ADVANCED ANALYSIS OF ALGORITHMS CPS 5440

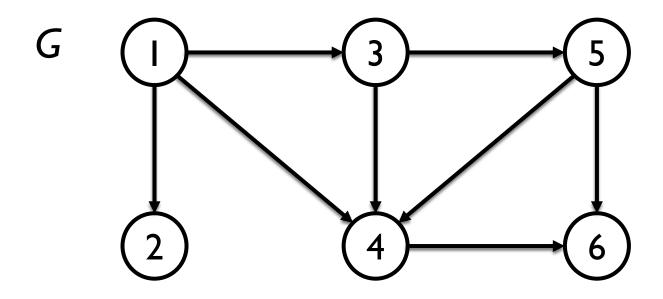
GRAPH ALGORITHMS. TOPOLOGICAL SORT.

TOPOLOGICAL SORT

Sorting technique over DAGs (Directed Acyclic Graphs)

- It creates a linear sequence (ordering) for the nodes such that:
 - If u has an outgoing edge to $v \rightarrow$ then u must finish before v starts
- Very common in ordering jobs or tasks

TOPOLOGICAL SORT: EXAMPLE



$$T = (1, 3, 2, 5, 4, 6)$$

Note: there may be multiple topological orderings.

T = (1, 2, 3, 5, 4, 6) is also valid.

A practical example of topological sorting is a list of tasks that needs to be completed, with some tasks having to be completed first. The tasks would be nodes in a graph.

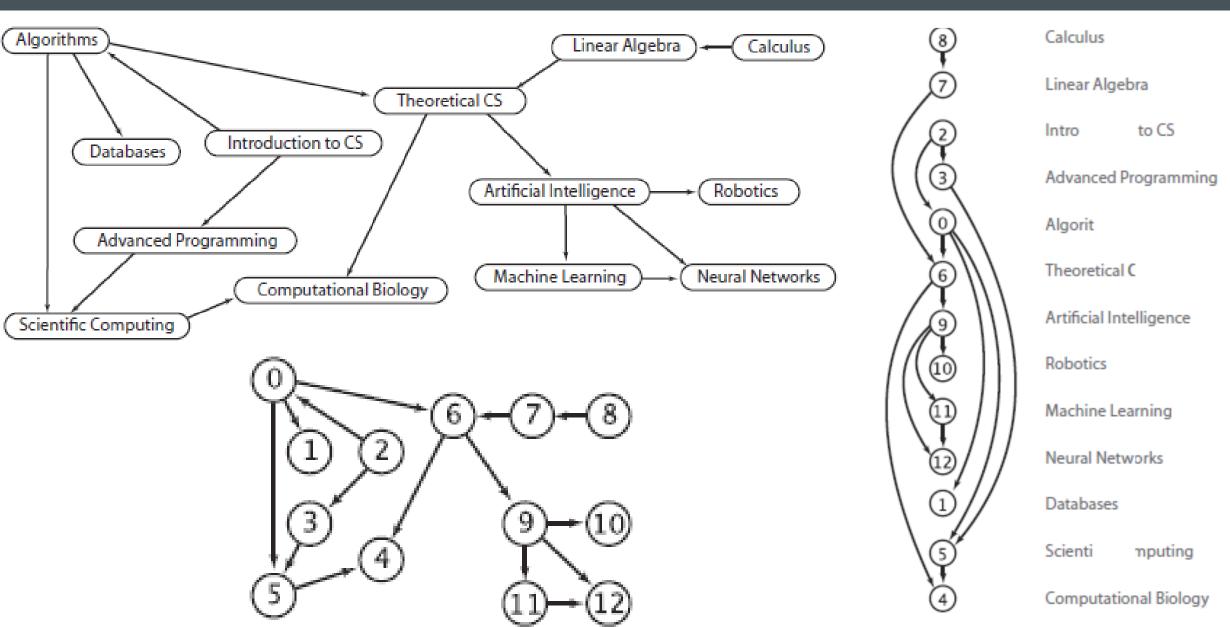
A practical example:

A cooking recipe.

You need to crack eggs before you can beat them, you must preheat the oven before you put food in it, etc.

Given a list of lectures that John wants to attend and the prerequisite lectures for each lecture, construct a list of the order in which John should attend the lectures.

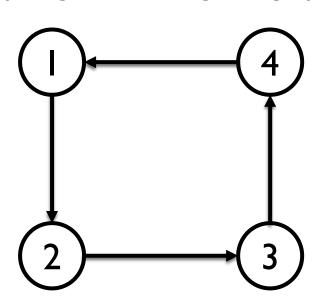
The lectures are vertices of a directed graph, and the prerequisites are directed edges of the graph. The topological sorting of the graph provides the list that is required.



- School class prerequisites
- Program dependencies
- Event scheduling
- Assembly instructions
- **Etc** ...

TOPOLOGICAL SORT: CONDITION

A topological ordering of a graph is possible if and only if the graph does not contain any directed cycles.



(A topological ordering of this graph does not exist.)

TOPOLOGICAL SORT: ALGORITHMS

There are two main algorithms for finding the topological order of a graph:

- I. Kahn's Algorithm
- 2. DFS

TOPOLOGICAL SORT: KAHN'S ALGORITHM

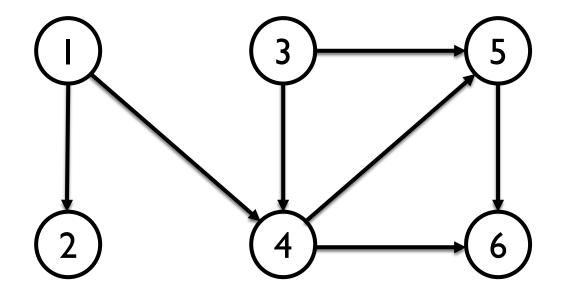
A DAG G has at least one vertex with in-degree 0 and one vertex with out-degree 0.

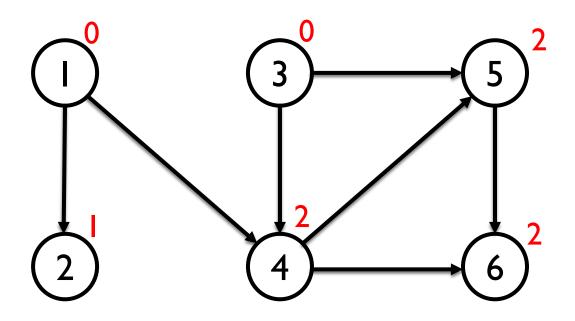
Proof: There's a simple proof to the above fact is that a DAG does not contain a cycle which means that all paths will be of finite length. Now let S be the longest path from u(source) to v(destination). Since S is the longest path there can be no incoming edge to u and no outgoing edge from v, if this situation had occurred then S would not have been the longest path

 $\Rightarrow indegree(u) = 0$ and outdegree(v) = 0

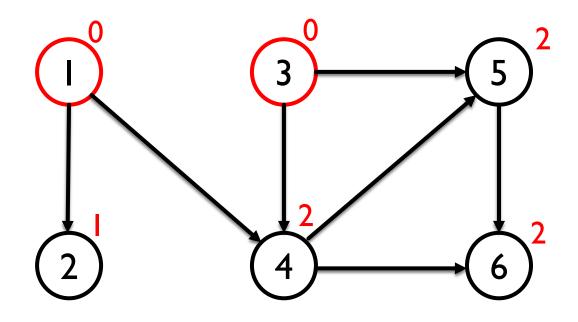
TOPOLOGICAL SORT: KAHN'S ALGORITHM

- I. Compute the in-degree of each vertex
- 2. Add all the vertices with an in-degree of 0 onto a queue Q
- 3. Remove a vertex V from Q
- 4. Increment the counter of visited nodes by 1
- 5. Add V onto T where T is the list that will contain the order of the nodes
- 6. Decrease the in-degree of all neighbours of V by 1
- 7. If a neighbour now has an in-degree of 0, add it to Q
- 8. If Q is not empty, go to step 3
- 9. If the vertex counter does not equal the total number of vertices, return ERROR (the topological ordering does not exist)
- 10. Return *T*





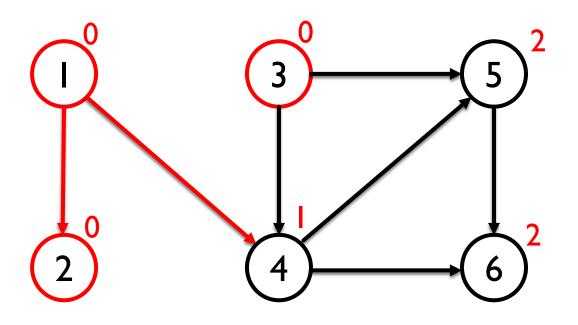
Compute the in-degree of each vertex.



Put the vertices with indegree 0 onto a queue.

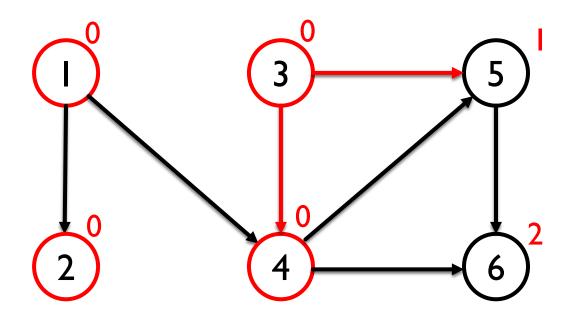
$$Q = (1,3)$$

 $T = ()$



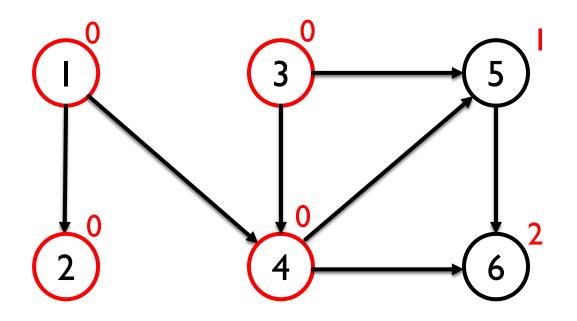
$$Q = (3, 2)$$

 $T = (1)$



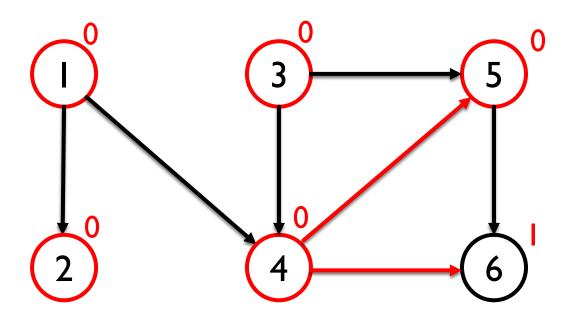
$$Q = (2,4)$$

$$T = (1,3)$$



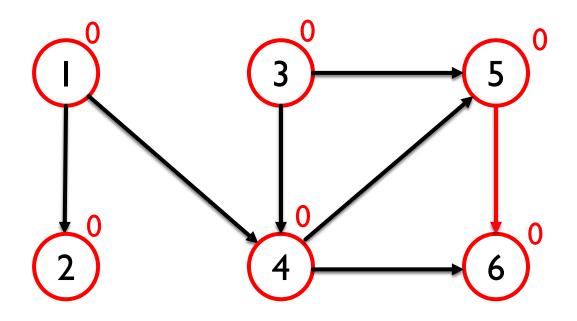
$$Q = (4)$$

 $T = (1, 3, 2)$



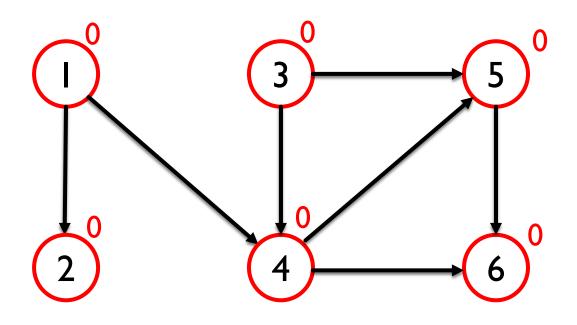
$$Q = (5)$$

 $T = (1, 3, 2, 4)$



$$Q = (6)$$

 $T = (1, 3, 2, 4, 5)$



Return *T*.

$$Q = ()$$

 $T = (1, 3, 2, 4, 5, 6)$

■ Time-complexity: O(V + E)

You go through each vertex once, and you check each edge once.

■ Space-complexity: O(V + E)

You only need a list containing the vertices and a list containing the edges.

TOPOLOGICAL SORT - DFS

- To create a topological sort from a DAG
 - I- Final linked list is empty
 - 2- Run DFS
 - 3-When a node becomes black (finishes), insert it to the top of a linked list

A job consists of 10 tasks with the following precedence rules:

Must start with 7, 5, 4 or 9.

Task 1 must follow 7.

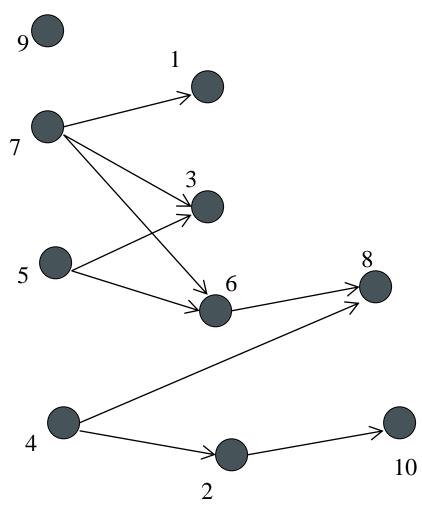
Tasks 3 & 6 must follow both 7 & 5.

8 must follow 6 & 4.

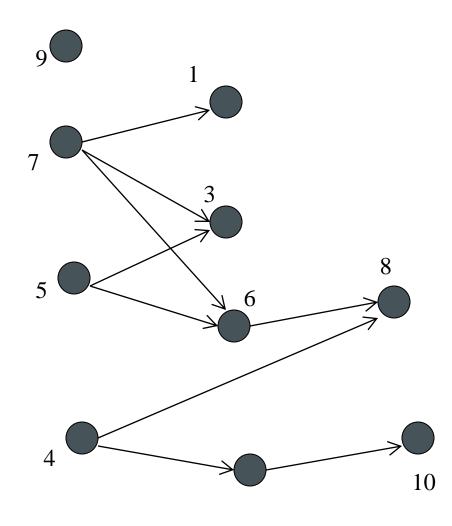
2 must follow 4.

