

# Hash functions

Search + Hash

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Searching algorithms

Sequential Search

Interval Search

Hash structure

Basic concepts

Hash functions

Direct Hashing

Modulo division

Digit extraction

Mid-square

Mid-square

Folding

Rotation

Pseudo-random

Collision resolution

Open addressing

Bucket hashing

Linked list resolution

# Hash functions

- Direct hashing
- Modulo division
- Digit extraction
- Mid-square
- Folding
- Rotation
- Pseudo-random

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# Direct Hashing

The address is the key itself:  
 $hash(Key) = Key$

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# Direct Hashing

- **Advantage:** there is no collision.
- **Disadvantage:** the address space (storage size) is as large as the key space.

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# Modulo division

$$Address = Key \bmod listSize$$

- Fewer collisions if *listSize* is a prime number.
- Example:  
Numbering system to handle 1,000,000 employees  
Data space to store up to 300 employees  
 $hash(121267) = 121267 \bmod 307 = 2$

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# Digit extraction

*Address = selected digits from Key*

Example:

379452 → 394

121267 → 112

378845 → 388

160252 → 102

045128 → 051

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# Mid-square

*Address = middle digits of  $Key^2$*

Example:

$$9452 * 9452 = 89340304 \rightarrow 3403$$

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# Mid-square

- **Disadvantage:** the size of the  $Key^2$  is too large.
- **Variations:** use only a portion of the key.

Example:

$$379452: 379 * 379 = 143641 \rightarrow 364$$

$$121267: 121 * 121 = 014641 \rightarrow 464$$

$$045128: 045 * 045 = 002025 \rightarrow 202$$





# Folding

The key is divided into parts whose size matches the address size.

Example:

Key = 123—456—789

*fold shift*

$123 + 456 + 789 = 1368$

→ 368

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# Folding

The key is divided into parts whose size matches the address size.

Example:

Key = 123—456—789

*fold shift*

$$123 + 456 + 789 = 1368$$

→ 368

*fold boundary*

$$321 + 456 + 987 = 1764$$

→ 764

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# Rotation

- Hashing keys that are identical except for the last character may create synonyms.
- The key is rotated before hashing.

original key	rotated key
60010 <b>1</b>	<b>1</b> 60010
60010 <b>2</b>	<b>2</b> 60010
60010 <b>3</b>	<b>3</b> 60010
60010 <b>4</b>	<b>4</b> 60010
60010 <b>5</b>	<b>5</b> 60010



# Rotation

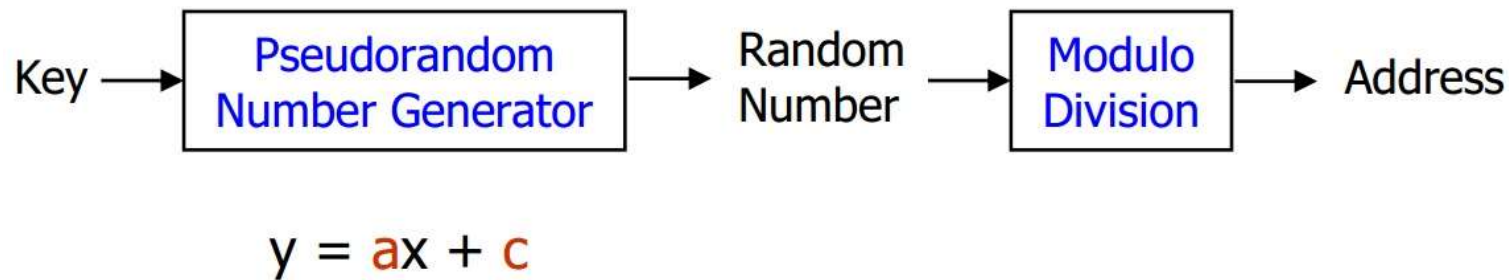
- Used in combination with fold shift.

original key	rotated key
600101 → 62	160010 → 26
600102 → 63	260010 → 36
600103 → 64	360010 → 46
600104 → 65	460010 → 56
600105 → 66	560010 → 66

Spreading the data more evenly across the address space.



