We denote their cardinalities by  $p_m = |I_{\lambda>0}|$  and  $q_m = |I_{\mu>0}|$ .

Obviously,  $p_f \leq p_m$  and  $q_f \leq q_m$ . There are  $p - p_m$  points  $u_i$  classified correctly on the blue side and outside the  $\delta$ -slab and there are  $q - q_m$  points  $v_j$  classified correctly on the red side and outside the  $\delta$ -slab. Intuitively a blue point that fails the margin is on the wrong side of the blue margin and a red point that fails the margin is on the wrong side of the red margin.

It can be shown that that K must be chosen so that

$$\max\left\{\frac{1}{2p_m}, \frac{1}{2q_m}\right\} \le K \le \min\left\{\frac{1}{2p_f}, \frac{1}{2q_f}\right\}.$$

If the optimal value is 0, then  $\gamma = 0$  and  $X \begin{pmatrix} \lambda \\ \mu \end{pmatrix} = 0$ , so in this case it is not possible to determine w. However, if the optimal value is > 0, then once a solution for  $\lambda$  and  $\mu$  is obtained, we have

$$\gamma = \frac{1}{2} \left( \begin{pmatrix} \lambda^{\top} & \mu^{\top} \end{pmatrix} X^{\top} X \begin{pmatrix} \lambda \\ \mu \end{pmatrix} \right)^{1/2}$$
$$w = \frac{1}{2\gamma} \left( \sum_{i=1}^{p} \lambda_i u_i - \sum_{j=1}^{q} \mu_j v_j \right),$$

so we get

$$w = \frac{\sum_{i=1}^{p} \lambda_i u_i - \sum_{j=1}^{q} \mu_j v_j}{\left( \begin{pmatrix} \lambda^\top & \mu^\top \end{pmatrix} X^\top X \begin{pmatrix} \lambda \\ \mu \end{pmatrix} \right)^{1/2}},$$

If the following mild hypothesis holds, then b and  $\delta$  can be found.

Standard Margin Hypothesis for (SVM<sub>s1</sub>). There is some index  $i_0$  such that  $0 < \lambda_{i_0} < K$  and there is some index  $j_0$  such that  $0 < \mu_{j_0} < K$ . This means that some  $u_{i_0}$  is a support vector of type 1 on the blue margin, and some  $v_{j_0}$  is a support vector of type 1 on the red margin.

If the **Standard Margin Hypothesis** for (SVM<sub>s1</sub>) holds, then  $\epsilon_{i_0} = 0$  and  $\mu_{j_0} = 0$ , and we have the active equations

$$w^{\mathsf{T}}u_{i_0} - b = \delta$$
 and  $-w^{\mathsf{T}}v_{j_0} + b = \delta$ ,

and we obtain the value of b and  $\delta$  as

$$b = \frac{1}{2} w^{\top} (u_{i_0} + v_{j_0})$$
$$\delta = \frac{1}{2} w^{\top} (u_{i_0} - v_{j_0}).$$