

is positive semidefinite, the pseudo-inverse  $A^+$  of  $A$  is given by

$$A^+ = U^\top \begin{pmatrix} \Sigma_r^{-1} & 0 \\ 0 & 0 \end{pmatrix} U,$$

and since

$$f(x) = g(y) = \frac{1}{2}y^\top \Sigma_r y - y^\top c,$$

by Proposition 42.4 the minimum of  $g$  is achieved iff  $y^* = \Sigma_r^{-1}c$ . Since  $f(x)$  is independent of  $z$ , we can choose  $z = 0$ , and since  $d = 0$ , for  $x^*$  given by

$$Ux^* = \begin{pmatrix} \Sigma_r^{-1}c \\ 0 \end{pmatrix} \quad \text{and} \quad Ub = \begin{pmatrix} c \\ 0 \end{pmatrix},$$

we deduce that

$$x^* = U^\top \begin{pmatrix} \Sigma_r^{-1}c \\ 0 \end{pmatrix} = U^\top \begin{pmatrix} \Sigma_r^{-1} & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} c \\ 0 \end{pmatrix} = U^\top \begin{pmatrix} \Sigma_r^{-1} & 0 \\ 0 & 0 \end{pmatrix} Ub = A^+b, \quad (*)$$

and the minimum value of  $f$  is

$$f(x^*) = \frac{1}{2}(A^+b)^\top AA^+b - b^\top A^+b = \frac{1}{2}b^\top A^+AA^+b - b^\top A^+b = -\frac{1}{2}b^\top A^+b,$$

since  $A^+$  is symmetric and  $A^+AA^+ = A^+$ . For any  $x \in \mathbb{R}^n$  of the form

$$x = A^+b + U^\top \begin{pmatrix} 0 \\ z \end{pmatrix}, \quad z \in \mathbb{R}^{n-r},$$

since

$$x = A^+b + U^\top \begin{pmatrix} 0 \\ z \end{pmatrix} = U^\top \begin{pmatrix} \Sigma_r^{-1}c \\ 0 \end{pmatrix} + U^\top \begin{pmatrix} 0 \\ z \end{pmatrix} = U^\top \begin{pmatrix} \Sigma_r^{-1}c \\ z \end{pmatrix},$$

and since  $f(x)$  is independent of  $z$  (because  $f(x) = g(y)$ ), we have

$$f(x) = f(x^*) = -\frac{1}{2}b^\top A^+b. \quad \square$$

The problem of minimizing the function

$$f(x) = \frac{1}{2}x^\top Ax - x^\top b$$

in the case where we add either linear constraints of the form  $C^\top x = 0$  or affine constraints of the form  $C^\top x = t$  (where  $t \in \mathbb{R}^m$  and  $t \neq 0$ ) where  $C$  is an  $n \times m$  matrix can be reduced to the unconstrained case using a  $QR$ -decomposition of  $C$ . Let us show how to do this for linear constraints of the form  $C^\top x = 0$ .