- (a) f = g and $\tau = 0$ iff f has some fixed point, i.e., iff $Fix(f) \neq \emptyset$.
- (b) If f has no fixed points, i.e., $Fix(f) = \emptyset$, then $\dim(\operatorname{Ker}(\overrightarrow{f} \operatorname{id})) \ge 1$.

The remarks made in the Euclidean case also apply to the Hermitian case. In particular, the fact that E has finite dimension is only used to prove (b).

A version of the Cartan–Dieudonné also holds for affine isometries, but it may not be possible to get rid of Hermitian reflections entirely.

Theorem 28.14. Let E be an affine Hermitian space of dimension $n \geq 1$. Every affine isometry in $\mathbf{Is}(n,\mathbb{C})$ can be written as the composition of at most 2n-1 affine isometries if it has a fixed point, or else as the composition of at most 2n+1 affine isometries, where all these isometries are affine hyperplane reflections except for possibly one affine Hermitian reflection. When $n \geq 2$, the identity is the composition of any reflection with itself.

Proof. The proof is very similar to the proof of Theorem 27.11, except that it uses Theorem 28.5 instead of Theorem 27.1. The details are left as an exercise. \Box

When $n \geq 3$, as in the Euclidean case, we can characterize the affine isometries in $\mathbf{SE}(n,\mathbb{C})$ in terms of flips, and we can even bound the number of flips by 2n-2.

Theorem 28.15. Let E be a Hermitian affine space of dimension $n \geq 3$. Every rigid motion $f \in \mathbf{SE}(E,\mathbb{C})$ is the composition of an even number of affine flips $f = f_{2k} \circ \cdots \circ f_1$, where $k \leq n-1$.

Proof. It is very similar to the proof of theorem 27.12, but it uses Proposition 28.6 instead of Proposition 27.5. The details are left as an exercise. \Box

A more detailed study of the rigid motions of Hermitian spaces of dimension 2 and 3 would seem worthwhile, but we are not aware of any reference on this subject.