

We now consider the situation where  $E$  is a finite direct sum. Given a normed affine space  $E = (E_1, a_1) \oplus \cdots \oplus (E_n, a_n)$  and a normed affine space  $F$ , given any open subset  $A$  of  $E$ , for any  $c = (c_1, \dots, c_n) \in A$ , we define the continuous functions  $i_j^c: E_j \rightarrow E$ , such that

$$i_j^c(x) = (c_1, \dots, c_{j-1}, x, c_{j+1}, \dots, c_n).$$

For any function  $f: A \rightarrow F$ , we have functions  $f \circ i_j^c: E_j \rightarrow F$ , defined on  $(i_j^c)^{-1}(A)$ , which contains  $c_j$ . If  $D(f \circ i_j^c)(c_j)$  exists, we call it the *partial derivative of  $f$  w.r.t. its  $j$ th argument, at  $c$* . We also denote this derivative by  $D_j f(c)$ . Note that  $D_j f(c) \in \mathcal{L}(\vec{E}_j; \vec{F})$ .

This notion is a generalization of the notion defined in Definition 39.4. In fact, when  $E$  is of dimension  $n$ , and a frame  $(a_0, (u_1, \dots, u_n))$  has been chosen, we can write  $E = (E_1, a_1) \oplus \cdots \oplus (E_n, a_n)$ , for some obvious  $(E_j, a_j)$  (as explained just after Proposition 39.9), and then

$$D_j f(c)(\lambda u_j) = \lambda \partial_j f(c),$$

and the two notions are consistent.

The definition of  $i_j^c$  and of  $D_j f(c)$  also makes sense for a finite product  $E_1 \times \cdots \times E_n$  of affine spaces  $E_i$ . We will use freely the notation  $\partial_j f(c)$  instead of  $D_j f(c)$ .

The notion  $\partial_j f(c)$  introduced in Definition 39.4 is really that of the vector derivative, whereas  $D_j f(c)$  is the corresponding linear map. Although perhaps confusing, we identify the two notions. The following proposition holds.

**Proposition 39.11.** *Given a normed affine space  $E = (E_1, a_1) \oplus \cdots \oplus (E_n, a_n)$ , and a normed affine space  $F$ , given any open subset  $A$  of  $E$ , for any function  $f: A \rightarrow F$ , for every  $c \in A$ , if  $Df(c)$  exists, then each  $D_j f(c)$  exists, and*

$$Df(c)(u_1, \dots, u_n) = D_1 f(c)(u_1) + \cdots + D_n f(c)(u_n),$$

for every  $u_i \in E_i$ ,  $1 \leq i \leq n$ . The same result holds for the finite product  $E_1 \times \cdots \times E_n$ .

*Proof.* Since every  $c \in E$  can be written as  $c = a + c - a$ , where  $a = (a_1, \dots, a_n)$ , defining  $f_a: \vec{E} \rightarrow F$  such that,  $f_a(u) = f(a + u)$ , for every  $u \in \vec{E}$ , clearly,  $Df(c) = Df_a(c - a)$ , and thus, we can work with the function  $f_a$  whose domain is the vector space  $\vec{E}$ . The proposition is then a simple application of Theorem 39.6.  $\square$

## 39.3 Jacobian Matrices

If both  $E$  and  $F$  are of finite dimension, for any frame  $(a_0, (u_1, \dots, u_n))$  of  $E$  and any frame  $(b_0, (v_1, \dots, v_m))$  of  $F$ , every function  $f: E \rightarrow F$  is determined by  $m$  functions  $f_i: E \rightarrow \mathbb{R}$  (or  $f_i: E \rightarrow \mathbb{C}$ ), where

$$f(x) = b_0 + f_1(x)v_1 + \cdots + f_m(x)v_m,$$