

12.5	Linear Isometries (Orthogonal Transformations) . . . . .	465
12.6	The Orthogonal Group, Orthogonal Matrices . . . . .	468
12.7	The Rodrigues Formula . . . . .	470
12.8	$QR$ -Decomposition for Invertible Matrices . . . . .	473
12.9	Some Applications of Euclidean Geometry . . . . .	478
12.10	Summary . . . . .	479
12.11	Problems . . . . .	481
<b>13</b>	<b><math>QR</math>-Decomposition for Arbitrary Matrices</b>	<b>493</b>
13.1	Orthogonal Reflections . . . . .	493
13.2	$QR$ -Decomposition Using Householder Matrices . . . . .	498
13.3	Summary . . . . .	508
13.4	Problems . . . . .	508
<b>14</b>	<b>Hermitian Spaces</b>	<b>515</b>
14.1	Hermitian Spaces, Pre-Hilbert Spaces . . . . .	515
14.2	Orthogonality, Duality, Adjoint of a Linear Map . . . . .	524
14.3	Linear Isometries (Also Called Unitary Transformations) . . . . .	529
14.4	The Unitary Group, Unitary Matrices . . . . .	531
14.5	Hermitian Reflections and $QR$ -Decomposition . . . . .	534
14.6	Orthogonal Projections and Involutions . . . . .	539
14.7	Dual Norms . . . . .	542
14.8	Summary . . . . .	549
14.9	Problems . . . . .	550
<b>15</b>	<b>Eigenvectors and Eigenvalues</b>	<b>555</b>
15.1	Eigenvectors and Eigenvalues of a Linear Map . . . . .	555
15.2	Reduction to Upper Triangular Form . . . . .	563
15.3	Location of Eigenvalues . . . . .	567
15.4	Conditioning of Eigenvalue Problems . . . . .	571
15.5	Eigenvalues of the Matrix Exponential . . . . .	573
15.6	Summary . . . . .	575
15.7	Problems . . . . .	576
<b>16</b>	<b>Unit Quaternions and Rotations in <math>\mathbf{SO}(3)</math></b>	<b>587</b>
16.1	The Group $\mathbf{SU}(2)$ and the Skew Field $\mathbb{H}$ of Quaternions . . . . .	587
16.2	Representation of Rotation in $\mathbf{SO}(3)$ By Quaternions in $\mathbf{SU}(2)$ . . . . .	589
16.3	Matrix Representation of the Rotation $r_q$ . . . . .	594
16.4	An Algorithm to Find a Quaternion Representing a Rotation . . . . .	596
16.5	The Exponential Map $\exp: \mathfrak{su}(2) \rightarrow \mathbf{SU}(2)$ . . . . .	599
16.6	Quaternion Interpolation $\otimes$ . . . . .	602
16.7	Nonexistence of a “Nice” Section from $\mathbf{SO}(3)$ to $\mathbf{SU}(2)$ . . . . .	604
16.8	Summary . . . . .	606