The above construction also works if  $O \in \Delta$ ; see Figures 26.32 and 26.33.

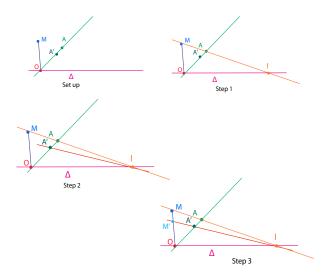


Figure 26.32: The three step process for determining the elation point h(M) = M' when M is not on the line  $\langle A, A' \rangle$ . Step 1 finds the intersection between the extension of  $\langle A, M \rangle$  and  $\Delta$ . Step 2 forms the line  $\langle A', I \rangle$ . Step 3 extends  $\langle A'I \rangle$  and determines its intersection with  $\langle O, M \rangle$ . The intersection point is M'.

Another useful property of homologies (here,  $O \notin \Delta$ ) is that for any line d passing through the center O, if I is the intersection point of the line d and  $\Delta$ , then for any  $M \in d$  distinct from O and not on  $\Delta$  and its image M', the cross-ratio [O, I, M, M'] is independent of d. If [O, I, M, M'] = -1 for all  $M \neq O$ , we say that h is a harmonic homology. It can be shown that a homography h is a harmonic homology iff h is an involution ( $h^2 = \mathrm{id}$ ); see Silder [161] (Chapter 4, Section 4.4). It can also be shown that any homography of  $\mathbb{RP}^2$  can be expressed as the composition of two homologies; see Silder [161] (Chapter 4, Section 4.5).

We now consider the generalization of the notion of homology (and projective transvection) to any projective space  $\mathbb{P}(E)$ , where E is a vector space of any finite dimension over a field K. We need to review a few concepts from Section 8.15.

Let E be a vector space and let H be a hyperplane in E. Recall from Definition 8.8 that for any nonzero vector  $u \in E$  such that  $u \notin H$ , and any scalar  $\alpha \neq 0, 1$ , a linear map  $f \colon E \to E$  such that f(x) = x for all  $x \in H$  and  $f(x) = \alpha x$  for every  $x \in D = Ku$  is called a dilatation of hyperplane H, direction D, and scale factor  $\alpha$ . See Figure 26.34.

From Definition 8.9, for any nonzero nonlinear form  $\varphi \in E^*$  defining H (which means that  $H = \text{Ker}(\varphi)$ ) and any nonzero vector  $u \in H$ , the linear map  $\tau_{\varphi,u}$  given by

$$\tau_{\varphi,u}(x) = x + \varphi(x)u, \quad \varphi(u) = 0,$$

for all  $x \in E$  is called a transvection of hyperplane H and direction u. See Figure 26.35.