

These equations imply that

$$\|e_k\|_A \leq \left(\inf_{P \in \mathcal{P}_k} \max_{1 \leq i \leq n} |P(\lambda_i)| \right) \|e_0\|_A.$$

It can be shown that the conjugate gradient method requires of the order of
 n^3 additions,
 n^3 multiplications,
 $2n$ divisions.

In theory, this is worse than the number of elementary operations required by the Cholesky method. Even though the conjugate gradient method does not seem to be the best method for *full* matrices, it usually outperforms other methods for *sparse* matrices. The reason is that the matrix A only appears in the computation of the vector Ad_k . If the matrix A is banded (for example, tridiagonal), computing Ad_k is very cheap and there is no need to store the entire matrix A , in which case the conjugate gradient method is fast. Also, although in theory, up to n iterations may be required, in practice, convergence may occur after a much smaller number of iterations.

Using the inequality

$$\|e_k\|_A \leq \left(\inf_{P \in \mathcal{P}_k} \max_{1 \leq i \leq n} |P(\lambda_i)| \right) \|e_0\|_A,$$

by choosing P to be a shifted Chebyshev polynomial, it can be shown that

$$\|e_k\|_A \leq 2 \left(\frac{\sqrt{\kappa} - 1}{\sqrt{\kappa} + 1} \right)^k \|e_0\|_A,$$

where $\kappa = \text{cond}_2(A)$; see Trefethen and Bau [176] (Lecture 38, Theorem 38.5). Thus the rate of convergence of the conjugate gradient method is governed by the ratio

$$\frac{\sqrt{\text{cond}_2(A)} - 1}{\sqrt{\text{cond}_2(A)} + 1},$$

where $\text{cond}_2(A) = \lambda_n/\lambda_1$ is the condition number of the matrix A . Since A is positive definite, λ_1 is its smallest eigenvalue and λ_n is its largest eigenvalue.

The above fact leads to the process of *preconditioning*, a method which consists in replacing the matrix of a linear system $Ax = b$ by an “equivalent” one for example $M^{-1}A$ (since M is invertible, the system $Ax = b$ is equivalent to the system $M^{-1}Ax = M^{-1}b$), where M is chosen so that $M^{-1}A$ is still symmetric positive definite and has a smaller condition number than A ; see Trefethen and Bau [176] (Lecture 40) and Demmel [48] (Section 6.6.5).