

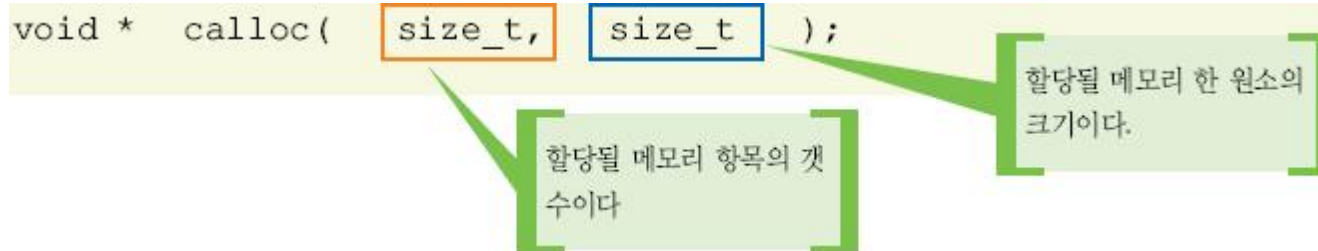
C 복습

- calloc, realloc

함수 **calloc()**

- 초기 값을 0으로 하는 동적 할당 함수
 - `stdlib.h` 헤더 파일에 함수원형 정의

```
void * calloc( size_t, size_t );
```



- 배열원소의 초기값 0인 `int`형 배열

```
int *ary;  
ary = (int *) calloc( 3, sizeof(int) );
```

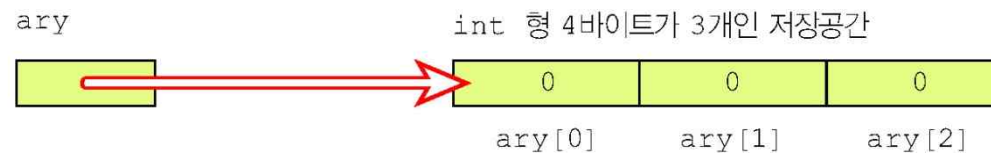


그림 18.5 함수 `calloc()`에 의한 저장공간의 할당

```
#include <stdio.h>
#include <stdlib.h>
```

```
int main(void)
{
```

```
    int *mary, *cary;
    int i = 0;
```

```
    printf("malloc()은 초기화를 하지 않는다. >>\n");
```

```
    mary = (int *) malloc( 2*sizeof(int) );
```

```
    if (mary == NULL)
```

```
    {
```

```
        printf("메모리 할당이 문제가 있습니다.\n");
```

```
        exit(EXIT_FAILURE);
```

```
    }
```

```
    printf("mary 주소는 %X이다. >>\n", mary);
```

```
    for (i = 0; i < 2; i++)
```

```
        printf("mary[%d](%#x) = %d ", i, mary + i, *(mary + i));
```

```
    printf("\n");
```

```
    printf("배열에 직접 값을 입력한 후 >>\n");
```

```
    mary[0] = 100; mary[1] = 200;
```

```
    for (i = 0; i < 2; i++)
```

```
        printf("mary[%d](%#x) = %d ", i, mary + i, *(mary + i));
```

```
    printf("\n\n");
```

```
    free(mary);
```

```
    printf("calloc()은 초기화를 0으로 한다. >>\n");
```

```
    cary = (int *) calloc( 2, sizeof(int) );
```

```
    if (cary == NULL)
```

```
    {
```

```
        printf("메모리 할당이 문제가 있습니다.\n");
```

```
        exit(EXIT_FAILURE);
```

```
    }
```

```
    printf("cary 주소는 %X이다. >>\n", cary);
```

```
    for (i = 0; i < 2; i++)
```

```
        printf("cary[%d](%#x) = %d ", i, cary + i, *(cary + i));
```

```
    printf("\n");
```

```
    free(cary);
```

C:\Windows\system32\cmd.exe

malloc()은 초기화를 하지 않는다. >>

mary 주소는 0X781460이다. >>

mary[0](0x781460) = -842150451 mary[1](0x781464) = -842150451

배열에 직접 값을 입력한 후 >>

mary[0](0x781460) = 100 mary[1](0x781464) = 200

calloc()은 초기화를 0으로 한다. >>

cary 주소는 0X781460이다. >>

cary[0](0x781460) = 0 cary[1](0x781464) = 0

malloc()은 초기화를 하지 않는다. >>

mary 주소는 0X781460이다. >>

mary[0]<0x781460> = -842150451 mary[1]<0x781464> = -842150451

```
int *mary, *cary;
```

```
int i = 0;
```

배열에 직접 값을 입력한 후 >>

mary[0]<0x781460> = 100 mary[1]<0x781464> = 200

```
printf("malloc()은 초기화를 하지 않는다. >>\n");
```

```
mary = (int *) malloc( 2*sizeof(int) );
```

```
if (mary == NULL)
```

```
{
```

```
    printf("메모리 할당이 문제가 있습니다.\n");
```

```
    exit(EXIT_FAILURE);
```

```
}
```

```
printf("mary 주소는 %X이다. >>\n", mary);
```

```
for (i = 0; i < 2; i++)
```

```
    printf("mary[%d](&mary[%d]) = %d ", i, mary + i, *(mary + i));
```

```
printf("\n");
```

```
printf("배열에 직접 값을 입력한 후 >>\n");
```

```
mary[0] = 100; mary[1] = 200;
```

```
for (i = 0; i < 2; i++)
```

```
    printf("mary[%d](&mary[%d]) = %d ", i, mary + i, *(mary + i));
```

```
printf("\n\n");
```

```
free(mary);
```

```

printf("calloc()은 초기화를 0으로 한다. >>\n");
cary = (int *) calloc( 2, sizeof(int) );
if (cary == NULL)
{
    printf("메모리 할당이 문제가 있습니다.\n");
    exit(EXIT_FAILURE);
}
printf("cary 주소는 %#X이다. >>\n", cary);
for (i = 0; i < 2; i++)
    printf("cary[%d](%#x) = %d ", i, cary + i, *(cary + i));

```

calloc<>은 초기화를 0으로 한다. >>

cary 주소는 0X781460이다. >>

cary[0]<0x781460> = 0 cary[1]<0x781464> = 0

함수 realloc()

- 이미 확보한 저장공간을 새로운 크기로 변경
 - 기존 영역을 이용하여 변경하거나, 새 영역 할당 후 이전 값을 복사할 수도 있음

```
void * realloc(void *, size_t);
```

- 첫 번째 인자 - 변경할 저장공간의 주소
- 두 번째 인자 - 변경하고 싶은 저장공간의 크기
- 첫 번째 인자가 NULL이면 함수 malloc()과 같은 기능을 수행

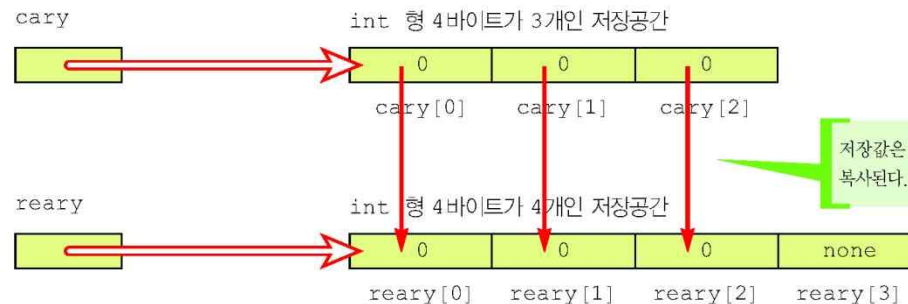
```
int *reary, *cary;  
cary = (int *) calloc( 3, sizeof(int) );
```

```
reary = (int *) realloc( cary, 4*sizeof(int) );
```

새로이 할당된 저장
공간의 기본 주소가
저장된다.

이전에 calloc(), malloc(),
realloc()에 의하여 이미 할당
된 저장공간의 기본 주소이다.

새로이 확보될 저장공간
의 전체 크기이다.



저장값은 자동으로
복사된다.

