and if

$$dJ(u)(v-u) \ge 0$$
 for all  $v \in U$ ,

then

$$J(v) - J(u) \ge 0$$
 for all  $v \in U$ ,

as claimed.

(4) If U is open, then for every  $u \in U$  we can find an open ball B centered at u of radius  $\epsilon$  small enough so that  $B \subseteq U$ . Then for any  $w \neq 0$  such that  $||w|| < \epsilon$ , we have both  $v = u + w \in B$  and  $v' = u - w \in B$ , so Condition (3) implies that

$$dJ(u)(w) \ge 0$$
 and  $dJ(u)(-w) \ge 0$ ,

which yields

$$dJ(u)(w) = 0.$$

Since the above holds for all  $w \neq 0$  such such that  $||w|| < \epsilon$  and since dJ(u) is linear, we leave it to the reader to fill in the details of the proof that dJ(u) = 0.

**Example 40.7.** Theorem 40.13 can be used to rederive the fact that the least squares solutions of a linear system Ax = b (where A is an  $m \times n$  matrix) are given by the normal equation

$$A^{\top}Ax = A^{\top}b.$$

For this, we consider the quadratic function

$$J(v) = \frac{1}{2} \|Av - b\|_{2}^{2} - \frac{1}{2} \|b\|_{2}^{2},$$

and our least squares problem is equivalent to finding the minima of J on  $\mathbb{R}^n$ . A computation reveals that

$$J(v) = \frac{1}{2} \|Av - b\|_{2}^{2} - \frac{1}{2} \|b\|_{2}^{2}$$

$$= \frac{1}{2} (Av - b)^{\top} (Av - b) - \frac{1}{2} b^{\top} b$$

$$= \frac{1}{2} (v^{\top} A^{\top} - b^{\top}) (Av - b) - \frac{1}{2} b^{\top} b$$

$$= \frac{1}{2} v^{\top} A^{\top} Av - v^{\top} A^{\top} b,$$

and so

$$dJ(u) = A^{\top} A u - A^{\top} b.$$

Since  $A^{\top}A$  is positive semidefinite, the function J is convex, and Theorem 40.13(4) implies that the minima of J are the solutions of the equation

$$A^{\top}Au - A^{\top}b = 0.$$