

Any $m + 1$ vectors (u_0, u_1, \dots, u_m) such that the $m + 1$ vectors $(\hat{u}_0, \dots, \hat{u}_m)$ are linearly independent are said to be *affinely independent*.

From (1) and (2), the vector (u_0, u_1, \dots, u_m) are affinely independent iff for any choice of i , with $0 \leq i \leq m$, the m vectors $u_j - u_i$ for $j \in \{0, \dots, m\}$ with $j - i \neq 0$ are linearly independent. If $m = n$, we say that $n + 1$ affinely independent vectors (u_0, u_1, \dots, u_n) form an *affine frame* of \mathbb{R}^n .

(3) if (u_0, u_1, \dots, u_n) is an affine frame of \mathbb{R}^n , then prove that for every vector $v \in \mathbb{R}^n$, there is a unique $(n + 1)$ -tuple $(\lambda_0, \lambda_1, \dots, \lambda_n) \in \mathbb{R}^{n+1}$, with $\lambda_0 + \lambda_1 + \dots + \lambda_n = 1$, such that

$$v = \lambda_0 u_0 + \lambda_1 u_1 + \dots + \lambda_n u_n.$$

The scalars $(\lambda_0, \lambda_1, \dots, \lambda_n)$ are called the *barycentric* (or *affine*) *coordinates* of v w.r.t. the affine frame (u_0, u_1, \dots, u_n) .

If we write $e_i = u_i - u_0$, for $i = 1, \dots, n$, then prove that we have

$$v = u_0 + \lambda_1 e_1 + \dots + \lambda_n e_n,$$

and since (e_1, \dots, e_n) is a basis of \mathbb{R}^n (by (1) & (2)), the n -tuple $(\lambda_1, \dots, \lambda_n)$ consists of the standard coordinates of $v - u_0$ over the basis (e_1, \dots, e_n) .

Conversely, for any vector $u_0 \in \mathbb{R}^n$ and for any basis (e_1, \dots, e_n) of \mathbb{R}^n , let $u_i = u_0 + e_i$ for $i = 1, \dots, n$. Prove that (u_0, u_1, \dots, u_n) is an affine frame of \mathbb{R}^n , and for any $v \in \mathbb{R}^n$, if

$$v = u_0 + x_1 e_1 + \dots + x_n e_n,$$

with $(x_1, \dots, x_n) \in \mathbb{R}^n$ (unique), then

$$v = (1 - (x_1 + \dots + x_n))u_0 + x_1 u_1 + \dots + x_n u_n,$$

so that $(1 - (x_1 + \dots + x_n), x_1, \dots, x_n)$, are the barycentric coordinates of v w.r.t. the affine frame (u_0, u_1, \dots, u_n) .

The above shows that there is a one-to-one correspondence between affine frames (u_0, \dots, u_n) and pairs $(u_0, (e_1, \dots, e_n))$, with (e_1, \dots, e_n) a basis. Given an affine frame (u_0, \dots, u_n) , we obtain the basis (e_1, \dots, e_n) with $e_i = u_i - u_0$, for $i = 1, \dots, n$; given the pair $(u_0, (e_1, \dots, e_n))$ where (e_1, \dots, e_n) is a basis, we obtain the affine frame (u_0, \dots, u_n) , with $u_i = u_0 + e_i$, for $i = 1, \dots, n$. There is also a one-to-one correspondence between barycentric coordinates w.r.t. the affine frame (u_0, \dots, u_n) and standard coordinates w.r.t. the basis (e_1, \dots, e_n) . The barycentric coordinates $(\lambda_0, \lambda_1, \dots, \lambda_n)$ of v (with $\lambda_0 + \lambda_1 + \dots + \lambda_n = 1$) yield the standard coordinates $(\lambda_1, \dots, \lambda_n)$ of $v - u_0$; the standard coordinates (x_1, \dots, x_n) of $v - u_0$ yield the barycentric coordinates $(1 - (x_1 + \dots + x_n), x_1, \dots, x_n)$ of v .

(4) Recall that an affine map is a map $f: E \rightarrow F$ between vector spaces that preserves *affine combinations*; that is,

$$f \left(\sum_{i=1}^m \lambda_i u_i \right) = \sum_{i=1}^m \lambda_i f(u_i),$$