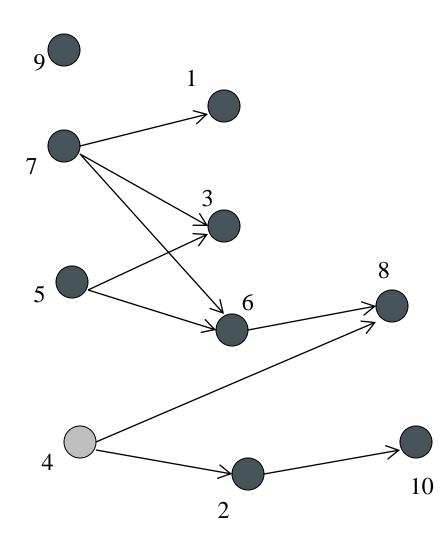
10 must follow 2.

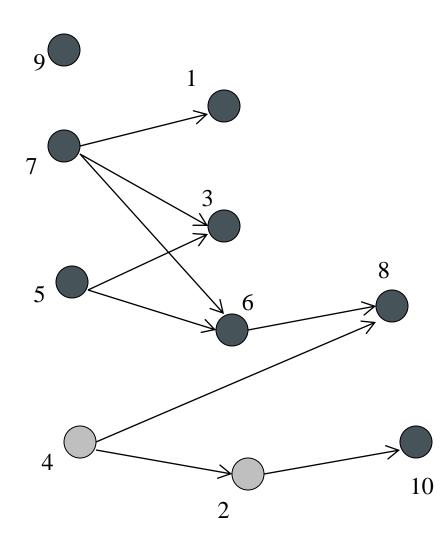
Make a directed graph and then do DFS.

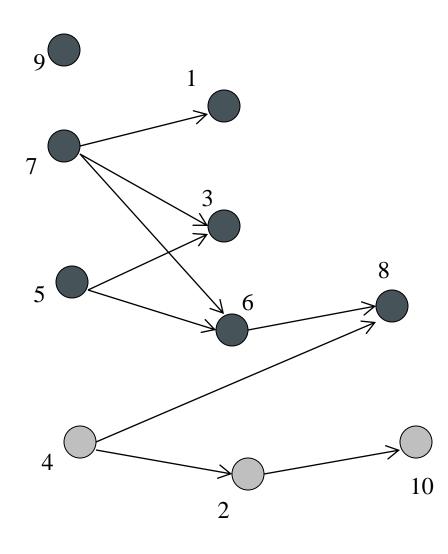


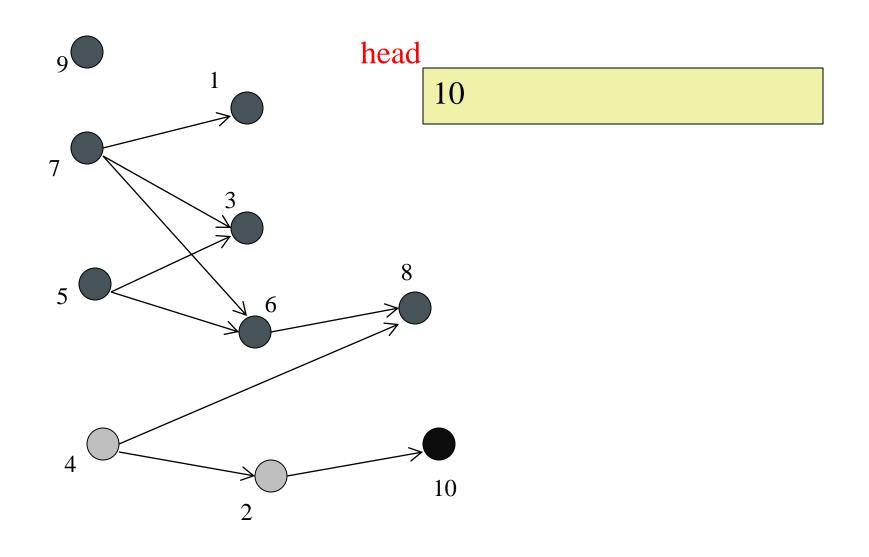
Tasks are shown as a directed graph.

