**Problem 12.6.** Let A be an invertible matrix. Prove that if  $A = Q_1R_1 = Q_2R_2$  are two QR-decompositions of A and if the diagonal entries of  $R_1$  and  $R_2$  are positive, then  $Q_1 = Q_2$  and  $R_1 = R_2$ .

**Problem 12.7.** Prove that the first Hadamard inequality can be deduced from the second Hadamard inequality.

**Problem 12.8.** Let E be a real vector space of finite dimension,  $n \geq 1$ . Say that two bases,  $(u_1, \ldots, u_n)$  and  $(v_1, \ldots, v_n)$ , of E have the same orientation iff  $\det(P) > 0$ , where P the change of basis matrix from  $(u_1, \ldots, u_n)$  to  $(v_1, \ldots, v_n)$ , namely, the matrix whose jth columns consist of the coordinates of  $v_j$  over the basis  $(u_1, \ldots, u_n)$ .

(1) Prove that having the same orientation is an equivalence relation with two equivalence classes.

An orientation of a vector space, E, is the choice of any fixed basis, say  $(e_1, \ldots, e_n)$ , of E. Any other basis,  $(v_1, \ldots, v_n)$ , has the same orientation as  $(e_1, \ldots, e_n)$  (and is said to be positive or direct) iff  $\det(P) > 0$ , else it is said to have the opposite orientation of  $(e_1, \ldots, e_n)$  (or to be negative or indirect), where P is the change of basis matrix from  $(e_1, \ldots, e_n)$  to  $(v_1, \ldots, v_n)$ . An oriented vector space is a vector space with some chosen orientation (a positive basis).

(2) Let  $B_1 = (u_1, \ldots, u_n)$  and  $B_2 = (v_1, \ldots, v_n)$  be two orthonormal bases. For any sequence of vectors,  $(w_1, \ldots, w_n)$ , in E, let  $\det_{B_1}(w_1, \ldots, w_n)$  be the determinant of the matrix whose columns are the coordinates of the  $w_j$ 's over the basis  $B_1$  and similarly for  $\det_{B_2}(w_1, \ldots, w_n)$ .

Prove that if  $B_1$  and  $B_2$  have the same orientation, then

$$\det_{B_1}(w_1,\ldots,w_n)=\det_{B_2}(w_1,\ldots,w_n).$$

Given any oriented vector space, E, for any sequence of vectors,  $(w_1, \ldots, w_n)$ , in E, the common value,  $\det_B(w_1, \ldots, w_n)$ , for all positive orthonormal bases, B, of E is denoted

$$\lambda_E(w_1,\ldots,w_n)$$

and called a *volume form* of  $(w_1, \ldots, w_n)$ .

(3) Given any Euclidean oriented vector space, E, of dimension n for any n-1 vectors,  $w_1, \ldots, w_{n-1}$ , in E, check that the map

$$x \mapsto \lambda_E(w_1, \dots, w_{n-1}, x)$$

is a linear form. Then prove that there is a unique vector, denoted  $w_1 \times \cdots \times w_{n-1}$ , such that

$$\lambda_E(w_1,\ldots,w_{n-1},x)=(w_1\times\cdots\times w_{n-1})\cdot x,$$

for all  $x \in E$ . The vector  $w_1 \times \cdots \times w_{n-1}$  is called the *cross-product* of  $(w_1, \dots, w_{n-1})$ . It is a generalization of the cross-product in  $\mathbb{R}^3$  (when n = 3).