

# Real Time Data Transfer to Google Drive

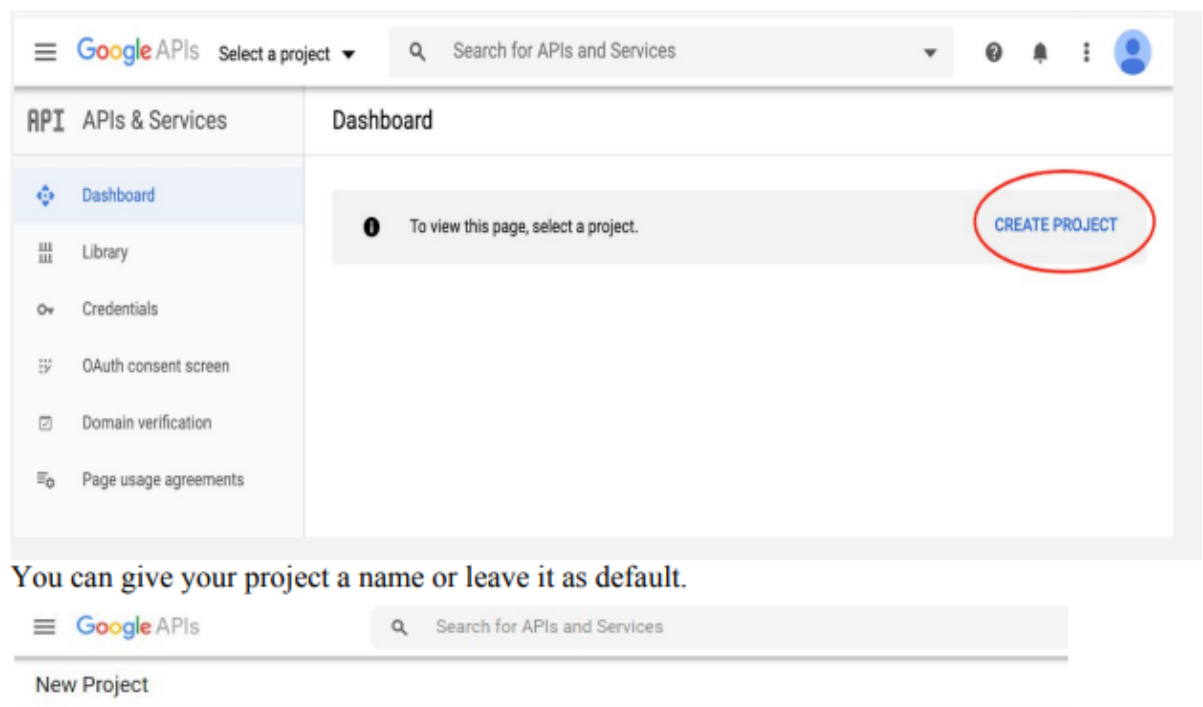
## Using “Python”

To visualize our sensor(Ex: Ultrasonic sensor, Temperature sensor) data from any where , we are transferring the sensor data to our personal Google Drive.

For the above process, this are the following steps.