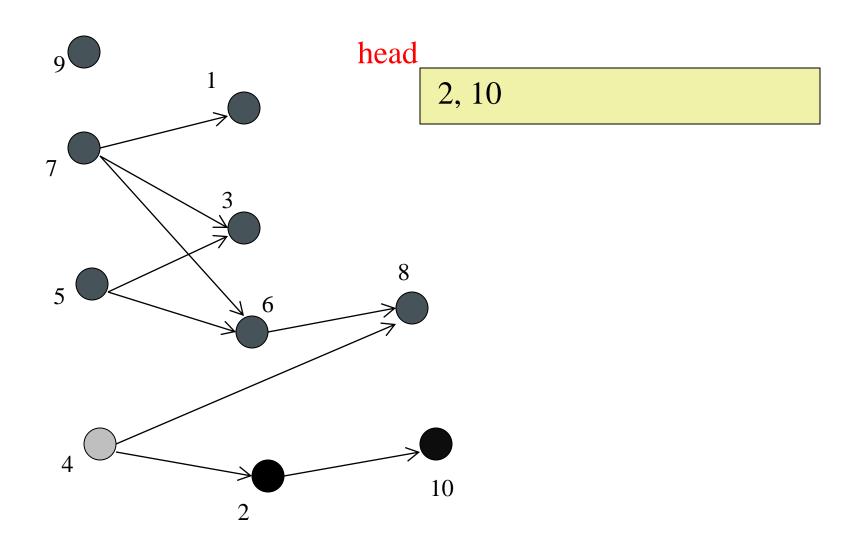


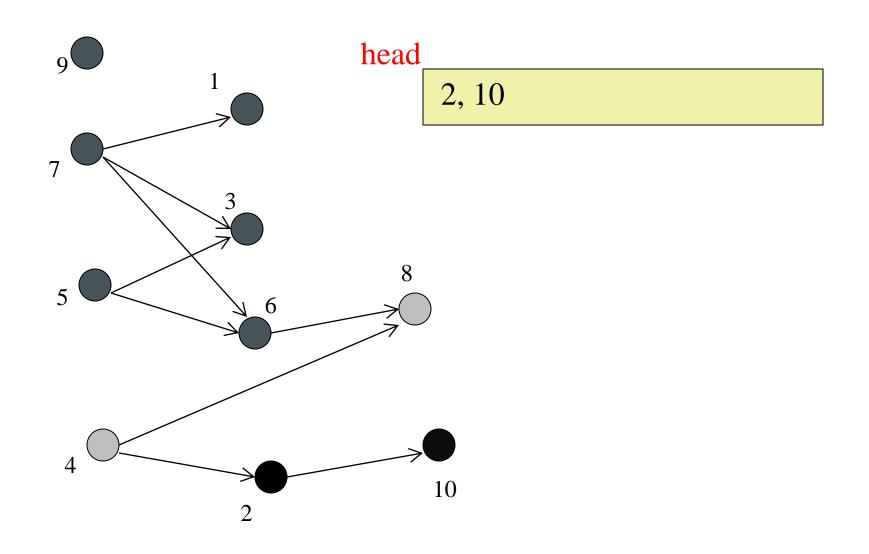


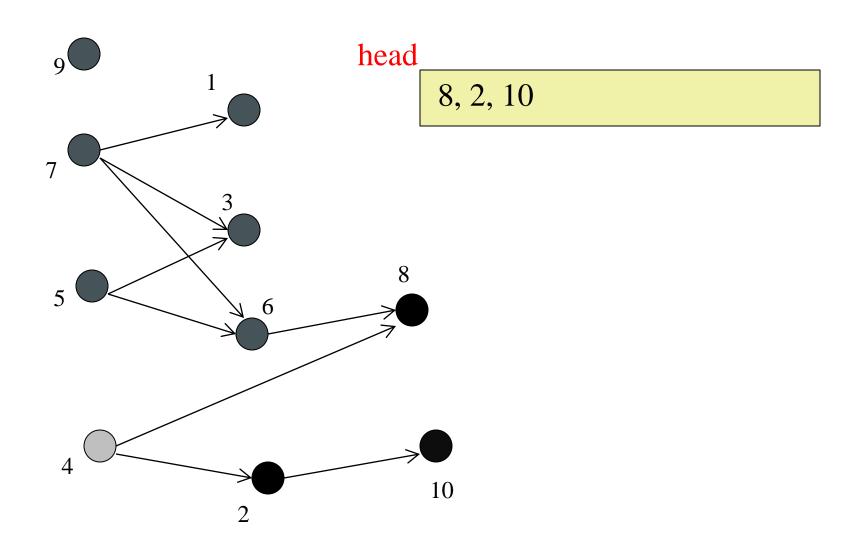


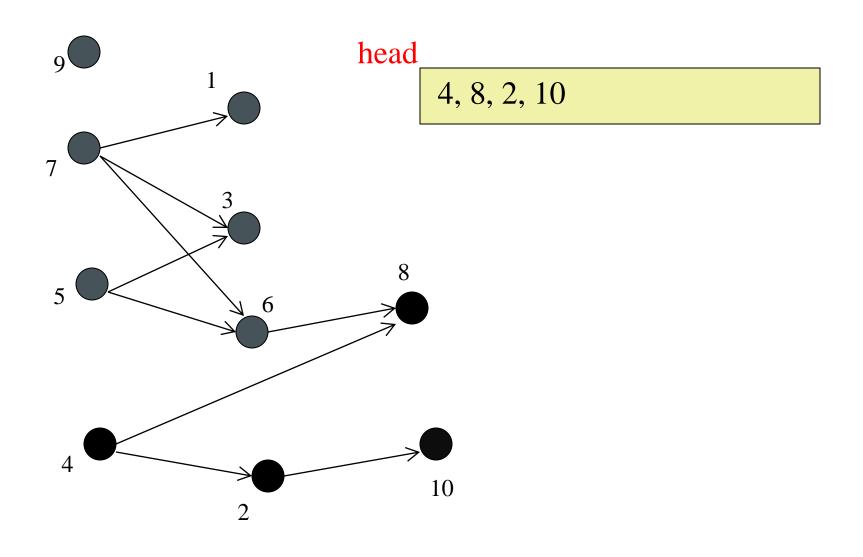


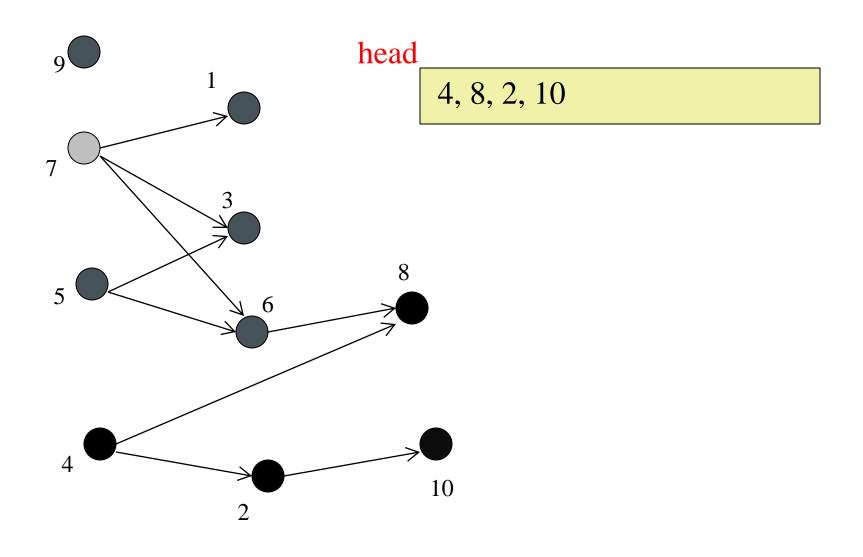


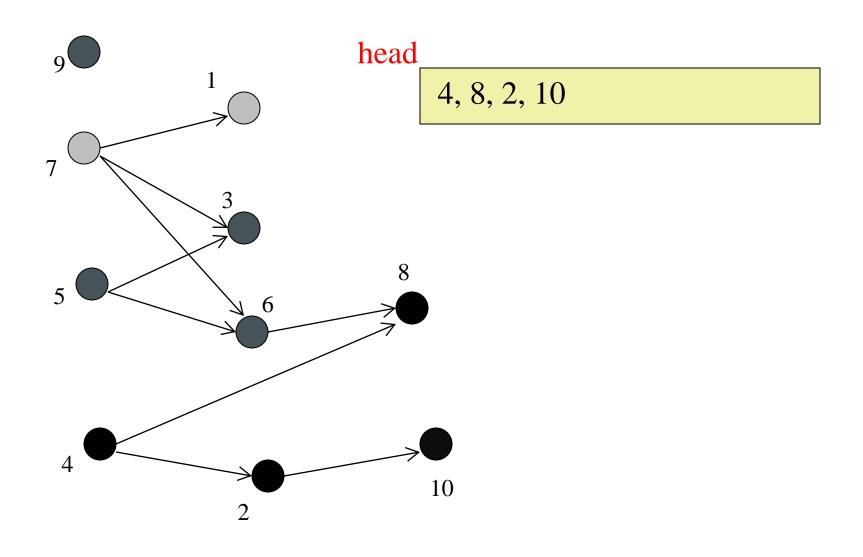


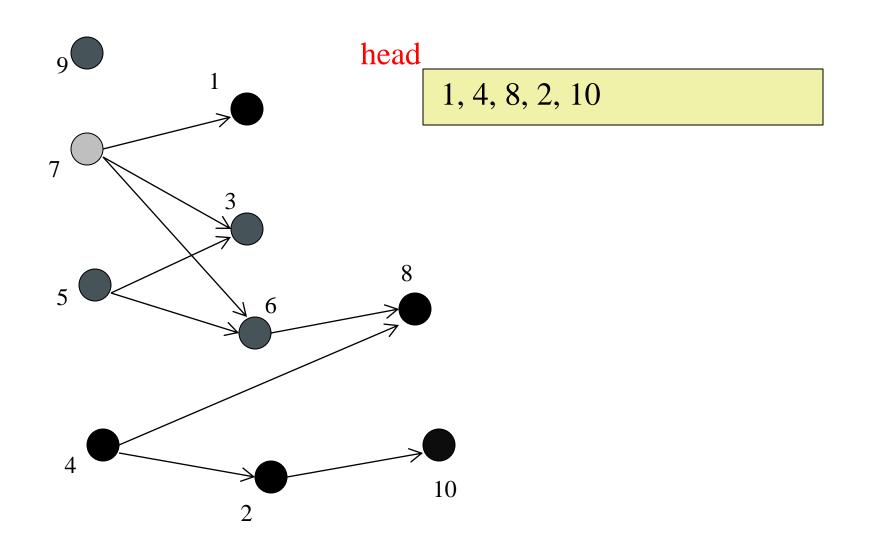


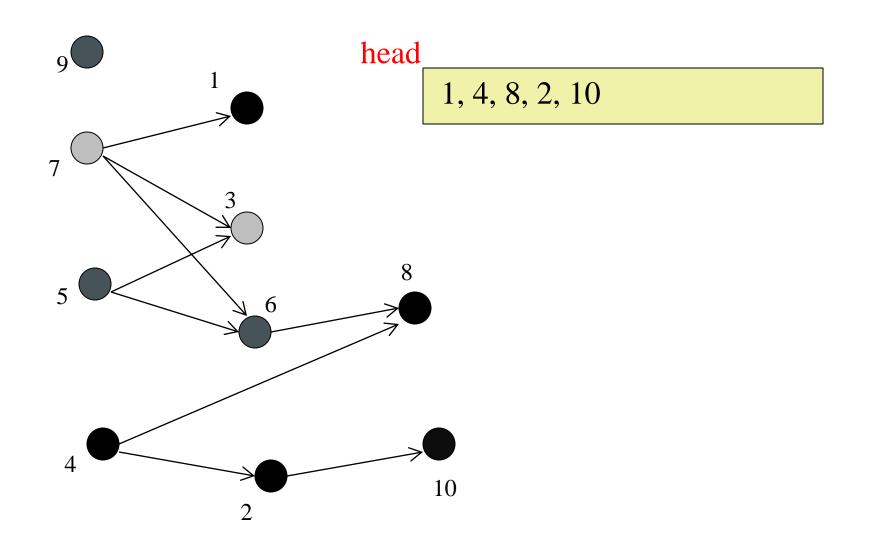


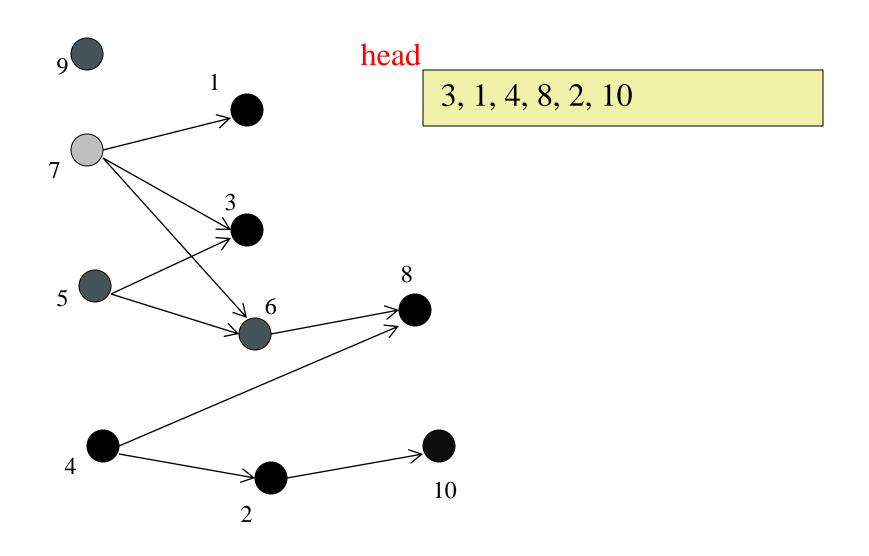


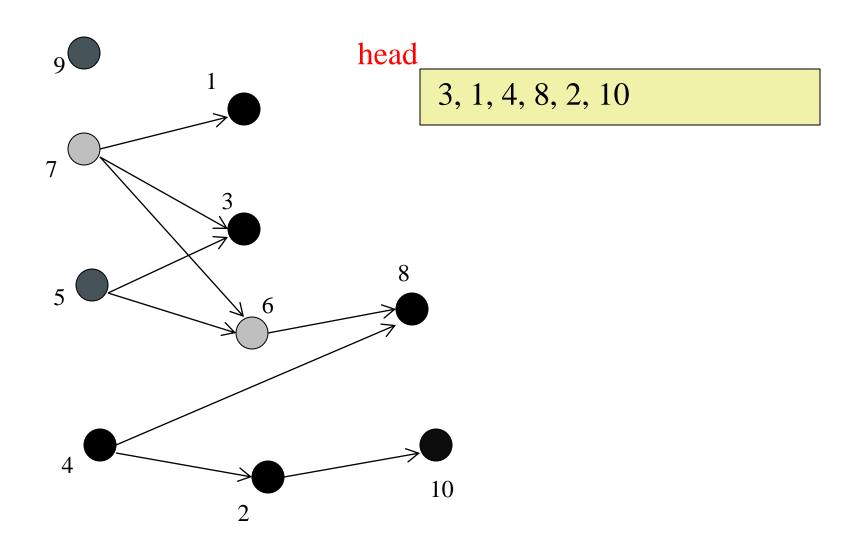


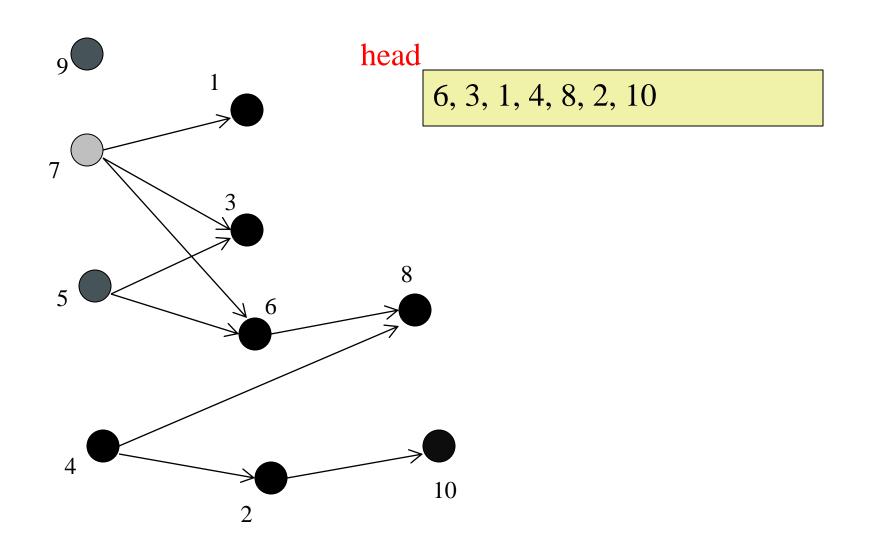


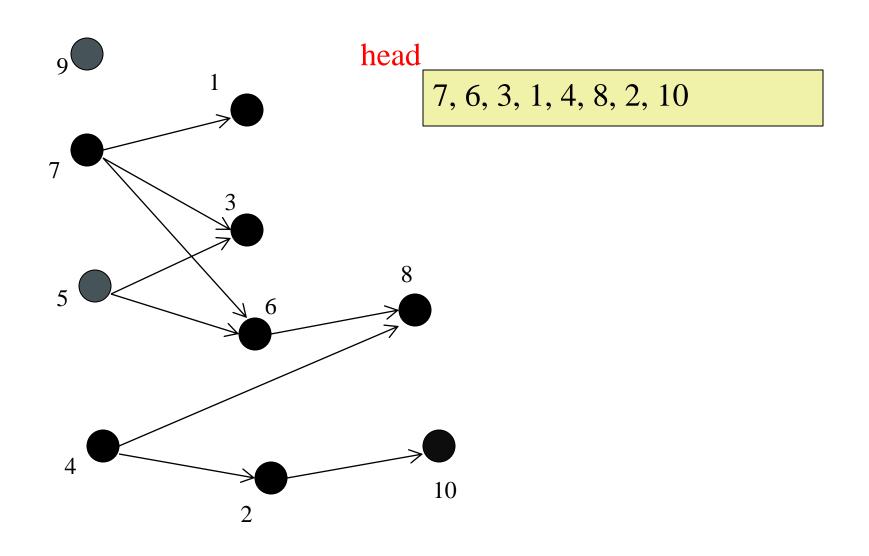


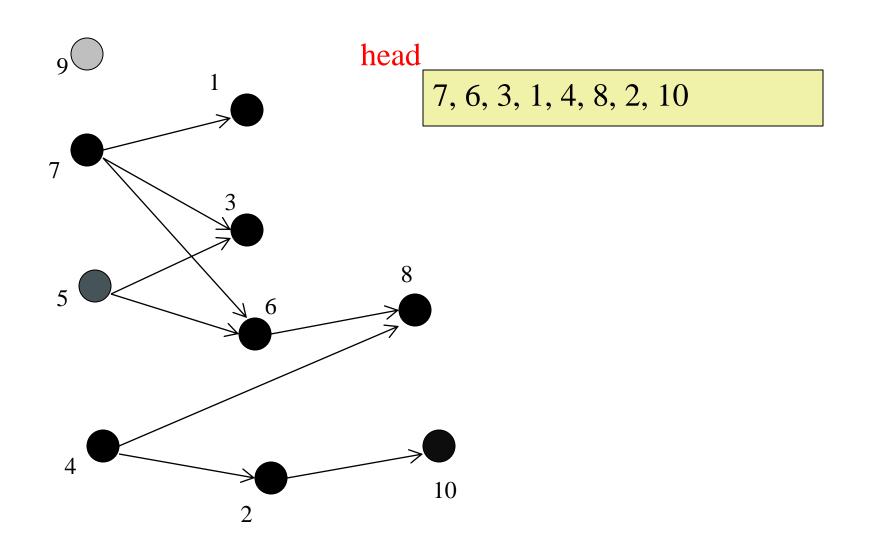


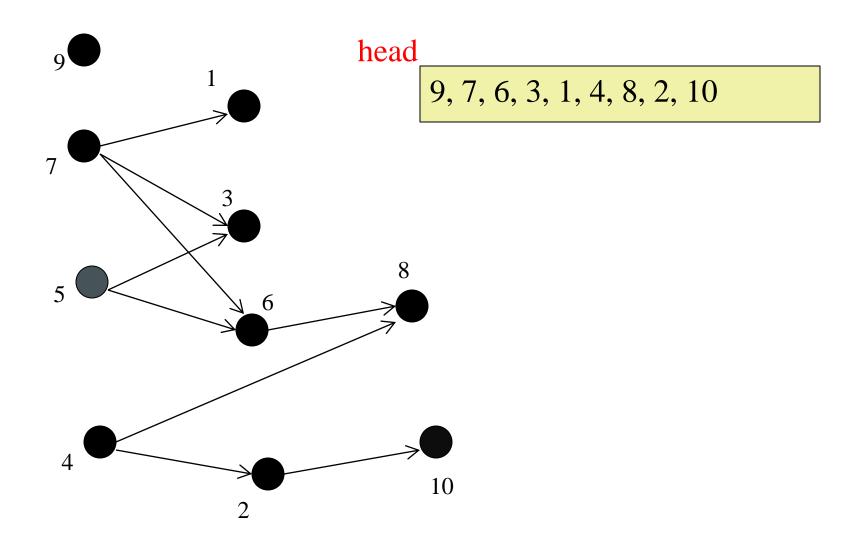


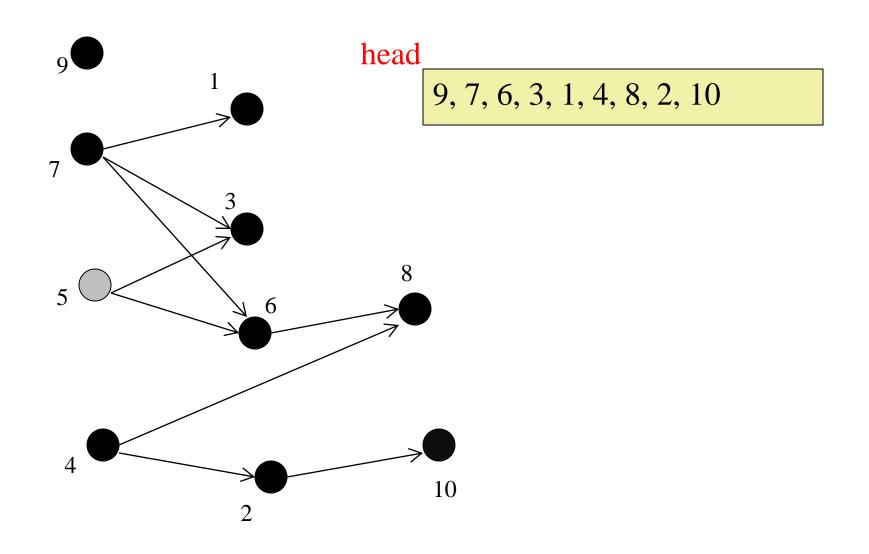


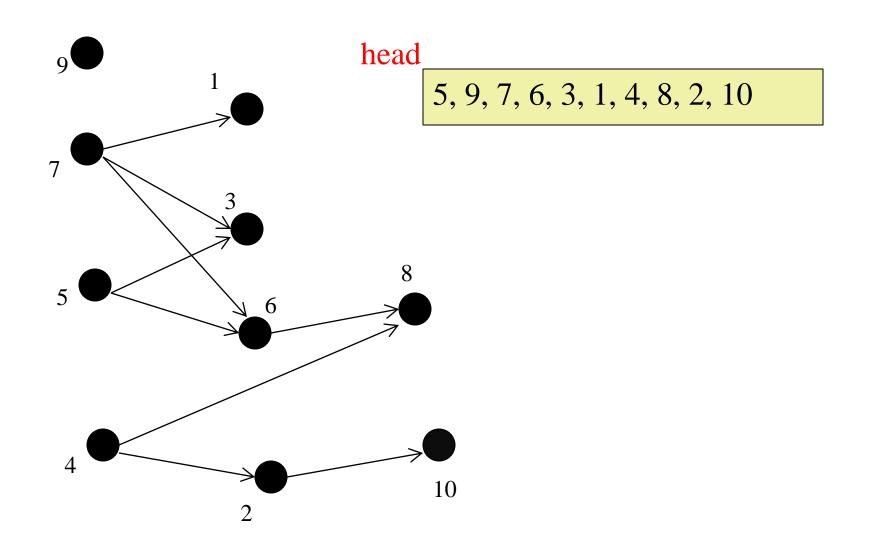


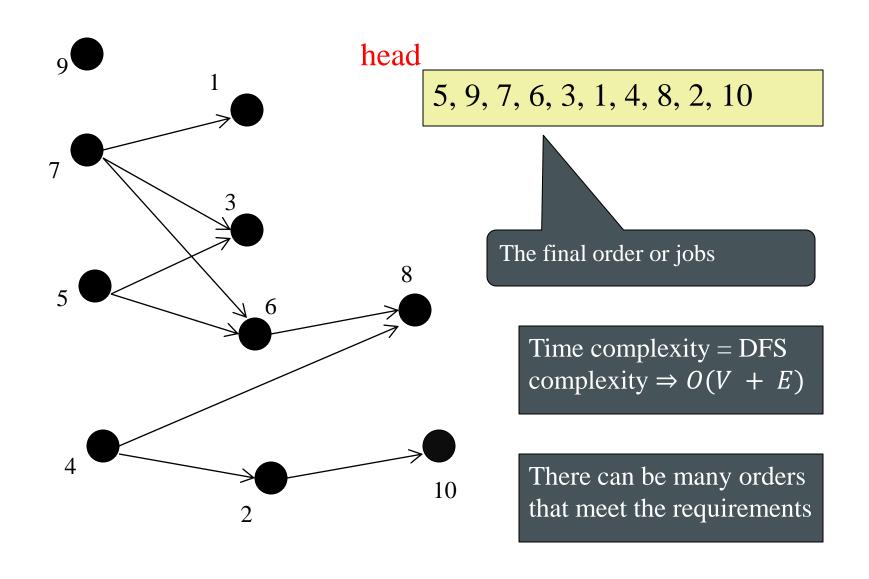












TOPOLOGICAL SORT - DFS COMPLEXITY

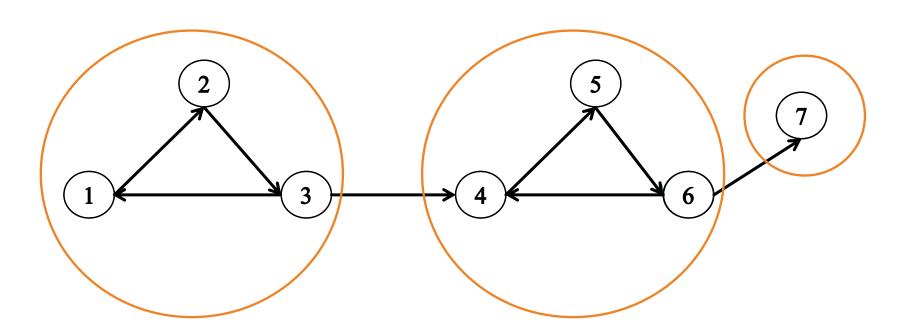
■ Time complexity: O(V + E)

