

for every  $x \in E$ . From Proposition 39.1, we have

$$Df(a)(u_j) = D_{u_j}f(a) = \partial_j f(a),$$

and from Proposition 39.10, we have

$$Df(a)(u_j) = Df_1(a)(u_j)v_1 + \cdots + Df_i(a)(u_j)v_i + \cdots + Df_m(a)(u_j)v_m,$$

that is,

$$Df(a)(u_j) = \partial_j f_1(a)v_1 + \cdots + \partial_j f_i(a)v_i + \cdots + \partial_j f_m(a)v_m.$$

Since the  $j$ -th column of the  $m \times n$ -matrix representing  $Df(a)$  w.r.t. the bases  $(u_1, \dots, u_n)$  and  $(v_1, \dots, v_m)$  is equal to the components of the vector  $Df(a)(u_j)$  over the basis  $(v_1, \dots, v_m)$ , the linear map  $Df(a)$  is determined by the  $m \times n$ -matrix  $J(f)(a) = (\partial_j f_i(a))$ , (or  $J(f)(a) = (\frac{\partial f_i}{\partial x_j}(a))$ ):

$$J(f)(a) = \begin{pmatrix} \partial_1 f_1(a) & \partial_2 f_1(a) & \cdots & \partial_n f_1(a) \\ \partial_1 f_2(a) & \partial_2 f_2(a) & \cdots & \partial_n f_2(a) \\ \vdots & \vdots & \ddots & \vdots \\ \partial_1 f_m(a) & \partial_2 f_m(a) & \cdots & \partial_n f_m(a) \end{pmatrix}$$

or

$$J(f)(a) = \begin{pmatrix} \frac{\partial f_1}{\partial x_1}(a) & \frac{\partial f_1}{\partial x_2}(a) & \cdots & \frac{\partial f_1}{\partial x_n}(a) \\ \frac{\partial f_2}{\partial x_1}(a) & \frac{\partial f_2}{\partial x_2}(a) & \cdots & \frac{\partial f_2}{\partial x_n}(a) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1}(a) & \frac{\partial f_m}{\partial x_2}(a) & \cdots & \frac{\partial f_m}{\partial x_n}(a) \end{pmatrix}$$

**Definition 39.5.** The matrix  $J(f)(a)$  is called the *Jacobian matrix* of  $Df$  at  $a$ . When  $m = n$ , the determinant,  $\det(J(f)(a))$ , of  $J(f)(a)$  is called the *Jacobian* of  $Df(a)$ .

From a previous result, we know that this determinant in fact only depends on  $Df(a)$ , and not on specific bases. However, partial derivatives give a means for computing it.

When  $E = \mathbb{R}^n$  and  $F = \mathbb{R}^m$ , for any function  $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ , it is easy to compute the partial derivatives  $\frac{\partial f_i}{\partial x_j}(a)$ . We simply treat the function  $f_i: \mathbb{R}^n \rightarrow \mathbb{R}$  as a function of its  $j$ -th argument, leaving the others fixed, and compute the derivative as in Definition 39.1, that is, the usual derivative.

**Example 39.3.** For example, consider the function  $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , defined such that

$$f(r, \theta) = (r \cos(\theta), r \sin(\theta)).$$