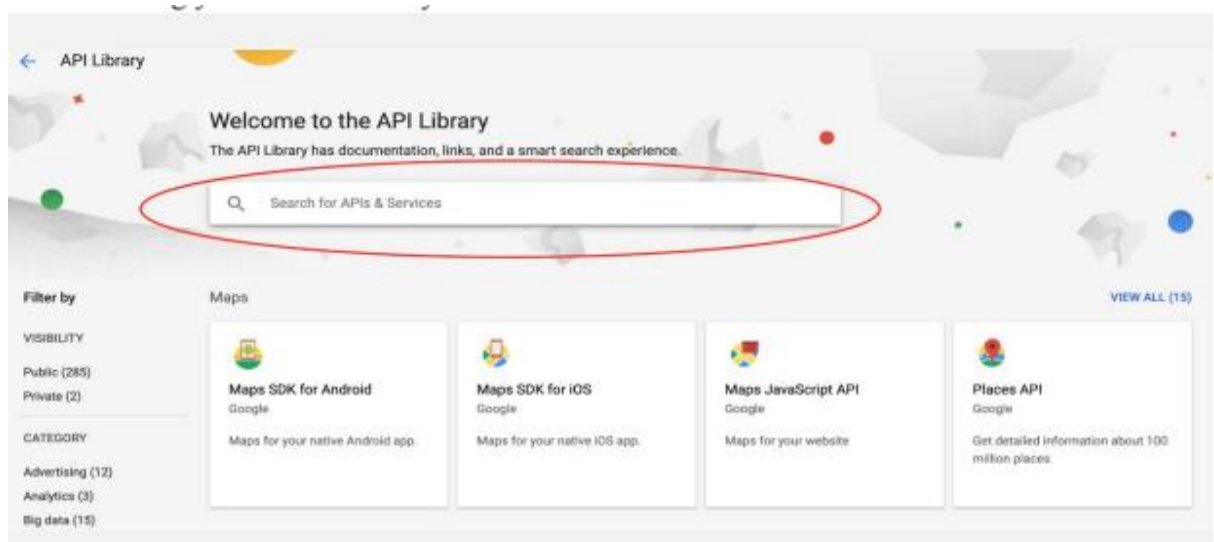
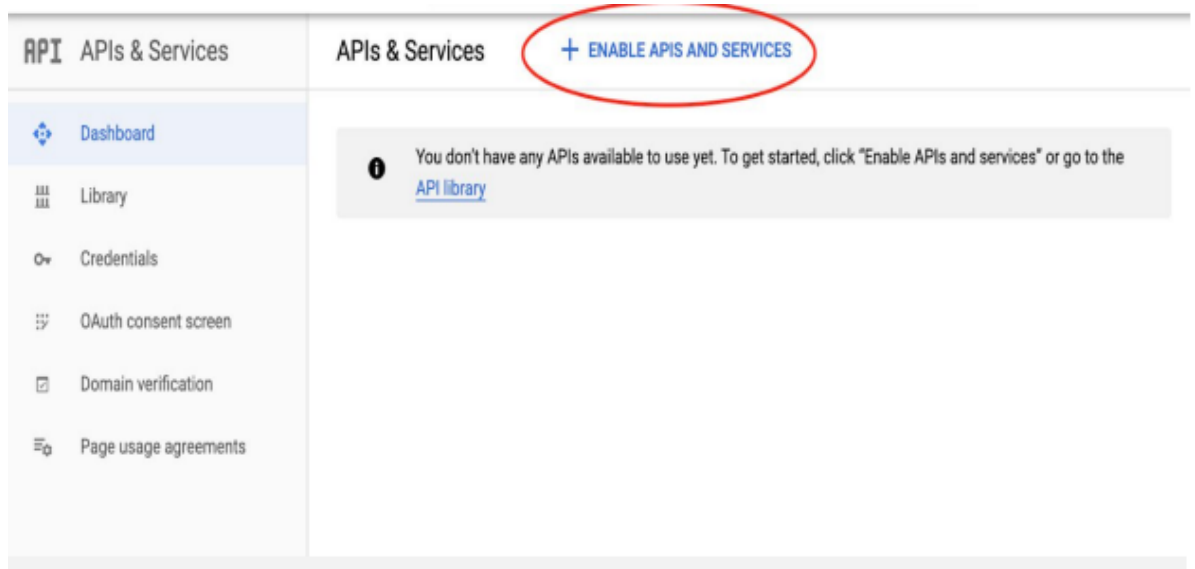
**Step 1:** First, we need to get the authentication files for Google Service API, so our Python code can access Google Drive. To do that, we need to :

- i. Create a new project in **Google Developer Console**(website) by clicking “CREATE PROJECT” as follows.