You traverse each edge once and you check each vertex once

GRAPH ALGORITHMS. STRONGLY CONNECTED COMPONENTS

STRONGLY CONNECTED COMPONENTS

- A graph is said to be strongly connected if every vertex is reachable from every other vertex.
- The strongly connected components of an arbitrarily directed graph form a partition into subgraphs that are themselves strongly connected.
- A subset of a directed graph is called strongly connected if there is a path in each direction between each pair of vertices of the subset.

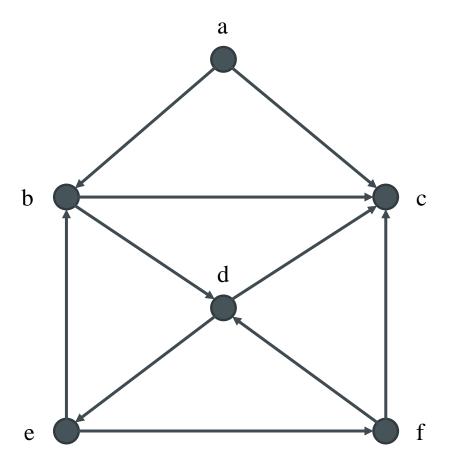


Algorithm 1 Path-Based Depth-First Search Algorithm

```
    Input: A directed graph G = (V, L)
    Output: Set of SCCs represented by SCC (initially empty)
    for v ∈ V do
    Set the node as unseen.
    Initiate a path P = {}
    for v ∈ V do
    if v is unseen then
    DFS(v).
```

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1: if v has no outgoing arc then
       Consider v as an SCC and add it to SCC
       Set v as seen.
       Remove it from P.
 5: else
       for arc (v, w) \in E do
 6:
          if w \in P (v_i = w) then
 7:
              Contract the nodes v_i, v_{i+1}, \dots, v_{|P|}.
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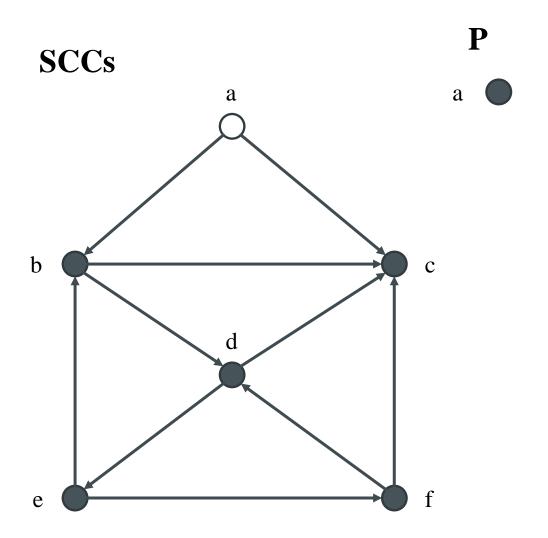
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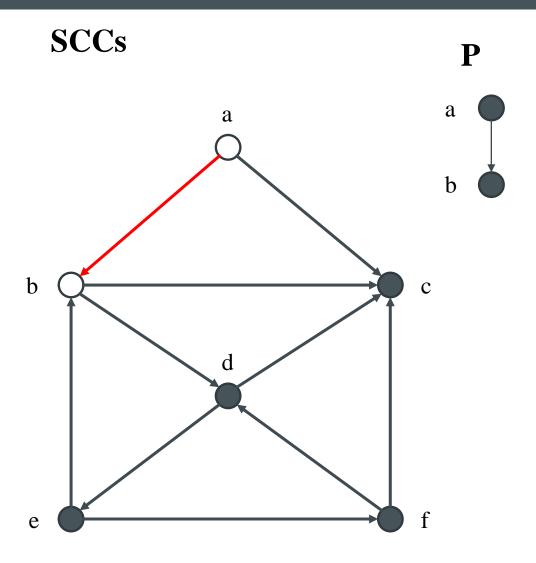
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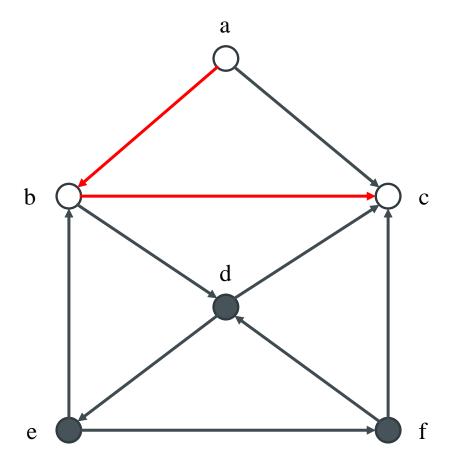
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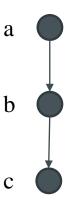
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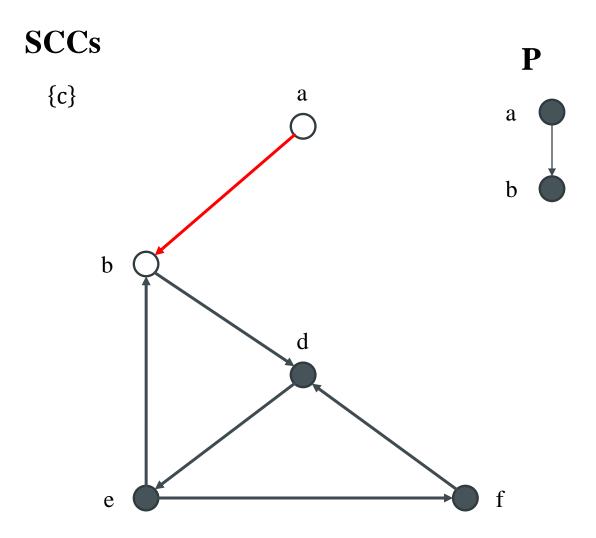
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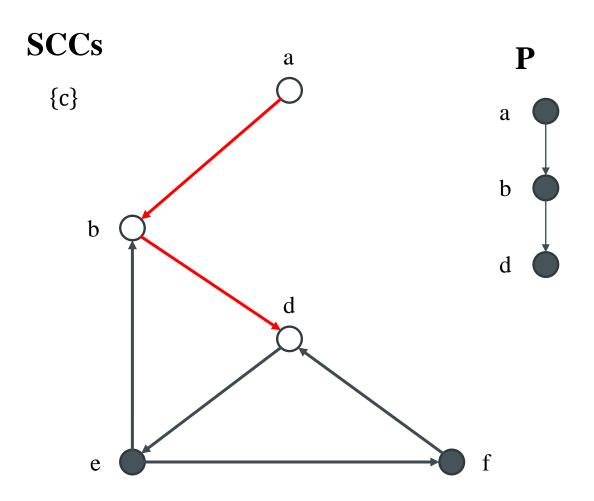
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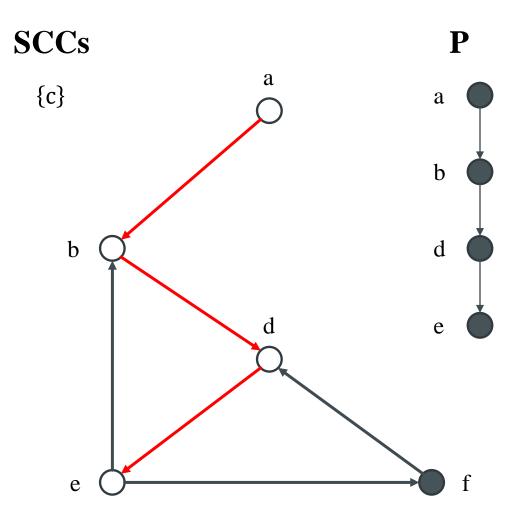
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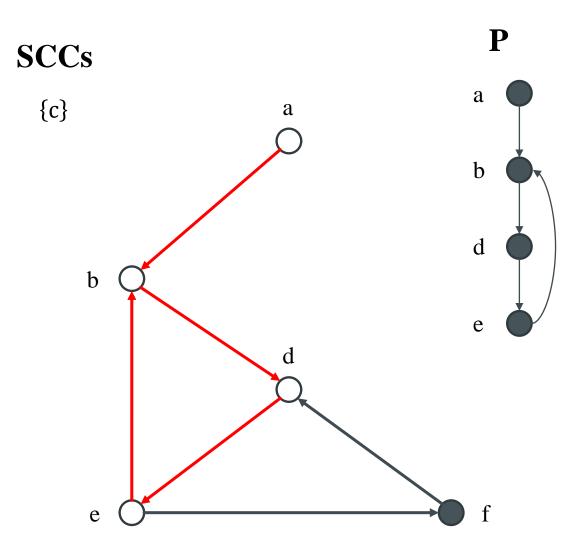
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Algorithm 2 DFS(v)

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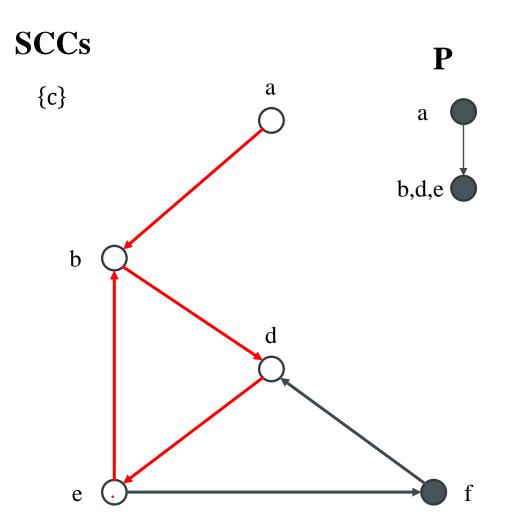
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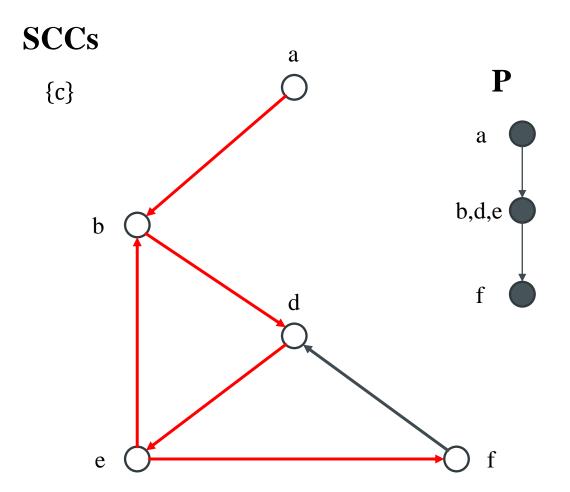
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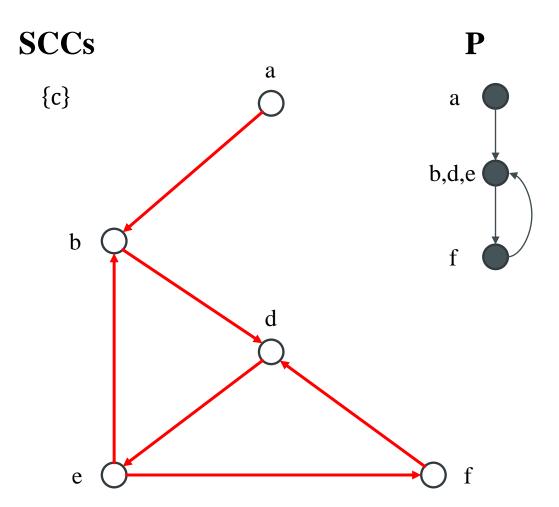
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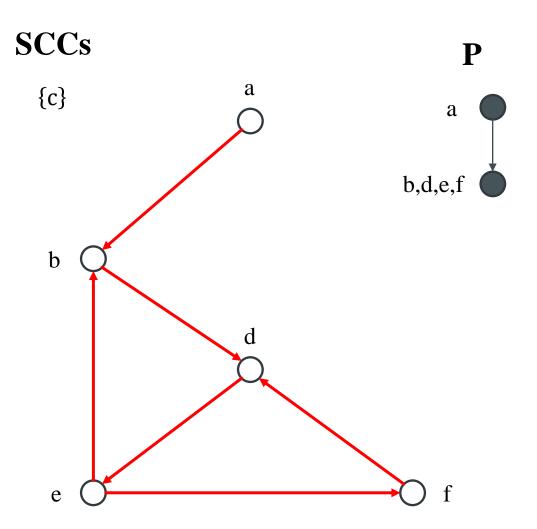
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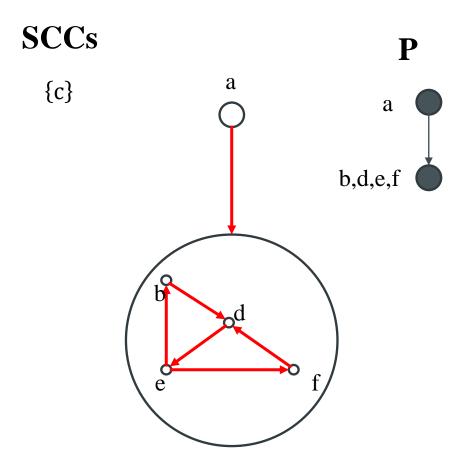
4: Set the node as unseen.
```

```
5: Initiate a path P = \{\}
6: for v \in V do
```

7: **if** v is unseen **then**

8: DFS(v).

