

## 40.2 Using Second Derivatives to Find Extrema

For the sake of brevity, we consider only the case of local minima; analogous results are obtained for local maxima (replace  $J$  by  $-J$ , since  $\max_u J(u) = -\min_u -J(u)$ ). We begin with a necessary condition for an unconstrained local minimum.

**Proposition 40.5.** *Let  $E$  be a normed vector space and let  $J: \Omega \rightarrow \mathbb{R}$  be a function, with  $\Omega$  some open subset of  $E$ . If the function  $J$  is differentiable in  $\Omega$ , if  $J$  has a second derivative  $D^2J(u)$  at some point  $u \in \Omega$ , and if  $J$  has a local minimum at  $u$ , then*

$$D^2J(u)(w, w) \geq 0 \quad \text{for all } w \in E.$$

*Proof.* Pick any nonzero vector  $w \in E$ . Since  $\Omega$  is open, for  $t$  small enough,  $u + tw \in \Omega$  and  $J(u + tw) \geq J(u)$ , so there is some open interval  $I \subseteq \mathbb{R}$  such that

$$u + tw \in \Omega \quad \text{and} \quad J(u + tw) \geq J(u)$$

for all  $t \in I$ . Using the Taylor–Young formula and the fact that we must have  $dJ(u) = 0$  since  $J$  has a local minimum at  $u$ , we get

$$0 \leq J(u + tw) - J(u) = \frac{t^2}{2} D^2J(u)(w, w) + t^2 \|w\|^2 \epsilon(tw),$$

with  $\lim_{t \rightarrow 0} \epsilon(tw) = 0$ , which implies that

$$D^2J(u)(w, w) \geq 0.$$

Since the argument holds for all  $w \in E$  (trivially if  $w = 0$ ), the proposition is proven.  $\square$

One should be cautioned that there is no converse to the previous proposition. For example, the function  $f: x \mapsto x^3$  has no local minimum at 0, yet  $df(0) = 0$  and  $D^2f(0)(u, v) = 0$ . Similarly, the reader should check that the function  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  given by

$$f(x, y) = x^2 - 3y^3$$

has no local minimum at  $(0, 0)$ ; yet  $df(0, 0) = 0$  since  $df(x, y) = (2x, -9y^2)$ , and for  $u = (u_1, u_2)$ ,  $D^2f(0, 0)(u, u) = 2u_1^2 \geq 0$  since

$$D^2f(x, y)(u, u) = \begin{pmatrix} u_1 & u_2 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & -18y \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix}.$$

See Figure 40.3.

When  $E = \mathbb{R}^n$ , Proposition 40.5 says that a necessary condition for having a local minimum is that the Hessian  $\nabla^2 J(u)$  be positive semidefinite (it is always symmetric).

We now give **sufficient** conditions for the existence of a local minimum.