

then the matrix representing  $\varphi$  becomes

$$\begin{pmatrix} 0 & I_r & 0 \\ -I_r & 0 & 0 \\ 0 & 0 & 0_{n-2r} \end{pmatrix}.$$

This particularly simple matrix is often preferable, especially when dealing with the matrices (symplectic matrices) representing the isometries of  $\varphi$  (in which case  $n = 2r$ ).

As a warm up for Proposition 29.29 of the next section, we prove an analog of Proposition 29.23 in the case of a symmetric bilinear form.

**Proposition 29.26.** *Let  $\varphi: E \times E \rightarrow K$  be a nondegenerate symmetric bilinear form with  $K$  a field of characteristic different from 2. For any nonzero isotropic vector  $u$ , there is another nonzero isotropic vector  $v$  such that  $\varphi(u, v) = 2$ , and  $u$  and  $v$  are linearly independent. In the basis  $(u, v/2)$ , the restriction of  $\varphi$  to the plane spanned by  $u$  and  $v/2$  is of the form*

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$$

*Proof.* Since  $\varphi$  is nondegenerate, there is some nonzero vector  $z$  such that (rescaling  $z$  if necessary)  $\varphi(u, z) = 1$ . If

$$v = 2z - \varphi(z, z)u,$$

then since  $\varphi(u, u) = 0$  and  $\varphi(u, z) = 1$ , note that

$$\varphi(u, v) = \varphi(u, 2z - \varphi(z, z)u) = 2\varphi(u, z) - \varphi(z, z)\varphi(u, u) = 2,$$

and

$$\begin{aligned} \varphi(v, v) &= \varphi(2z - \varphi(z, z)u, 2z - \varphi(z, z)u) \\ &= 4\varphi(z, z) - 4\varphi(z, z)\varphi(u, z) + \varphi(z, z)^2\varphi(u, u) \\ &= 4\varphi(z, z) - 4\varphi(z, z) = 0. \end{aligned}$$

If  $u$  and  $z$  were linearly dependent, as  $u, z \neq 0$ , we could write  $z = \mu u$  for some  $\mu \neq 0$ , but then, we would have

$$\varphi(u, z) = \varphi(u, \mu u) = \mu\varphi(u, u) = 0,$$

contradicting the fact that  $\varphi(u, z) \neq 0$ . Then  $u$  and  $v = 2z - \varphi(z, z)u$  are also linearly independent, since otherwise  $z$  could be expressed as a multiple of  $u$ . The rest is obvious.  $\square$

Proposition 29.26 yields a plane spanned by two vectors  $u_1, v_1$  such that  $\varphi(u_1, u_1) = \varphi(v_1, v_1) = 0$  and  $\varphi(u_1, v_1) = 1$ . Such a plane is called an *Artinian plane*. Proposition 29.26 also shows that nonzero isotropic vectors come in pair.

Proposition 29.26 has the following corollary which has applications in number theory; see Serre [157], Chapter IV.