and  $\mu_j \neq 0$  for some  $j \in I$ . But then,

$$v = \sum_{i \in I} \lambda_i u_i + 0 = \sum_{i \in I} \lambda_i u_i + \sum_{i \in I} \mu_i u_i = \sum_{i \in I} (\lambda_i + \mu_i) u_i,$$

with  $\lambda_j \neq \lambda_j + \mu_j$  since  $\mu_j \neq 0$ , contradicting the assumption that  $(\lambda_i)_{i \in I}$  is the unique family such that  $v = \sum_{i \in I} \lambda_i u_i$ .

**Definition 3.10.** If  $(u_i)_{i\in I}$  is a basis of a vector space E, for any vector  $v \in E$ , if  $(x_i)_{i\in I}$  is the unique family of scalars in K such that

$$v = \sum_{i \in I} x_i u_i,$$

each  $x_i$  is called the component (or coordinate) of index i of v with respect to the basis  $(u_i)_{i \in I}$ .

Given a field K and any (nonempty) set I, we can form a vector space  $K^{(I)}$  which, in some sense, is the standard vector space of dimension |I|.

**Definition 3.11.** Given a field K and any (nonempty) set I, let  $K^{(I)}$  be the subset of the cartesian product  $K^I$  consisting of all families  $(\lambda_i)_{i\in I}$  with finite support of scalars in K.<sup>3</sup> We define addition and multiplication by a scalar as follows:

$$(\lambda_i)_{i \in I} + (\mu_i)_{i \in I} = (\lambda_i + \mu_i)_{i \in I},$$

and

$$\lambda \cdot (\mu_i)_{i \in I} = (\lambda \mu_i)_{i \in I}.$$

It is immediately verified that addition and multiplication by a scalar are well defined. Thus,  $K^{(I)}$  is a vector space. Furthermore, because families with finite support are considered, the family  $(e_i)_{i\in I}$  of vectors  $e_i$ , defined such that  $(e_i)_j = 0$  if  $j \neq i$  and  $(e_i)_i = 1$ , is clearly a basis of the vector space  $K^{(I)}$ . When  $I = \{1, \ldots, n\}$ , we denote  $K^{(I)}$  by  $K^n$ . The function  $\iota \colon I \to K^{(I)}$ , such that  $\iota(i) = e_i$  for every  $i \in I$ , is clearly an injection.



When I is a finite set,  $K^{(I)} = K^I$ , but this is false when I is infinite. In fact,  $\dim(K^{(I)}) = |I|$ , but  $\dim(K^I)$  is strictly greater when I is infinite.

## 3.6 Matrices

In Section 2.1 we introduced informally the notion of a matrix. In this section we define matrices precisely, and also introduce some operations on matrices. It turns out that matrices form a vector space equipped with a multiplication operation which is associative, but noncommutative. We will explain in Section 4.1 how matrices can be used to represent linear maps, defined in the next section.

<sup>&</sup>lt;sup>3</sup>Where  $K^I$  denotes the set of all functions from I to K.