

with $\sigma(d) < \sigma(a_{11})$. Then, go back to Step 2a.

In Step 2b, if a_{11} does not divide a_{1k} , then first permute column 2 and column k (if $k \neq 2$). Then, if we write $a = a_{11}$ and $b = a_{1k}$, if d is a gcd of a and b and if x, y, s, t are determined as explained above, multiply on the right by the matrix

$$\begin{pmatrix} x & s & 0 & 0 & \cdots & 0 \\ y & t & 0 & 0 & \cdots & 0 \\ 0 & 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 & \cdots & 1 \end{pmatrix}$$

to obtain a matrix of the form

$$\begin{pmatrix} d & 0 & a_{13} & \cdots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \cdots & a_{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & a_{m3} & \cdots & a_{mn} \end{pmatrix}$$

with $\sigma(d) < \sigma(a_{11})$. Then, go back to Step 2b. The other steps remain the same. Whenever we return to Step 2a or Step 2b, the σ -value of the $(1, 1)$ -entry strictly decreases, so the whole procedure terminates. \square

We conclude this section by explaining how the rational canonical form of a matrix A can be obtained from the canonical form QDP^{-1} of $XI - A$.

Let $f: E \rightarrow E$ be a linear map over a K -vector space of dimension n . Recall from Theorem 36.3 (see Section 36.1) that as a $K[X]$ -module, E_f is the image of the free module $E[X]$ by the map $\sigma: E[X] \rightarrow E_f$, where $E[X]$ consists of all linear combinations of the form

$$p_1 e_1 + \cdots + p_n e_n,$$

where (e_1, \dots, e_n) is a basis of E and $p_1, \dots, p_n \in K[X]$ are polynomials, and σ is given by

$$\sigma(p_1 e_1 + \cdots + p_n e_n) = p_1(f)(e_1) + \cdots + p_n(f)(e_n).$$

Furthermore, the kernel of σ is equal to the image of the map $\psi: E[X] \rightarrow E[X]$, where

$$\psi(p_1 e_1 + \cdots + p_n e_n) = Xp_1 e_1 + \cdots + Xp_n e_n - (p_1 f(e_1) + \cdots + p_n f(e_n)).$$

The matrix A is the representation of a linear map f over the canonical basis (e_1, \dots, e_n) of $E = K^n$, and $XI - A$ is the matrix of ψ with respect to the basis (e_1, \dots, e_n)