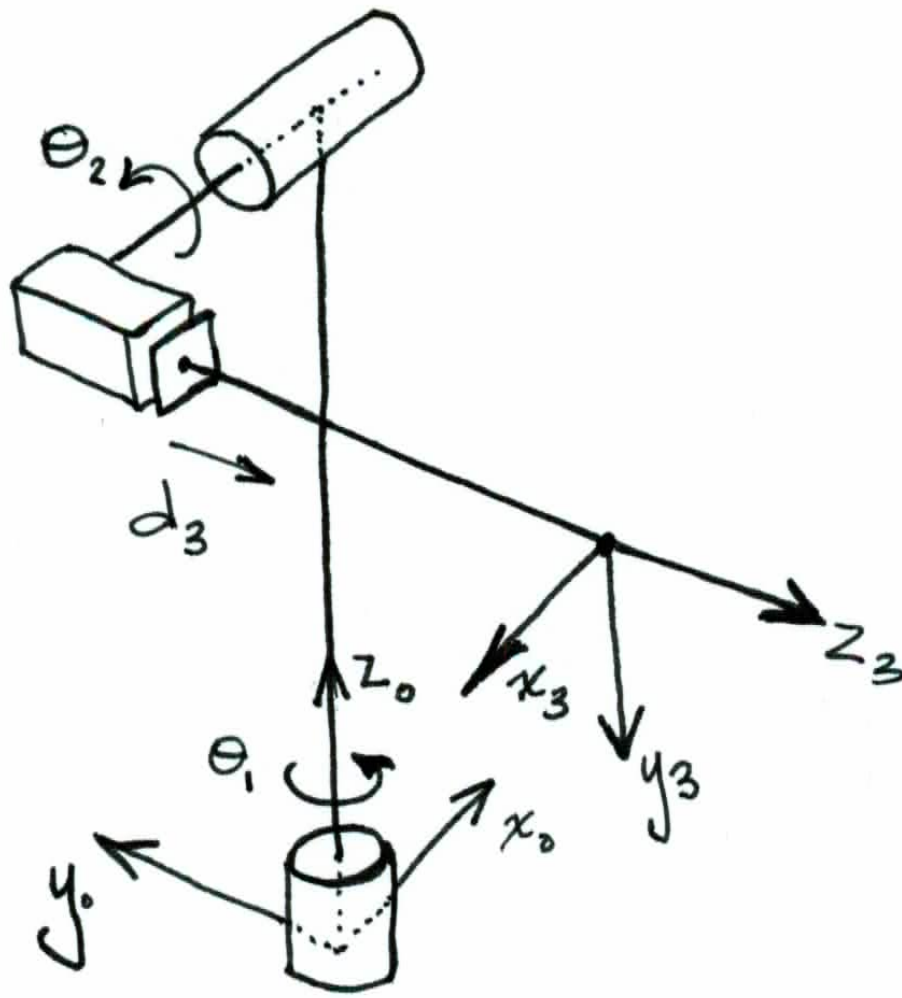


# DH Parameters for Another Robot



Link	$a_i$	$\alpha_i$	$d_i$	$\theta_i$
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