

In [7]: *## ChatGPT was used to understand the working of SymPy, its syntax and helper funct*

```
import numpy as np
from scipy import linalg
import sympy as sp
import matplotlib.pyplot as plt

## for continuous time

# using the sympy library to define a continuous time state space system
# variables
t = sp.symbols('t')
x1 = sp.Function('x1')(t)
x2 = sp.Function('x2')(t)
y = sp.Function('y')(t)

# matrices
A = sp.Matrix([[0, 1], [-2, -2]])
B = sp.Matrix([[1], [1]])
C = sp.Matrix([2, 3]).reshape(1, 2)
D = sp.Matrix([0])
x = sp.Matrix([[x1], [x2]])
u = sp.Matrix([1])

# dynamics and observation
dxdt = A * x + B * u
y = C * x + D * u

# solving analytically
solns = sp.dsolve([sp.Eq(x1.diff(t), dxdt[0]), sp.Eq(x2.diff(t), dxdt[1])], ics = {

# substituting the solution of x into y's equation
y_t = y.subs({x1: solns[0].rhs, x2: solns[1].rhs})
y_t5 = y_t.subs(t, 5)
```

In [8]:

```
print('y(t) = \n')
sp.pprint(y_t)
print('\ny(5) = \n')
sp.pprint(y_t5)

# converting to numerical solution to plot
y_numeric = sp.lambdify(t, y_t[0], modules='numpy')

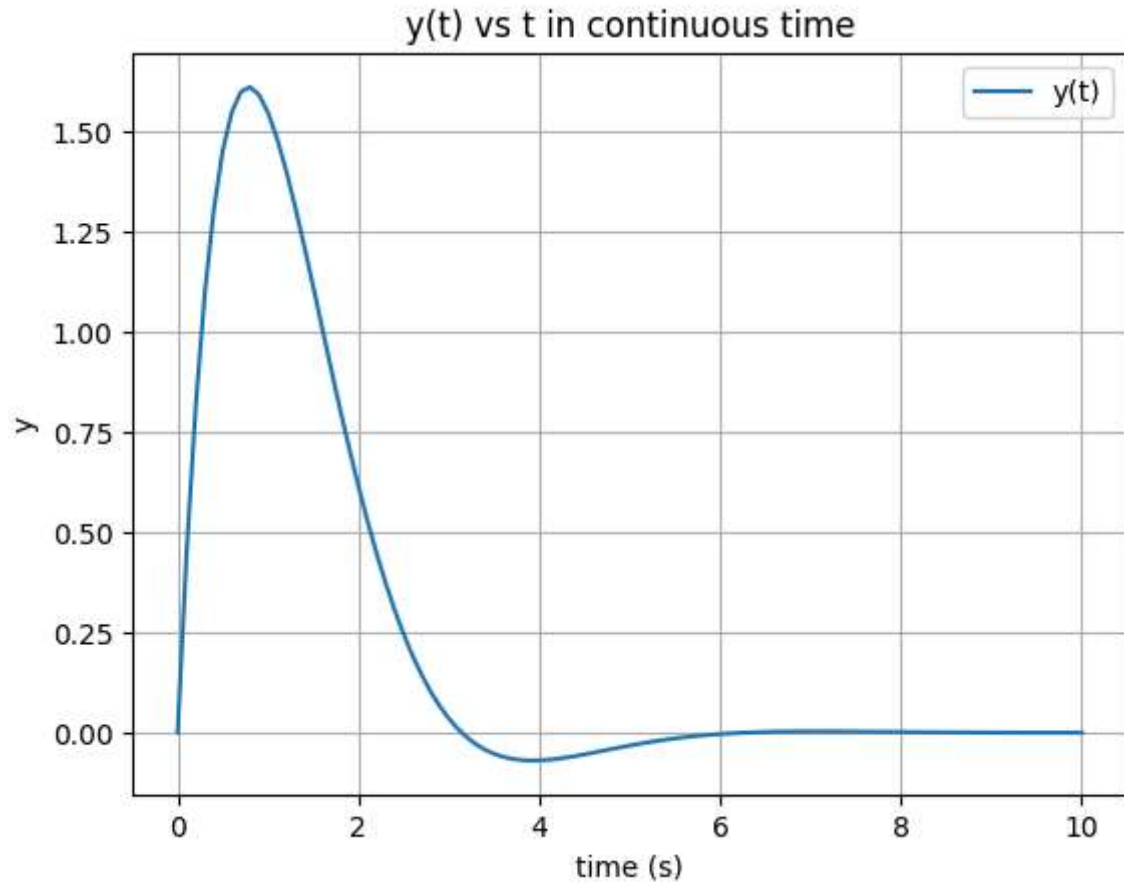
# generating time array for plotting
time = np.linspace(0, 10, 101)
y_values = y_numeric(time)
```