확장된 공간은
초기값 없음

그림 18.6 함수 realloc()에 의한 메모리 공간의 재할당

```
reary = (int *) realloc( cary, 4*sizeof(int) );
```

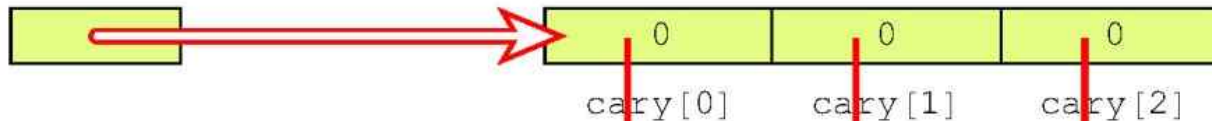
새로이 할당된 저장
공간의 기본 주소가
저장된다.

이전에 calloc(), malloc(),
realloc() 에 의하여 이미 할당
된 저장공간의 기본 주소이다.

새로이 확보될 저장공간
의 전체 크기이다.

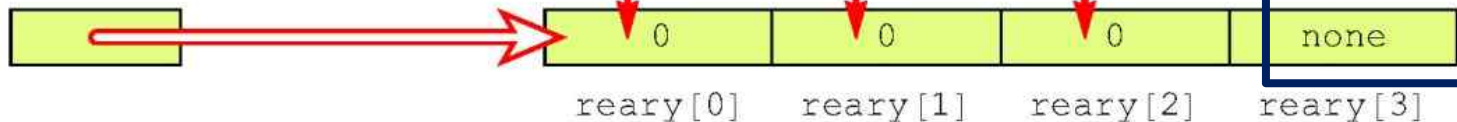
cary

int 형 4바이트가 3개인 저장공간



reary

int 형 4바이트가 4개인 저장공간



저장값은 자동으로
복사된다.

그림 18.6 함수 realloc()에 의한 메모리 공간의 재할당

C:\Windows\system32\cmd.exe

calloc()은 초기화를 0으로 한다. >>
cary 주소는 0X401460이다. >>

realloc()은 기존의 값이 남아 있다. >>

realloc() 호출 후에 >>

cary 주소는 0X401460이다. >>

reary 주소는 0X401460이다. >>

cary[0](0X401460) = 10 cary[1](0X401464) = 11

reary[0](0X401460) = 10 reary[1](0X401464) = 11

reary[2](0X401468) = 30 reary[3](0X40146C) = -842150451

reary[4](0X401470) = 40 reary[5](0X401474) = 50

/* realloc.c */

#include <stdio.h>

#include <stdlib.h>

cary (0x401460)

0

0

int main(void) {

int *reary, *cary;

int i = 0;

printf("calloc()은 초기화를 0으로 한다. >>\n");

cary = (int *) calloc(2, sizeof(int));

if (cary == NULL)

{

printf("메모리 할당이 문제가 있습니다.\n");

exit(EXIT_FAILURE);

}

printf("cary 주소는 %#X이다. >>\n\n", cary);


```

cary[0] = 10; cary[1] = 11;

printf("realloc()은 기존의 값이 남아 있다. >>#\n");
reary = (int *) realloc( cary, 6*sizeof(int) );
if (reary == NULL)
{
    printf("메모리 할당이 문제가 있습니다.#\n");
    exit(EXIT_FAILURE);
}
printf("realloc() 호출 후에 >>#\n");
printf("cary 주소는 %#X이다. >>#\n", cary);
printf("reary 주소는 %#X이다. >>#\n", reary);
reary[2] = 30; //reary[3]에는 저장할 하지 않음
reary[4] = 40; reary[5] = 50;

```

cary(0x401460)

10

11

C:\Windows\system32\cmd.exe

```

calloc()은 초기화를 0으로 한다. >>
cary 주소는 0X401460이다. >>

```

```

realloc()은 기존의 값이 남아 있다. >>
realloc() 호출 후에 >>
cary 주소는 0X401460이다. >>
reary 주소는 0X401460이다. >>

```

```

cary[0](0X401460) = 10 cary[1](0X401464) = 11
reary[0](0X401460) = 10 reary[1](0X401464) = 11
reary[2](0X401468) = 30 reary[3](0X40146C) = -842150451
reary[4](0X401470) = 40 reary[5](0X401474) = 50

```

```
printf("realloc() 호출 후에 >>\n");
printf("cary 주소는 %#X이다. >>\n", cary);
printf("reary 주소는 %#X이다. >>\n", reary);
reary[2] = 30; //reary[3]에는 저장할 하지 않음
reary[4] = 40; reary[5] = 50;
```

```
for (i = 0; i < 2; i++)
    printf("cary[%d](%#X) = %d ", i, cary + i, *(cary + i));
printf("\n");
```

```
for (i = 0; i < 6; i++)
{
    printf("reary[%d](%#X) = %d ", i, reary + i, *(reary + i));
    if (i%2 == 1) printf("\n");
}
```

```
free(reary);
```

cary(0x401460)

10	11
----	----

```
return 0;
```

reary(0x401460)

10	11	30	쓰레	40	50
----	----	----	----	----	----

realloc()은 기존의 값이 남아 있다. >>

realloc() 호출 후에 >>

cary 주소는 0X401460이다. >>

reary 주소는 0X401460이다. >>

cary[0]<0X401460> = 10 cary[1]<0X401464> = 11

reary[0]<0X401460> = 10 reary[1]<0X401464> = 11

reary[2]<0X401468> = 30 reary[3]<0X40146C> = -842150451

reary[4]<0X401470> = 40 reary[5]<0X401474> = 50

Arrays and Structures

Chapter 2

Contents

2.1 Arrays

2.2 Dynamically Allocated Arrays

2.3 Structures

2.4 Polynomials

2.5 Sparse Matrices

2.6 Representation of Multidimensional Arrays

Data structure

- Data structure \equiv data type + storage structure
- Data type
 - How to categorize data objects
 - **Object + operator**
- Abstract Data Type (ADT)
 - Specification of objects and operations independent of their implementation

Performance of a program largely
depends on data structures !!

Abstract Data Type (ADT) of Array

- A set of pairs $\langle \text{index}, \text{value} \rangle$
- ADT for array provides operations that
 - retrieves a value
 - stores a value

ADT Array is

objects: A set of pairs $\langle index, value \rangle$ where for each value of *index* there is a value from the set *item*. *Index* is a finite ordered set of one or more dimensions, for example, $\{0, \dots, n-1\}$ for one dimension, $\{(0, 0), (0, 1), (0, 2), (1, 0), (1, 1), (1, 2), (2, 0), (2, 1), (2, 2)\}$ for two dimensions, etc.

functions:

for all $A \in Array, i \in index, x \in item, j, size \in integer$

Array Create(*j, list*) ::= **return** an array of *j* dimensions where *list* is a *j*-tuple whose *i*th element is the size of the *i*th dimension. *Items* are undefined.

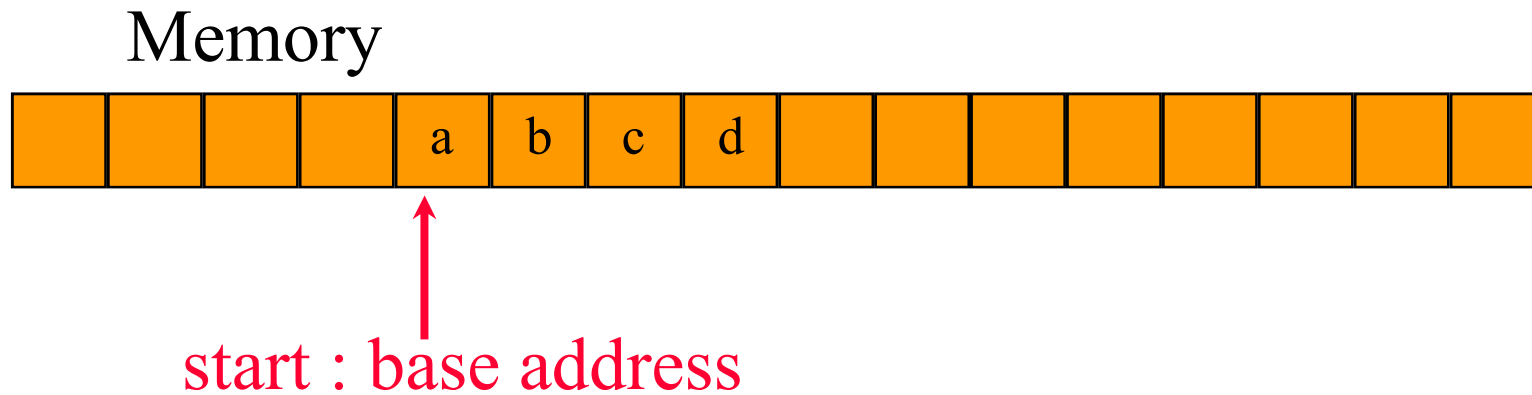
Item Retrieve(*A, i*) ::= **if** (*i* \in *index*) **return** the item associated with index value *i* in array *A*
else return error