```
1: if v has no outgoing arc then
       Consider v as an SCC and add it to SCC
       Set v as seen.
       Remove it from P.
 5: else
       for arc (v, w) \in E do
          if w \in P (v_i = w) then
 7:
              Contract the nodes v_i, v_{i+1}, ..., v_{|P|}.
 8:
 9:
          else
              Add w to P.
10:
              Set w as seen.
11:
             DFS(w).
12:
```



Algorithm 1 Path-Based Depth-First Search Algorithm

```
1: Input: A directed graph G = (V, L)

2: Output: Set of SCCs represented by SCC (initially empty)

3: for v \in V do

4: Set the node as unseen.

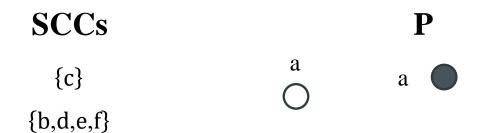
5: Initiate a path P = \{\}

6: for v \in V do

7: if v is unseen then

8: DFS(v).
```

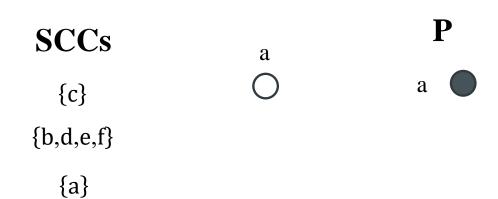
```
1: if v has no outgoing arc then
       Consider v as an SCC and add it to SCC
       Set v as seen.
       Remove it from P.
5: else
       for arc (v, w) \in E do
          if w \in P (v_i = w) then
 7:
              Contract the nodes v_i, v_{i+1}, ..., v_{|P|}.
 8:
          else
 9:
              Add w to P.
10:
              Set w as seen.
11:
              DFS(w).
12:
```



Algorithm 1 Path-Based Depth-First Search Algorithm

```
    Input: A directed graph G = (V, L)
    Output: Set of SCCs represented by SCC (initially empty)
    for v ∈ V do
    Set the node as unseen.
    Initiate a path P = {}
    for v ∈ V do
    if v is unseen then
    DFS(v).
```

```
1: if v has no outgoing arc then
       Consider v as an SCC and add it to SCC
       Set v as seen.
 3:
       Remove it from P.
 5: else
       for arc (v, w) \in E do
 6:
          if w \in P (v_i = w) then
 7:
              Contract the nodes v_i, v_{i+1}, \dots, v_{|P|}.
 8:
          else
 9:
              Add w to P.
10:
              Set w as seen.
11:
              DFS(w).
12:
```



```
Algorithm 1 Path-Based Depth-First Search Algorithm
```

```
1: Input: A directed graph G = (V, L)

2: Output: Set of SCCs represented by SCC (initially empty)

3: for v \in V do

4: Set the node as unseen.

5: Initiate a path P = \{\}

6: for v \in V do

7: if v is unseen then

8: DFS(v).
```

```
1: if v has no outgoing arc then
       Consider v as an SCC and add it to SCC
       Set v as seen.
 3:
       Remove it from P.
 5: else
       for arc (v, w) \in E do
 6:
          if w \in P (v_i = w) then
 7:
              Contract the nodes v_i, v_{i+1}, \dots, v_{|P|}.
 8:
          else
 9:
              Add w to P.
10:
              Set w as seen.
11:
              DFS(w).
12:
```

5: **else**

6:

9:

10:

11:

12:

for arc $(v, w) \in E$ do

else

if $w \in P (v_i = w)$ then

Add w to P.

Set w as seen.

DFS(w).

Contract the nodes $v_i, v_{i+1}, \dots, v_{|P|}$.

```
$CCs P

{c}
{b,d,e,f}

{a}
```

```
Algorithm 1 Path-Based Depth-First Search Algorithm

1: Input: A directed graph G = (V, L)

2: Output: Set of SCCs represented by SCC (initially empty)

3: for v \in V do

4: Set the node as unseen.

5: Initiate a path P = \{\}

6: for v \in V do

7: if v is unseen then

8: DFS(v).

Algorithm 2 DFS(v)

1: if v has no outgoing arc then

2: Consider v as an SCC and add it to SCC

3: Set v as seen.

4: Remove it from P.
```

Complexity

```
O(E+V)
```

Algorithm 1 Path-Based Depth-First Search Algorithm

```
1: Input: A directed graph G = (V, L)

2: Output: Set of SCCs represented by SCC (initially empty)

3: for v \in V do

4: Set the node as unseen.