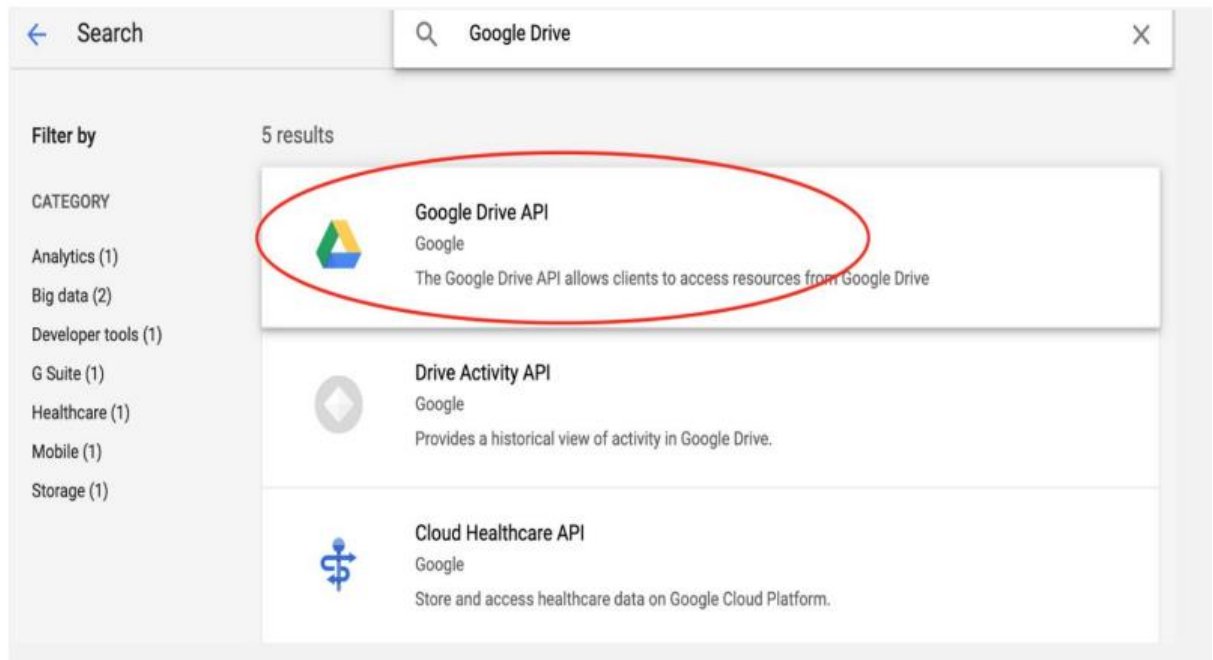
- ii. Enable APIs and Services by clicking the “**ENABLE APIS AND SERVICES**” as indicated by the red circle in the following picture.

That will bring you the API library as below

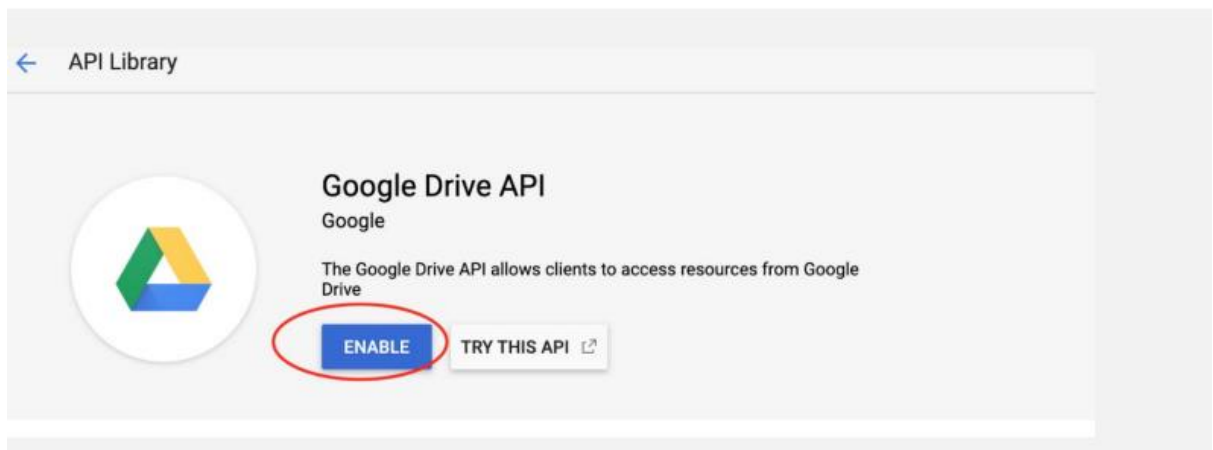


iii.