Array Store(*A, i, x*) ::= **if** (*i* in *index*)
return an array that is identical to array *A* except the new pair $\langle i, x \rangle$ has been inserted **else return** error.

end Array

ADT 2.1: Abstract Data Type *Array*

1D Array Representation In C



- 1-dimensional array $x = [a, b, c, d]$
- map into contiguous memory locations
- $\text{location}(x[i]) = \text{start} + i$

1D Array Addressing

- `int one[] = {0,1,2,3,4}; print1(,);`

```
void print1(int *ptr, int row)
{
/* print out a one-dimensional array using a pointer */
    int i;
    printf("Address Contents\n");
    for (i=0; i<row; i++)
        printf("%08u%05d\n", ptr+i, *(ptr+i) );
    printf("\n");
}
```

Address		Contents
Base address: α	1224	0
$\alpha+1*\text{sizeof}(\text{int})$	1228	1
$\alpha+2*\text{sizeof}(\text{int})$	1232	2
$\alpha+3*\text{sizeof}(\text{int})$	1236	3
$\alpha+4*\text{sizeof}(\text{int})$	1240	4

- Pointer and Arrays
 - `int *list1, list2[5]; list1 = list2;`
 - `list2 == &list2[0]`
 - `list2 + i == &list1[i]`
 - `*(list1+i) == list2[i]`

```
#include <stdio.h>
```

```
void print1(int*, int);
```

```
void main()
```

```
{
```

```
    int one[] = { 0, 1, 2, 3, 4 };
```

```
    int size = sizeof(one) / sizeof(int);
```

```
    print1(one, size);
```

```
}
```

```
void print1(int *ptr, int row)
```

```
{
```

```
    /* print out a one-dimensional array using a pointer */
```

```
    int i;
```

```
    printf("Address Contents\n");
```

```
    for (i = 0; i < row; i++)
```

```
        printf("%8u%5d\n", ptr + i, *(ptr + i));
```

```
    printf("\n");
```

```
}
```

Address	Contents
---------	----------

11335848	0
----------	---

11335852	1
----------	---

11335856	2
----------	---

11335860	3
----------	---

11335864	4
----------	---

1D Array Program: examples

```
#define MAX_SIZE 100
float sum(float [], int);
float input[MAX_SIZE], answer;
int i;

float sum(float list[], int n)
{
    int i;
    float tempsum = 0;
    for (i = 0; i < n; i++)
        tempsum += list[i];
    return tempsum;
}
```

```
void main(void)
{
    for (i = 0; i < MAX_SIZE; i++)
        input[i] = 1;
    answer = sum(input, MAX_SIZE);
    printf("The sum is: %f\n", answer);
}
```

- When sum is called, input (= &input[0]) is stored in a temporary storage
- Dereference (역참조)
 - list[i]가 '=' 우측 : (list+i)가 가리키는 값 반환
 - list[i]가 '=' 좌측 : 값을 (list+i) 위치에 저장
 - (예) list[1]=list[2]

2D Arrays

- `int a[3][4];`
- may be shown as a table

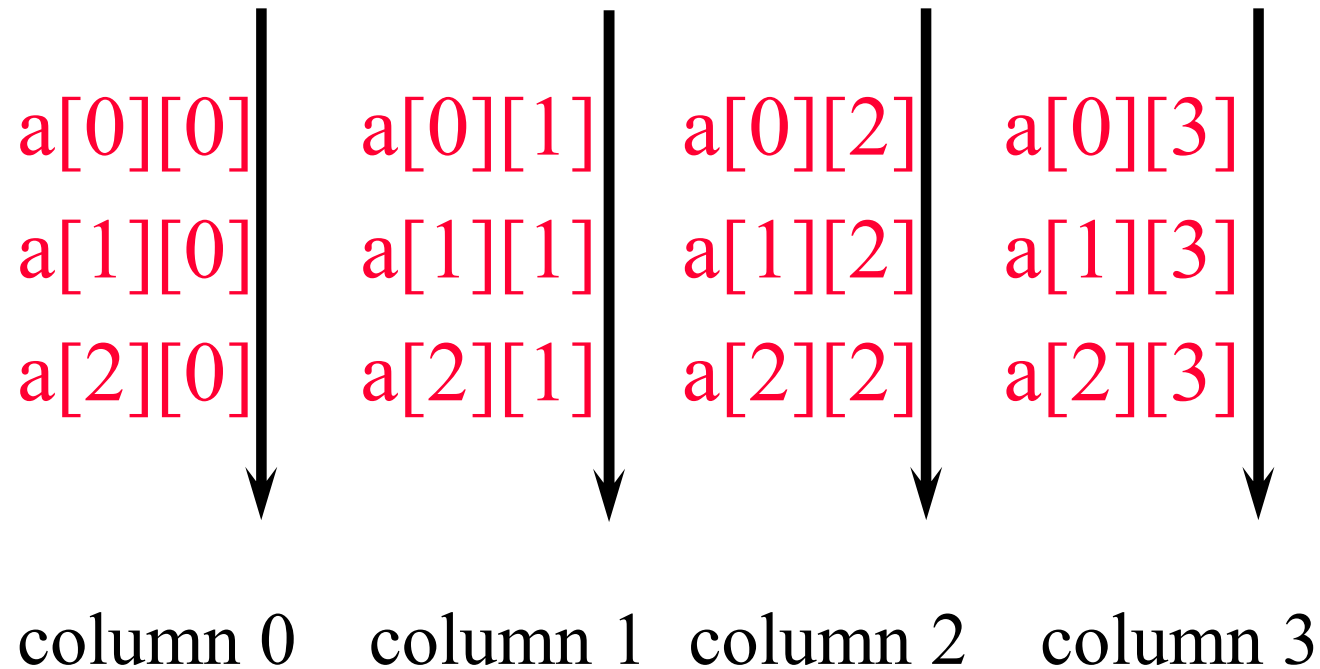
<code>a[0][0]</code>	<code>a[0][1]</code>	<code>a[0][2]</code>	<code>a[0][3]</code>
<code>a[1][0]</code>	<code>a[1][1]</code>	<code>a[1][2]</code>	<code>a[1][3]</code>
<code>a[2][0]</code>	<code>a[2][1]</code>	<code>a[2][2]</code>	<code>a[2][3]</code>

Rows Of A 2D Array

<u>a[0][0]</u>	<u>a[0][1]</u>	<u>a[0][2]</u>	<u>a[0][3]</u>	→ row 0
<u>a[1][0]</u>	<u>a[1][1]</u>	<u>a[1][2]</u>	<u>a[1][3]</u>	→ row 1
<u>a[2][0]</u>	<u>a[2][1]</u>	<u>a[2][2]</u>	<u>a[2][3]</u>	→ row 2

a[0][0] a[0][1] a[0][2] a[0][3] a[1][0] a[1][1] a[1][2] a[1][3]

Columns Of A 2D Array



Representation of arrays (1)

- $A[u_1][u_2] \dots [u_n]$
 - the number of elements :
 - an element $A[i_1][i_2] \dots [i_n]$ is mapped onto a position in a one-dim C array
 - Row major order example
 - $A[2][3][2][2] : 2*3*2*2 = 24$ elements
 - stored as $A[0][0][0][0], A[0][0][0][1], \dots, A[1][2][1][0], A[1][2][1][1]$
 - translate to locations in the one-dim array
- $A[u_1][u_2][u_3][u_4]$
- $A[0][0][0][0] \rightarrow \text{position } a$
- $A[0][0][0][1] \rightarrow \text{position } a+1$
- $A[i][j][k][m] \rightarrow \text{position: } a + i*u_2*u_3*u_4 + j*u_3*u_4 + k*u_4 + m$

