(over K[X]). What Theorem 36.20 tells us is that there are K[X]-bases (u_1, \ldots, u_n) and (v_1, \ldots, v_n) of E_f with respect to which the matrix of ψ is D. Then

$$\psi(u_i) = v_i, \quad i = 1, \dots, n - m,$$

 $\psi(u_{n-m+i}) = q_i v_{n-m+i}, \quad i = 1, \dots, m,$

and because $\operatorname{Im}(\psi) = \operatorname{Ker}(\sigma)$, this implies that

$$\sigma(v_i) = 0, \quad i = 1, \dots, n - m.$$

Consequently, $w_1 = \sigma(v_{n-m+1}), \ldots, w_m = \sigma(v_n)$ span E_f as a K[X]-module, with $w_i \in E$, and we have

$$M(f) = K[X]w_1 \oplus \cdots \oplus K[X]w_m,$$

where $K[X]w_i \approx K[X]/(q_i)$ as a cyclic K[X]-module. Since $Im(\psi) = Ker(\sigma)$, we have

$$0 = \sigma(\psi(u_{n-m+i})) = \sigma(q_i v_{n-m+i}) = q_i \sigma(v_{n-m+i}) = q_i w_i,$$

so as a K-vector space, the cyclic subspace $Z(w_i; f) = K[X]w_i$ has q_i as annihilator, and by a remark from Section 36.1, it has the basis (over K)

$$(w_i, f(w_i), \dots, f^{n_i-1}(w_i)), \quad n_i = \deg(q_i).$$

Furthermore, over this basis, the restriction of f to $Z(w_i; f)$ is represented by the companion matrix of q_i . By putting all these bases together, we obtain a block matrix which is the canonical rational form of f (and A).

Now, $XI - A = QDP^{-1}$ is the matrix of ψ with respect to the canonical basis (e_1, \ldots, e_n) (over K[X]), and D is the matrix of ψ with respect to the bases (u_1, \ldots, u_n) and (v_1, \ldots, v_n) (over K[X]), which tells us that the columns of Q consist of the coordinates (in K[X]) of the basis vectors (v_1, \ldots, v_n) with respect to the basis (e_1, \ldots, e_n) . Therefore, the coordinates (in K) of the vectors (w_1, \ldots, w_m) spanning E_f over K[X], where $w_i = \sigma(v_{n-m+i})$, are obtained by substituting the matrix A for X in the coordinates of the columns vectors of Q, and evaluating the resulting expressions.

Since

$$D = Q^{-1}(XI - A)P,$$

the matrix D is obtained from A by a sequence of elementary row operations whose product is Q^{-1} and a sequence of elementary column operations whose product is P. Therefore, to compute the vectors w_1, \ldots, w_m from A, we simply have to figure out how to construct Q from the sequence of elementary row operations that yield Q^{-1} . The trick is to use column operations to gather a product of row operations in reverse order.

Indeed, if Q^{-1} is the product of elementary row operations

$$Q^{-1} = E_k \cdots E_2 E_1,$$