**Remark:** The isomorphism (3) can be generalized to finite and even arbitrary direct sums  $\bigoplus_{i \in I} E_i$  of vector spaces (where I is an arbitrary nonempty index set). We have an isomorphism

$$\left(\bigoplus_{i\in I} E_i\right)\otimes G\cong \bigoplus_{i\in I}\left(E_i\otimes G\right).$$

This isomorphism (with isomorphism (1)) can be used to give another proof of Proposition 33.12 (see Bertin [15], Chapter 4, Section 1) or Lang [109], Chapter XVI, Section 2).

**Proposition 33.14.** Given any three vector spaces E, F, G, we have the canonical isomorphism

$$\operatorname{Hom}(E, F; G) \cong \operatorname{Hom}(E, \operatorname{Hom}(F, G)).$$

*Proof.* Any bilinear map  $f: E \times F \to G$  gives the linear map  $\varphi(f) \in \text{Hom}(E, \text{Hom}(F, G))$ , where  $\varphi(f)(u)$  is the linear map in Hom(F, G) given by

$$\varphi(f)(u)(v) = f(u, v).$$

Conversely, given a linear map  $g \in \text{Hom}(E, \text{Hom}(F, G))$ , we get the bilinear map  $\psi(g)$  given by

$$\psi(q)(u,v) = q(u)(v),$$

and it is clear that  $\varphi$  and  $\psi$  and mutual inverses.

Since by Proposition 33.7 there is a canonical isomorphism

$$\operatorname{Hom}(E \otimes F, G) \cong \operatorname{Hom}(E, F; G),$$

together with the isomorphism

$$\operatorname{Hom}(E, F; G) \cong \operatorname{Hom}(E, \operatorname{Hom}(F, G))$$

given by Proposition 33.14, we obtain the important corollary:

**Proposition 33.15.** For any three vector spaces E, F, G, we have the canonical isomorphism

$$\operatorname{Hom}(E \otimes F, G) \cong \operatorname{Hom}(E, \operatorname{Hom}(F, G)).$$

## 33.5 Duality for Tensor Products

In this section all vector spaces are assumed to have *finite dimension*, unless specified otherwise. Let us now see how tensor products behave under duality. For this, we define a pairing between  $E_1^* \otimes \cdots \otimes E_n^*$  and  $E_1 \otimes \cdots \otimes E_n$  as follows: For any fixed  $(v_1^*, \ldots, v_n^*) \in E_1^* \times \cdots \times E_n^*$ , we have the multilinear map

$$l_{v_1^*,\dots,v_n^*}: (u_1,\dots,u_n) \mapsto v_1^*(u_1) \cdots v_n^*(u_n)$$