

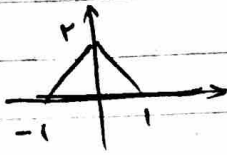
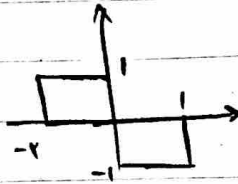
Subject:

Year:

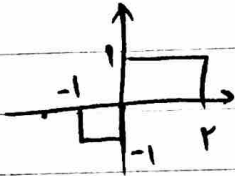
Month:

Date:

NOTEBOOK

 $x(t)$  $h(t) =$ 

(Sol 1)

 $h(-\tau)$ 

$$t \leq -r \rightarrow y(t) = 0$$

$$-r < t < -r \rightarrow h(t - \tau)$$



$$y(t) = \int_{-1}^{t+r} r x + r = x + r x \Big|_{-1}^{t+r} = t^2 + 4t + 4 \quad \text{Max}\{y\} = 4$$

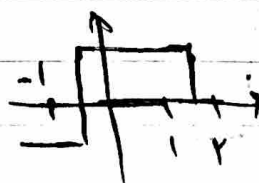
$$-r < t < -1 \rightarrow h(t - \tau)$$



$$y(t) = \int_{-1}^0 r x + r + \int_0^{t+r} -r x + r = x + r x \Big|_{-1}^0 + -x + r x \Big|_0^{t+r} = -t^2 - r t - r$$

$$\text{Max}\{y\} = -r$$

$$-1 < t < 0 \rightarrow h(t - \tau)$$



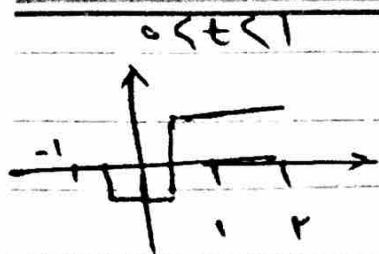
$$y(t) = \int_{-1}^{-1+t} -r x + r + \int_{-1+t}^0 r x + r + \int_0^{t+r} -r x + r$$

$$= -x + r x \Big|_{-1}^{-1+t} + x + r x \Big|_{-1+t}^0 + -x + r x \Big|_0^{t+r}$$

$$\text{Max}\{y\} = -1$$

$$\text{Arang} = (t-1)^2 - r(t-1) - (t-1)^2 + r(t-1) - 1 + (t+r)^2 + r(t+r) - r t^2 + r t - r = 1 - t^2 - 2t - 2 + r t + r = -t^2 + t - r$$

$$\text{Max}\{y\} = -r$$



$$y(t) = \int_{-1+t}^0 -(r_2 + r) + \int_0^t (r_2 - r) + \int_t^1 (-r_2 + r)$$

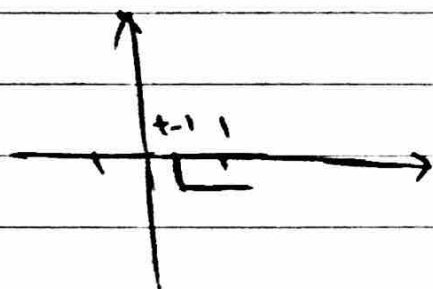
$$= -\lambda^r - r_2 \Big|_{t-1}^0 + \lambda^r - r_2 \Big|_0^t + -\lambda^r + r_2 \Big|_t^1$$

$$= (t-1)^r + r(t-1) + t^r - r t + t^r - r t + 1$$

$$= t^r - r t + 1 - r t - r + t^r - r t + t^r - r t + 1$$

$$= 3t^r - \frac{3}{2}t \quad \boxed{\text{Max}(y) = 0 \rightarrow t = 0}$$

$1 < t < r$



$$y(t) = \int_{t-1}^1 (r_2 - r) = \lambda^r - r_2 \Big|_{t-1}^1$$

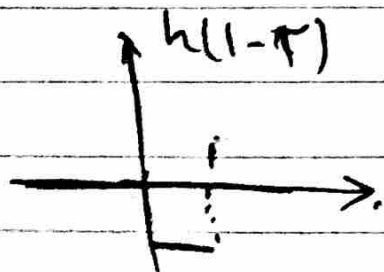
$$= -1 - (t-1) + r(t-1)$$

$$= -1 - t^r + r t - 1 + r t - r = -t^r + 2t - 2$$

$$\boxed{\text{Max}(y) = 0 \rightarrow t = r}$$

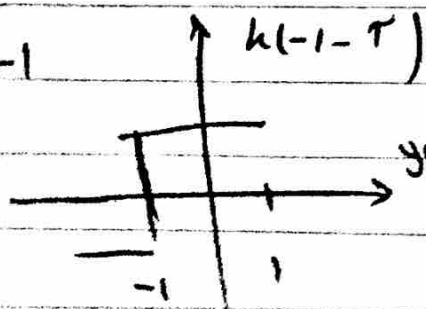
$$t > r \rightarrow \boxed{y(t) = 0}$$

$t = 1$



$$y(1) = \int_0^1 (r_2 + r) = \lambda^r - r_2 \Big|_0^1 = -1$$

$t = -1$



$$y(t) = \int_{-1}^0 (r_2 + r) + \int_0^1 (-r_2 + r)$$

$$= \lambda^r + r_2 \Big|_{-1}^0 + -\lambda^r + r_2 \Big|_0^1 = r$$

Subject:

