Then by $(*_1)$ we obtain

$$w = \frac{2(u-v)}{(u-v)^{\mathsf{T}}(u-v)}.$$

We verify easily that

$$2(u_1 - v_1)x_1 + \dots + 2(u_n - v_n)x_n = (u_1^2 + \dots + u_n^2) - (v_1^2 + \dots + v_n^2)$$

is the equation of the bisector hyperplane between u and v; see Figure 50.16.

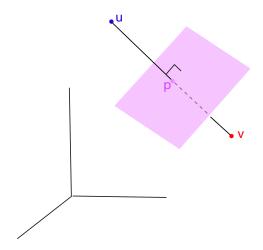


Figure 50.16: In \mathbb{R}^3 , the solution to Hard Margin SVM_{h2} for the points u and v is the purple perpendicular planar bisector of u - v.

In the next section we will derive the dual of the optimization problem discussed in this section. We will also consider a more flexible solution involving a *soft margin*.

50.7 Lagrangian Duality and Saddle Points

In this section we investigate methods to solve the *Minimization Problem* (P):

minimize
$$J(v)$$

subject to $\varphi_i(v) \leq 0$, $i = 1, ..., m$.

It turns out that under certain conditions the original Problem (P), called *primal problem*, can be solved in two stages with the help another Problem (D), called the *dual problem*. The Dual Problem (D) is a maximization problem involving a function G, called the Lagrangian