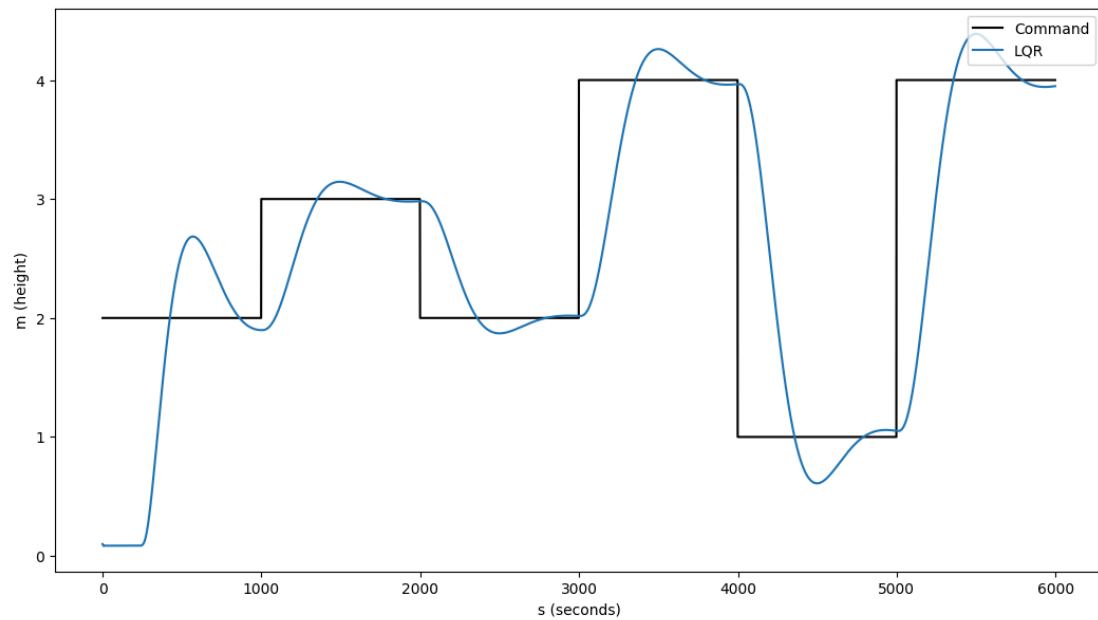


Name: Barathkrishna Satheeshkumar
Andrew ID: bsathees

Exercise 1

Plot:



Evaluation:

