If we pick $\rho > 0$ such that $\rho < 2\alpha/C^2$, then

$$k^2 = 1 - 2\rho\alpha + \rho^2 C^2 < 1,$$

and then

$$||F(v_1) - F(v_2)|| \le k ||v_1 - v_2||, \tag{*7}$$

with $0 \le k < 1$, which shows that F is a contraction. By Theorem 49.5, the map F has a unique fixed point $u \in U$, which concludes the proof of the first statement. If a is also symmetric, then the second statement is just the first part of Theorem 49.4.

Remark: Many physical problems can be expressed in terms of an unknown function u that satisfies some inequality

$$a(u, v - u) \ge h(v - u)$$
 for all $v \in U$,

for some set U of "admissible" functions which is closed and convex. The bilinear form a and the linear form h are often given in terms of integrals. The above inequality is called a variational inequality.

In the special case where U = V we obtain the Lax–Milgram theorem.

Theorem 49.7. (Lax–Milgram's Theorem) Given a Hilbert space V, let $a: V \times V \to \mathbb{R}$ be a continuous bilinear form (not necessarily symmetric), let $h \in V'$ be a continuous linear form, and let J be given by

$$J(v) = \frac{1}{2}a(v,v) - h(v), \quad v \in V.$$

If a is coercive, which means that there is some $\alpha > 0$ such that

$$a(v, v) \ge \alpha \|v\|^2$$
 for all $v \in V$,

then there is a unique $u \in V$ such that

$$a(u, v) = h(v)$$
 for all $v \in V$.

If a is symmetric, then $u \in V$ is the unique element of V such that

$$J(u) = \inf_{v \in V} J(v).$$

The Lax–Milgram theorem plays an important role in solving linear elliptic partial differential equations; see Brezis [31].

We now consider various methods, known as gradient descents, to find minima of certain types of functionals.