

where $a = (a_1, \dots, a_d)$.

Thus, we are looking for a unit vector a solving $(X - \mu)a = 0$ in the least squares sense, that is, some a such that $a^\top a = 1$ minimizing

$$a^\top (X - \mu)^\top (X - \mu) a.$$

Compute some SVD VDU^\top of $X - \mu$, where the main diagonal of D consists of the singular values $\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_d$ of $X - \mu$ arranged in descending order. Then

$$a^\top (X - \mu)^\top (X - \mu) a = a^\top U D^2 U^\top a,$$

where $D^2 = \text{diag}(\sigma_1^2, \dots, \sigma_d^2)$ is a diagonal matrix, so pick a to be *the last column in U* (corresponding to the smallest eigenvalue σ_d^2 of $(X - \mu)^\top (X - \mu)$). This is a solution to our best fit problem.

Therefore, if U_{d-1} is the linear hyperplane defined by a , that is,

$$U_{d-1} = \{u \in \mathbb{R}^d \mid \langle u, a \rangle = 0\},$$

where a is the last column in U for some SVD VDU^\top of $X - \mu$, we have shown that the affine hyperplane $A_1 = \mu + U_{d-1}$ is a best approximation of the data set X_1, \dots, X_n in the least squares sense.

It is easy to show that this hyperplane $A_1 = \mu + U_{d-1}$ minimizes the sum of the square distances of each X_i to its orthogonal projection onto A_1 . Also, since U_{d-1} is the orthogonal complement of a , the last column of U , we see that U_{d-1} is spanned by the first $d-1$ columns of U , that is, the first $d-1$ principal directions of $X - \mu$.

All this can be generalized to a *best $(d-k)$ -dimensional affine subspace A_k approximating X_1, \dots, X_n in the least squares sense* ($1 \leq k \leq d-1$). Such an affine subspace A_k is cut out by k independent hyperplanes H_i (with $1 \leq i \leq k$), each given by some equation

$$a_{i1}x_1 + \dots + a_{id}x_d + c_i = 0.$$

If we write $a_i = (a_{i1}, \dots, a_{id})$, to say that the H_i are independent means that a_1, \dots, a_k are linearly independent. In fact, we may assume that a_1, \dots, a_k form an *orthonormal system*.

Then finding a best $(d-k)$ -dimensional affine subspace A_k amounts to solving the homogeneous linear system

$$\begin{pmatrix} X & \mathbf{1} & 0 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 0 & X & \mathbf{1} \end{pmatrix} \begin{pmatrix} a_1 \\ c_1 \\ \vdots \\ a_k \\ c_k \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 0 \end{pmatrix},$$