If Y is a constant vector field, it is immediately verified that the map

$$X \mapsto D_Y X(a)$$

is a linear map called the *derivative* of the vector field X, and denoted by DX(a). If $f: E \to \mathbb{R}$ is a function, we define $D_Y f(a)$ as the limit (if it exists)

$$\lim_{t \to 0, t \in U} \frac{f(a + tY(a)) - f(a)}{t},$$

where $U = \{t \in \mathbb{R} \mid a + tY(a) \in \Omega, t \neq 0\}$. It is the directional derivative of f w.r.t. the vector field Y at a, and it is also often denoted by Y(f)(a), or $Y(f)_a$.

From now on, we assume that all the vector fields and all the functions under consideration are smooth (C^{∞}) . The set $C^{\infty}(\Omega)$ of smooth C^{∞} -functions $f : \Omega \to \mathbb{R}$ is a ring. Given a smooth vector field X and a smooth function f (both over Ω), the vector field fX is defined such that (fX)(a) = f(a)X(a), and it is immediately verified that it is smooth. Thus, the set $\mathcal{X}(\Omega)$ of smooth vector fields over Ω is a $C^{\infty}(\Omega)$ -module.

The following proposition is left as an exercise. It shows that $D_Y X(a)$ is a \mathbb{R} -bilinear map on $\mathcal{X}(\Omega)$, is $C^{\infty}(\Omega)$ -linear in Y, and satisfies the Leibniz derivation rules with respect to X.

Proposition 39.28. The covariant derivative $D_YX(a)$ satisfies the following properties:

$$D_{(Y_1+Y_2)}X(a) = D_{Y_1}X(a) + D_{Y_2}X(a),$$

$$D_{fY}X(a) = f(a)D_YX(a),$$

$$D_Y(X_1 + X_2)(a) = D_YX_1(a) + D_YX_2(a),$$

$$D_YfX(a) = D_Yf(a)X(a) + f(a)D_YX(a),$$

where X, Y, X_1, X_2, Y_1, Y_2 are smooth vector fields over Ω , and $f: E \to \mathbb{R}$ is a smooth function.

In differential geometry, the above properties are taken as the axioms of affine connections, in order to define covariant derivatives of vector fields over manifolds. In many cases, the vector field Y is the tangent field of some smooth curve γ :] $-\eta$, η [$\to E$. If so, the following proposition holds.

Proposition 39.29. Given a smooth curve γ : $] - \eta, \eta[\to E, letting Y be the vector field defined on <math>\gamma(] - \eta, \eta[)$ such that

$$Y(\gamma(u)) = \frac{d\gamma}{dt}(u),$$

for any vector field X defined on $\gamma(]-\eta,\eta[)$, we have

$$D_Y X(a) = \frac{d}{dt} \left[X(\gamma(t)) \right] (0),$$

where $a = \gamma(0)$.