# Pseudo-random



For maximum efficiency,  $a$  and  $c$  should be prime numbers.

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# Pseudo-random

Example:

Key = 121267

a = 17

c = 7

listSize = 307

$$\begin{aligned}\text{Address} &= ((17 * 121267 + 7) \bmod 307) \\ &= (2061539 + 7) \bmod 307 \\ &= 2061546 \bmod 307 \\ &= 41\end{aligned}$$

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# Collision resolution

- Except for the direct hashing, none of the others are **one-to-one mapping**  
→ Requiring collision resolution methods
- Each collision resolution method can be used **independently** with each hash function

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# Collision resolution

- Closed Hashing
  - Open addressing
  - Bucket hashing
- Open Hashing
  - Linked list resolution

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# Open addressing

When a collision occurs, an **unoccupied element** is searched for placing the new element in.

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# Open addressing

Hash function:

$$h : U \rightarrow \{0, 1, 2, \dots, m - 1\}$$

set of keys

addresses

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# Open addressing

Hash and probe function:

$$hp : U \times \{0, 1, 2, \dots, m-1\} \rightarrow \{0, 1, 2, \dots, m-1\}$$

set of keys      probe numbers

addresses

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# Open Addressing

```
1 Algorithm hashInsert(ref T [array], val k [key])
2 Inserts key k into table T.

3 i = 0
4 while i < m do
5     j = hp(k, i)
6     if T[j] = nil then
7         T[j] = k
8         return j
9     else
10        i = i + 1
11    end
12 end
13 return error: "hash table overflow"
14 End hashInsert
```

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# Open Addressing

```
1 Algorithm hashSearch(val T [array], val k [key])
2 Searches for key k in table T.

3 i = 0
4 while i < m do
5     j = hp(k, i)
6     if T[j] = k then
7         | return j
8     else if T[j] = nil then
9         | return nil
10    else
11        | i = i + 1
12    end
13 end
14 return nil
15 End hashSearch
```

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# Open Addressing

There are different methods:

- Linear probing
- Quadratic probing
- Double hashing
- Key offset

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## Linear Probing

- When a home address is occupied, go to the **next address** (the current address + 1):