=====YOUR RESULT=====

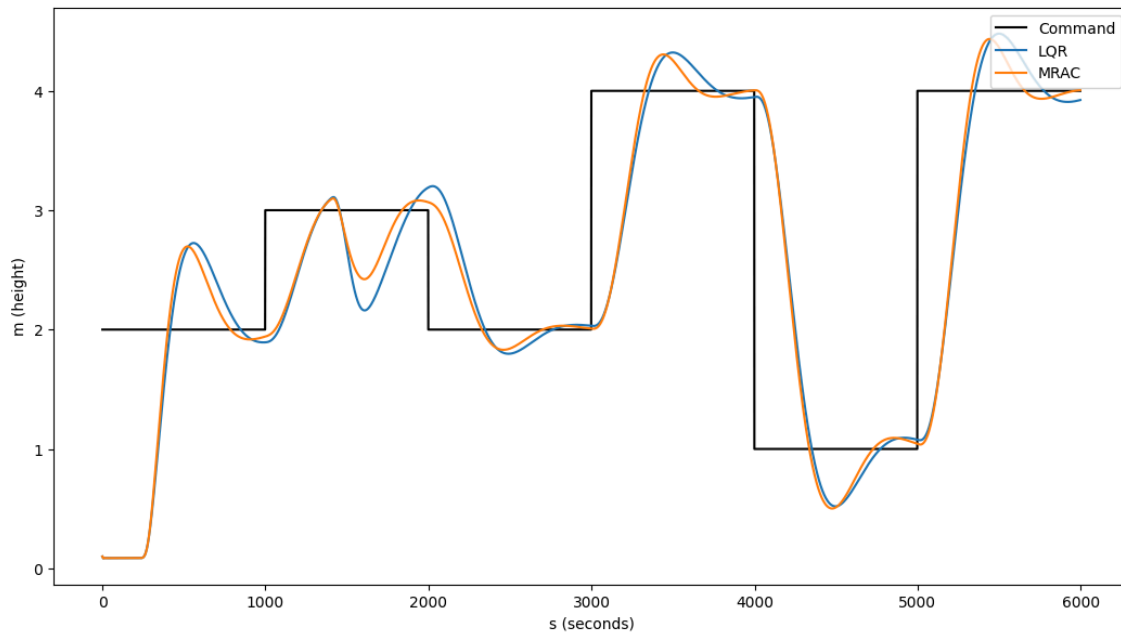
ERROR: 0.204

SCORE: 50.000

Exercise 2

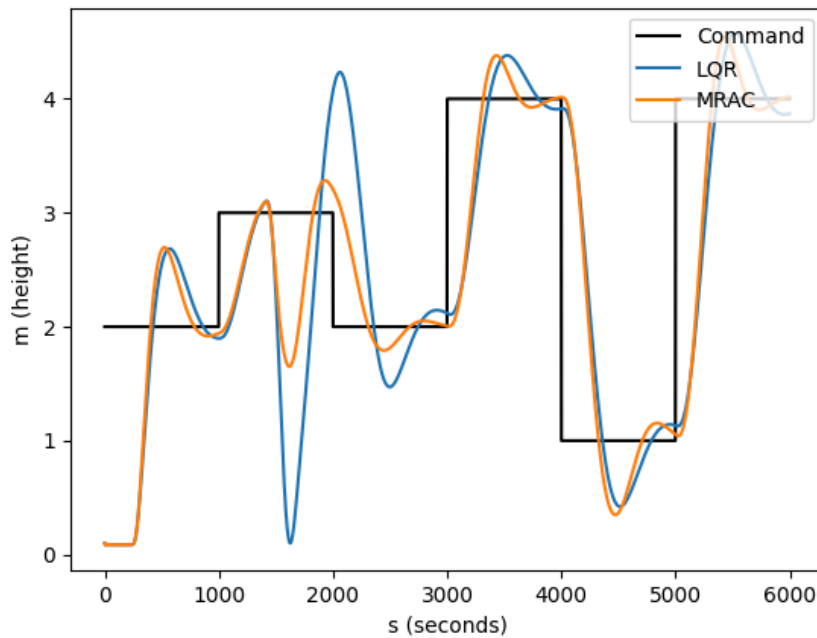
Plot:

50% loss in thrust



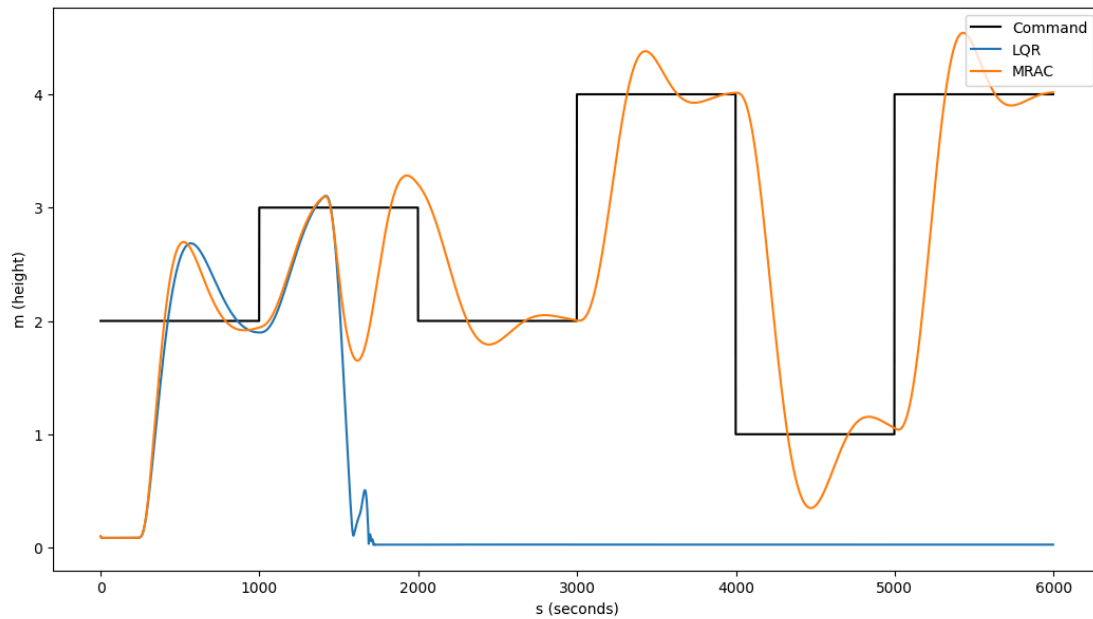
Point of failure of LQR:

67% loss in thrust:



At 67% loss in thrust, the drone is just able to stay in the air with the LQR controller.

At 68% loss in thrust:



At 68% loss in thrust, the LQR controller fails and the drone hits the ground. However, the MRAC controller is still able to keep the drone stable and track the reference trajectory.