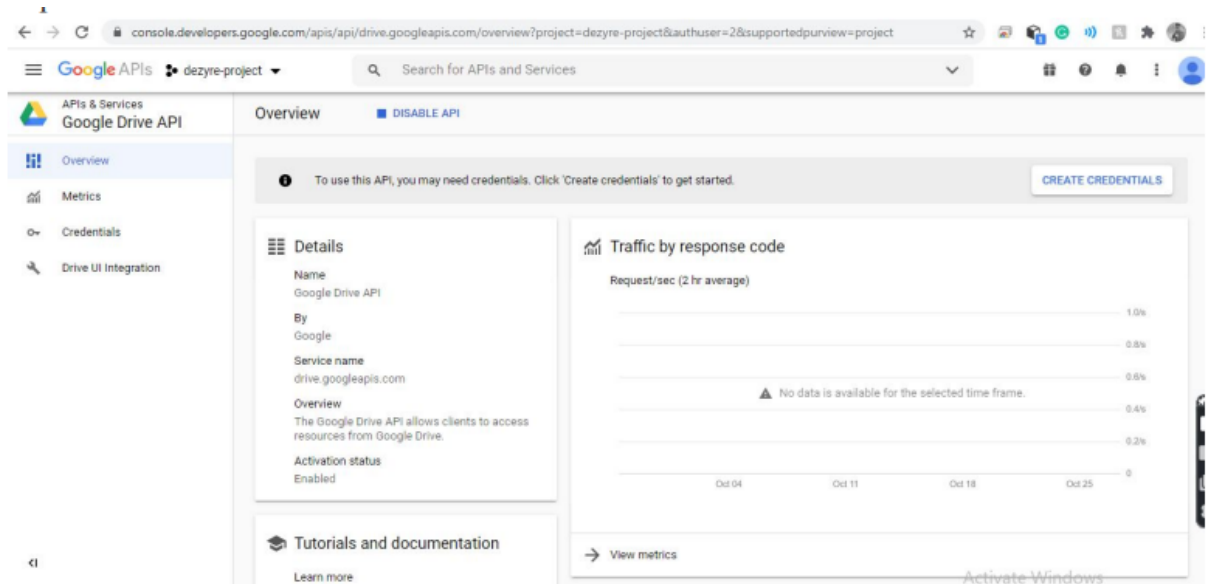
Search “Google Drive” in the API library (indicated by the red circle in the picture). You’ll get the following snapshot.



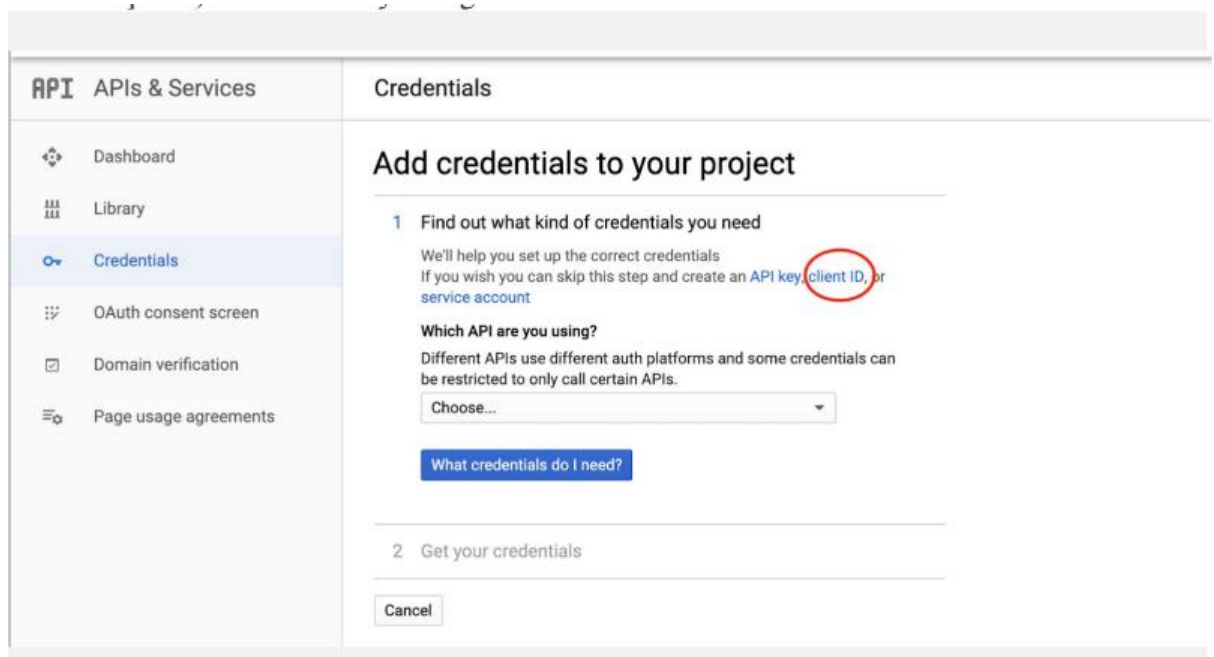
Click the “Google Drive API” icon and it will bring you to the next step as follows.



