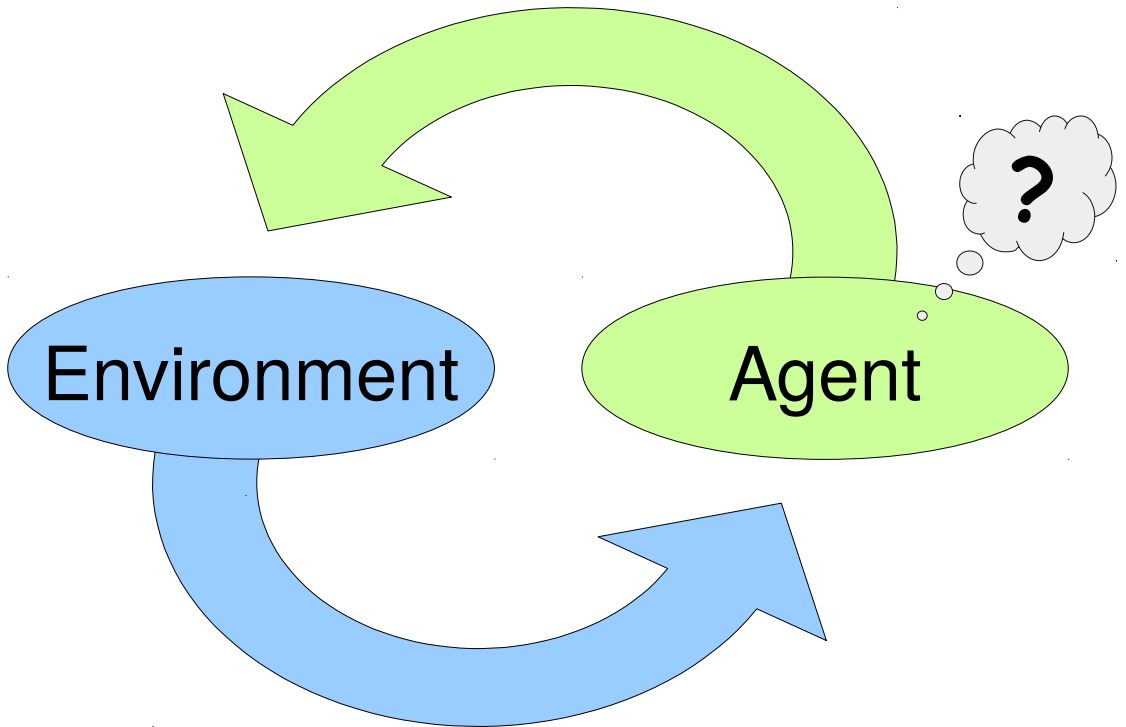


Actions



Observed states, rewards