5: Initiate a path P = \{\}

6: for v \in V do

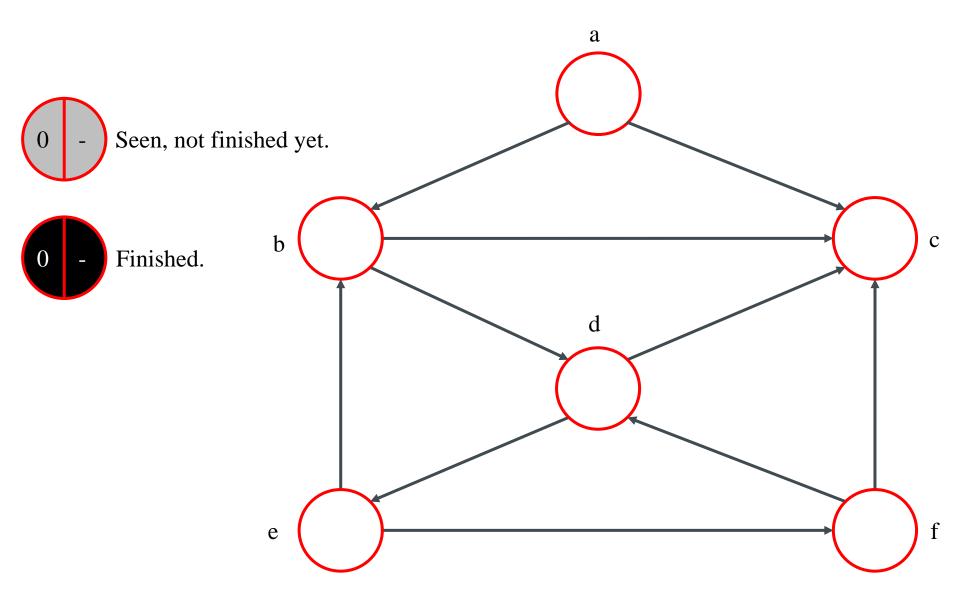
7: if v is unseen then

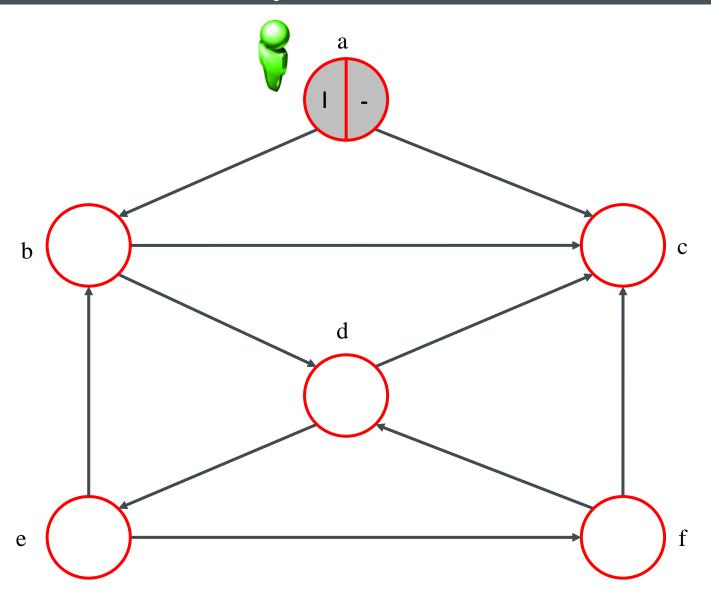
8: DFS(v).
```

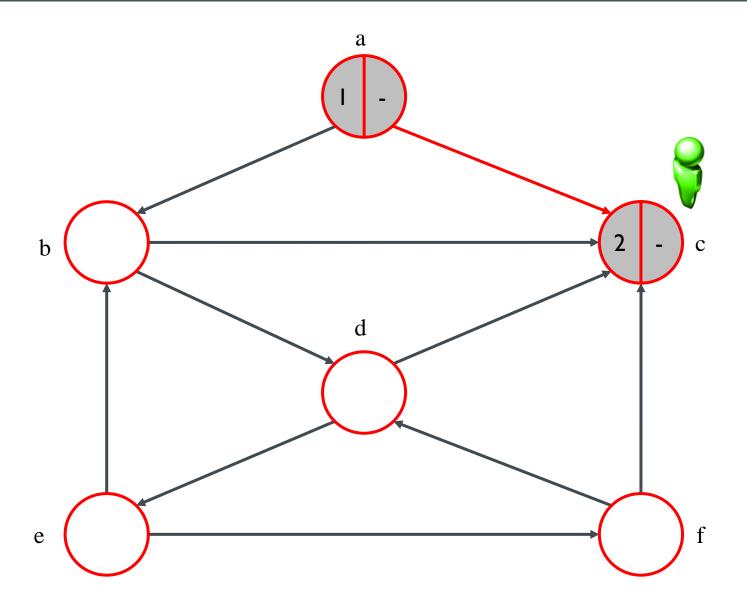
```
1: if v has no outgoing arc then
       Consider v as an SCC and add it to SCC
       Set v as seen.
       Remove it from P.
 5: else
       for arc (v, w) \in E do
          if w \in P (v_i = w) then
 7:
              Contract the nodes v_i, v_{i+1}, \dots, v_{|P|}.
           else
 9:
              Add w to P.
10:
              Set w as seen.
11:
              DFS(w).
12:
```

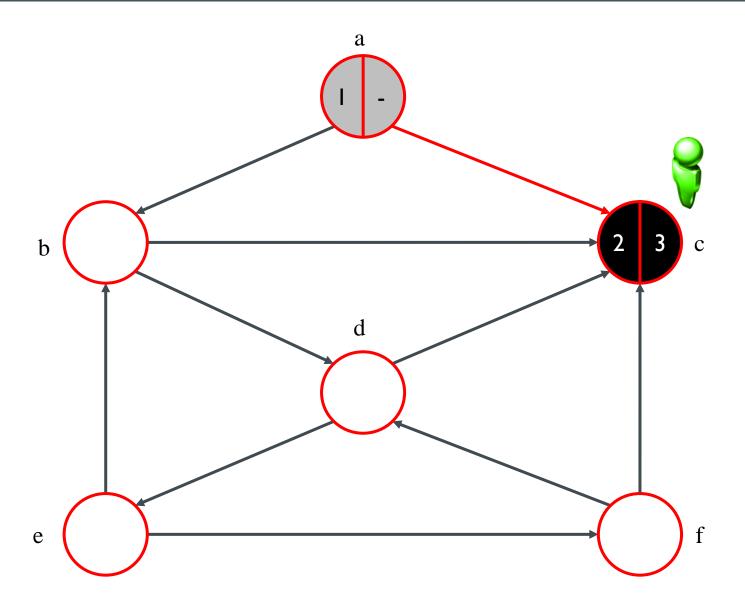
Algorithm 3 Kosaraju-Sharir Algorithm

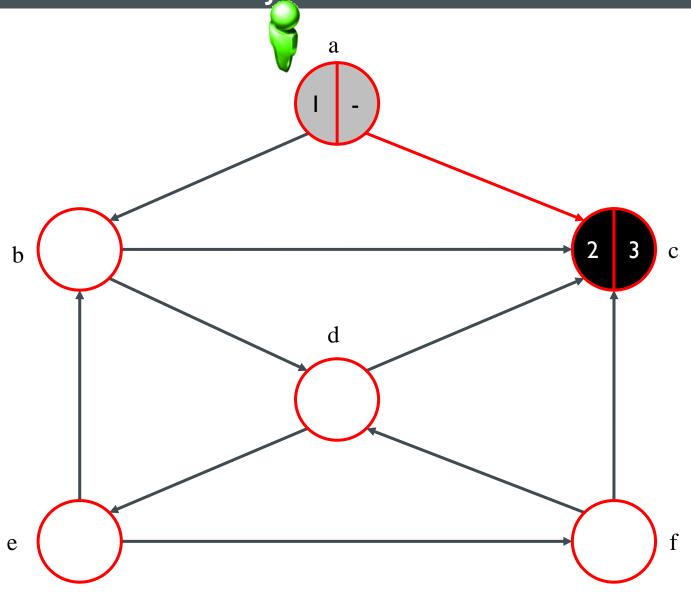
- 1: **Input:** A directed graph G = (V, L)
- 2: **Output:** Set of SCCs represented by SCC (initially empty)
- 3: Run DFS on Graph G to compute finishing time (reverse postorder) of each node.
- 4: $V^R = V, L^R = \emptyset$.
- 5: Build $G^R = (V^R, L^R)$
- 6: **for** $l = (u, v) \in L$ **do**
- 7: $L^R = L^R \cup (v, u)$
- 8: Run DFS on G^R , considering vertices in the decreasing reverse postorder.