- `int A[2][4][3];`
- `A[1][2][2]`의 경우...
- `A[0]`

– `A[0][0]` 000 001 002

– `A[0][1]` 010 011 012

– `A[0][2]` 020 021 022

– `A[0][3]` 030 031 032

$$1 * 4 * 3 + 2 * 3 + 2$$

- `A[1]`

– `A[1][0]` 100 101 102

– `A[1][1]` 110 111 112

– `A[1][2]` 120 121 122

– `A[1][3]` 130 131 132

$A[u_1][u_2][u_3][u_4]$

$A[0][0][0][0] \rightarrow \text{position } a$

$A[0][0][0][1] \rightarrow \text{position } a+1$

$A[i][j][k][m] \rightarrow \text{position: } a + i * u_2 + j * u_3 + k * u_4 + m$

- $A[i] \rightarrow$
 - $A[u_2][u_3][u_4]$ 가 0~ i-1 개 있음
- $A[][j] \rightarrow$
 - $A[u_3][u_4]$ 가 0~ j-1 개 있음
- $A[][][k] \rightarrow$
 - $A[u_4]$ 가 0~ k-1 개 있음

Representation of arrays (2)

- two-dim array $A[u_1][u_2]$

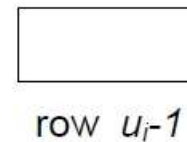
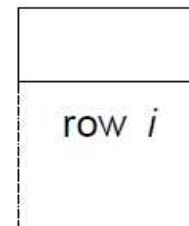
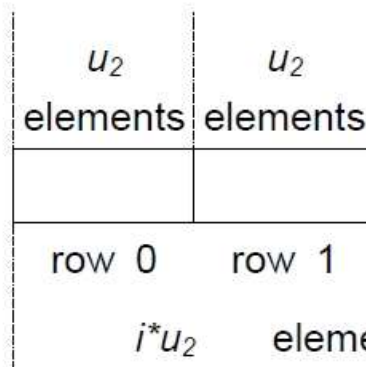
let a be the address of $A[0][0]$

$A[i][0] : a + i * u_2$ $\text{sizeof(element)} = 10$ 이라 가정

$A[i][j] : a + i * u_2 + j$

	col 0	col 1	col u_2-1
row 0	X	X	X
row 1	X	X	X
row 2	X	X	X
row u_1-1	X	X	X

(a)



(b)

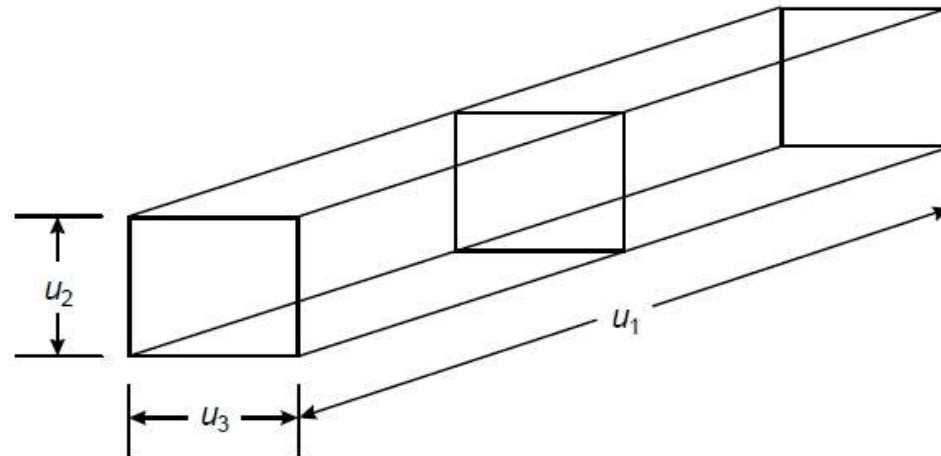
Representation of arrays (3)

three-dim array $A[u_1][u_2][u_3]$

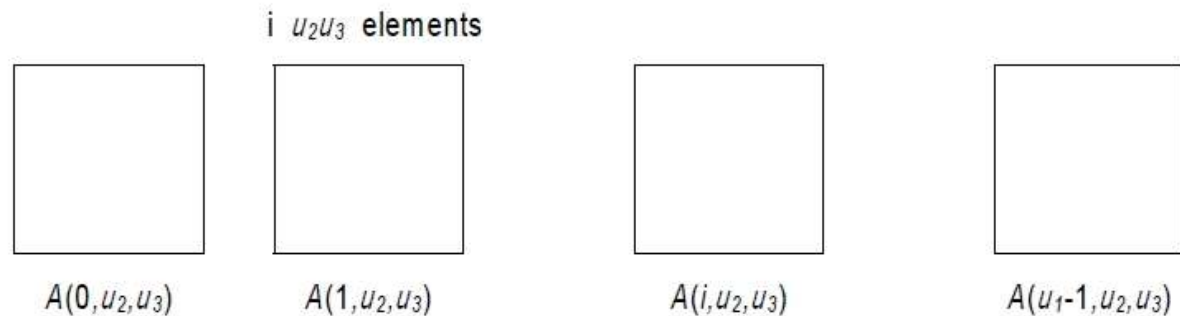
the address of $A[0][0][0] : \alpha$

$A[i][0][0] : \alpha + iu_2u_3$

$A[i][j][k] : \alpha + iu_2u_3 + ju_3 + k$



(a) 3-dimensional array $A[u_1][u_2][u_3]$ regarded as u_1 2-dimensional array



(b) Sequential row major representation of a 3-dimensional array

Representation of arrays (4)

int A[u₀][u₁]...[u_{n-1}]

Repeating in this way the address for A [i₀][i₁] . . . [i_{n-1}] is:

$$\begin{aligned}
 & \alpha + i_0 \text{upper}_1 \text{upper}_2 \dots \text{upper}_{n-1} \\
 & + i_1 \text{upper}_2 \text{upper}_3 \dots \text{upper}_{n-1} \\
 & + i_2 \text{upper}_3 \text{upper}_4 \dots \text{upper}_{n-1} \\
 & \vdots \\
 & + i_{n-2} \text{upper}_{n-1} \\
 & + i_{n-1}
 \end{aligned}$$

$n-1$

$$= \alpha + \sum_{j=0}^{n-1} i_j a_j \text{ where: } \begin{cases} a_j = \prod_{k=j+1}^{n-1} \text{upper}_k & 0 \leq j < n-1 \\ a_{n-1} = 1 \end{cases}$$

- `int arr[3][4][5][6];`
- `arr[2][3][1][0]`은 `&a[0][0][0][0] + 336` ?
 - int는 4bytes로 가정
 - $2*(4*5*6) + 3*(5*6) + 1*6 + 0$

Dynamic memory allocation (1)

```
pf = (float *) malloc (sizeof(float));
```

is replaced by

```
#define MALLOC(p,s) \
    if (! ( (p) = malloc ( s) ) ) { \
        fprintf(stderr, "Insufficient memory"); \
        exit(EXIT_FAILURE);\
    }
```

Dynamic memory allocation (2)

- calloc

```
int *x;
```

```
x = calloc(n, sizeof(int));
```

```
// allocated bits are set to 0
```