$y(t) =$

$$\begin{bmatrix} -t \\ 5 \cdot e^{-t} \cdot \sin(t) \end{bmatrix}$$

$y(5) =$

$$\begin{bmatrix} -5 \\ 5 \cdot e^{-5} \cdot \sin(5) \end{bmatrix}$$



In [34]: *## discrete time*

```
# deriving the matrices for discrete time from the continuous time matrices
A_d = np.array([[0, 1],
                [-2, -2]])
B_d = np.array([[1],
                [1]])
C_d = np.array([[2, 3]])
D_d = np.array([[0]])

xd = np.zeros([2, 1])
xd_new = np.zeros_like(x)
yd = np.zeros([10, 1])

T = 1 # sample time
ud = np.ones([1, 1]) # constant input for all k >= 0

# defining matrices for discrete time system
Ad = linalg.expm(A_d * T)
```

```

Bd = np.linalg.inv(A_d) @ (Ad - np.identity(2)) @ B_d
Cd = C_d
Dd = D_d

#  $x[k + 1] = Ad * x[k] + Bd * u[k]$ ;  $y[k] = Cd * x[k] + Dd * u[k]$ 
# To get  $y[5]$ , let's iterate the system 4 times

for i in range(10):
    xd_new = Ad @ xd + Bd * ud
    yd[i] = Cd @ xd + Dd @ u
    xd = xd_new

```

```

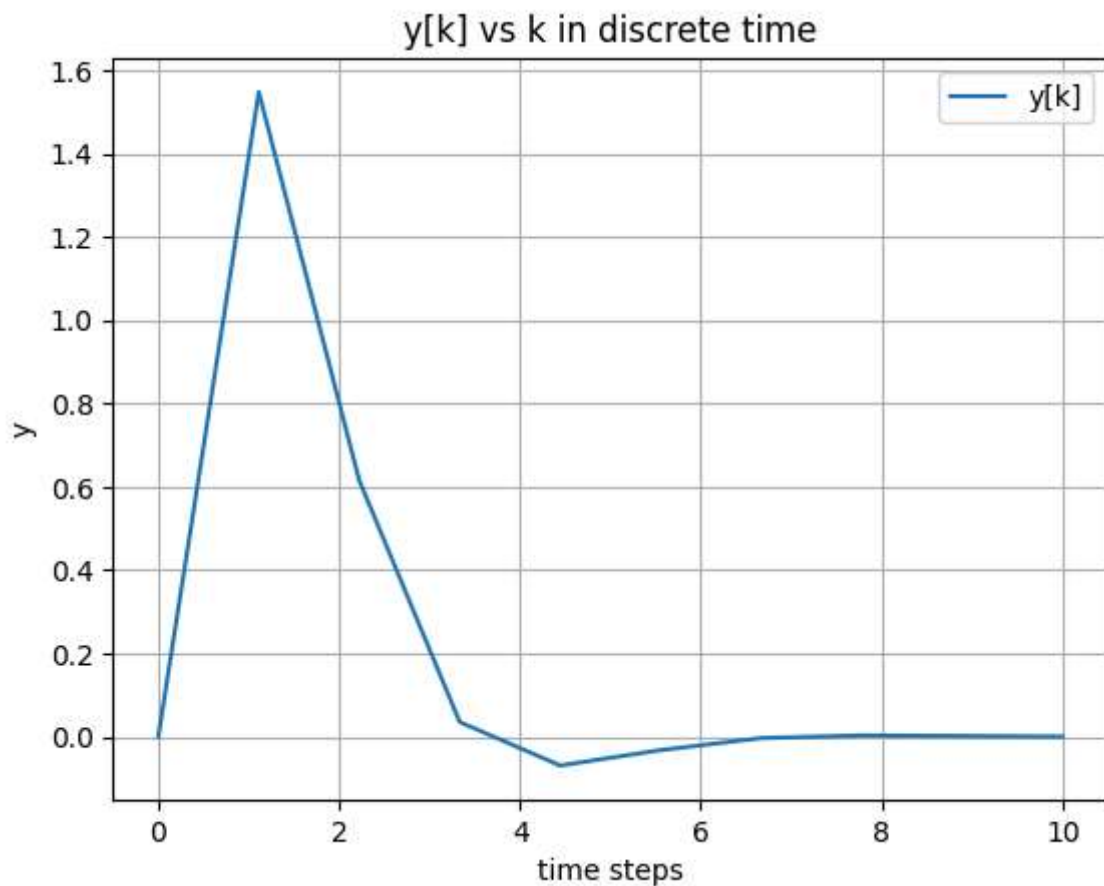
In [39]: print('y(5) =', yd[5])

# generating time array for plotting
time_d = np.linspace(0, 10, 10)

# plotting
plt.plot(time_d, yd, label='y[k]')
plt.xlabel('time steps')
plt.ylabel('y')
plt.title('y[k] vs k in discrete time')
plt.grid()
plt.legend()
plt.show()

```

y(5) = [-0.0323059]



```
In [40]: # plotting in same figure
plt.plot(time, y_values, label = 'continuous')
plt.plot(time_d, yd, label = 'discrete')
plt.xlabel('time/steps')
plt.ylabel('y')
plt.title('y vs t')
plt.grid()
plt.legend()
plt.show()
```

