

and it is unique, since  $\vec{f} - \text{id}$  is injective. Conversely, if  $f$  has a unique fixed point, say  $a$ , from

$$(\vec{f} - \text{id})(\vec{\Omega a}) = -\vec{\Omega f(\Omega)},$$

we have  $(\vec{f} - \text{id})(\vec{\Omega a}) = 0$  iff  $f(\Omega) = \Omega$ , and since  $a$  is the unique fixed point of  $f$ , we must have  $a = \Omega$ , which shows that  $\vec{f} - \text{id}$  is injective.  $\square$

**Remark:** The fact that  $E$  has finite dimension is used only to prove (2), and (1) holds in general.

If an affine isometry  $f$  leaves some point fixed, we can take such a point  $\Omega$  as the origin, and then  $f(\Omega) = \Omega$  and we can view  $f$  as a rotation or an improper orthogonal transformation, depending on the nature of  $\vec{f}$ . Note that it is quite possible that  $\text{Fix}(f) = \emptyset$ . For example, nontrivial translations have no fixed points. A more interesting example is provided by the composition of a plane reflection about a line composed with a nontrivial translation parallel to this line.

Otherwise, we will see in Theorem 27.10 that every affine isometry is the (commutative) composition of a translation with an affine isometry that always has a fixed point.

## 27.4 Affine Isometries and Fixed Points

Let  $E$  be an affine space. Given any two affine subspaces  $F, G$ , if  $F$  and  $G$  are orthogonal complements in  $E$ , which means that  $\vec{F}$  and  $\vec{G}$  are orthogonal subspaces of  $\vec{E}$  such that  $\vec{E} = \vec{F} \oplus \vec{G}$ , for any point  $\Omega \in F$ , we define  $q: E \rightarrow G$  such that

$$q(a) = p_{\vec{G}}(\vec{\Omega a}).$$

Note that  $q(a)$  is independent of the choice of  $\Omega \in F$ , since we have

$$\vec{\Omega a} = p_{\vec{F}}(\vec{\Omega a}) + p_{\vec{G}}(\vec{\Omega a}),$$

and for any  $\Omega_1 \in F$ , we have

$$\vec{\Omega_1 a} = \vec{\Omega_1 \Omega} + p_{\vec{F}}(\vec{\Omega a}) + p_{\vec{G}}(\vec{\Omega a}),$$

and since  $\vec{\Omega_1 \Omega} \in \vec{F}$ , this shows that

$$p_{\vec{G}}(\vec{\Omega_1 a}) = p_{\vec{G}}(\vec{\Omega a}).$$

Then the map  $g: E \rightarrow E$  such that  $g(a) = a - 2q(a)$ , or equivalently

$$\vec{ag(a)} = -2q(a) = -2p_{\vec{G}}(\vec{\Omega a}),$$