

The reason for the terminology *coordinate form* is as follows: If E has finite dimension and if (u_1, \dots, u_n) is a basis of E , for any vector

$$v = \lambda_1 u_1 + \dots + \lambda_n u_n,$$

we have

$$\begin{aligned} u_i^*(v) &= u_i^*(\lambda_1 u_1 + \dots + \lambda_n u_n) \\ &= \lambda_1 u_i^*(u_1) + \dots + \lambda_i u_i^*(u_i) + \dots + \lambda_n u_i^*(u_n) \\ &= \lambda_i, \end{aligned}$$

since $u_i^*(u_j) = \delta_{ij}$. Therefore, u_i^* is the linear function that returns the i th coordinate of a vector expressed over the basis (u_1, \dots, u_n) .

The following theorem shows that in finite-dimension, every basis (u_1, \dots, u_n) of a vector space E yields a basis (u_1^*, \dots, u_n^*) of the dual space E^* , called a *dual basis*.

Theorem 3.23. (*Existence of dual bases*) *Let E be a vector space of dimension n . The following properties hold: For every basis (u_1, \dots, u_n) of E , the family of coordinate forms (u_1^*, \dots, u_n^*) is a basis of E^* (called the dual basis of (u_1, \dots, u_n)).*

Proof. (a) If $v^* \in E^*$ is any linear form, consider the linear form

$$f^* = v^*(u_1)u_1^* + \dots + v^*(u_n)u_n^*.$$

Observe that because $u_i^*(u_j) = \delta_{ij}$,

$$\begin{aligned} f^*(u_i) &= (v^*(u_1)u_1^* + \dots + v^*(u_n)u_n^*)(u_i) \\ &= v^*(u_1)u_1^*(u_i) + \dots + v^*(u_i)u_i^*(u_i) + \dots + v^*(u_n)u_n^*(u_i) \\ &= v^*(u_i), \end{aligned}$$

and so f^* and v^* agree on the basis (u_1, \dots, u_n) , which implies that

$$v^* = f^* = v^*(u_1)u_1^* + \dots + v^*(u_n)u_n^*.$$

Therefore, (u_1^*, \dots, u_n^*) spans E^* . We claim that the covectors u_1^*, \dots, u_n^* are linearly independent. If not, we have a nontrivial linear dependence

$$\lambda_1 u_1^* + \dots + \lambda_n u_n^* = 0,$$

and if we apply the above linear form to each u_i , using a familiar computation, we get

$$0 = \lambda_i u_i^*(u_i) = \lambda_i,$$

proving that u_1^*, \dots, u_n^* are indeed linearly independent. Therefore, (u_1^*, \dots, u_n^*) is a basis of E^* . \square