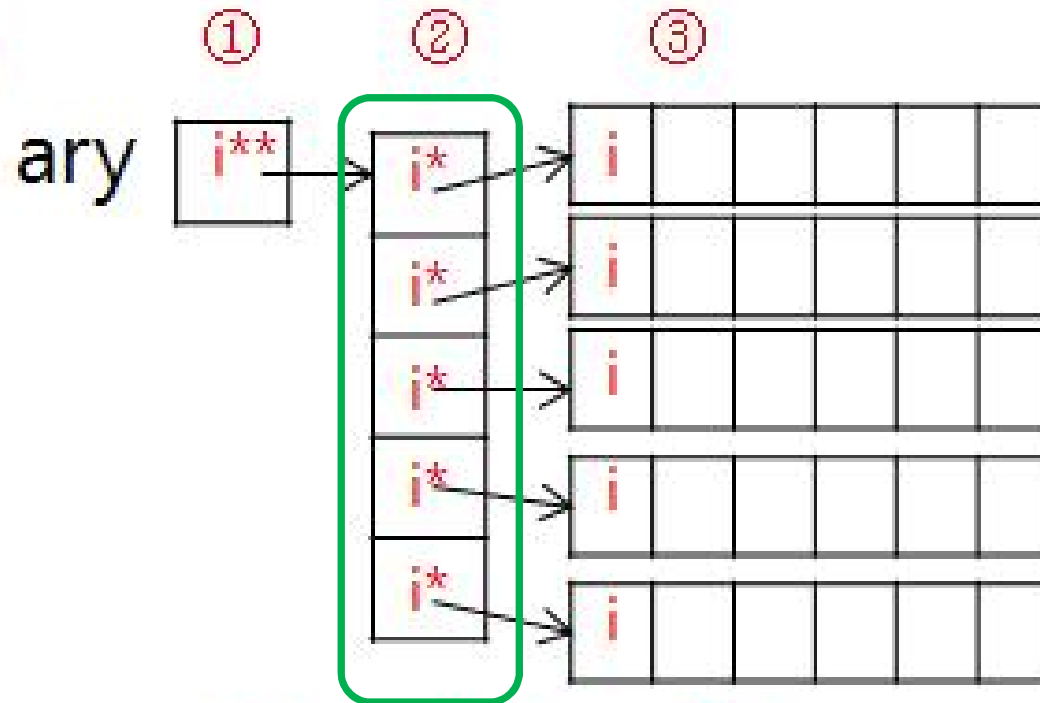
- realloc

```
realloc(p, s);
```

```
// changes the size of memory block
```

```
// pointed by p to s
```

할당 순서



해제 순서

③

②

①

- `int **arr;`
- `arr=(int**)malloc(sizeof(int*)*5);`
- `for(int i=0;i<5;i++)`
 - `arr[i]=(int*)malloc(sizeof(int)*6);`

Dynamic memory allocation (3)

```
int **myArray;  
myArray = make2dArray(5,10);  
myArray[2][4] = 6;
```

```
int** make2dArray(int rows, int cols)  
{/* create a two dimensional rows X cols array */  
    int **x, i;  
  
    /* get memory for row pointers */  
    MALLOC(x, rows * sizeof (*x));  
  
    /* get memory for each row */  
    for (i = 0; i < rows; i++)  
        MALLOC(x[i], cols * sizeof(**x));  
    return x;  
}
```

Program 2.3: Dynamically create a two-dimensional array

2차원 배열 예제(1)

```
#include <stdlib.h>
#include <stdio.h>
void main()
{
    double **x;
    int i, j, row = 2, col = 3;    double*
    x = (double **)malloc(sizeof(*x)*row);
    printf("sizeof(x) = %d\n", sizeof(x));
    for (i = 0; i < row; i++) {
        x[i] = (double *)malloc(col * sizeof(*x));
        printf("sizeof(x[%d]) = %d\n", i, sizeof(x[i]));
        for (j = 0; j < col; j++) {
            x[i][j] = i * 10 + j;
            printf("x[%d][%d] = %f\n", i, j, x[i][j]);
            printf("sizeof(x[%d][%d]) = %d\n", i, j, sizeof(x[i][j]));
        }
    }
}
```

```
sizeof(x) = 4
sizeof(x[0]) = 4
x[0][0] = 0.000000
sizeof(x[0][0]) = 8
x[0][1] = 1.000000
sizeof(x[0][1]) = 8
x[0][2] = 2.000000
sizeof(x[0][2]) = 8
sizeof(x[1]) = 4
x[1][0] = 10.000000
sizeof(x[1][0]) = 8
x[1][1] = 11.000000
sizeof(x[1][1]) = 8
x[1][2] = 12.000000
sizeof(x[1][2]) = 8
```

2차원 배열 예제(2)

```
sizeof(x) = 4    x = 51729952    sizeof(y)=48    y = 15727296
sizeof(x[0]) = 4    x[0]= 51748776    sizeof(y[0]) = 24    y[0] = 15727296
x[0][0] = 0.000000
x[0][1] = 1.000000
x[0][2] = 2.000000
sizeof(x[1]) = 4    x[1]= 51748848    sizeof(y[1]) = 24    y[1] = 15727320
x[1][0] = 10.000000
x[1][1] = 11.000000
x[1][2] = 12.000000
```

```
#include <stdlib.h>
#include <stdio.h>
void main()
{
    double **x, y[2][3];
    int i, j, row = 2, col = 3;
    x = (double **)malloc(sizeof(*x)*row);
    printf("sizeof(x) = %d    x = %d    sizeof(y)=%d    y = %d\n",
           sizeof(x), x, sizeof(y), y);
    for (i = 0; i < row; i++) {
        x[i] = (double *)malloc(col * sizeof(**x));
        printf("sizeof(x[%d]) = %d    x[%d]= %d    sizeof(y[%d]) = %d    y[%d] = %d\n",
               i, sizeof(x[i]), i, x[i], i, sizeof(y[i]), i, y[i]);
        for (j = 0; j < col; j++) {
            x[i][j] = i * 10 + j;
            printf("x[%d][%d] = %f\n", i, j, x[i][j]);
        }
    }
}
```

y[0]과 y[1]의 차이는 24.

x[0]과 x[1]의 차이는 일정치 않음.

```

double **x, y[2][3];
int i, j, row = 2, col = 3;
x = (double **)malloc(sizeof(*x)*row);
printf("sizeof(x) = %d   x = %d   sizeof(y)=%d   y = %d\n",
      sizeof(x), x, sizeof(y), y);
for (i = 0; i < row; i++) {
    x[i] = (double *)malloc(col * sizeof(**x));
}

```

```

sizeof(x) = 4   x = 51729952   sizeof(y)=48   y = 15727296
sizeof(x[0]) = 4   x[0]= 51748776   sizeof(y[0]) = 24   y[0] = 15727296

sizeof(x[1]) = 4   x[1]= 51748848   sizeof(y[1]) = 24   y[1] = 15727320

```

Structures

- A structure is a collection of data items
 - Each item is identified as to its type and name

```
struct {  
    char name[10];  
    int age;  
    float salary;  
} person;
```

- Examples of the use of the structure member operator

```
strcpy(person.name, "james");  
person.age = 10;  
person.salary = 35000;
```

Create your own structure using *typedef*

```
struct humanBeing
{
    char name[10];
    int age;
    float salary;
};
typedef struct humanBeing humanBeing;
```

```
typedef struct
{
    char name[10];
    int age;
    float salary;
} humanBeing ;
```

- Variable declaration
 - humanBeing person1, person2;
- Equality check
 - if (person1 == person2)
- Replacement
 - person1 = person2
 - strcpy(person1.name, person2.name);
 - person1.age = person2.age;
 - person1.salary = person2.salary;

Usage of structure: example

```
int humansEqual(humanBeing person1,
                humanBeing person2)
{
    /* return TRUE if person1 and person2 are the same human
       being otherwise return FALSE */
    if (strcmp(person1.name, person2.name))
        return FALSE;
    if (person1.age != person2.age)
        return FALSE;
    if (person1.salary != person2.salary)
        return FALSE;
    return TRUE;
}
```

```
typedef struct
{
    char name[10];
    int age;
    float salary;
} humanBeing ;
```

```
humanBeing person1, person2;

if (humansEqual(person1, person2))
    printf("The same people\n");
else
    printf("Different people\n");
```

Embedding a structure within structure

```
typedef struct {  
    int month;  
    int day;  
    int year;  
} date ;  
typedef struct {  
    char name[10];  
    int age;  
    float salary;  
    date dob;  
} humanBeing;
```

```
humanBeing person1;
```

```
person1.dob.month = 2;  
person1.dob.day = 11;  
person1.dob.year = 1944;
```


Self-Referential Structures

- A self-referential structure is one in which one or more of its components is a pointer to itself.

```
typedef struct list {  
    char data;  
    struct list *link;  
}list;
```

```
struct list {  
    char data;  
    struct list *link;  
};  
typedef struct list list;
```

list item1, item2, item3;



item1.data = 'a';

item2.data = 'b';

item3.data = 'c';

item1.link = item2.link = item3.link = NULL;

item1.link = &item2; \Rightarrow *link the structures*

item2.link = &item3; (*item1* \rightarrow *item2* \rightarrow *item3*)

Polynomials

- $A(x) = 3x^{20} + 2x^5 + 4$
- $B(x) = x^4 + 10x^3 + 3x^2 + 1$
- A polynomial $P(x) = a_1x^{e_1} + \dots + a_nx^{e_n}$ can be considered as an ordered (linear) list.

