

Because h yields a unique linear map $h_{\odot}: S^2(E) \rightarrow F$ such that

$$h_{\odot}(e_i \odot e_j) = w_{ij}, \quad 1 \leq i \leq j \leq 3,$$

by Proposition 33.4, the vectors

$$e_1 \odot e_1, \quad e_1 \odot e_2, \quad e_1 \odot e_3, \quad e_2 \odot e_2, \quad e_2 \odot e_3, \quad e_3 \odot e_3$$

are linearly independent. This suggests understanding how a symmetric bilinear function $f: E^2 \rightarrow F$ is expressed in terms of its values $f(e_i, e_j)$ on the basis vectors (e_1, e_2, e_3) , and this can be done easily. Using bilinearity and symmetry, we obtain

$$\begin{aligned} f(u_1 e_1 + u_2 e_2 + u_3 e_3, v_1 e_1 + v_2 e_2 + v_3 e_3) &= u_1 v_1 f(e_1, e_1) + (u_1 v_2 + u_2 v_1) f(e_1, e_2) \\ &\quad + (u_1 v_3 + u_3 v_1) f(e_1, e_3) + u_2 v_2 f(e_2, e_2) \\ &\quad + (u_2 v_3 + u_3 v_2) f(e_2, e_3) + u_3 v_3 f(e_3, e_3). \end{aligned}$$

Therefore, given $w_{11}, w_{12}, w_{13}, w_{22}, w_{23}, w_{33} \in F$, the function h given by

$$\begin{aligned} h(u_1 e_1 + u_2 e_2 + u_3 e_3, v_1 e_1 + v_2 e_2 + v_3 e_3) &= u_1 v_1 w_{11} + (u_1 v_2 + u_2 v_1) w_{12} \\ &\quad + (u_1 v_3 + u_3 v_1) w_{13} + u_2 v_2 w_{22} \\ &\quad + (u_2 v_3 + u_3 v_2) w_{23} + u_3 v_3 w_{33} \end{aligned}$$

is clearly bilinear symmetric, and by construction $h(e_i, e_j) = w_{ij}$, so it does the job.

The generalization of this argument to any $m \geq 2$ and to a space E of any dimension (even infinite) is conceptually clear, but notationally messy. If $\dim(E) = n$ and if (e_1, \dots, e_n) is a basis of E , for any m vectors $v_j = \sum_{i=1}^n u_{i,j} e_i$ in E , for any symmetric multilinear map $f: E^m \rightarrow F$, we have

$$\begin{aligned} &f(v_1, \dots, v_m) \\ &= \sum_{k_1 + \dots + k_n = m} \left(\sum_{\substack{I_1 \cup \dots \cup I_n = \{1, \dots, m\} \\ I_i \cap I_j = \emptyset, i \neq j, |I_j| = k_j}} \left(\prod_{i_1 \in I_1} u_{1, i_1} \right) \cdots \left(\prod_{i_n \in I_n} u_{n, i_n} \right) \right) f(\underbrace{e_1, \dots, e_1}_{k_1}, \dots, \underbrace{e_n, \dots, e_n}_{k_n}). \end{aligned}$$

Definition 33.19. Given any set J of $n \geq 1$ elements, say $J = \{j_1, \dots, j_n\}$, and given any $m \geq 2$, for any sequence (k_1, \dots, k_n) of natural numbers $k_i \in \mathbb{N}$ such that $k_1 + \dots + k_n = m$, the multiset M of size m

$$M = \{ \underbrace{j_1, \dots, j_1}_{k_1}, \underbrace{j_2, \dots, j_2}_{k_2}, \dots, \underbrace{j_n, \dots, j_n}_{k_n} \}$$

is denoted by $M(m, J, k_1, \dots, k_n)$. Note that $M(j_i) = k_i$, for $i = 1, \dots, n$. Given any $k \geq 1$, and any $u \in E$, we denote $\underbrace{u \odot \dots \odot u}_k$ as $u^{\odot k}$.