

Now that we have defined \hat{E} and investigated the relationship between affine frames in E and bases in \hat{E} , we can give another construction of a vector space \mathcal{F} from E and \vec{E} that will allow us to “visualize” in a much more intuitive fashion the structure of \hat{E} and of its operations $\hat{+}$ and \cdot .

25.3 Another Construction of \hat{E}

One would probably wish that we could start with this construction of \mathcal{F} first, and then define \hat{E} using the isomorphism $\hat{\Omega}: \hat{E} \rightarrow \mathcal{F}$ defined below. Unfortunately, we first need the vector space structure on \hat{E} to show that $\hat{\Omega}$ is linear!

Definition 25.1. Given any affine space (E, \vec{E}) , we define the vector space \mathcal{F} as the direct sum $\vec{E} \oplus \mathbb{R}$, where \mathbb{R} denotes the field \mathbb{R} considered as a vector space (over itself). Denoting the unit vector in \mathbb{R} by 1, since $\mathcal{F} = \vec{E} \oplus \mathbb{R}$, every vector $v \in \mathcal{F}$ can be written as $v = u + \lambda 1$, for some unique $u \in \vec{E}$ and some unique $\lambda \in \mathbb{R}$. Then, for any choice of an origin Ω_1 in E , we define the map $\hat{\Omega}: \hat{E} \rightarrow \mathcal{F}$, as follows:

$$\hat{\Omega}(\theta) = \begin{cases} \lambda(1 + \overrightarrow{\Omega_1 a}) & \text{if } \theta = \langle a, \lambda \rangle, \text{ where } a \in E \text{ and } \lambda \neq 0; \\ u & \text{if } \theta = u, \text{ where } u \in \vec{E}. \end{cases}$$

The idea is that, once again, viewing \mathcal{F} as an affine space under its canonical structure, E is embedded in \mathcal{F} as the hyperplane $H = 1 + \vec{E}$, with direction \vec{E} , the hyperplane \vec{E} in \mathcal{F} . Then, every point $a \in E$ is in bijection with the point $A = 1 + \overrightarrow{\Omega_1 a}$, in the hyperplane H . If we denote the origin 0 of the canonical affine space \mathcal{F} by Ω , the map $\hat{\Omega}$ maps a point $\langle a, \lambda \rangle \in \hat{E}$ to a point in \mathcal{F} , as follows: $\hat{\Omega}(\langle a, \lambda \rangle)$ is the point on the line passing through both the origin Ω of \mathcal{F} and the point $A = 1 + \overrightarrow{\Omega_1 a}$ in the hyperplane $H = 1 + \vec{E}$, such that

$$\hat{\Omega}(\langle a, \lambda \rangle) = \lambda \overrightarrow{\Omega A} = \lambda(1 + \overrightarrow{\Omega_1 a}).$$

The following proposition shows that $\hat{\Omega}$ is an isomorphism of vector spaces.

Proposition 25.4. *Given any affine space (E, \vec{E}) , for any choice Ω_1 of an origin in E , the map $\hat{\Omega}: \hat{E} \rightarrow \mathcal{F}$ is a linear isomorphism between \hat{E} and the vector space \mathcal{F} of Definition 25.1. The inverse of $\hat{\Omega}$ is given by*

$$\hat{\Omega}^{-1}(u + \lambda 1) = \begin{cases} \langle \Omega_1 + \lambda^{-1}u, \lambda \rangle & \text{if } \lambda \neq 0; \\ u & \text{if } \lambda = 0. \end{cases}$$

Proof. It is a straightforward verification. We check that $\hat{\Omega}$ is invertible, leaving the verification that it is linear as an exercise. We have

$$\langle a, \lambda \rangle \mapsto \lambda 1 + \lambda \overrightarrow{\Omega_1 a} \mapsto \langle \Omega_1 + \overrightarrow{\Omega_1 a}, \lambda \rangle = \langle a, \lambda \rangle$$