

# Yocto Project and OpenEmbedded training

On-line seminar

Title	Yocto Project and OpenEmbedded development training
Overview	Understanding the Yocto Project Using it to build a root filesystem and run it on your target Writing and extending recipes Creating layers Integrating your board in a BSP Creating custom images Application development with the Yocto Project SDK
Materials	Check that the course contents correspond to your needs: https://bootlin.com/doc/training/yocto.
Duration	<b>Four</b> half days - 16 hours (4 hours per half day). 80% of lectures, 20% of practical demos.
Trainer	One of the engineers listed on 80% of lectures, 20% of practical demos.
Language	Oral lectures: English Materials: English.
Audience	Companies and engineers interested in using the Yocto Project to build their embedded Linux system.
Prerequisites	Familiarity with embedded Linux as covered in our embedded Linux training (https://bootlin.com/training/embedded-linux/)  Familiarity with UNIX or GNU/Linux commands  People lacking experience on this topic may get trained by themselves, for example with our freely available on-line slides: https://bootlin.com/blog/command-line/
Required equipment	Computer with the operating system of your choice, with the Google Chrome or Chromium browser for videoconferencing.

# Computer with the operating system of your choice, with the Google Chrome or Chromium browser for videoconferencing. Webcam and microphone (preferably from an audio headset) High speed access to the Internet Materials Electronic copies of presentations, demo instructions and data.



#### Hardware

STMicroelectronics STM32MP157A-DK1 Discovery board

- STM32MP157A (dual Cortex-A7) CPU from STMicroelectronics
- USB powered
- 512 MB DDR3L RAM
- Gigabit Ethernet port
- 4 USB 2.0 host ports
- 1 USB-C OTG port
- 1 Micro SD slot
- On-board ST-LINK/V2-1 debugger
- Arduino Uno v3-compatible headers
- · Audio codec
- Misc: buttons, LEDs



# Half day 1

#### Lecture - Introduction to embedded Linux build systems

- Overview of an embedded Linux system architecture
- Methods to build a root filesystem image
- · Usefulness of build systems

# Lecture - Overview of the Yocto Project and the Poky reference system

#### **Demo - First Yocto Project build**

- Organization of the project source tree
- Building a root filesystem image using the Yocto Project
- Downloading the Poky reference build system
- Building a system image



#### **Lecture - Using Yocto Project - basics**

- Organization of the build output
- Flashing and installing the system image

#### **Demo - Flashing and booting**

• Flashing and booting the image on the board

### Half day 2

#### Lecture - Using Yocto Project - advanced usage Demo - Using NFS and configuring the build

- Configuring the build system
- Customizing the package selection
- Configuring the board to boot over NFS
- Learn how to use the PREFERRED\_ PROVIDER mechanism

#### **Lecture - Writing recipes - basics**

- Writing a minimal recipe
- Adding dependencies
- Development workflow with bitbake

#### Demo - Adding an application to the build

- Writing a recipe for *nInvaders*
- Adding *nInvaders* to the final image



#### **Lecture - Writing recipes - advanced features**

- Extending and overriding recipes
- Adding steps to the build process
- Learn about classes
- Analysis of examples
- Logging
- Debugging dependencies

## Half day 3

#### **Demo - Learning how to configure packages**

- Extending a recipe to add configuration files
- Using ROOTFS\_POSTPROCESS\_COMMAND to modify the final rootfs
- Studying package dependencies

#### **Lecture - Layers**

- What layers are
- Where to find layers
- Creating a layer

#### **Demo - Writing a layer**

- Learn how to write a layer
- Add the layer to the build
- Move *nInvaders* to the new layer

#### **Lecture - Writing a BSP**

- · Extending an existing BSP
- Adding a new machine
- Bootloaders
- Linux and the linux-yocto recipe
- · Adding a custom image type

#### **Demo - Implementing the kernel changes**

- Extend the kernel recipe to add the nunchuk driver
- Configure the kernel to compile the nunchuk driver
- Play nInvaders



## Half day 4

#### **Lecture - Creating a custom image**

**Demo - Creating a custom image** 

- Writing an image recipe
- Adding users/groups
- Adding custom configuration
- Writing and using package groups recipes
- Writing a custom image recipe
- Adding nInvaders to the custom image

#### **Lecture - Creating and using an SDK**

- Understanding the purpose of an SDK for the application developer
- · Building an SDK for the custom image

#### **Demo - Experimenting with the SDK**

- Building an SDK
- Using the Yocto Project SDK

#### **Questions and Answers**

- Questions and answers with the audience about the course topics
- Extra presentations if time is left, according what most participants are interested in.