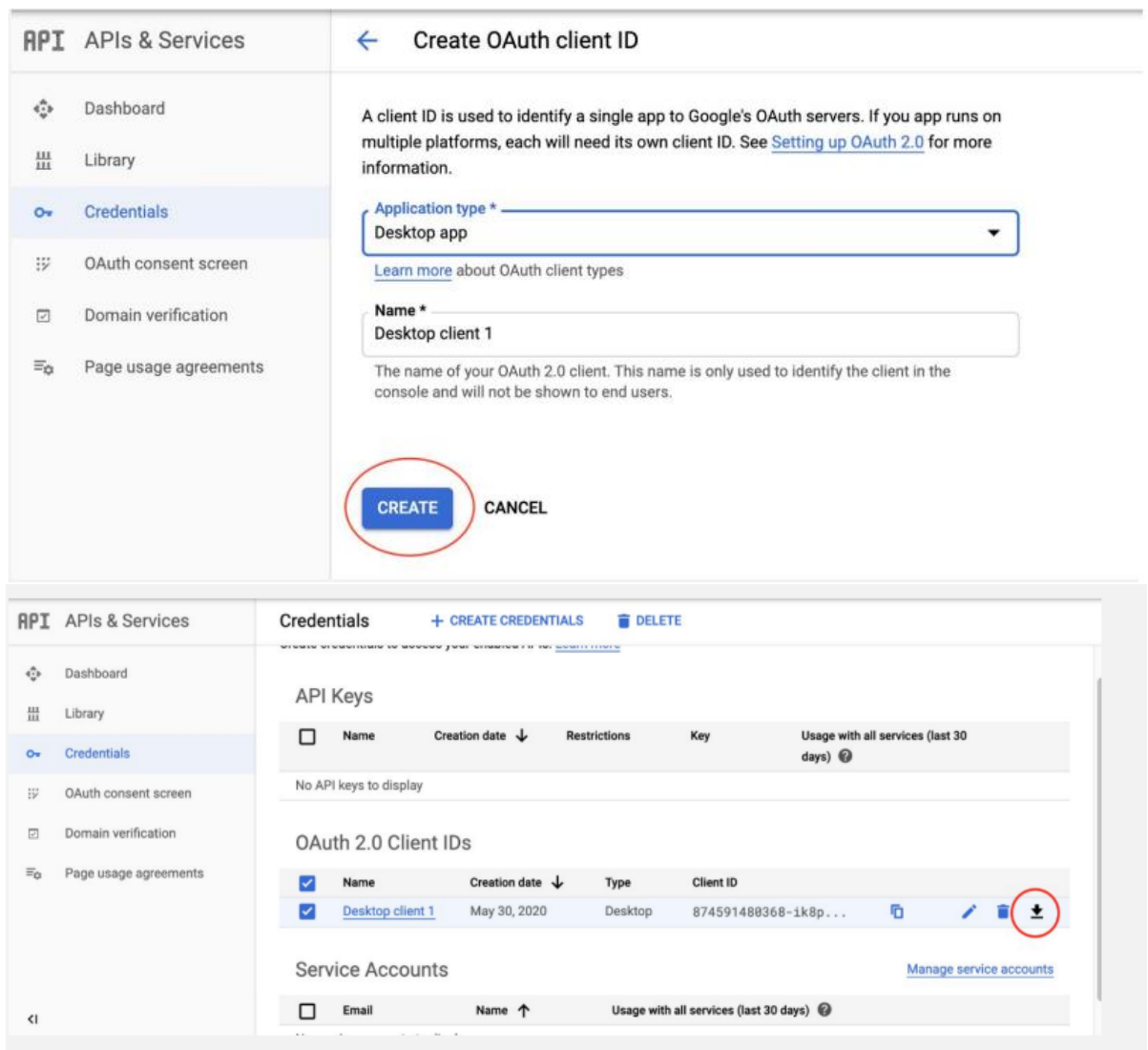
Then click “ENABLE”, which will enable your Google Drive API service. You’ll get to the next step as follows.