- 9: Output the vertices of each Depth First Traversal as an SCC.

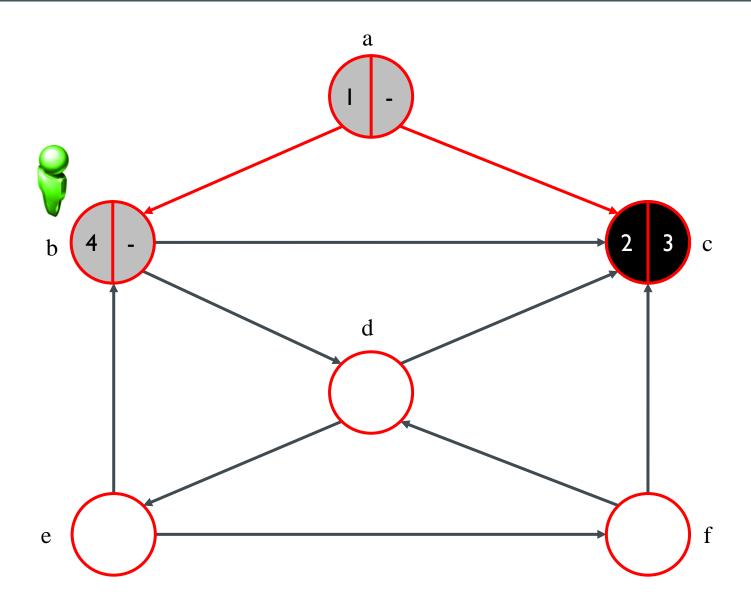


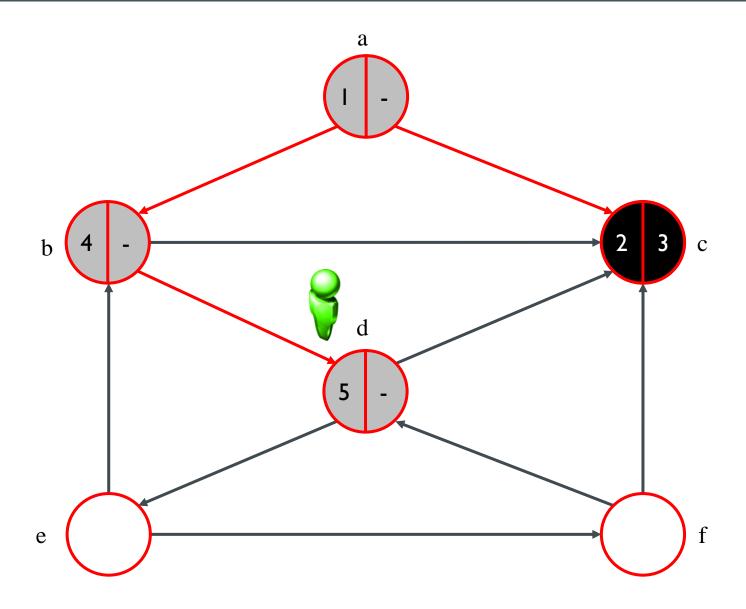


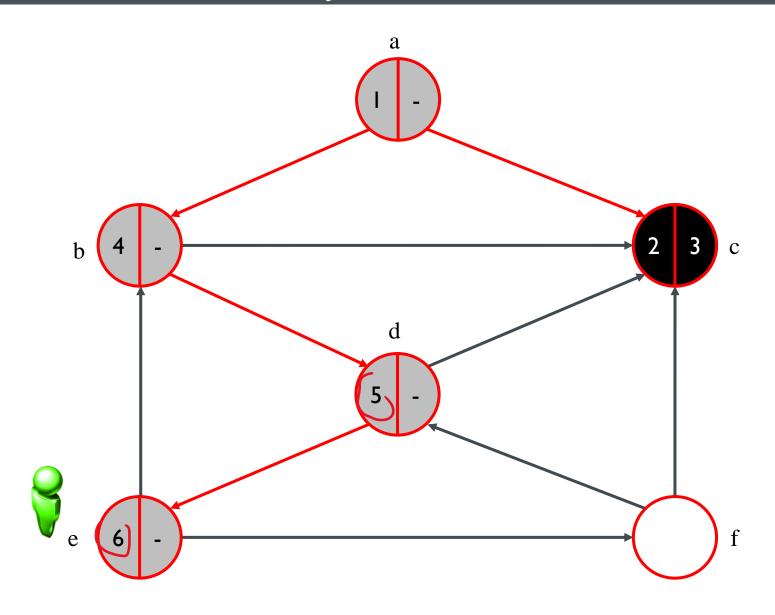


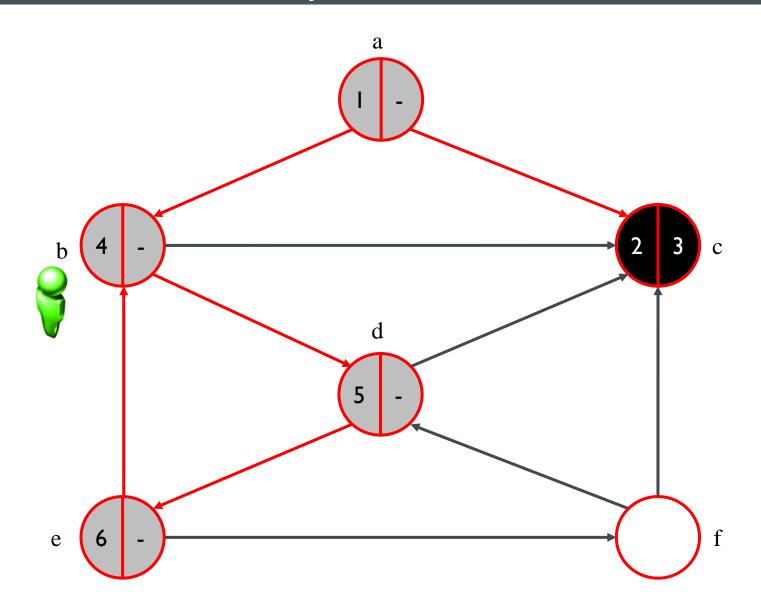


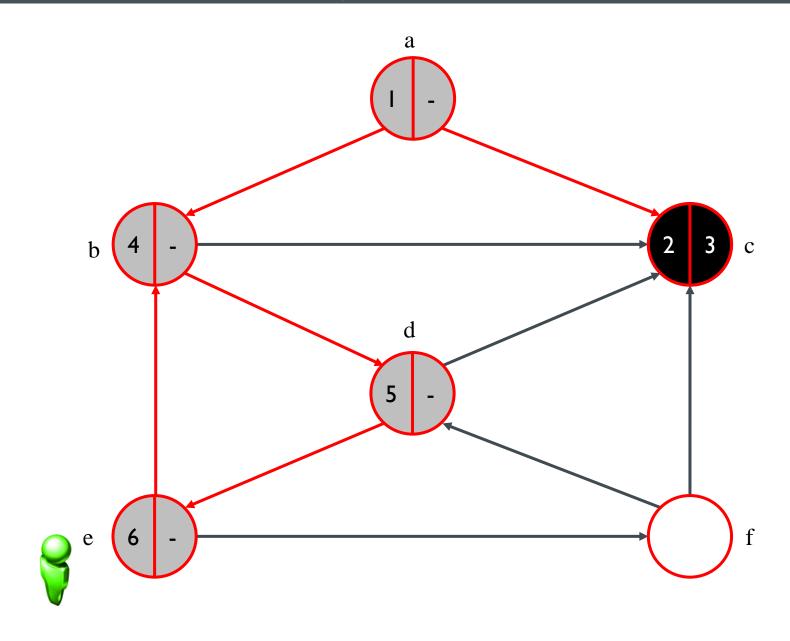


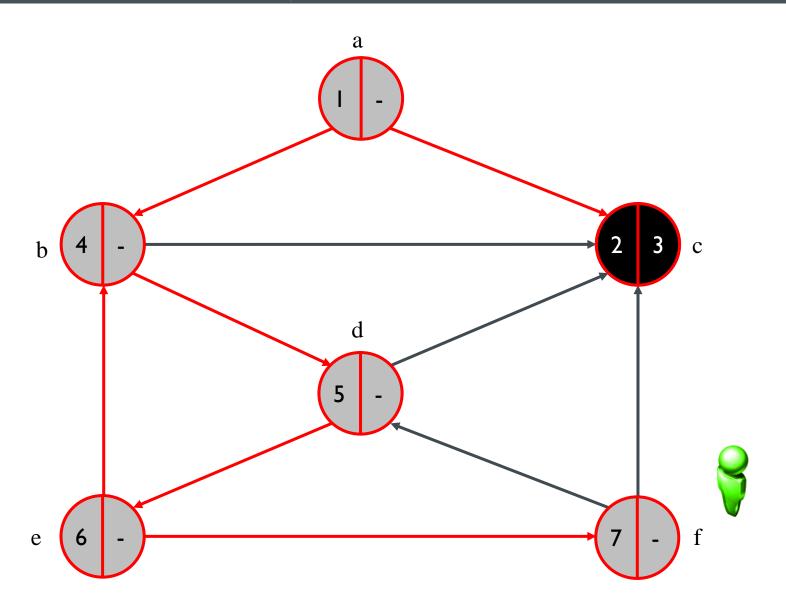


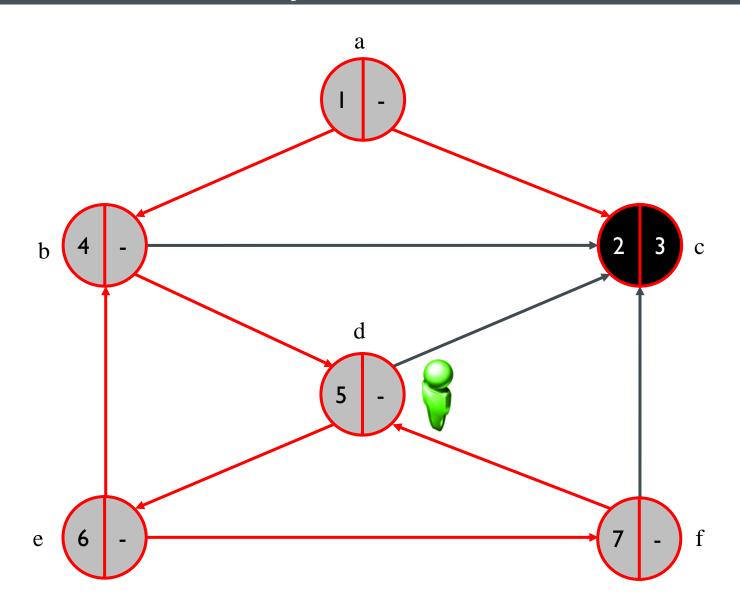


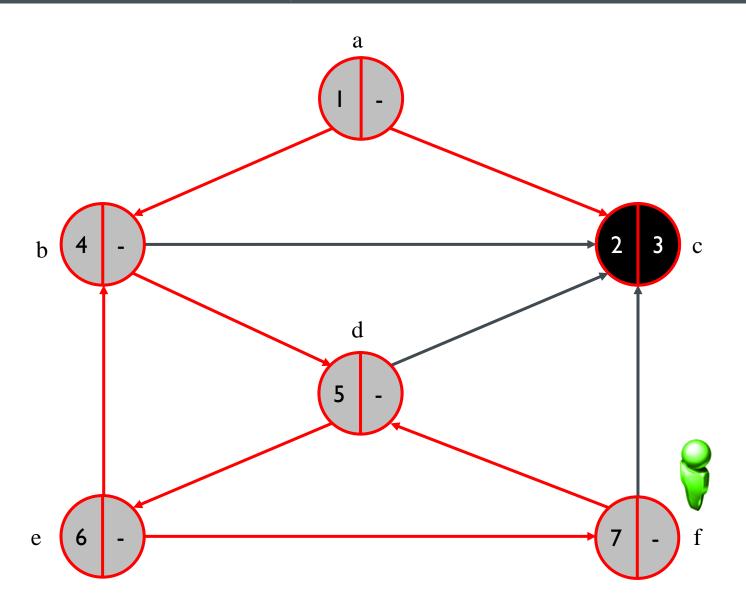


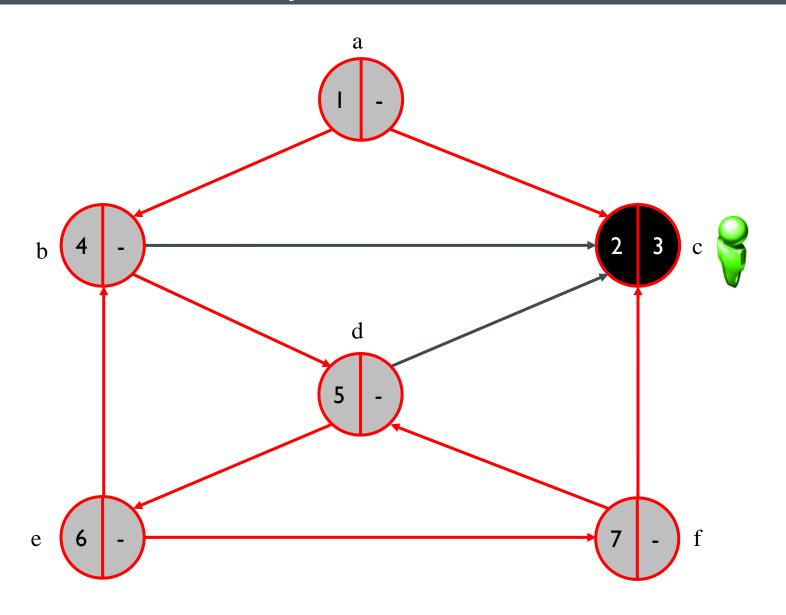


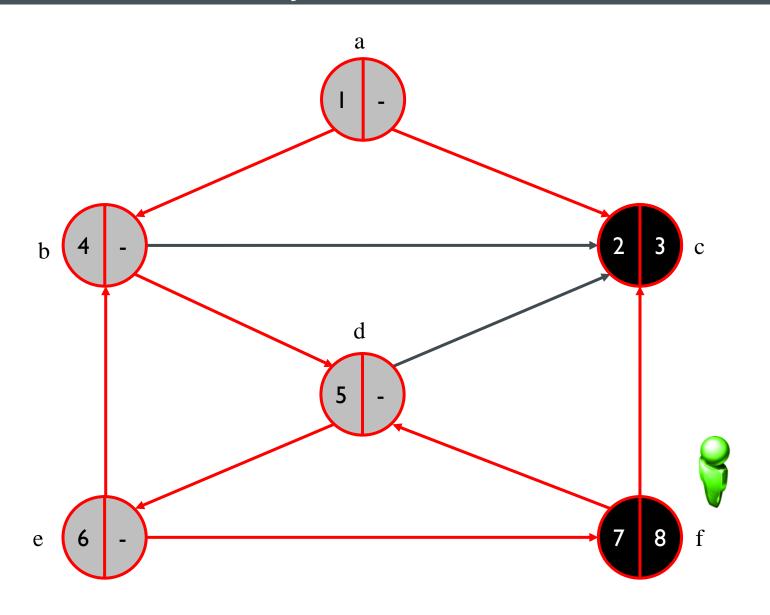


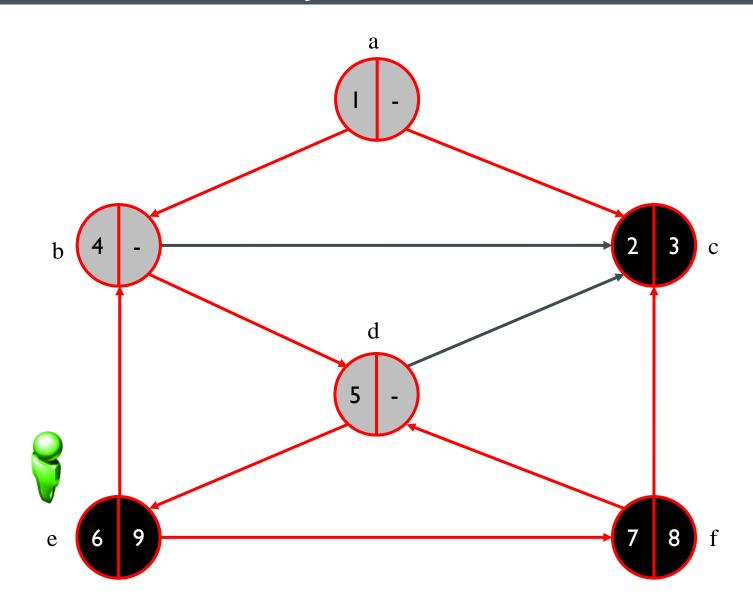


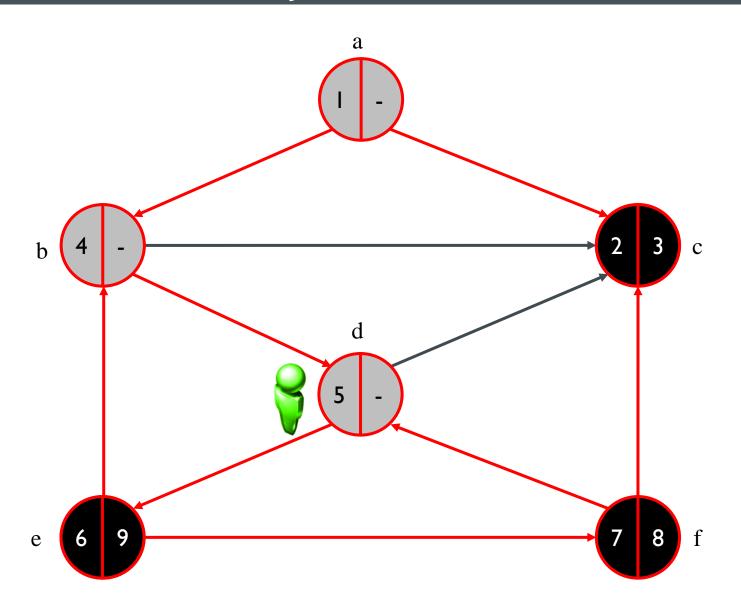


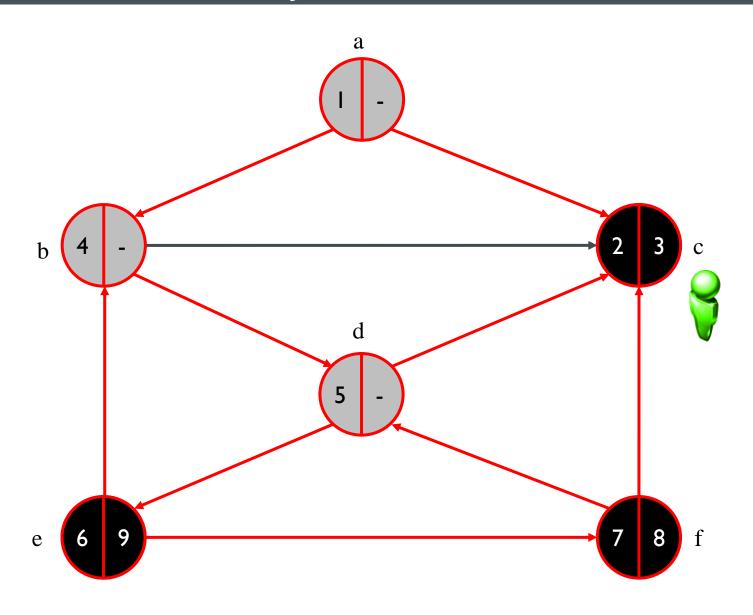


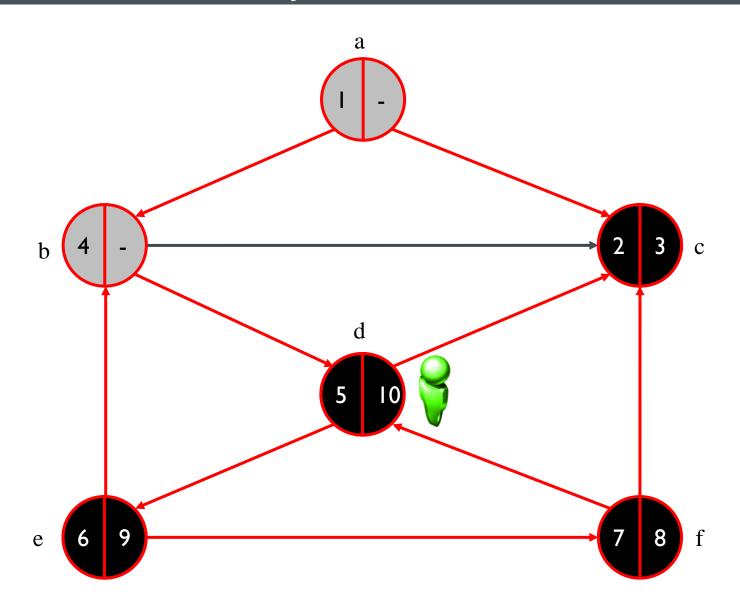


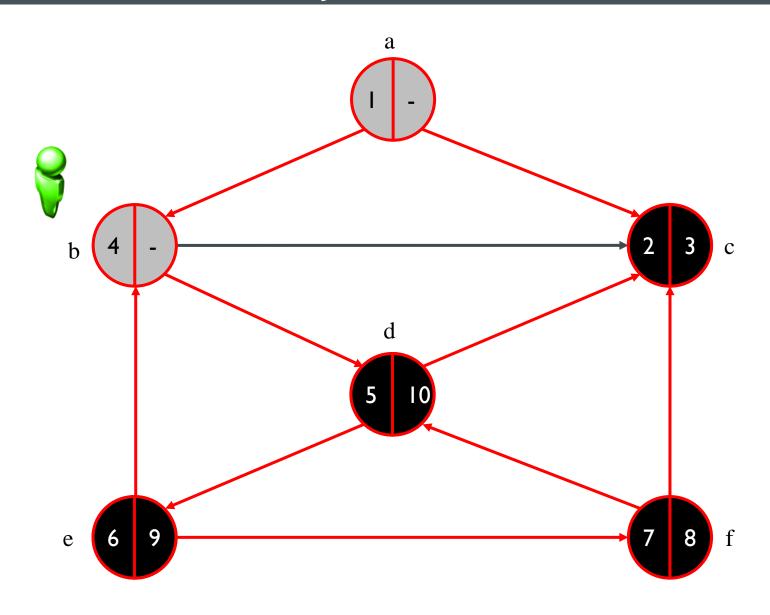


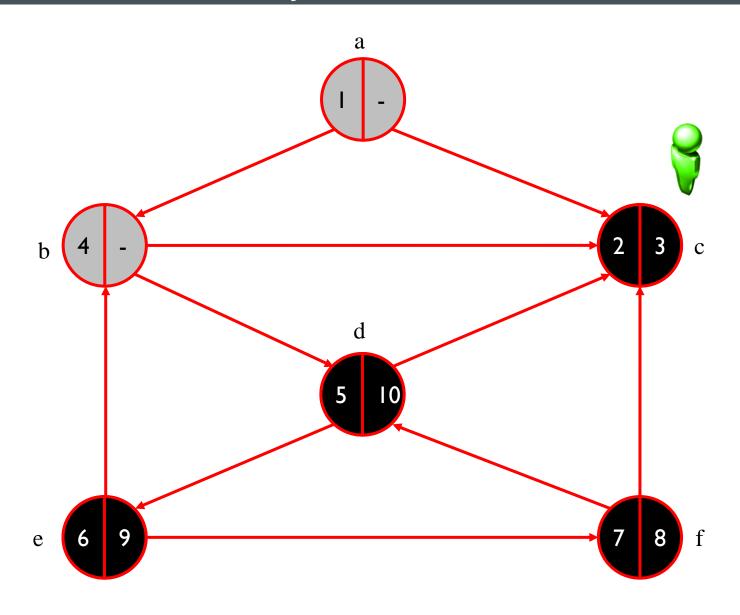


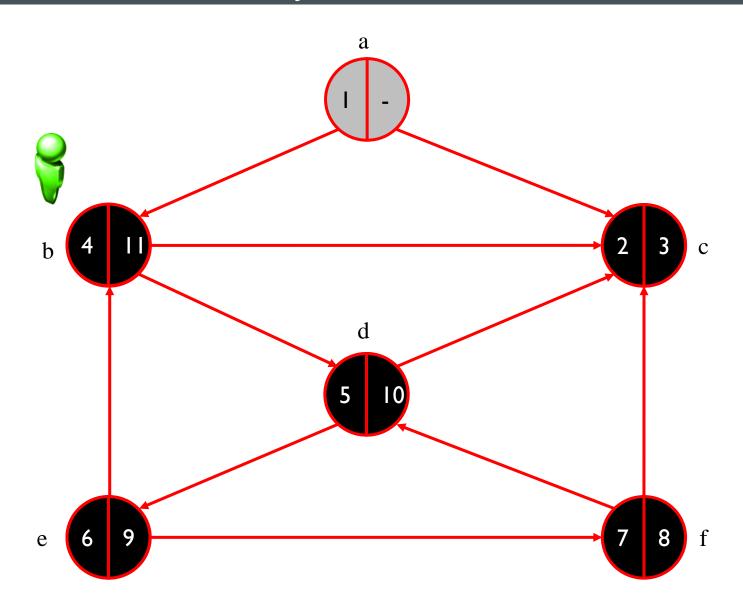


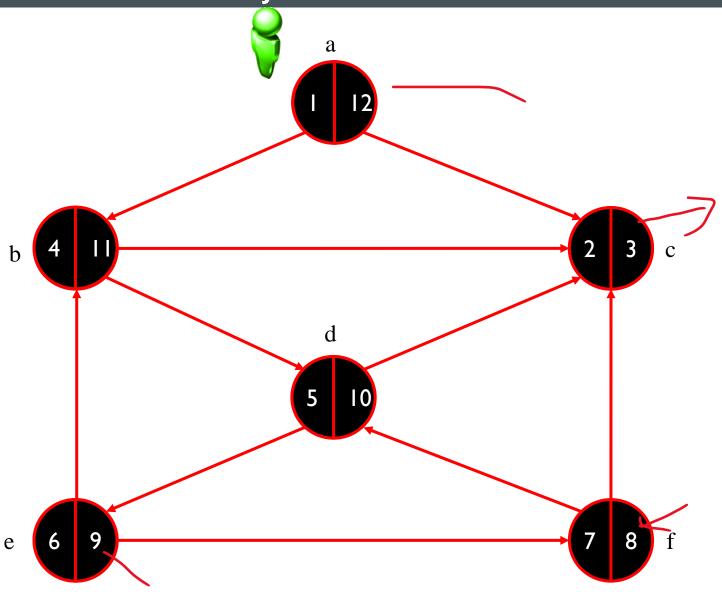


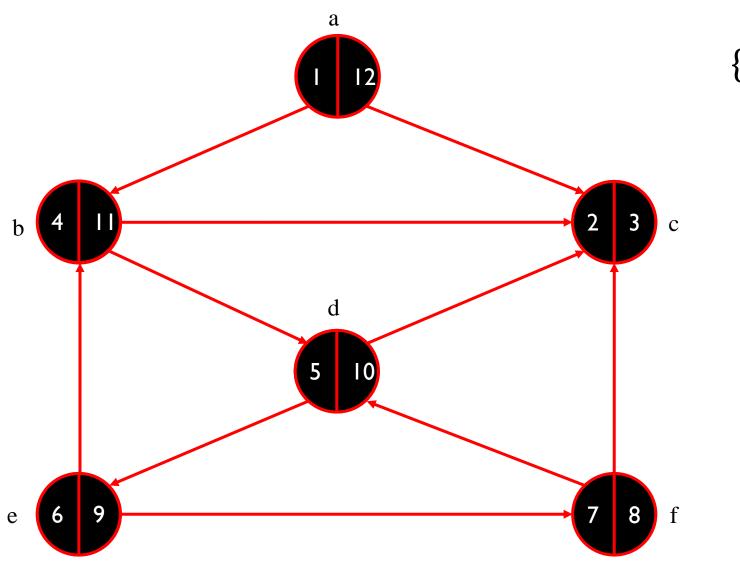




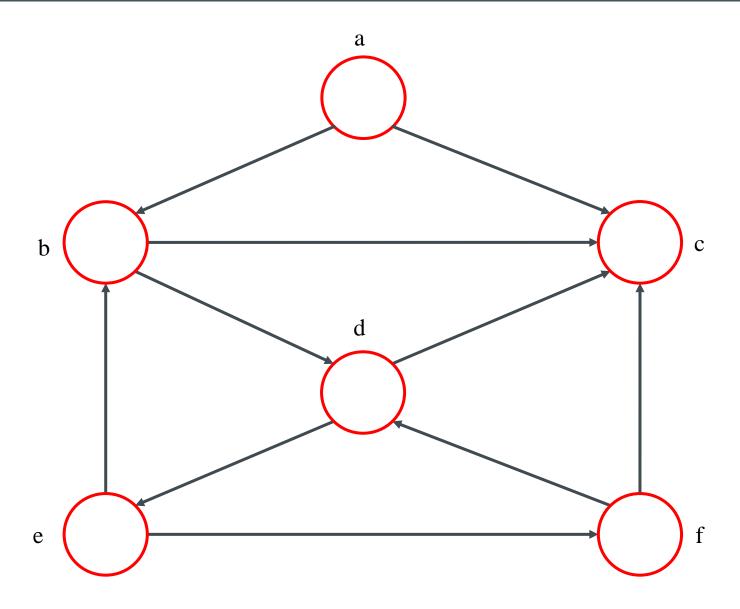


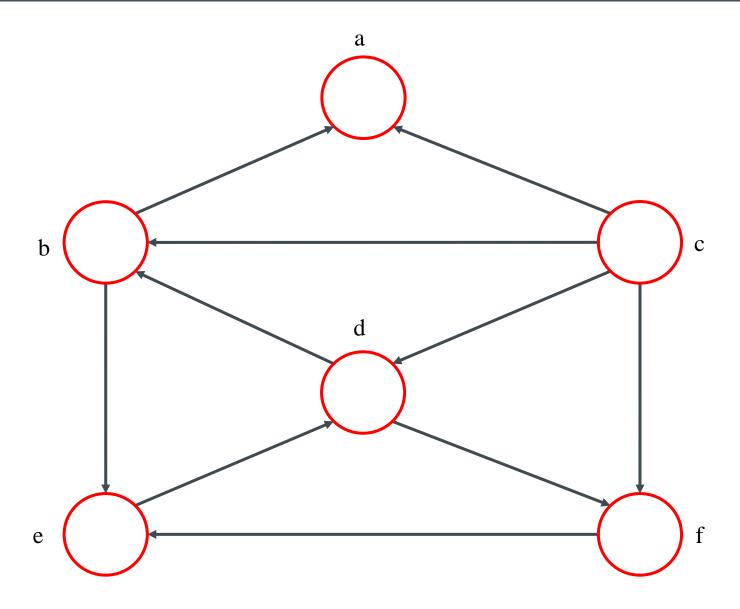


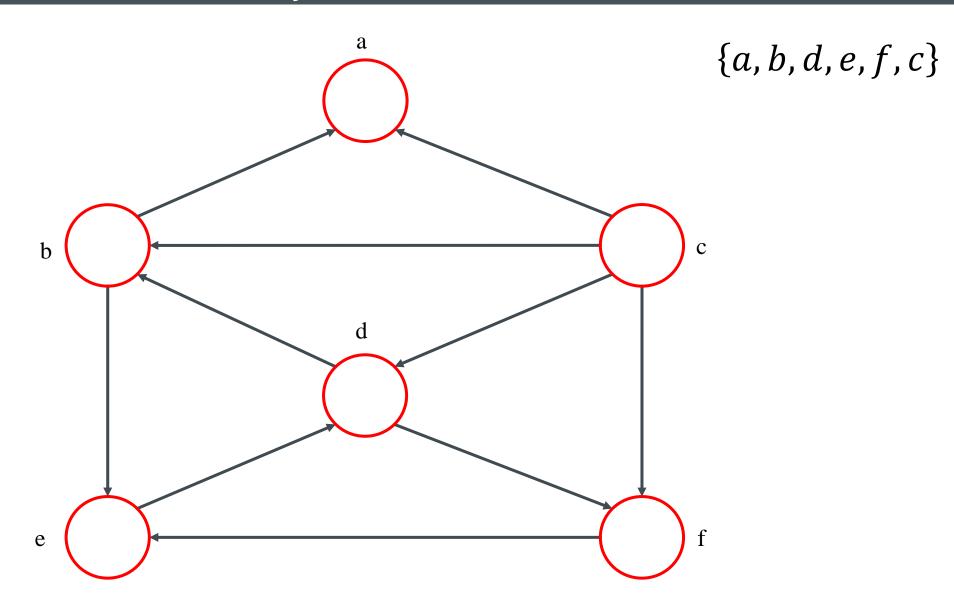




 $\{a, b, d, e, f, c\}$

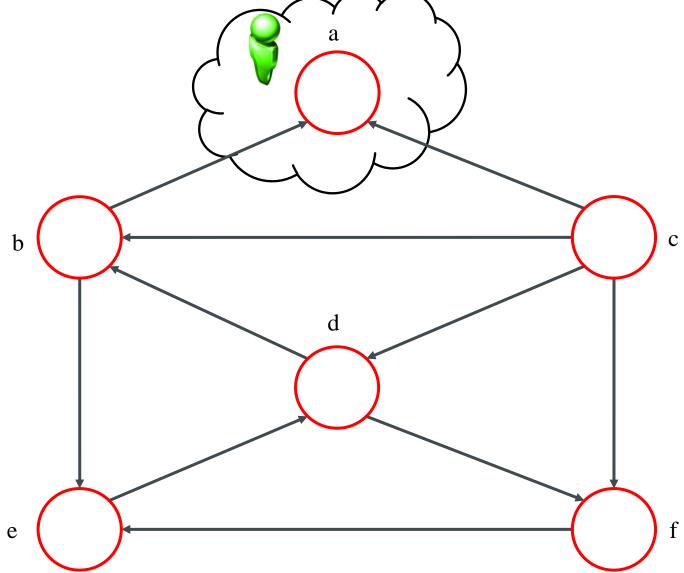








