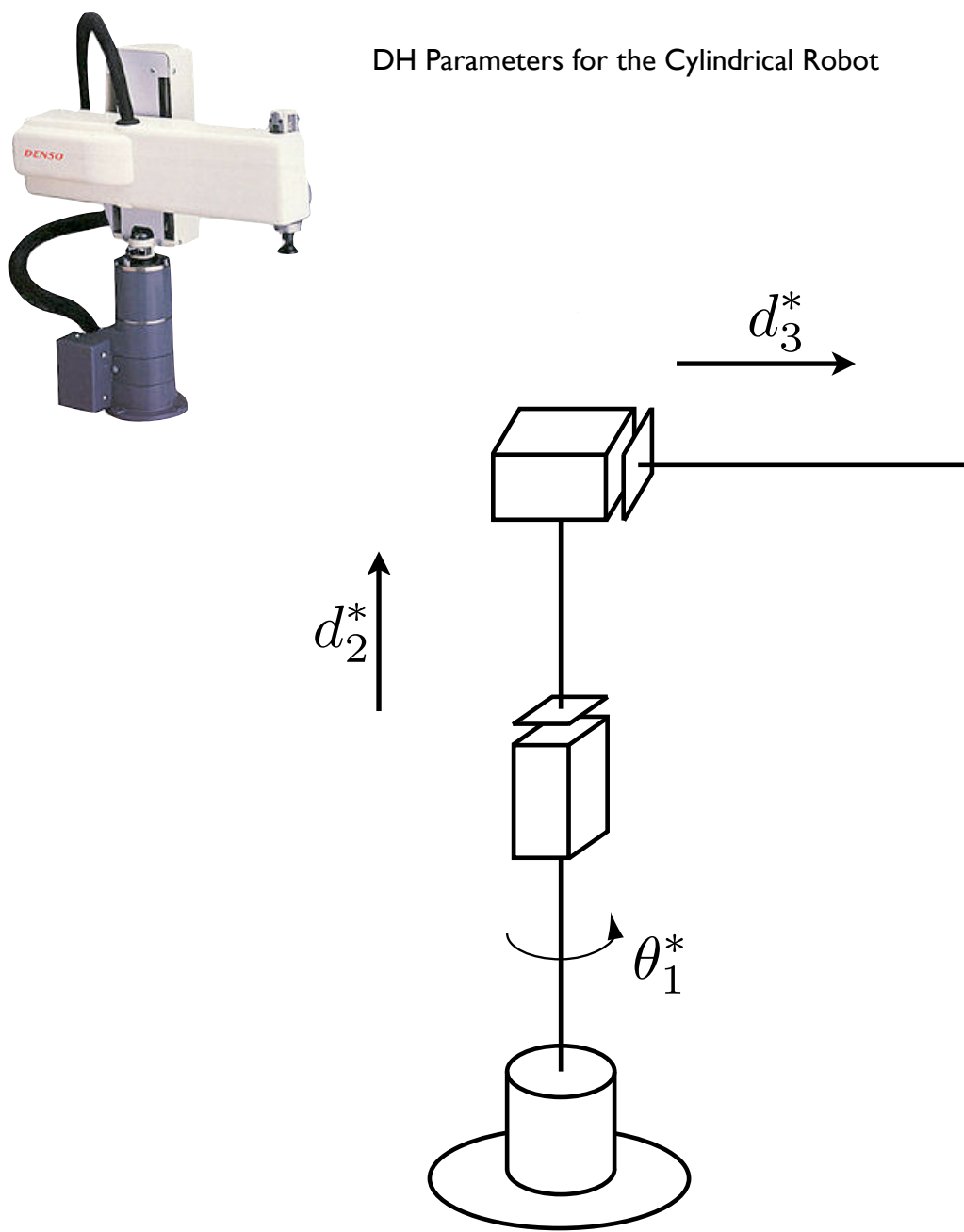


DH Parameters for the Cylindrical Robot



Link	a_i	α_i	d_i	θ_i
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DH Parameters for the Stanford Arm

