```
% with the constraint
\% \sum_{i=1}^p + \sum_{j=1}^q u_j = K_m
% (without the variable gamma) and the right-hand side c
% u: vector of p blue points (each an n-dim vector)
% v: vector of q red points (each an n-dim vector)
% builds the matrix X = [-u_1 \dots -u_p \ v1 \dots \ v_q]
% and the matrix Pa as 2(p+q) matrix obtained
% by augmenting X'*X with zeros
% K is a scale factor (K = Ks)
p = size(u,2); q = size(v,2);
% Ks = 1/(p+q);
Ks = K; Km = (p+q)*K*nu;
A = [ones(1,p) - ones(1,q) zeros(1,p+q);
     ones(1,p) ones(1,q) zeros(1,p+q);
     eye(p) zeros(p,q) eye(p) zeros(p,q);
     zeros(q,p) eye(q) zeros(q,p) eye(q) ];
c = [0; Km; Ks*ones(p+q,1)];
X = [-u \ v];
XX = X'*X;
Pa = [XX zeros(p+q,p+q); zeros(p+q, 2*(p+q))];
q = zeros(2*(p+q),1);
end
   The function findpsv2 makes a vector of \lambda_i (and \mu_i) corresponding to support vectors
of type 1.
function [lampsv,num] = findpsv2(lambda,K,tols,tolh)
%
%
    This function find the vector of
%
    lambda_i's such that 0 < lambda_i < K</pre>
%
    and the number of such lambda_i.
% tols = 10^{(-11)}; % the smaller this is, the larger the number of
                 % points on the margin
% tolh = 10^{(-9)}; %
m = size(lambda,1); lampsv = zeros(m,1);
num = 0;
for i = 1:m
    if lambda(i) > tols && lambda(i) < K - tolh</pre>
       lampsv(i) = lambda(i);
       num = num + 1;
    end
```