- iv. Create credentials by clicking the “CREATE CREDENTIALS” icon (indicated by red circle in above snapshot). Here’s what you’ll get.



In the above snapshot, we need to click “client ID” as that’s the Python program needs. Then click “CREATE” and download the JSON file as shown by the following snapshots  
**NOTE :** In the above step sometimes it doesn’t show the client id options, at that time you just need to choose the Google drive in the choose options.



The downloaded JSON file is the one we need for our Python code to access Google Drive.

- v. Now open the python Terminal and install the PyDrive Module.

By using this command : **pip install pydrive**

The google authentication code will do authentication and list all files in your Google Drive. Note that every time you run the following program, the code will open a web browser to ask you to input your Google account and password.

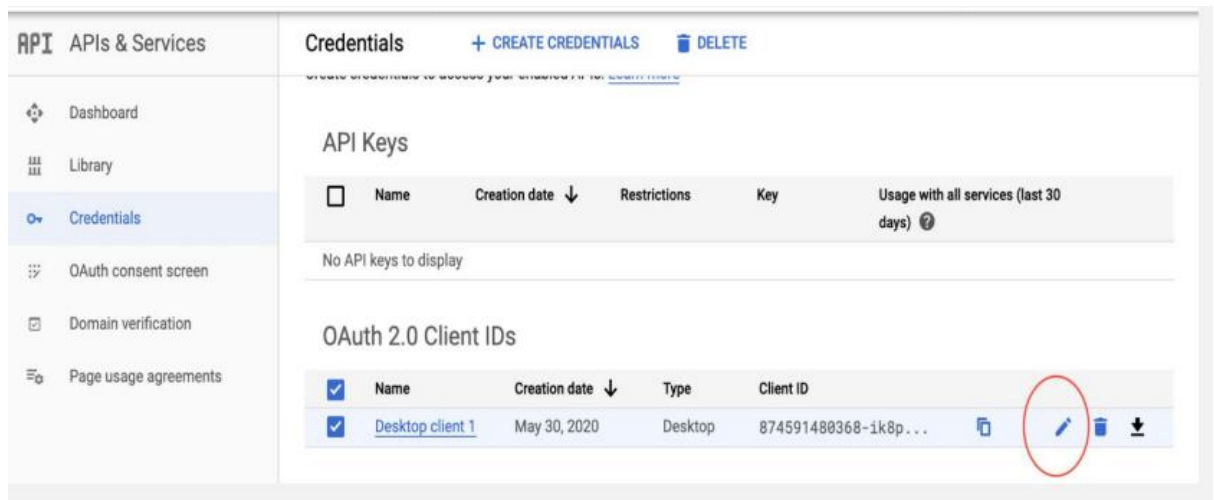
To avoid inputting passwords every time, we can create a **settings.yaml** file to save all the credentials.

```

client_config_backend: settings
client_config:
  client_id: your_client_id
  client_secret: your_client_secret
save_credentials_backend: file
save_credentials_file: credentials.json
get_refresh_token: True
oauth_scope:
  - https://www.googleapis.com/auth/drive.file

```

The client\_id and client\_secret can be found by clicking the editing icon in the following picture.



