

where  $y \in (\mathbb{R}^*)^m$ . Since  $c \leq 0$ , observe that  $y = 0_m^\top$  is a feasible solution of the dual.

If a basic solution  $u$  of (P2) is found such that  $u \geq 0$ , then  $cu = yb$  for  $y = c_K A_K^{-1}$ , and we have found an optimal solution  $u$  for (P2) and  $y$  for (D). The dual simplex method makes progress by attempting to make negative components of  $u$  zero and by decreasing the objective function of the dual program.

The dual simplex method starts with a basic solution  $(u, K)$  of  $Ax = b$  which is not feasible but for which  $y = c_K A_K^{-1}$  is dual feasible. In many cases the original linear program is specified by a set of inequalities  $Ax \leq b$  with some  $b_i < 0$ , so by adding slack variables it is easy to find such basic solution  $u$ , and if in addition  $c \leq 0$ , then because the cost associated with slack variables is 0, we see that  $y = 0$  is a feasible solution of the dual.

Given a basic solution  $(u, K)$  of  $Ax = b$  (feasible or not),  $y = c_K A_K^{-1}$  is dual feasible iff  $c_K A_K^{-1} A \geq c$ , and since  $c_K A_K^{-1} A_K = c_K$ , the inequality  $c_K A_K^{-1} A \geq c$  is equivalent to  $c_K A_K^{-1} A_N \geq c_N$ , that is,

$$c_N - c_K A_K^{-1} A_N \leq 0, \quad (*_1)$$

where  $N = \{1, \dots, n\} - K$ . Equation  $(*_1)$  is equivalent to

$$c_j - c_K \gamma_K^j \leq 0 \quad \text{for all } j \in N, \quad (*_2)$$

where  $\gamma_K^j = A_K^{-1} A^j$ . Recall that the notation  $\bar{c}_j$  is used to denote  $c_j - c_K \gamma_K^j$ , which is called the *reduced cost* of the variable  $x_j$ .

As in the simplex algorithm we need to decide which column  $A^k$  leaves the basis  $K$  and which column  $A^j$  enters the new basis  $K^+$ , in such a way that  $y^+ = c_{K^+} A_{K^+}^{-1}$  is a feasible solution of (D), that is,  $c_{N^+} - c_{K^+} A_{K^+}^{-1} A_{N^+} \leq 0$ , where  $N^+ = \{1, \dots, n\} - K^+$ . We use Proposition 46.2 to decide which column  $k^-$  should leave the basis.

Suppose  $(u, K)$  is a solution of  $Ax = b$  for which  $y = c_K A_K^{-1}$  is dual feasible.

*Case (A).* If  $u \geq 0$ , then  $u$  is an optimal solution of (P2).

*Case (B).* There is some  $k \in K$  such that  $u_k < 0$ . In this case pick some  $k^- \in K$  such that  $u_{k^-} < 0$  (according to some pivot rule).

*Case (B1).* Suppose that  $\gamma_{k^-}^j \geq 0$  for all  $j \notin K$  (in fact, for all  $j$ , since  $\gamma_{k^-}^j \in \{0, 1\}$  for all  $j \in K$ ). If so, we claim that (P2) is not feasible.

Indeed, let  $v$  be some basic feasible solution. We have  $v \geq 0$  and  $Av = b$ , that is,

$$\sum_{j=1}^n v_j A^j = b,$$

so by multiplying both sides by  $A_K^{-1}$  and using the fact that by definition  $\gamma_K^j = A_K^{-1} A^j$ , we obtain

$$\sum_{j=1}^n v_j \gamma_K^j = A_K^{-1} b = u_K.$$