so the feasibility equations become

$$Ax = b$$
$$Px + q + A^{\mathsf{T}}\lambda = 0,$$

which in matrix form become

$$\begin{pmatrix} P & A^{\top} \\ A & 0 \end{pmatrix} \begin{pmatrix} x \\ \lambda \end{pmatrix} = \begin{pmatrix} -q \\ b \end{pmatrix}. \tag{KKT-eq}$$

The matrix of the linear system is usually called the *KKT-matrix*. Observe that the KKT matrix was already encountered in Proposition 42.3 with a different notation; there we had  $P = A^{-1}$ ,  $A = B^{T}$ , q = b, and b = f.

If the KKT matrix is invertible, then its unique solution  $(x^*, \lambda^*)$  yields a unique minimum  $x^*$  of Problem (P). If the KKT matrix is singular but the System (KKT-eq) is solvable, then any solution  $(x^*, \lambda^*)$  yields a minimum  $x^*$  of Problem (P).

**Proposition 50.10.** If the System (KKT-eq) is not solvable, then Program (P) is unbounded below.

*Proof.* We use the fact shown in Section 30.7, that a linear system Bx = c has no solution iff there is some y that  $B^{\top}y = 0$  and  $y^{\top}c \neq 0$ . By changing y to -y if necessary, we may assume that  $y^{\top}c > 0$ . We apply this fact to the linear system (KKT-eq), so B is the KKT-matrix, which is symmetric, and we obtain the condition that there exist  $v \in \mathbb{R}^n$  and  $\lambda \in \mathbb{R}^m$  such that

$$Pv + A^{\mathsf{T}}\lambda = 0$$
,  $Av = 0$ ,  $-q^{\mathsf{T}}v + b^{\mathsf{T}}\lambda > 0$ .

Since the  $m \times n$  matrix A has rank m and  $b \in \mathbb{R}^m$ , the system Ax = b, is solvable, so for any feasible  $x_0$  (which means that  $Ax_0 = b$ ), since Av = 0, the vector  $x = x_0 + tv$  is also a feasible solution for all  $t \in \mathbb{R}$ . Using the fact that  $Pv = -A^{\top}\lambda$ ,  $v^{\top}P = -\lambda^{\top}A$ , Av = 0,  $x_0^{\top}A^{\top} = b^{\top}$ , and P is symmetric, we have

$$J(x_0 + tv) = J(x_0) + (v^{\top} P x_0 + q^{\top} v)t + (1/2)(v^{\top} P v)t^2$$
  
=  $J(x_0) + (x_0^{\top} P v + q^{\top} v)t - (1/2)(\lambda^{\top} A v)t^2$   
=  $J(x_0) + (-x_0^{\top} A^{\top} \lambda + q^{\top} v)t$   
=  $J(x_0) - (b^{\top} \lambda - q^{\top} v)t$ ,

and since  $-q^{\top}v + b^{\top}\lambda > 0$ , the above expression goes to  $-\infty$  when t goes to  $+\infty$ .

It is obviously important to have criteria to decide whether the KKT-matrix is invertible. There are indeed such criteria, as pointed in Boyd and Vandenberghe [29] (Chapter 10, Exercise 10.1).