Polynomials

- Ordered list (linear list): an ordered set of data items.

ex) Days-of-week

(Mon,	Tue,	Wed,	Thu,	Fri,	Sat,	Sun)	: <i>list</i>
1st	2nd	3rd	4th	5th	6th	7th	: <i>order</i>

- There can be an empty list
- Operations on ordered list

i . finding the length
ii . reading from right to left (or left to right)
iii . retrieve i-th element, $0 \leq i < n$
iv . update i-th element's value, $0 \leq i < n$ <u>before</u> <u>after</u>
v . insertion (i번째 위치, $0 \leq i < n$) : - i, i+1, ..., n-1 -> i+1, i+2, ..., n
vi . deletion (i번째 항목, $0 \leq i < n$) : - i+1, ..., n-1 -> i, i+1, ..., n-2

ADT of Polynomial

ADT Polynomial is

objects: $p(x) = a_1x^{e_1} + \dots + a_nx^{e_n}$; a set of ordered pairs of $\langle e_i, a_i \rangle$ where a_i in *Coefficients* and e_i in *Exponents*, e_i are integers ≥ 0

functions:

for all $poly, poly1, poly2 \in \text{Polynomial}$, $coef \in \text{Coefficients}$, $expon \in \text{Exponents}$

<i>Polynomial</i> Zero()	::=	return the polynomial, $p(x) = 0$
<i>Boolean</i> IsZero(<i>poly</i>)	::=	if (<i>poly</i>) return <i>FALSE</i> else return <i>TRUE</i>
<i>Coefficient</i> Coef(<i>poly</i> , <i>expon</i>)	::=	if (<i>expon</i> \in <i>poly</i>) return its coefficient else return zero
<i>Exponent</i> LeadExp(<i>poly</i>)	::=	return the largest exponent in <i>poly</i>
<i>Polynomial</i> Attach(<i>poly</i> , <i>coef</i> , <i>expon</i>)	::=	if (<i>expon</i> \in <i>poly</i>) return error else return the polynomial <i>poly</i> with the term $\langle coef, expon \rangle$ inserted
<i>Polynomial</i> Remove(<i>poly</i> , <i>expon</i>)	::=	if (<i>expon</i> \in <i>poly</i>) return the polynomial <i>poly</i> with the term whose exponent is <i>expon</i> deleted else return error
<i>Polynomial</i> SingleMult(<i>poly</i> , <i>coef</i> , <i>expon</i>)	::=	return the polynomial $poly \cdot coef \cdot x^{expon}$
<i>Polynomial</i> Add(<i>poly1</i> , <i>poly2</i>)	::=	return the polynomial $poly1 + poly2$
<i>Polynomial</i> Mult(<i>poly1</i> , <i>poly2</i>)	::=	return the polynomial $poly1 \cdot poly2$

end Polynomial

$$B(x) = x^4 + 10x^3 + 3x^2 + 1$$

ADT Polynomial is

objects: $p(x) = a_1x^{e_1} + \dots + a_nx^{e_n}$; a set of ordered pairs of $\langle e_i, a_i \rangle$ where a_i in *Coefficients* and e_i in *Exponents*, e_i are integers ≥ 0

functions:

for all $poly, poly1, poly2 \in \text{Polynomial}$, $coef \in \text{Coefficients}$, $expon \in \text{Exponents}$

<i>Polynomial</i> Zero()	::=	return the polynomial, $p(x) = 0$
<i>Boolean</i> IsZero(<i>poly</i>)	::=	if (<i>poly</i>) return <i>FALSE</i> else return <i>TRUE</i>
<i>Coefficient</i> Coef(<i>poly</i> , <i>expon</i>)	::=	if (<i>expon</i> \in <i>poly</i>) return its coefficient else return zero
<i>Exponent</i> LeadExp(<i>poly</i>)	::=	return the largest exponent in <i>poly</i>
<i>Polynomial</i> Attach(<i>poly</i> , <i>coef</i> , <i>expon</i>)	::=	if (<i>expon</i> \in <i>poly</i>) return error else return the polynomial <i>poly</i> with the term $\langle coef, expon \rangle$ inserted

$$B(x) = x^4 + 10x^3 + 3x^2 + 1$$

<i>Polynomial Remove</i> (<i>poly</i> , <i>expon</i>)	::=	if (<i>expon</i> \in <i>poly</i>) return the polynomial <i>poly</i> with the term whose exponent is <i>expon</i> deleted else return error
<i>Polynomial SingleMult</i> (<i>poly</i> , <i>coef</i> , <i>expon</i>)	::=	return the polynomial <i>poly</i> \cdot <i>coef</i> $\cdot x^{\textit{expon}}$
<i>Polynomial Add</i> (<i>poly1</i> , <i>poly2</i>)	::=	return the polynomial <i>poly1</i> + <i>poly2</i>
<i>Polynomial Mult</i> (<i>poly1</i> , <i>poly2</i>)	::=	return the polynomial <i>poly1</i> \cdot <i>poly2</i>

Polynomial Representation

- Principle
 - Unique exponents are arranged in decreasing order

Polynomial Representation(1)

- Use *typedef* to create the type *polynomial*

$$A(x) = 2x^{1000} + 1 \text{ and } B(x) = x^4 + 10x^3 + 3x^2 + 1$$

```
#define MAX-DEGREE 101 /*Max degree of polynomial+1*/
typedef struct {
    int degree;
    float coef[MAX-DEGREE];
} polynomial;
```

a.coef[i]: 차수i의 계수

polynomial a;
a.degree = n
a.coef[i] = a_{n-i}, 0 ≤ i ≤ n

- leads to a very simple algorithms for many of the operations on polynomials
- Wastes computer memory

$$A(x) = 2x^{1000} + 1 \text{ and } B(x) = x^4 + 10x^3 + 3x^2 + 1$$

```
#define MAX-DEGREE 101 /*Max degree of polynomial+1*/  
typedef struct {  
    int degree;  
    float coef[MAX-DEGREE];  
} polynomial;
```

- polynomial A, B;
- A.coef[0], A.coef[1], ..., A.coef[1000]
- B.coef[0], A.coef[1], ..., B.coef[4]

Polynomial Representation(2)

- Store only non-zero exponents
- All polynomials are represented in a single array called terms

```
#define MAX_TERMS 100  /* size of terms array */
typedef struct {
    float coef;
    int expon;
} polynomial;

polynomial terms[MAX_TERMS];
int avail = 0;
int starta, finisha
```

Polynomial Repre

```
#define MAX_TERMS 100  /* size c
typedef struct {
    float coef;
    int expon;
} polynomial;

polynomial terms[MAX_TERMS];
int avail = 0;
int starta, finisha
```

$$A(x) = 2x^{1000} + 1 \text{ and } B(x) = x^4 + 10x^3 + 3x^2 + 1$$

	<i>startA</i>	<i>finishA</i>	<i>startB</i>		<i>finishB</i>	<i>avail</i>
	↓	↓	↓		↓	↓
<i>coef</i>	2	1	1	10	3	1
<i>exp</i>	1000	0	4	3	2	0
	0	1	2	3	4	5
						6

Figure 2.3: Array representation of two polynomials

Polynomial Addition

Ex. $A(x) = 2x^{1000} + 1$ and $B(x) = x^4 + 10x^3 + 3x^2 + 1$

$$\begin{aligned} \rightarrow D(x) &= A(x) + B(x) \\ &= 2x^{1000} + x^4 + 10x^3 + 3x^2 + 2 \end{aligned}$$

