where Q is an orthogonal matrix and D is a diagonal matrix,

$$D = \operatorname{diag}(d_1, \dots, d_n),$$

with  $d_i > 0$ , for i = 1, ..., n. If we define the matrices  $B^{1/2}$  and  $B^{-1/2}$  by

$$B^{1/2} = Q \operatorname{diag}\left(\sqrt{d_1}, \dots, \sqrt{d_n}\right) Q^{\top}$$

and

$$B^{-1/2} = Q \operatorname{diag}\left(1/\sqrt{d_1}, \dots, 1/\sqrt{d_n}\right) Q^{\top},$$

it is clear that these matrices are symmetric, that  $B^{-1/2}BB^{-1/2}=I$ , and that  $B^{1/2}$  and  $B^{-1/2}$  are mutual inverses. Then if we make the change of variable

$$x = B^{-1/2}y,$$

the equation  $x^{\top}Bx = 1$  becomes  $y^{\top}y = 1$ , and the optimization problem

minimize 
$$x^{\top}Ax$$
  
subject to  $x^{\top}Bx = 1, x \in \mathbb{R}^n$ ,

is equivalent to the problem

minimize 
$$y^{\top}B^{-1/2}AB^{-1/2}y$$
  
subject to  $y^{\top}y = 1, y \in \mathbb{R}^n$ ,

where  $y = B^{1/2}x$  and  $B^{-1/2}AB^{-1/2}$  are symmetric.

The complex version of our basic optimization problem in which A is a Hermitian matrix also arises in computer vision. Namely, given an  $n \times n$  complex Hermitian matrix A,

maximize 
$$x^*Ax$$
  
subject to  $x^*x = 1, x \in \mathbb{C}^n$ .

Again by Proposition 23.10, the maximum value of  $x^*Ax$  on the unit sphere is equal to the largest eigenvalue  $\lambda_1$  of the matrix A, and it is achieved for any unit eigenvector  $u_1$  associated with  $\lambda_1$ .

**Remark:** It is worth pointing out that if A is a skew-Hermitian matrix, that is, if  $A^* = -A$ , then  $x^*Ax$  is pure imaginary or zero.

Indeed, since  $z = x^*Ax$  is a scalar, we have  $z^* = \overline{z}$  (the conjugate of z), so we have

$$\overline{x^*Ax} = (x^*Ax)^* = x^*A^*x = -x^*Ax,$$

so  $\overline{x^*Ax} + x^*Ax = 2\text{Re}(x^*Ax) = 0$ , which means that  $x^*Ax$  is pure imaginary or zero.