**Remark:** When writing a program implementing row reduction, we may stop when the last column of the matrix A is reached. In this case, the test whether the system Ax = b is solvable is that the row-reduced matrix A' has no zero row of index i > r such that  $b'_i \neq 0$  (where r is the number of pivots, and b' is the row-reduced right-hand side).

If we have a homogeneous system Ax = 0, which means that b = 0, of course x = 0 is always a solution, but Theorem 8.16 implies that if the system Ax = 0 has more variables than equations, then it has some nonzero solution (we call it a nontrivial solution).

**Proposition 8.17.** Given any homogeneous system Ax = 0 of m equations in n variables, if m < n, then there is a nonzero vector  $x \in \mathbb{R}^n$  such that Ax = 0.

*Proof.* Convert the matrix A to a reduced row echelon matrix A'. We know that Ax = 0 iff A'x = 0. If r is the number of pivots of A', we must have  $r \leq m$ , so by Theorem 8.16 we may assign arbitrary values to n - r > 0 nonpivot variables and we get nontrivial solutions.  $\square$ 

Theorem 8.16 can also be used to characterize when a square matrix is invertible. First, note the following simple but important fact:

If a square  $n \times n$  matrix A is a row reduced echelon matrix, then either A is the identity or the bottom row of A is zero.

**Proposition 8.18.** Let A be a square matrix of dimension n. The following conditions are equivalent:

- (a) The matrix A can be reduced to the identity by a sequence of elementary row operations.
- (b) The matrix A is a product of elementary matrices.
- (c) The matrix A is invertible.
- (d) The system of homogeneous equations Ax = 0 has only the trivial solution x = 0.

*Proof.* First we prove that (a) implies (b). If (a) can be reduced to the identity by a sequence of row operations  $E_1, \ldots, E_p$ , this means that  $E_p \cdots E_1 A = I$ . Since each  $E_i$  is invertible, we get

$$A = E_1^{-1} \cdots E_p^{-1},$$

where each  $E_i^{-1}$  is also an elementary row operation, so (b) holds. Now if (b) holds, since elementary row operations are invertible, A is invertible and (c) holds. If A is invertible, we already observed that the homogeneous system Ax = 0 has only the trivial solution x = 0, because from Ax = 0, we get  $A^{-1}Ax = A^{-1}0$ ; that is, x = 0. It remains to prove that (d) implies (a) and for this we prove the contrapositive: if (a) does not hold, then (d) does not hold.

Using our basic observation about reducing square matrices, if A does not reduce to the identity, then A reduces to a row echelon matrix A' whose bottom row is zero. Say A' = PA,