$$hp(k, i) = (h(k) + i) \bmod m$$

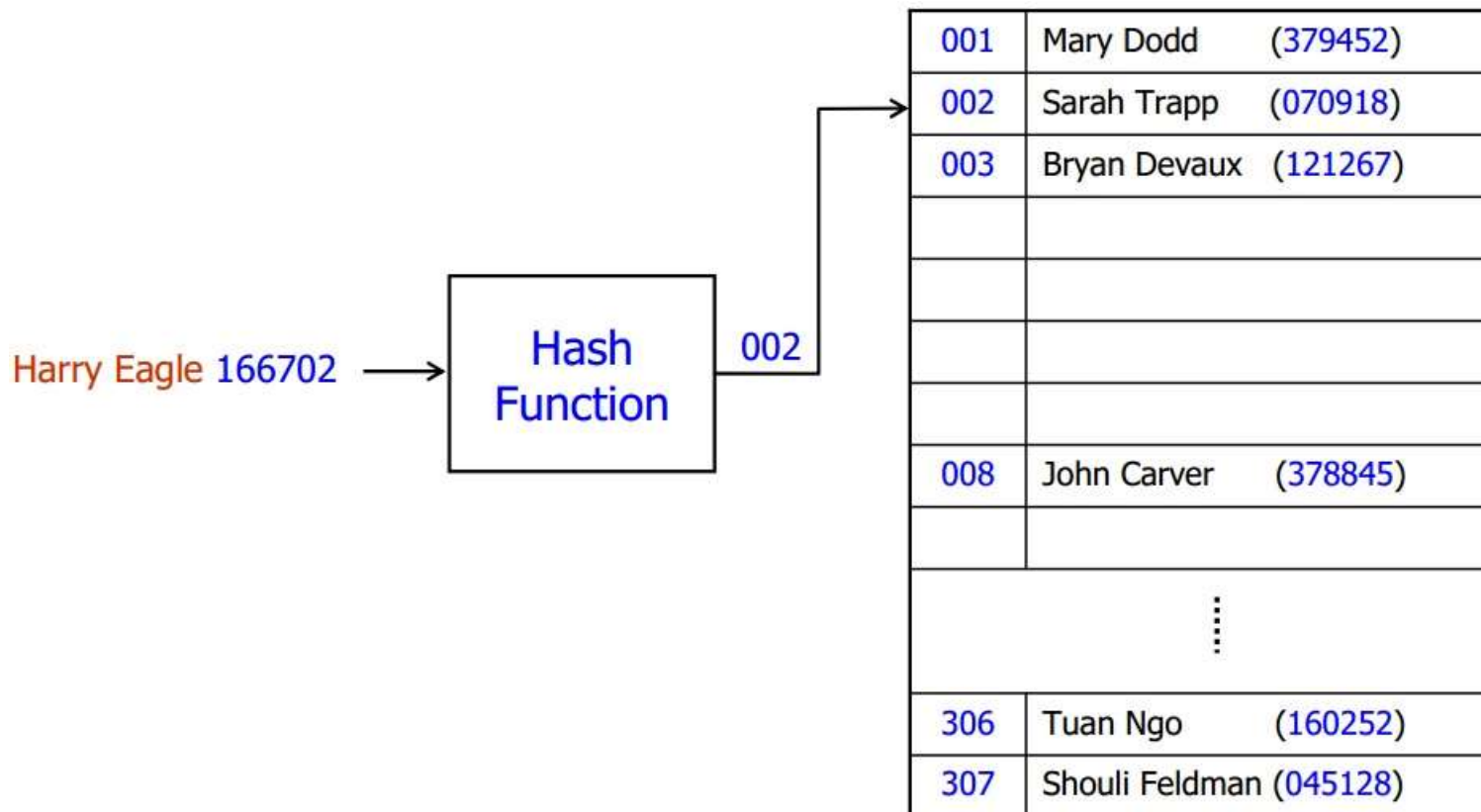




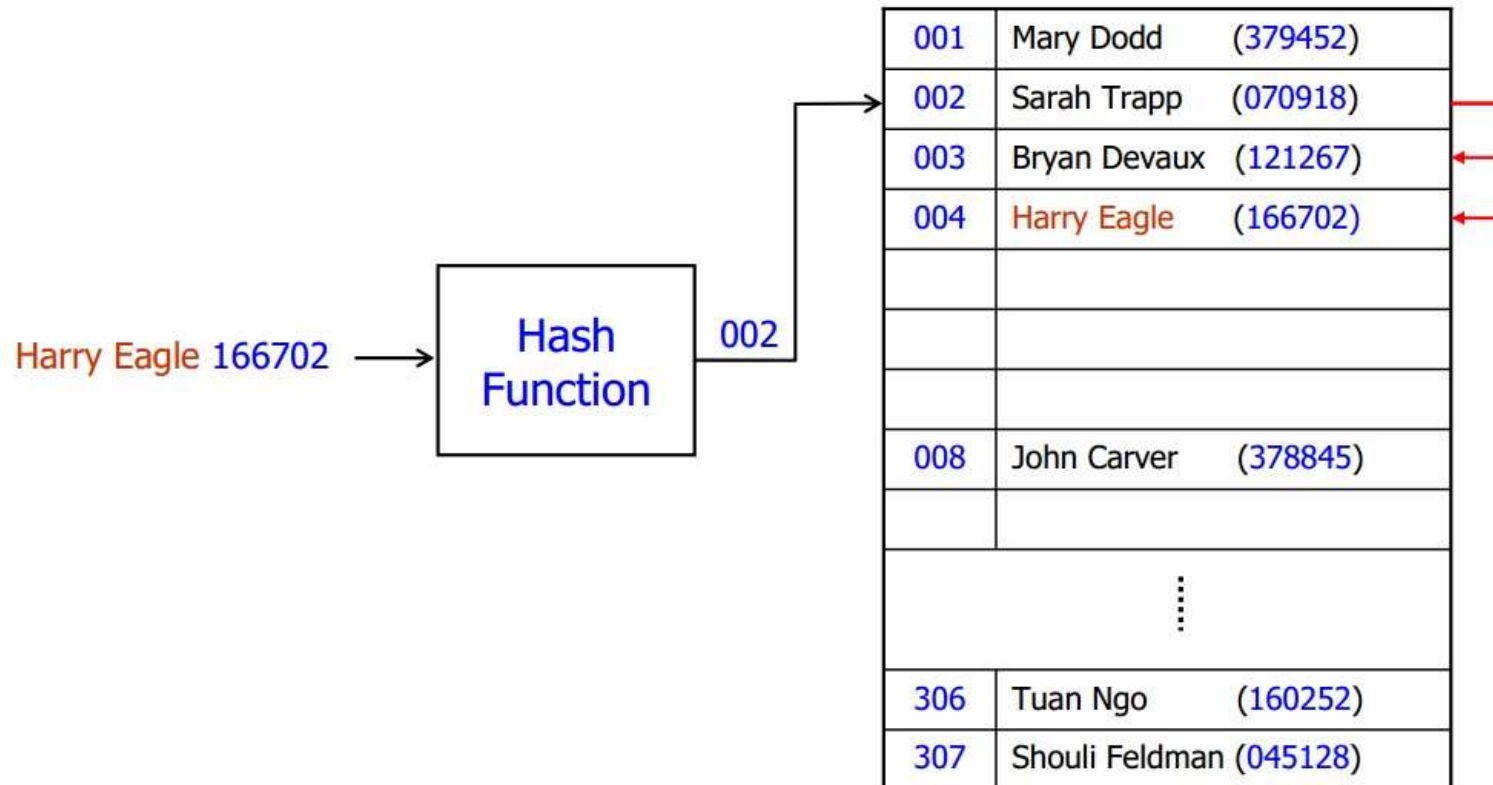
# Linear Probing

- When a home address is occupied, go to the **next address** (the current address + 1):

$$hp(k, i) = (h(k) + i) \bmod m$$



# Linear Probing



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### Linked list resolution

# Linear Probing

- Advantages:
  - quite simple to implement
  - data tend to remain near their home address (significant for disk addresses)
- Disadvantages:
  - produces primary clustering

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# Quadratic Probing

- The address increment is the **collision probe number** squared:  
$$hp(k, i) = (h(k) + i^2) \bmod m$$

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# Quadratic Probing

- Advantages:
  - works much better than linear probing
- Disadvantages:
  - time required to square numbers
  - produces secondary clustering
$$h(k_1) = h(k_2) \rightarrow hp(k_1, i) = hp(k_2, i)$$



# Double Hashing

- Using **two** hash functions:  
$$hp(k, i) = (h_1(k) + ih_2(k)) \bmod m$$

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# Key Offset

- The new address is a function of the collision address and the key.

$$offset = [key / listSize]$$

$$newAddress = (collisionAddress + offset) \bmod listSize$$



# Key Offset

- The new address is a function of the collision address and the key.

$$offset = [key / listSize]$$

$$newAddress = (collisionAddress + offset) \bmod listSize$$

$$hp(k, i) = (hp(k, i - 1) + [k/m]) \bmod m$$





# Open addressing

Hash and probe function:

$$hp : U \times \{0, 1, 2, \dots, m - 1\} \rightarrow \{0, 1, 2, \dots, m - 1\}$$

set of **keys**      **probe numbers**

**addresses**

$\{hp(k, 0), hp(k, 1), \dots, hp(k, m - 1)\}$  is a permutation of  $\{0, 1, \dots, m - 1\}$

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# Bucket hashing

- Hashing data to **buckets** that can hold multiple pieces of data.
- Each bucket has an address and **collisions are postponed** until the bucket is full.