	<i>startA</i>	<i>finishA</i>	<i>startB</i>		<i>finishB</i>	<i>avail</i>					
	↓	↓	↓		↓	↓					
<i>coef</i>	2	1	1	10	3	1					
<i>exp</i>	1000	0	4	3	2	0					
	0	1	2	3	4	5	6				

$$A(x) = 3x^{10} - 2x^4 + 5x + 1, \quad B(x) = 2x^4 + x^2 + 10x$$

Polynomial Addition (전체)

```
/* add A(x) and B(x) to obtain D(x) */
void padd(int startA, int finishA, int startB,
          int finishB, int *startD, int *finishD){
    float coefficient;
    *startD = avail;
    while (startA <= finishA && startB <= finishB)
        switch(COMPARE(terms[startA].expon,
                       terms[startB].expon)){
            case -1: /* a expon < b expon */
                attach(terms[startB].coef,
                      terms[startB].expon);
                startB++;
                break;
            case 0: /* equal exponents */
                coefficient = terms[startA].coef +
                             terms[startB].coef;
```

```
            if(coefficient)
                attach(coefficient, terms[startA].expon);
            startA++;
            startB++;
            break;
            case 1: /* a expon > b expon */
                attach(terms[startA].coef,
                      terms[startA].expon);
                startA++;
        }
    /* add in remaining terms of A(x) */
    for( ; startA <= finishA; startA++)
        attach(terms[startA].coef, terms[startA].expon);
    /* add in remaining terms of B(x) */
    for( ; startB <= finishB; startB++)
        attach(terms[startB].coef, terms[startB].expon);
    *finishD = avail - 1;
}
```

	<i>startA</i>	<i>finishA</i>	<i>startB</i>		<i>finishB</i>	<i>avail</i>					
	↓	↓	↓		↓	↓					
<i>coef</i>	2	1	1	10	3	1					
<i>exp</i>	1000	0	4	3	2	0					
	0	1	2	3	4	5	6				

/* add A(x) and B(x) to obtain D(x) */

void padd(int *startA*, int *finishA*, int *startB*, int *finishB*, int *startD, int *finishD){

int main(){

int sa=0, fa=1, sb=2, fb=5;
int sd, fd;
padd(sa, fa, sb, fb, &sd, &fd);
...

#define MAX_TERMS 100 /* size of array
typedef struct {

float coef;
int expon;
} polynomial;

polynomial terms[MAX_TERMS];
int avail = 0;
int starta, finisha

$$A(x) = 3x^{10} - 2x^4 + 5x + 1, \quad B(x) = 2x^4 + x^2 + 10x$$


```

void padd(int startA, int finishA, int startB, int finishB, int *startD, int *finishD){
    float coefficient;
    *startD = avail;
    while (startA <= finishA && startB <= finishB)
        switch(COMPARE(terms[startA].expon, terms[startB].expon)){
            case -1: /* a expon < b expon */
                attach(terms[startB].coef, terms[startB].expon);
                startB++; break;
            case 0: /* equal exponents */
                coefficient = terms[startA].coef + terms[startB].coef;
                if(coefficient)
                    attach(coefficient, terms[startA].expon);
                startA++; startB++; break;
            case 1: /* a expon > b expon */
                attach(terms[startA].coef, terms[startA].expon);
                startA++;
        }
}

```

$$A(x) = 3x^{10} - 2x^4 + 5x + 1, \quad B(x) = 2x^4 + x^2 + 10x$$


```

/* add in remaining terms of A(x) */
for( ; startA <= finishA; startA++)
    attach(terms[startA].coef, terms[startA].expon);
/* add in remaining terms of B(x) */
for( ; startB <= finishB; startB++)
    attach(terms[startB].coef, terms[startB].expon);
*finishD = avail -1;
}

```

```

void attach(float coefficient, int exponent)
{ /* add a new term to the polynomial */
    if (avail >= MAX_TERMS) {
        fprintf(stderr, "Too many terms in the polynomial\n");
        exit(EXIT_FAILURE);
    }
    terms[avail].coef = coefficient;
    terms[avail++].expon = exponent;
}

```


Sparse Matrices

- Standard representation of a matrix:

$A[\text{MAX_ROWS}][\text{MAX_COLS}]$

	col0	col1	Col2
Row0	-27	3	4
Row1	6	82	-2
Row2	109	-64	11
Row3	12	8	9
row4	48	27	47

	0	1	2	3	4	5
0	15	0	0	22	0	-15
1	0	11	3	0	0	0
2	0	0	0	-6	0	0
3	0	0	0	0	0	0
4	91	0	0	0	0	0
5	0	0	28	0	0	0

- Sparse matrix : $m \times n$ matrix A
such that
$$\frac{\text{no. of non - zero elements}}{m \times n} \ll 1$$

Sparse Matrix Representation

- Use an array of triples to represent a sparse matrix.
 - $\langle \text{row}, \text{column}, \text{value} \rangle$: 3-tuples (triples)
 - no. of rows & columns
 - no. of non-zero elements
 - ordering (column major or row major)

SparseMatrix Create(*maxRow*, *maxCol*) ::=

```
#define MAX_TERMS 101 /* maximum number of terms +1*/
typedef struct {
    int col;
    int row;
    int value;
} term;
term a[MAX_TERMS];
```

Sparse Matrix Representation: example

A[6][6]

	0	1	2	3	4	5
0	15	0	0	22	0	-15
1	0	11	3	0	0	0
2	0	0	0	-6	0	0
3	0	0	0	0	0	0
4	91	0	0	0	0	0
5	0	0	28	0	0	0

```
typedef struct {  
    int col;  
    int row;  
    int value;  
} term;  
term a[MAX_TERMS];
```

Row-major order

	row	col	val
a[0]	6	6	8
[1]	0	0	15
[2]	0	3	22
[3]	0	5	-15
[4]	1	1	11
[5]	1	2	3
[6]	2	3	-6
[7]	4	0	91
[8]	5	2	28

Transposing a Matrix

- 행렬 전치
 - 어떤 행렬의 행과 열을 바꾼 것

Transposing a Matrix

```
for j ← 1 to n do
  for i ← 1 to m do
    B(j, i) ← A(i, j)
  end
End
```

	row	col	val		row	col	val
a[0]	6	6	8	b[0]	6	6	8
[1]	0	0	15	[1]	0	0	15
[2]	0	3	22	[2]	0	4	91
[3]	0	5	-15	[3]	1	1	11
[4]	1	1	11	[4]	2	1	3
[5]	1	2	3	[5]	2	5	28
[6]	2	3	-6	[6]	3	0	22
[7]	4	0	91	[7]	3	2	-6
[8]	5	2	28	[8]	5	0	-15

좀 더 효율적인 방법은 없을까?

	row	col	val
a[0]	6	6	8
[1]	0	0	15
[2]	0	3	22
[3]	0	5	-15
[4]	1	1	11
[5]	1	2	3
[6]	2	3	-6
[7]	4	0	91
[8]	5	2	28

	row	col	val
b[0]	6	6	8
[1]	0	0	15
[2]	0	4	91
[3]	1	1	11
[4]	2	1	3
[5]	2	5	28
[6]	3	0	22
[7]	3	2	-6
[8]	5	0	-15

