

polynomials used in approximation theory and in physics arise by a suitable choice of the weight function  $W$ . Besides the previous two examples, the *Hermite polynomials* correspond to  $W(x) = e^{-x^2}$ , the *Laguerre polynomials* to  $W(x) = e^{-x}$ , and the *Jacobi polynomials* to  $W(x) = (1-x)^\alpha(1+x)^\beta$ , with  $\alpha, \beta > -1$ . Comprehensive treatments of orthogonal polynomials can be found in Lebedev [114], Sansone [144], and Andrews, Askey and Roy [3].

We can also prove the following proposition regarding orthogonal spaces.

**Proposition 12.11.** *Given any nontrivial Euclidean space  $E$  of finite dimension  $n \geq 1$ , for any subspace  $F$  of dimension  $k$ , the orthogonal complement  $F^\perp$  of  $F$  has dimension  $n - k$ , and  $E = F \oplus F^\perp$ . Furthermore, we have  $F^{\perp\perp} = F$ .*

*Proof.* From Proposition 12.9, the subspace  $F$  has some orthonormal basis  $(u_1, \dots, u_k)$ . This linearly independent family  $(u_1, \dots, u_k)$  can be extended to a basis  $(u_1, \dots, u_k, v_{k+1}, \dots, v_n)$ , and by Proposition 12.10, it can be converted to an orthonormal basis  $(u_1, \dots, u_n)$ , which contains  $(u_1, \dots, u_k)$  as an orthonormal basis of  $F$ . Now any vector  $w = w_1u_1 + \dots + w_nu_n \in E$  is orthogonal to  $F$  iff  $w \cdot u_i = 0$ , for every  $i$ , where  $1 \leq i \leq k$ , iff  $w_i = 0$  for every  $i$ , where  $1 \leq i \leq k$ . Clearly, this shows that  $(u_{k+1}, \dots, u_n)$  is a basis of  $F^\perp$ , and thus  $E = F \oplus F^\perp$ , and  $F^\perp$  has dimension  $n - k$ . Similarly, any vector  $w = w_1u_1 + \dots + w_nu_n \in E$  is orthogonal to  $F^\perp$  iff  $w \cdot u_i = 0$ , for every  $i$ , where  $k+1 \leq i \leq n$ , iff  $w_i = 0$  for every  $i$ , where  $k+1 \leq i \leq n$ . Thus,  $(u_1, \dots, u_k)$  is a basis of  $F^{\perp\perp}$ , and  $F^{\perp\perp} = F$ .  $\square$

## 12.5 Linear Isometries (Orthogonal Transformations)

In this section we consider linear maps between Euclidean spaces that preserve the Euclidean norm. These transformations, sometimes called *rigid motions*, play an important role in geometry.

**Definition 12.5.** Given any two nontrivial Euclidean spaces  $E$  and  $F$  of the same finite dimension  $n$ , a function  $f: E \rightarrow F$  is an *orthogonal transformation*, or a *linear isometry*, if it is linear and

$$\|f(u)\| = \|u\|, \quad \text{for all } u \in E.$$

**Remarks:**

- (1) A linear isometry is often defined as a linear map such that

$$\|f(v) - f(u)\| = \|v - u\|,$$

for all  $u, v \in E$ . Since the map  $f$  is linear, the two definitions are equivalent. The second definition just focuses on preserving the distance between vectors.

- (2) Sometimes, a linear map satisfying the condition of Definition 12.5 is called a *metric map*, and a linear isometry is defined as a *bijective metric map*.