- (a) Either the constraints  $\varphi_i$  are affine for all i = 1, ..., m and  $U \neq \emptyset$ , or
- (b) There is some vector  $v \in \Omega$  such that the following conditions hold for  $i = 1, \ldots, m$ :
  - (i)  $\varphi_i(v) \leq 0$ .
  - (ii) If  $\varphi_i$  is not affine, then  $\varphi_i(v) < 0$ .

The above qualification conditions are known as *Slater's conditions*.

Condition (b)(i) also implies that U has nonempty relative interior. If  $\Omega$  is convex, then U is also convex. This is because for all  $u, v \in \Omega$ , if  $u \in U$  and  $v \in U$ , that is  $\varphi_i(u) \leq 0$  and  $\varphi_i(v) \leq 0$  for  $i = 1, \ldots, m$ , since the functions  $\varphi_i$  are convex, for all  $\theta \in [0, 1]$  we have

$$\varphi_i((1-\theta)u + \theta v) \le (1-\theta)\varphi_i(u) + \theta\varphi_i(v)$$
 since  $\varphi_i$  is convex  
 $\le 0$  since  $1-\theta \ge 0, \theta \ge 0, \varphi_i(u) \le 0, \varphi_i(v) \le 0,$ 

and any intersection of convex sets is convex.



It is important to observe that a nonaffine equality constraint  $\varphi_i(u) = 0$  is never qualified.

Indeed,  $\varphi_i(u) = 0$  is equivalent to  $\varphi_i(u) \leq 0$  and  $-\varphi_i(u) \leq 0$ , so if these constraints are qualified and if  $\varphi_i$  is not affine then there is some nonzero vector  $v \in \Omega$  such that both  $\varphi_i(v) < 0$  and  $-\varphi_i(v) < 0$ , which is impossible. For this reason, equality constraints are often assumed to be affine.

The following theorem yields a more flexible version of Theorem 50.5 for constraints given by convex functions. If in addition, the function J is also convex, then the KKT conditions are also a sufficient condition for a local minimum.

**Theorem 50.6.** Let  $\varphi_i \colon \Omega \to \mathbb{R}$  be m convex constraints defined on some open convex subset  $\Omega$  of a finite-dimensional Euclidean vector space V (more generally, a real Hilbert space V), let  $J \colon \Omega \to \mathbb{R}$  be some function, let U be given by

$$U = \{ x \in \Omega \mid \varphi_i(x) \le 0, \ 1 \le i \le m \},\$$

and let  $u \in U$  be any point such that the functions  $\varphi_i$  and J are differentiable at u.

(1) If J has a local minimum at u with respect to U, and if the constraints are qualified, then there exist some scalars  $\lambda_i(u) \in \mathbb{R}$ , such that the KKT condition hold:

$$J_u' + \sum_{i=1}^m \lambda_i(u)(\varphi_i')_u = 0$$

and

$$\sum_{i=1}^{m} \lambda_i(u)\varphi_i(u) = 0, \quad \lambda_i(u) \ge 0, \quad i = 1, \dots, m.$$