

Heuristics and Optimization based for Path/Motion Planning Problems

Assignment Topics HK251

Below are some typical case studies for your choice, but not limited.

Shortest Path and Motion planning

A survey for the heuristic based robot path planning: *Mac et al., Heuristic approaches in robot path planning: A survey, Robotics and Autonomous Systems, pp. 13-28, 2016.* ([pdf in LMS](#))

(1) Multi-strategy fusion methods

- **References:**

- <https://www.nature.com/articles/s41598-025-92675-5>
- <https://www.nature.com/articles/s41598-025-13915-2>

(2) Bi-directional sampling based for path planning in dynamic environments

- **References:**

- <https://arxiv.org/pdf/2301.11816.pdf>, <https://arxiv.org/abs/2010.14693>
- Fu et al., Adaptive Goal-Biased Bi-RRT for Online Path Planning of Robotic Manipulators, ICIRA 2023. ([pdf in LMS](#))

(3) Optimization based

- **References:** <https://www.science.org/doi/10.1126/scirobotics.adf7843>

(4) ACO based method:

- **References:** <https://www.nature.com/articles/s41598-025-93571-8>

Complete Coverage Path Planning

A comprehensive survey: <https://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=9523743>

(5) C* Algorithm

- **References:** <https://arxiv.org/abs/2505.13782>

(6) BA* and B-Theta*

- **References:**

- BA*: <https://link.springer.com/article/10.1007/s10489-012-0406-4> ([pdf in LMS](#))
- B-Theta*: <https://link.springer.com/article/10.1007/s10846-017-0485-x> ([pdf in LMS](#))

(7) ACO based method:

- **References:** <https://doi.org/10.1016/j.compag.2014.08.013> ([pdf in LMS](#))

Evaluation

- Student teams will submit all materials of the assignment to LMS.
- Full report will also be examined.

Reports and presentation

- **Starting week: 43 (Learning week: 9)**

- Reports
 - o A full (text) report should include:
 - Introduction (*Problem statement, Applications, How the problem has been solving together with their pros and cons, why we use this our method.*)
 - Methods/Approaches (*Overview description, architecture/method pipeline, main steps.*)
 - Experiments (*Implementation description, testing for benchmark datasets, experimental results, evaluation*)
 - Improvement or application proposal (***Optional and bonus.***)
 - References.
 - o Presentation slides. (***optional but encouraged***)
 - o Source codes.
- Report submission: **Team leader should upload to LMS.**
- Deadline for report submission: **The date of the final exam.**