Stanford CS 229, Public Course, Problem Set 1

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a)

Find the Hessian of the cost function $J(\theta) = \frac{1}{2} \sum_{i=1}^{m} (\theta^T x^{(i)} - y^{(i)})^2$

We know that $H_{jk} = \frac{\partial^2 J(\theta)}{\partial \theta_j \theta_k}$

First find $\frac{\partial J(\theta)}{\partial \theta_k}$,

$$\begin{split} \frac{\partial J(\theta)}{\partial \theta_k} &= \frac{1}{2} \sum_{i=1}^m \frac{\partial}{\partial \theta_k} (\theta^T x^{(i)} - y^{(i)})^2 \\ &= \frac{1}{2} \sum_{i=1}^m 2(\theta^T x^{(i)} - y^{(i)}) (x_k^{(i)}) \\ &= \sum_{i=1}^m (\theta^T x^{(i)} - y^{(i)}) (x_k^{(i)}) \end{split}$$

Now find $\frac{\partial^2 J(\theta)}{\partial \theta_j \theta_k}$,

$$\begin{split} \frac{\partial^2 J(\theta)}{\partial \theta_j \theta_k} &= \frac{\partial}{\partial \theta_j} (\frac{\partial J(\theta)}{\partial \theta_k}) \\ &= \sum_{i=1}^m \frac{\partial}{\partial \theta_j} ((\theta^T x^{(i)} - y^{(i)}) (x_k^{(i)})) \\ &= \sum_{i=1}^m x_j^{(i)} x_k^{(i)} \text{ for } 1 \leq j \leq n \text{ and } 1 \leq k \leq n \end{split}$$

Therefore

$$H = \begin{bmatrix} \sum_{i=1}^{m} x_1^{(i)} x_1^{(i)} & \sum_{i=1}^{m} x_2^{(i)} x_1^{(i)} & \cdots & \sum_{i=1}^{m} x_n^{(i)} x_1^{(i)} \\ \sum_{i=1}^{m} x_1^{(i)} x_2^{(i)} & \sum_{i=1}^{m} x_2^{(i)} x_2^{(i)} & \cdots & \sum_{i=1}^{m} x_n^{(i)} x_2^{(i)} \\ \vdots & \vdots & \ddots & \vdots \\ \sum_{m} x_1^{(i)} x_n^{(i)} & \sum_{i=1}^{m} x_2^{(i)} x_n^{(i)} & \cdots & \sum_{i=1}^{m} x_n^{(i)} x_n^{(i)} \end{bmatrix}$$

$$= \begin{bmatrix} x_1^{(i)} & \cdots & x_1^{(n)} \\ \vdots & \ddots & \vdots \\ x_m^{(1)} & \cdots & x_m^{(n)} \end{bmatrix} \begin{bmatrix} x_1^{(1)} & \cdots & x_m^{(1)} \\ \vdots & \ddots & \vdots \\ x_1^{(n)} & \cdots & x_m^{(n)} \end{bmatrix}$$

$$= X^T X$$

b)

Show that the first iteration of Newton's method gives us $\theta^* = (X^T X)^{-1} X^T \vec{y}$, the solution to our least squares problem.

One iteration of Newton's Method:

 $\theta := \theta - H^{-1} \nabla_{\theta} J(\theta)$

Therefore,

$$\theta^* = \theta - (X^T X)^{-1} \begin{bmatrix} \frac{\partial J(\theta)}{\partial \theta_1} \\ \vdots \\ \frac{\partial J(\theta)}{\partial \theta_m} \end{bmatrix}$$

$$= \theta - (X^T X)^{-1} \begin{bmatrix} \sum_{i=1}^m (x_1^{(i)} \theta^T x^{(i)} - x_1^{(i)} y^{(i)}) \\ \vdots \\ \sum_{i=1}^m (x_m^{(i)} \theta^T x^{(i)} - x_m^{(i)} y^{(i)}) \end{bmatrix}$$

let $\theta = \vec{0}$ (initialize θ)

$$= -(X^T X)^{-1} \begin{bmatrix} \sum_{i=1}^m (-x_1^{(i)} y^{(i)}) \\ \vdots \\ \sum_{i=1}^m (-x_m^{(i)} y^{(i)}) \end{bmatrix}$$
$$= (X^T X)^{-1} \begin{bmatrix} \sum_{i=1}^m (x_1^{(i)} y^{(i)}) \\ \vdots \\ \sum_{i=1}^m (x_m^{(i)} y^{(i)}) \end{bmatrix}$$
$$= (X^T X)^{-1} X^T \vec{y}$$

$\mathbf{2}$

\mathbf{a}

See q2/ folder

\mathbf{b}

At low values of τ , the classification boundaries are clustered around the positive training examples. As you increase τ , these boundaries begin to merge into bigger areas, i.e. the classification boundaries look less 'local' to the positive training examples. At high values of τ , the classification boundary is essentially a straight line dividing positive and negative classes.

The decision boundary of unweighted logistic regression would look like the plots with the highest values of τ . This is because as τ approaches infinity, the weight function $w^{(i)}$ goes to 1 for every training example, making the regression unweighted (that is, every training example gets the same weight).