

# N- Body Problem

**Microprocessor Systems** 

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#### **Motivation**

- Understanding of
  - Arm Cortex M4 Tiva C Launchpad
  - PC Serial Communication using any programming language.
- Real time computation and communication between a microprocessor and host
- Applications
  - Astrophysical applications which use adaptive time steps
  - N-body algorithm have numerous application in molecular dynamics and plasma physics

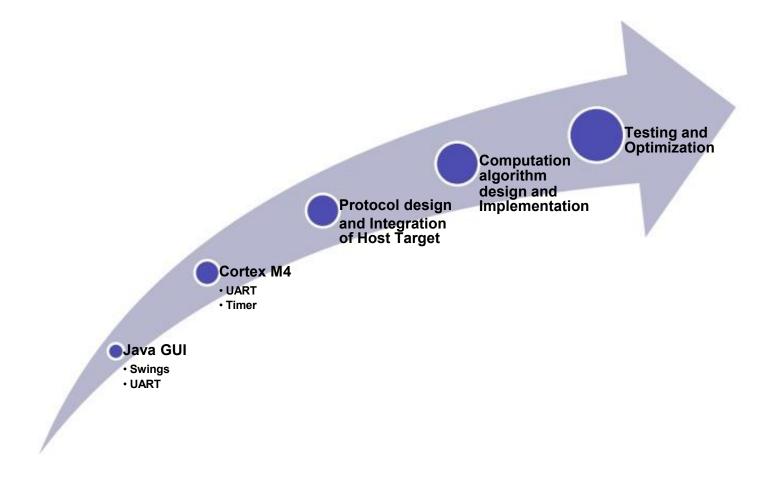


#### **Problem Description**

- Simulate N body Problem
- -Use the Launchpad to simulate the motion of a given set of planetary objects as governed by the effects of the forces of gravity on each other.
- ARM Cortex-M4 (Tiva C Launchpad) to be used to
  - –Two separate modes are to be made
  - Computation mode
  - Visualization mode



# **Technical Approach**

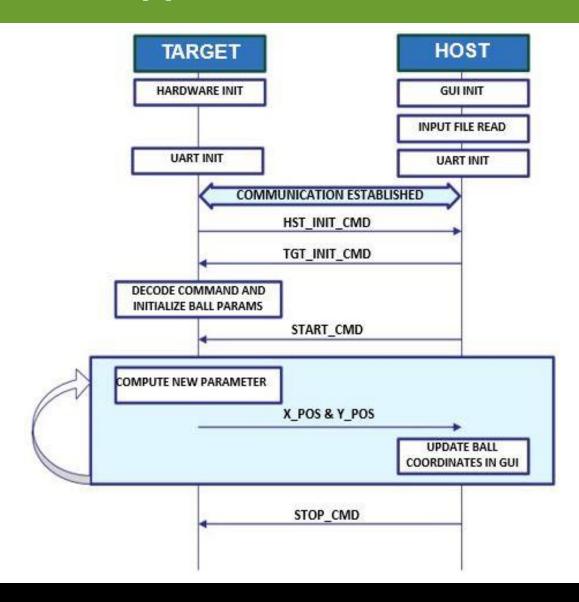


### **Composition & Tasks**

- GUI
  - Java Swing 8
- Microcontroller
  - ARM Cortex M-4
- Communication
  - UART



## **Technical Approach**



#### **Design – JAVA**

- Developed required skills required for GUI development in JAVA
- Develop method of integration of JAVA and Microcontroller.
- Develop Communication protocol between Microcontroller and JAVA
- Real time simulation of the ball according to the values sent by microcontroller

#### **Design - Microcontroller**

Receive parameter from JAVA through input text file.

 Develop algorithm for the computation of N-Body Problem

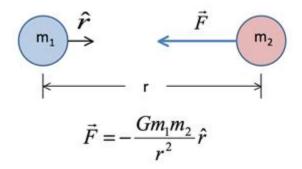
 Real time computation of the position of the N-body based on the gravitational forces due to n bodies.

 Send the final computed coordinate values of the n bodies



#### Computation

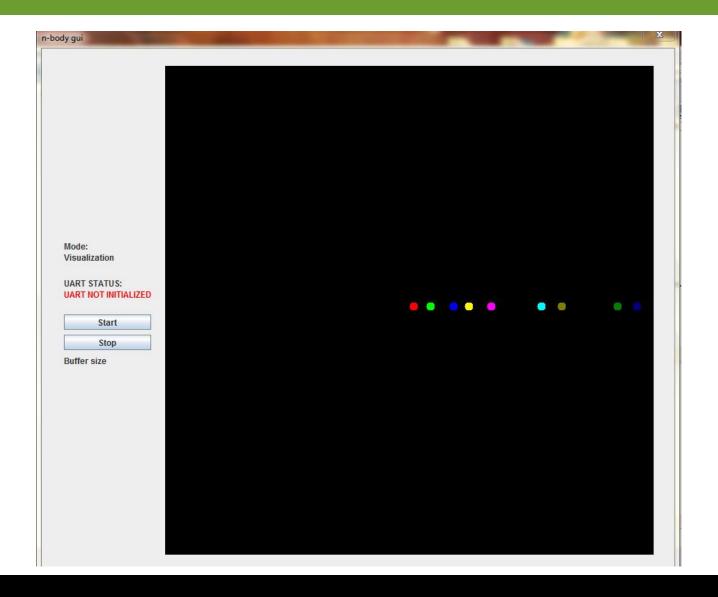
#### **Newton's law for Universal Gravitation**



#### Formula for computation of position of N-Body

$$\ddot{\mathbf{y}}_i = G \sum_{j=1, j \neq i}^{N} \frac{m_j(\mathbf{y}_j - \mathbf{y}_i)}{|\mathbf{y}_j - \mathbf{y}_i|^3},$$

#### Results





#### **Challenges We Faced**

- Communication
  - UART
  - Real Time Updating
- Collision algorithm
- Decoding of host and target commands
- Accuracy
- Making the design scalable for dynamic number of balls
- Optimization: Max number of balls



