## 10.6 Summary

The main concepts and results of this chapter are listed below:

- Iterative methods. Splitting A as A = M N.
- Convergence of a sequence of vectors or matrices.
- A criterion for the convergence of the sequence  $(B^k)$  of powers of a matrix B to zero in terms of the spectral radius  $\rho(B)$ .
- A characterization of the spectral radius  $\rho(B)$  as the limit of the sequence  $(\|B^k\|^{1/k})$ .
- A criterion of the convergence of iterative methods.
- Asymptotic behavior of iterative methods.
- Splitting A as A = D E F, and the methods of Jacobi, Gauss-Seidel, and relaxation (and SOR).
- The Jacobi matrix,  $J = D^{-1}(E + F)$ .
- The Gauss-Seidel matrix,  $\mathcal{L}_1 = (D E)^{-1}F$ .
- The matrix of relaxation,  $\mathcal{L}_{\omega} = (D \omega E)^{-1}((1 \omega)D + \omega F)$ .
- Convergence of iterative methods: a general result when A = M N is Hermitian positive definite.
- A sufficient condition for the convergence of the methods of Jacobi, Gauss–Seidel, and relaxation. The *Ostrowski-Reich theorem*: A is Hermitian positive definite and  $\omega \in (0,2)$ .
- A necessary condition for the convergence of the methods of Jacobi , Gauss–Seidel, and relaxation:  $\omega \in (0, 2)$ .
- The case of tridiagonal matrices (possibly by blocks). Simultaneous convergence or divergence of Jacobi's method and Gauss–Seidel's method, and comparison of the spectral radii of  $\rho(J)$  and  $\rho(\mathcal{L}_1)$ :  $\rho(\mathcal{L}_1) = (\rho(J))^2$ .
- The case of tridiagonal Hermitian positive definite matrices (possibly by blocks). The methods of Jacobi, Gauss–Seidel, and relaxation, all converge.
- In the above case, there is a unique optimal relaxation parameter for which  $\rho(\mathcal{L}_{\omega_0}) < \rho(\mathcal{L}_1) = (\rho(J))^2 < \rho(J)$  (if  $\rho(J) \neq 0$ ).