	0	1	2	3	4	5
startingPos						

Transposing a Matrix: program(1)

```
void transpose(term a[], term b[])
{
    /* b is set to the transpose of a */
    int n,i,j, currentb;
    n = a[0].value;          /* total number of elements */
    b[0].row = a[0].col; /* rows in b = columns in a */
    b[0].col = a[0].row; /* columns in b = rows in a */
    b[0].value = n;
    if (n > 0 ) { /* non zero matrix */
        currentb = 1;
        for (i = 0; i < a[0].col; i++)
            /* transpose by the columns in a */
            for (j = 1; j <= n; j++)
                /* find elements from the current column */
                if (a[j].col == i) {
                    /* element is in current column, add it to b */
                    b[currentb].row = a[j].col;
                    b[currentb].col = a[j].row;
                    b[currentb].value = a[j].value;
                    currentb++;
                }
    }
}
```

time complexity: $O(\text{columns} \cdot \text{elements})$

	row	col	val		row	col	val
a[0]	6	6	8	b[0]			
[1]	0	0	15	[1]			
[2]	0	3	22	[2]			
[3]	0	5	-15	[3]			
[4]	1	1	11	[4]			
[5]	1	2	3	[5]			
[6]	2	3	-6	[6]			
[7]	4	0	91	[7]			
[8]	5	2	28	[8]			

```

void transpose(term a[], term b[])
{
    /* b is set to the transpose of a */
    int n,i,j, currentb;
    n = a[0].value;          /* total number of elements */
    b[0].row = a[0].col; /* rows in b = columns in a */
    b[0].col = a[0].row; /* columns in b = rows in a */
    b[0].value = n;
}

```


i=0

i=1

i=2

i=3

i=4

i=5

	row	col	val
a[0]	6	6	8
[1]	0	0	15
[2]	0	3	22
[3]	0	5	-15
[4]	1	1	11
[5]	1	2	3
[6]	2	3	-6
[7]	4	0	91
[8]	5	2	28

	row	col	val
b[0]	6	6	8
[1]			
[2]			
[3]			
[4]			
[5]			
[6]			
[7]			
[8]			

```
if (n > 0) { /* non zero
currentb = 1;
for (i = 0; i < a[0].col; i++)
/* transpose by the columns in a */
for (j = 1; j <= n; j++)
/* find elements from the current column */
if (a[j].col == i) {
/* element is in current column, add it to b */
b[currentb].row = a[j].col;
b[currentb].col = a[j].row;
b[currentb].value = a[j].value;
currentb++;
}
}
```

Transposing a Matrix: program(2)

```
void fastTranspose(term a[], term b[])
{
    /* the transpose of a is placed in b */
    int rowTerms[MAX-COL], startingPos[MAX-COL];
    int i, j, numCols = a[0].col, numTerms = a[0].value;
    b[0].row = numCols; b[0].col = a[0].row;
    b[0].value = numTerms;
    if (numTerms > 0) { /* nonzero matrix */
        for (i = 0; i < numCols; i++)
            rowTerms[i] = 0;
        for (i = 1; i <= numTerms; i++)
            rowTerms[a[i].col]++;
        startingPos[0] = 1;
        for (i = 1; i < numCols; i++)
            startingPos[i] =
                startingPos[i-1] + rowTerms[i-1];
        for (i = 1; i <= numTerms; i++) {
            j = startingPos[a[i].col]++;
            b[j].row = a[i].col; b[j].col = a[i].row;
            b[j].value = a[i].value;
        }
    }
}
```

time complexity: **$O(\text{columns} + \text{elements})$**

	row	col	val		row	col	val
a[0]	6	6	8	b[0]	6	6	8
[1]	0	0	15	[1]			
[2]	0	3	22	[2]			
[3]	0	5	-15	[3]			
[4]	1	1	11	[4]			
[5]	1	2	3	[5]			
[6]	2	3	-6	[6]			
[7]	4	0	91	[7]			
[8]	5	2	28	[8]			

```

int rowTerms[MAX-COL], startingPos[MAX-COL];
int i,j, numCols = a[0].col, numTerms = a[0].value;
b[0].row = numCols;  b[0].col = a[0].row;
b[0].value = numTerms;
if (numTerms > 0) { /* nonzero matrix */

```

	0	1	2	3	4	5
rowTerms						

	0	1	2	3	4	5
startingPos						

	row	col	val
a[0]	6	6	8
[1]	0	0	15
[2]	0	3	22
[3]	0	5	-15
[4]	1	1	11
[5]	1	2	3
[6]	2	3	-6
[7]	4	0	91
[8]	5	2	28

numTerms=8

numCols=6

	row	col	val
b[0]	6	6	8
[1]	0	0	15
[2]	0	4	91
[3]	1	1	11
[4]	2	1	3
[5]	2	5	28
[6]	3	0	22
[7]	3	2	-6
[8]	5	0	-15

```

for (i = 0; i < numCols; i++)
    rowTerms[i] = 0;
for (i = 1; i <= numTerms; i++)
    rowTerms[a[i].col]++;

```

rowTerms

0	1	2	3	4	5

	row	col	val		row	col	val
a[0]	6	6	8	b[0]	6	6	8
[1]	0	0	15	[1]	0	0	15
[2]	0	3	22	[2]	0	4	91
[3]	0	5	-15	[3]	1	1	11
[4]	1	1	11	[4]	2	1	3
[5]	1	2	3	[5]	2	5	28
[6]	2	3	-6	[6]	3	0	22
[7]	4	0	91	[7]	3	2	-6
[8]	5	2	28	[8]	5	0	-15

	0	1	2	3	4	5
rowTerms	2	1	2	2	0	1

```

startingPos[0] = 1;
for (i = 1; i < numCols; i++)
    startingPos[i] =
        startingPos[i-1] + rowTerms[i-1];

```

	0	1	2	3	4	5
startingPos						

i=1
 i=2
 i=3
 i=4
 i=5
 i=6
 i=7
 i=8

	row	col	val
a[0]	6	6	8
[1]	0	0	15
[2]	0	3	22
[3]	0	5	-15
[4]	1	1	11
[5]	1	2	3
[6]	2	3	-6
[7]	4	0	91
[8]	5	2	28

	row	col	val
b[0]	6	6	8
[1]			
[2]			
[3]			
[4]			
[5]			
[6]			
[7]			
[8]			

numTerms=8

```

for (i = 1; i <= numTerms; i++) {
    j = startingPos[a[i].col]++;
    b[j].row = a[i].col;    b[j].col = a[i].row;
    b[j].value = a[i].value;
}
  
```

	0	1	2	3	4	5
rowTerms	2	1	2	2	0	1

	0	1	2	3	4	5
startingPos	1	3	4	6	8	8

	row	col	val		row	for (i = 1; i <= numTerms; i++) { j = startingPos[a[i].col]++; b[j].row = a[i].col; b[j].col = a[i].row; b[j].value = a[i].value; }		
a[0]	6	6	8	b[0]	6			
[1]	0	0	15	[1]	0			
[2]	0	3	22	[2]	0	4	91	
[3]	0	5	-15	[3]	1	1	11	
[4]	1	1	11	[4]	2	1	3	
[5]	1	2	3	[5]	2	5	28	
[6]	2	3	-6	[6]	3	0	22	
[7]	4	0	91	[7]	3	2	-6	
[8]	5	2	28	[8]	5	0	-15	

```

for (i = 1; i <= numTerms; i++)
    rowTerms[a[i].col]++;
startingPos[0] = 1;

```

numTerms=8
numCols=6

	0	1	2	3	4	5
rowTerms	2	1	2	2	0	1

```

startingPos[0] = 1;
for (i = 1; i < numCols; i++)
    startingPos[i] =
        startingPos[i-1] + rowTerms[i-1];

```

	0	1	2	3	4	5
startingPos	1	3	4	6	8	8

	row	col	val		row				
a[0]	6	6	8	b[0]	6				
[1]	0	0	15	[1]	0				
[2]	0	3	22	[2]	0	4	91		
[3]	0	5	-15	[3]	1	1	11		
[4]	1	1	11	[4]	2	1	3		
[5]	1	2	3	[5]	2	5	28		
[6]	2	3	-6	[6]	3	0	22		
[7]	4	0	91	[7]	3	2	-6		
[8]	5	2	28	[8]	5	0	-15		

```
for (i = 1; i <= numTerms; i++)
    rowTerms[a[i].col]++;
startingPos[0] = 1;
```

numTerms=8
numCols=6

rowTerms

0	1	2	3	4	5

```
startingPos[0] = 1;
for (i = 1; i < numCols; i++)
    startingPos[i] =
        startingPos[i-1] + rowTerms[i-1];
```

startingPos

0	1	2	3	4	5

	row	col	val
b[0]			
b[1]			
b[2]			
b[3]			
b[4]			
b[5]			
b[6]			
b[7]			
b[8]			