The Python program will ask you to input your Google password again. Then it will create a credentials.json file. Next time, Python will just pick up that file to finish authentication automatically. Therefore, you don't need to type your password again.

**Step 2 :** Here is the python code.

```

#Libraries
import RPi.GPIO as GPIO
import time

from pydrive.auth import GoogleAuth
from pydrive.drive import GoogleDrive

# Rename the downloaded JSON file to client_secrets.json which downloaded from
the googleapi
# The client_secrets.json file needs to be in the same directory as the
script.
gauth = GoogleAuth()

```

```

gauth.LocalWebserverAuth()
drive = GoogleDrive(gauth)

#GPIO Mode (BOARD / BCM)
GPIO.setmode(GPIO.BCM)
#set GPIO Pins
GPIO_TRIGGER = 23
GPIO_ECHO = 24
#set GPIO direction (IN / OUT)
GPIO.setup(GPIO_TRIGGER, GPIO.OUT)
GPIO.setup(GPIO_ECHO, GPIO.IN)
#string name
def distance():
    # set Trigger to HIGH
    GPIO.output(GPIO_TRIGGER, True)
    # set Trigger after 0.01ms to LOW
    time.sleep(0.00001)
    GPIO.output(GPIO_TRIGGER, False)
    StartTime = time.time()
    StopTime = time.time()
    # save StartTime
    while GPIO.input(GPIO_ECHO) == 0:
        StartTime = time.time()
        # save time of arrival
    while GPIO.input(GPIO_ECHO) == 1:
        StopTime = time.time()
    # time difference between start and arrival
    TimeElapsed = StopTime - StartTime
    # multiply with the sonic speed (34300 cm/s)
    # and divide by 2, because there and back
    distance = (TimeElapsed * 34300) / 2
    return distance

if __name__ == '__main__':
    while True:
        try:
            while True:
                dist = distance()
                print ("Measured Distance = %.1f cm" % dist)

                if(dist<10):
                    print("you are close to Object")

                time.sleep(1)
                # Reset by pressing CTRL + C
                dis = str(dist) #{0:4d}

```

```

        #{1:3}%".format (adcout, percent)
    reporttime = (time.strftime("%H:%M:%S"))
    csvresult = open("paste the path of the folder where code was
saved/Ultrasonic_data22.csv", "a")
    #csvresult.write(dis + "," + closer + " , " + reporttime + "\n")
    csvresult.write(dis + "," + reporttime + "\n")
    csvresult.close
    # # Upload files to your Google Drive
    upload_file_list = ["Ultrasonic_data22.csv"]
    for upload_file in upload_file_list:
        gfile = drive.CreateFile({'parents': [{'id': 'google
folder id where you want to store'}]})
        # Read file and set it as a content of this instance.
        gfile.SetContentFile(upload_file)
        gfile.Upload() # Upload the file.
except KeyboardInterrupt:
    print("Measurement stopped by User")
    GPIO.cleanup()

```

**Note:** while running the code, you must the save the **settings.yml** file , **client\_secrets.json** (renaming the downloaded json file) in the same folder.

And you must change the code as per your sensor connections(Here I am using ultrasonic sensor with Raspbeery\_pi board.)

**google folder id where you want to store :** To find the id open the folder in the google drive where you want to store after opening you will find the path of the folder in the google search bar as

[https://drive.google.com/drive/folders/1T\\_dwqjhKSazj\\_3m-ylthSeZgmbjbG2KQ](https://drive.google.com/drive/folders/1T_dwqjhKSazj_3m-ylthSeZgmbjbG2KQ)

The black part of the above url is your folder id

**By :** Nagarjuna Bantu.

Reference : <https://www.projectpro.io/recipes/upload-files-to-google-drive-using-python>