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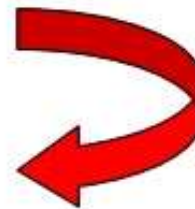
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# Bucket hashing

001	Mary Dodd (379452)
002	Sarah Trapp (070918)
	Harry Eagle (166702)
	Ann Georgis (367173)
003	Bryan Devaux (121267)
	Chris Walljasper(572556)
⋮	
307	Shouli Feldman (045128)



linear probing

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# Linked List Resolution

- Major disadvantage of Open Addressing:  
each collision resolution increases the probability for future collisions.  
→ use **linked lists** to store synonyms

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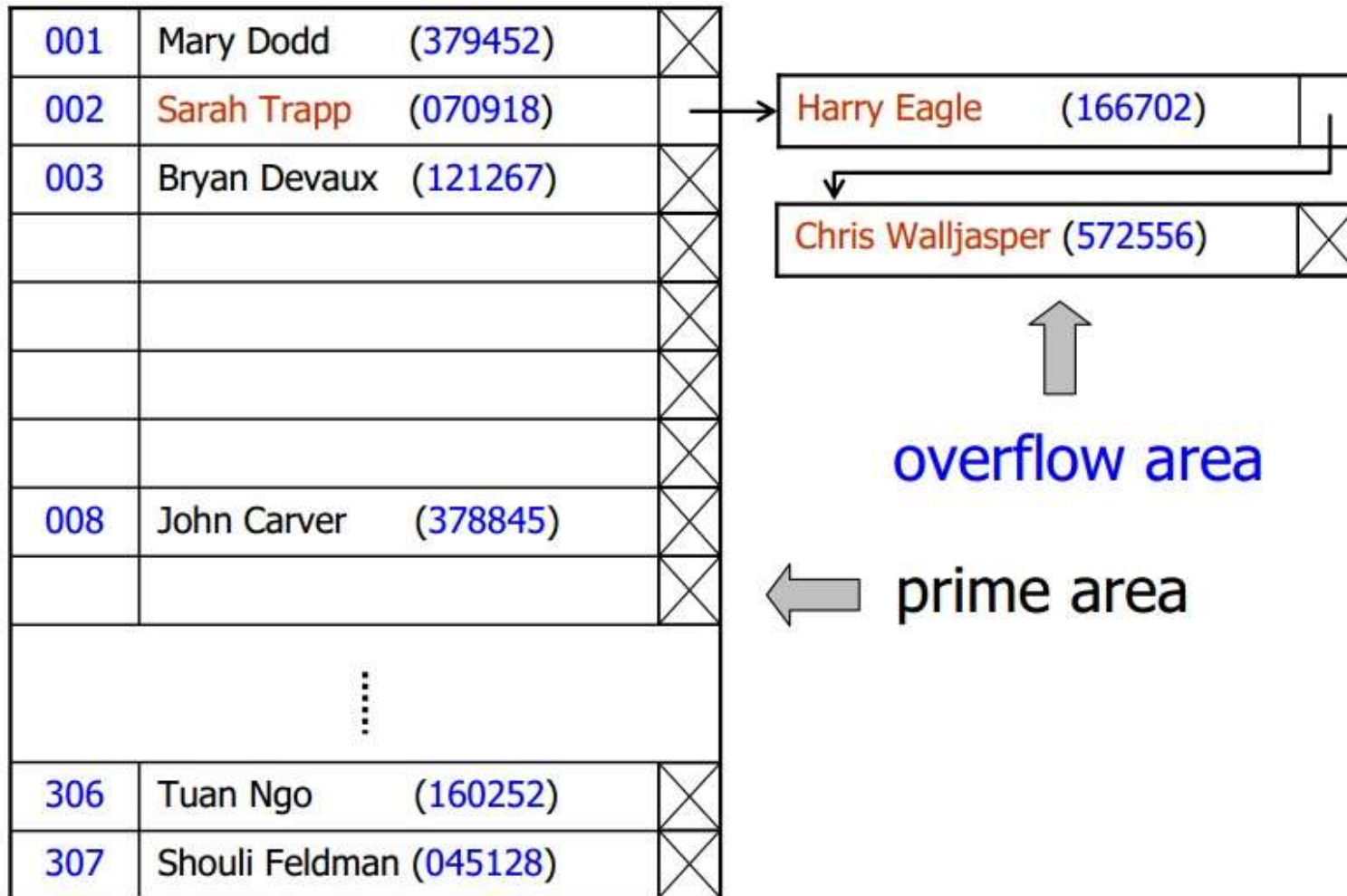
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# Linked list resolution



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# THANK YOU.

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