Year

Month

Date

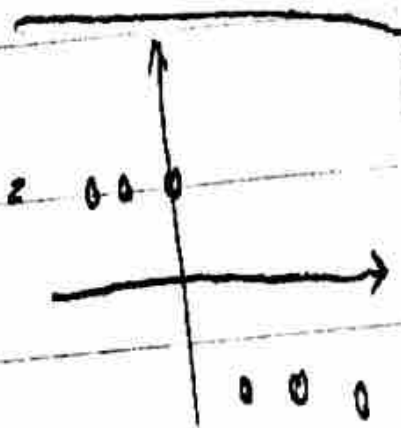
NOTE BOOK

$$x[n] = u[n] \rightarrow y[n] \checkmark$$

(10)

$$\text{if: } x[n] = \delta[n] = u[n] - u[n-1] = x[n] - x[n-1]$$

$$\Rightarrow y_1[n] = y[n] - y[n-1] \Rightarrow y_1[n] = 0$$



$$z+1 = 1 + \cos(\pi T) + j \sin(\pi T) + \pi_j$$

(in ①)

$$T=1$$

$$T=\frac{1}{2}$$

$$\rightarrow T=1 \quad \omega_s = \pi$$

$$e^{-j\omega_s n} + \frac{1}{r} e^{j\omega_s n} + \frac{1}{r} e^{-j\omega_s n} + \frac{1}{rs} e^{j\omega_s n + \pi_j} - \frac{1}{rs} e^{-j\omega_s n + \pi_j}$$

$$\rightarrow a_0 = 1 \quad a_3 = \frac{e^{j\omega_s \pi_j}}{rs}$$

$$a_1 = \frac{1}{r}$$

$$a_2 = -\frac{e^{-j\omega_s \pi_j}}{rs}$$

$$a_{-1} = \frac{1}{r}$$

$$X[k] = \sum_{n=-\infty}^{\infty} a_n e^{j\omega_s k n} \rightarrow x_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{j\omega_s k n} \quad (1)$$

$$a_k = \frac{1}{r} \sum_{n=-\infty}^{\infty} x[n] e^{j\omega_s k n} = \frac{1}{r} \left(\frac{1}{r} e^{j\omega_s k \pi_j} + 1 + \frac{1}{r} + \frac{1}{r} e^{-j\omega_s k \pi_j} \right)$$

$$= \frac{1}{r} + \frac{1}{r} \left(\frac{e^{j\omega_s k \pi_j} + e^{-j\omega_s k \pi_j}}{r} \right) = \frac{1}{r} + \frac{1}{r} \cos\left(\frac{\pi_j k}{r}\right)$$

$$a_k = \frac{1}{\Delta} \sum_{n=-\infty}^{\infty} x[n] e^{j\omega_s k n} = \frac{1}{\Delta} \left(\frac{1}{r} e^{-j\omega_s k \frac{\Delta}{2}} + \frac{1}{r} e^{j\omega_s k \frac{\Delta}{2}} + 1 \right) \quad (2)$$

$$\star \star = \frac{1}{\Delta} + \frac{1}{\Delta} \cos\left(\frac{\pi_j k}{\Delta}\right)$$

(a) (u)

$$a_k = \frac{1}{T} \int_{\langle T \rangle} x(t) e^{-j k \omega_0 t}$$

$$\omega_0 = \pi/\tau$$

$$a_k = \frac{1}{4} \left(\int_{-\tau}^{\tau} e^{-j k (\pi/\tau) t} dt + \int_{-1}^1 e^{-j k \pi/\tau t} \right)$$

$$= \frac{1}{4} \left(\left. \frac{-1}{j k \pi/\tau} e^{-j k \pi/\tau t} \right|_{-\tau}^{\tau} + \left. \frac{1}{j k \pi/\tau} e^{-j k \pi/\tau t} \right|_{-1}^1 \right)$$

$$= \frac{1}{4} \left(\frac{-\tau}{j k \pi} (e^{-j k \pi/\tau \tau} - e^{j k \pi/\tau \tau}) + \frac{\tau}{j k \pi} (e^{-j k \pi/\tau} - e^{j k \pi/\tau}) \right)$$

$$= \frac{-1}{\tau j k \pi} \left(e^{-j k \pi/\tau \tau} - e^{j k \pi/\tau \tau} + e^{-j k \pi/\tau} - e^{j k \pi/\tau} \right)$$

$$= \frac{-1}{k \pi} \left(\sin(\tau/\tau k) - \sin(\pi/\tau k) \right)$$