

LAB2

8 Puzzle problem

```
import heapq
import numpy as np.
```

```
goal = [[0,1,2], [3,4,5], [6,7,8]]
```

```
vis = set()
```

```
q = []
```

```
parent_map = {}
```

```
move_map = {}
```

```
def manhattan(curr):
```

```
    ans = 0
```

```
    pos = [goal[i][j] for i in range(3) for j in range(3)]
```

```
    for i in range(3):
```

```
        for j in range(3):
```

```
            x, y = pos[curr[i][j]]
```

```
            ans += abs(x-i) + abs(y-j)
```

```
    return ans
```

```
def move(curr):
```

```
    x, y = [i, j] for i in range(3) for j in range(3) if curr[i][j] == 0
```

```
    pos = [[0, -1, 'up'], [-1, 0, 'up'], [1, 0, 'down'], [0, 1, 'right']]
```

```
    for dx, dy, direction in pos:
```

```
        nx, ny = x+dx, y+dy
```

```
        if 0 <= nx < 3 and 0 <= ny < 3:
```

```
            curr1 = [row[:] for row in curr]
```

```
            curr1[x][y], curr1[nx][ny] = curr1[nx][ny], curr1[x][y]
```

```
            tuple_curr1 = tuple(map(tuple, curr1))
```

```
            if tuple_curr1 not in vis:
```

```
                heapq.heappush(q, (manhattan(curr1), tuple_curr1))
```

```
                vis.add(tuple_curr1)
```

```
                parent_map[tuple_curr1] = curr
```

move_map[tuple(map(tuple, curr))] = directions

```
def dfs(curr):
    vis.add(tuple(map(tuple, curr)))
    if curr == goal:
        return True
    moves(curr)
    if q:
        curr = heapq.heappop(q)[1]
        if dfs(curr):
            return True
    return False
```

```
def display_board(board):
    print("\n+---+---+---+")
    for row in board:
        print(" ".join(str(x) if x != 0 else "." for x in row) + "\n")
    print("\n+---+---+---+")
```

c = [[3, 0, 2], [5, 6, 7], [8, 4, 1]]

dfs(c)

result_path = []

directions = []

state = goal

while state:

result_path.append(state)

directions.append(move_map.get(tuple(map(tuple, state)), None))

state = param_map.get(tuple(map(tuple, state)))

for ind, (state, direction) in enumerate(reversed(list(result_path, directions)))):

print(f"Step {ind}:")

display_board(state)

if ind == 0:

```
print("initial state")
if drawm:
    print(f"move empty space {drawm[4]}")
print()
print(f"steps taken: {len(result-path)-1}") //
```

O/P

Trying depth limit 0

1

2

3

4

5

Solution found at depth 5 with path:

1 2 3

5 6 0

4 7 8

1 2 3

4 5 6

7 8 0

1 2 3

5 0 6

4 7 8

1 2 3

4 5 6

7 0 8

1 2 3

0 5 6

4 7 8

1 2 3

4 5 6

7 8 0

True

Iterative Deepening - Depth first search

```
class Graph:
```

```
    def __init__(self, vertices):
```

```
        self.V = vertices
```

```
        self.graph = {i: [] for i in range(vertices)}
```

```
    def add_edge(self, u, v):
```

```
        self.graph[u].append(v)
```

```
    def dfs(self, src, target, limit):
```

```
        if src == target:
```

```
            return True
```

```
        if limit <= 0:
```

```
            return False
```

```
        for neighbor in self.graph[src]:
```

```
            if self.dfs(neighbor, target, limit-1):
```

```
                return True
```

```
        return False
```

```
    def iddfs(self, src, target, max_depth):
```

```
        for depth in range(max_depth+1):
```

```
            if self.dfs(src, target, depth):
```

```
                return True
```

```
        return False
```

```
g = Graph(7)
```

```
g.add_edge(0, 1)
```

```
g.add_edge(0, 2)
```

```
g.add_edge(4, 3)
```

```
g.add_edge(1, 4)
```

```
g.add_edge(2, 5)
```

```
g.add_edge(2, 6)
```

```
src = 0
```

```
target = 6
```

max-depth = 3

if g. saddle(srl, target, max-depth) \neq 0
print-C¹¹ "target is found within depth (max-depth)"
else:

print-C¹¹ "Target is not found within depth (max-depth)"

O/P

Target is found within depth 3.

Solutions for the search problem is provided.

2.

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