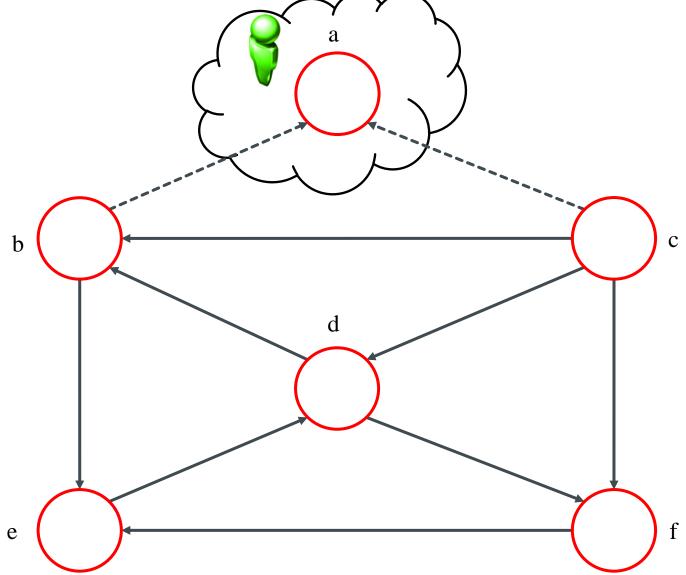
{*a*}



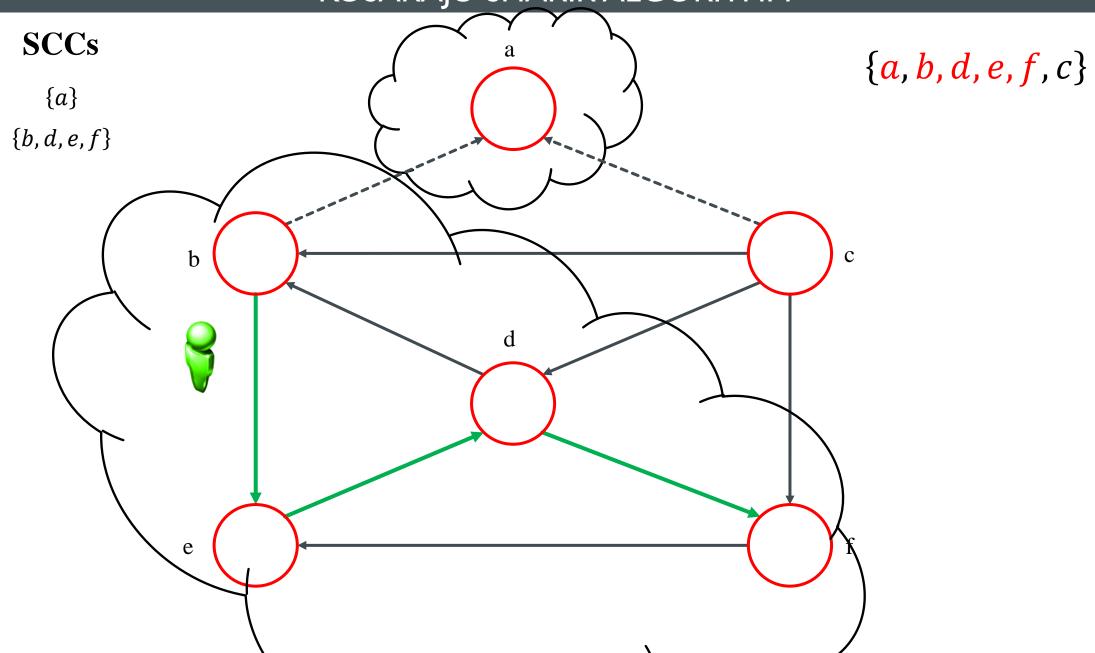
 $\{a, b, d, e, f, c\}$

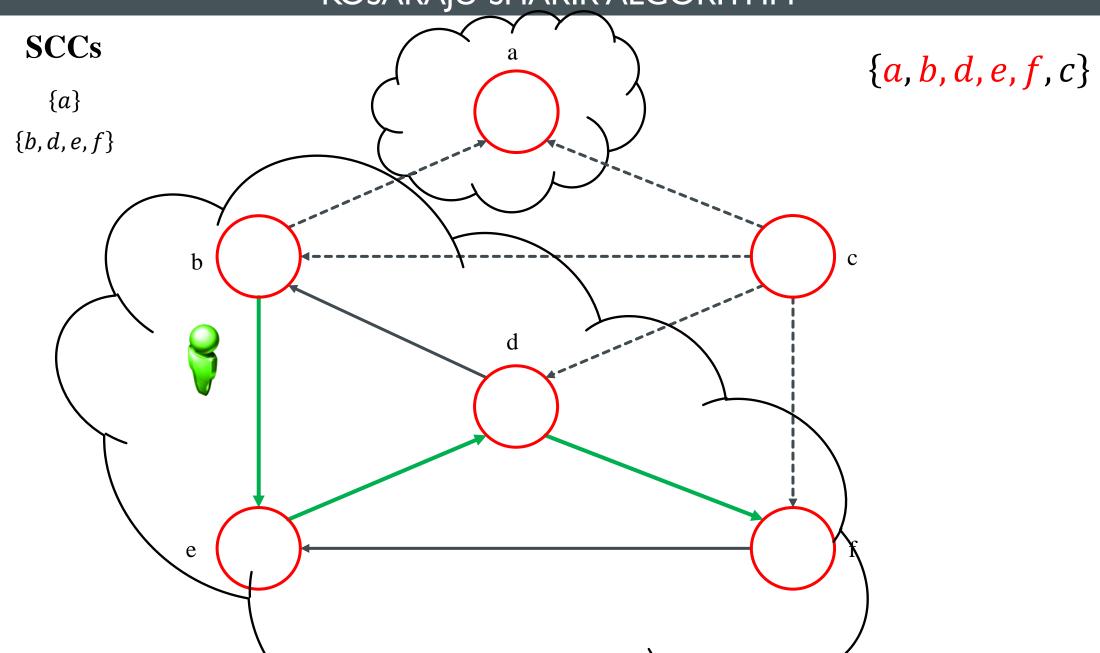


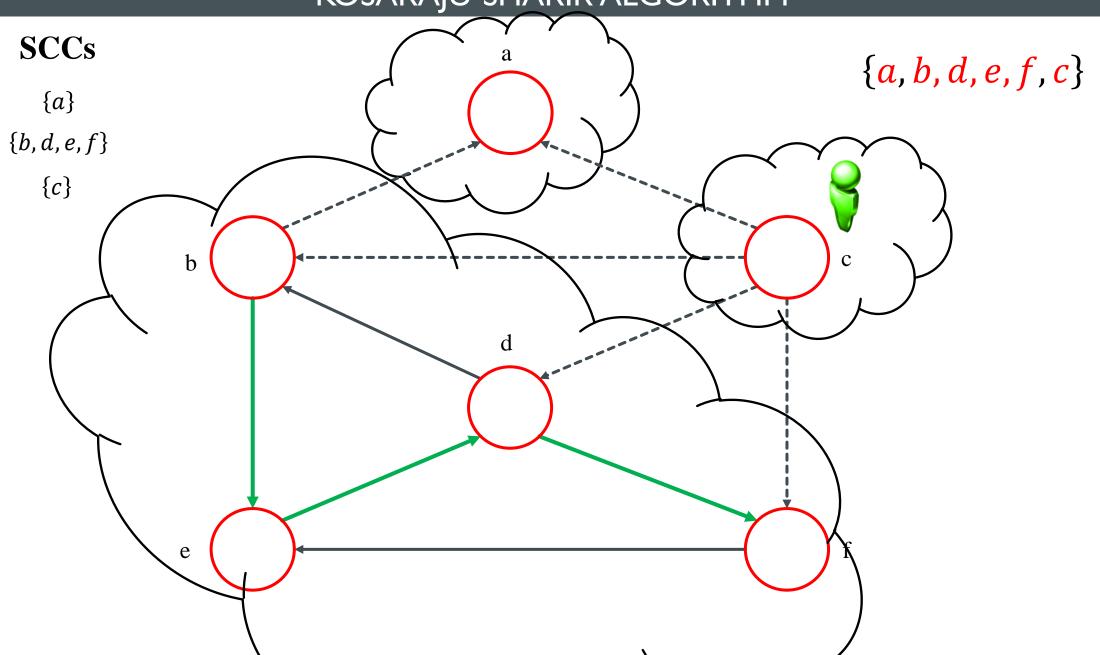
{*a*}



 $\{a, b, d, e, f, c\}$







Time Complexity

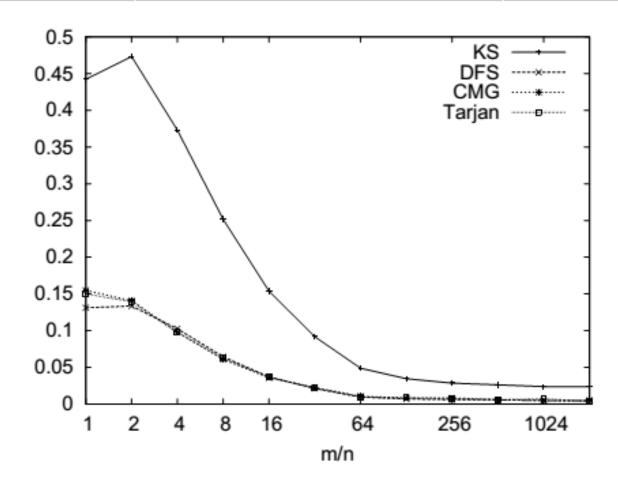
$$O(E+V)$$

Algorithm 3 Kosaraju-Sharir Algorithm

- 1: **Input:** A directed graph G = (V, L)
- 2: Output: Set of SCCs represented by SCC (initially empty)
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- 7: $L^R = L^R \cup (v, u)$
- 8: Run DFS on G^R , considering vertices in the decreasing reverse postorder.
- 9: Output the vertices of each Depth First Traversal as an SCC.

Comparison

Tarjan's Alg.	Path-Based Alg.	Kosaraju-Sharir Alg.
O(E+V)	O(E+V)	O(E+V)



[1] H. N. Gabow, "Path-based depth-first search for strong and biconnected components," *Information Processing Letters*, vol. 74, no. 3-4, pp. 107–114, 2000.

[2] M. Sharir, "A strong-connectivity algorithm and its applications in data flow analysis," *Computers & Mathematics with Applications*, vol. 7, no. 1, pp. 67–72, 1981.

QUESTIONS/ANSWERS

