The basis

$$((f - \lambda \mathrm{id})^{n-1}(u), (f - \lambda \mathrm{id})^{n-2}(u), \dots, (f - \lambda \mathrm{id})(u), u),$$

provided by Proposition 36.16 is known as a *Jordan chain*. Note that  $(f - \lambda id)^{n-1}(u)$  is an eigenvector for f. To construct the Jordan chain, we must find u which is a generalized eigenvector of f. This is done by first finding an eigenvector  $x_1$  of f and recursively solving the system  $(f - \lambda id)x_{i+1} = x_i$  for  $i \le 1 \le n-1$ . For example suppose  $f: \mathbb{R}^3 \to \mathbb{R}^3$  where f(x, y, z) = (x + y + z, y + z, z). In terms of the standard basis, the matrix representation

for f is  $M = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ . By using M, it is readily verified that the minimal polynomial

f equals the characteristic polynomial, namely  $(X-1)^3$ . Thus f has the eigenvalue  $\lambda=1$  with repeated three times. To find the eigenvector  $x_1$  associated with  $\lambda=1$ , we solve the system  $(M-I)x_1=0$ , or equivalently

$$\begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

Thus y = z = 0 with x = 1 solves this system to provide the eigenvector  $x_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ . We next solve the system  $(M - I)x_2 = x_1$ , namely

$$\begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix},$$

which implies that z = 0 and y = 1. Hence  $x_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$  will work. To finish constructing our Jordan chain, we must solve the system  $(M - I)x_3 = x_2$ , namely

$$\begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix},$$

from which we see that z = 1, y = 0, and  $x_3 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ . By setting  $x_3 = u$ , we form the basis

$$((f - \lambda id)^2(u), (f - \lambda id)^1(u), \dots, (f - \lambda id)(u), u) = (x_1, x_2, x_3).$$