NAME

antBASIC - A modern version of Tiny BASIC with GPIO functions

SYNTAX

```
antbasic [file [arguments]]
```

ARGUMENTS

```
number-to-A [number-to-B [string-to-@]]
example:
antbasic
    activate interactive session
antbasic test.bas
    execute test.bas and return to the shell
antbasic test.bas 10
    invoke program and pass number 10 to variable A
antbasic test.bas 10 20
    invoke program and pass numbers 10 and 20 to variables A and B
```

invoke and pass numbers to variables and string to string array @

RETURNS

antBASIC returns an 8bit status code to the shell (default value is zero). You can use the **END** statement to pass a non-zero value to the shell.

example: END 123 returns 123 as a status code to the shell

VERSION

This man page documents antBASIC version 1.0.1.

antbasic test.bas 10 20 'Hello, world!'

DESCRIPTION

antBASIC is a product of the **BMH** (**Bare Metal Hacking**) project. It is a modernized version of **Tiny BASIC**, with the addition of I/O manipulation instructions prepared for the **Raspberry Pi**. Although the language specification is minimal, beginners can learn the basics of programming, and a wide range of I/O controls through antBASIC.

PROGRAM

A program consists of several lines, and each line always starts with a line number (1-9999). The maximum program size is **2,000 lines** and **30,000 bytes** (you can check the program size with the FREE command). Users can enter sentences interactively through the **GNU Readline** input editor. Usually, there will be ten intervals between line numbers so that you can make additions easily later. When there is no more space between lines, you can create a new gap with the RENUM command. Multiple statements can be written in a single line, separated by a *colon*.

example:

```
10 FOR I=1 TO 10
20 PRINT "Hello, ";:PRINT "world! ";
30 NEXT
40 END
```

NUMBERS

Signed 16bit integer (range from -32768 to 32767). Decimal and hexadecimal (0x prefix is needed) numbers are distinguished internally.

```
example: 1234, -1234, 0xABCD, 0xEF
```

STRINGS

A string is defined as **Unicode** characters (encoded by **UTF-8**) surrounded by double quotations. Escaped special characters are as follows.

```
Alarm (BELL) \a BS \b TAB \t
```

LF \n
CR \r
ESCAPE \e
backslash \\

ASCII code \x## (## is a two-digit hexadecimal number)

Special array @ holds a string. It must be terminated with NULL (0).

example:

```
@="hello!":@[0]=@[0]-0x20:print @ -> Hello!  
@[0]=33:@[1]=7:@[2]=0:print @ -> ! with alarm
```

VARIABLES

Vaiables A to Z hold integer.

example: A=123:B=A+0x1234

ARRAYS

Arrays A[] to Z[] hold integers (index starts from ZERO). Two-dimensional array form is X[column,row].

example:

```
DIM A[1],B[2,3]:A[0]=1:B[0,0]=0,1,2,3,4,5
A[0] \rightarrow 1,B[0,2] \rightarrow 2,B[1,0] \rightarrow 3,B[1,2] \rightarrow 5
```

OPERATORS

Operator precedence: Unary > Mul/Div/Mod > Add/Sub > Condition > Bitwise

Unary -xxx, +xxx
Mul/Div/Mod *, /, %
Add/Sub +, -

Condition ==, !=, <, <=, >, >=

Bitwise &, |

STATEMENTS

CLS Clear screen

DIM Define array *size* (not the maximum index number): DIM[colum,row].

NOTE: There is an array size limitation ($column*row \le 512$).

END Terminate program. If a number is given, antBASIC returns the value to the shell.

FOR/NEXT Iterate statements between FOR and NEXT.

example: S=0:FOR A=1 TO 10:S=S+A:NEXT

NOTE: increment step is fixed to ONE

GOTO Jump to specified line number.

example: GOTO 100, GOTO X

GOSUB/RETURN

Call subroutine / return to caller.

example: GOSUB 200, GOSUB Y

IN Read bit status. Argument is *BMH-style GPIO number (1-14)*.

returns: 0 or 1

example: IN (B) $\rightarrow 0|1$

INPUT Input data from user and stores it in a variable or string array @.

example: in the case of number) INPUT A, string) INPUT @

OUT Set bit output as zero or one. First argument is a BMH-style GPIO number (1-14)

and second argument is a bit Level (0 GND|1 Vdd).

example: OUT (B, L)

OUTHZ Set bit output as zero or high-impedance (HiZ). First argument is a BMH-style

number (1-14), second argument is a bit Level (0 GND|1 Vdd), and third argument

is a mode of internal Pull-up resistor (0 None 1 Pull-up).

example: OUTHZ (B, L, P)

PRINT Print data.

integer: immediate value, variable, array

hexadecimal format (2 or 4-digit): HEX2(number), HEX4(number)

string: @

separator: semicolon = no spacing, comma = do tabulation

example: PRINT "H"; "I"; "!" -> HI!

REM Insert a remark. Comment must be added as a STRING.

example: REM, REM "This is a comment string"

RND Returns random number (range from 0 to 32767).

example: RND ()

MSLEEP Suspend execution for *milli*-seconds.

example: MSLEEP (1000) -> 1sec wait

USLEEP Suspend execution for *micro*-seconds.

example: USLEEP (1000) -> 1msec wait

DIRECT COMMANDS

CLEAR Clear containers (variables and arrays).

CLS Clear screen.

DELETE Delete program lines.

example: single line) DELETE 100, multiple lines) DELETE 210, 290

DUMP Dump containers.

example: DUMP (all), DUMP V (variables), DUMP A (arrays), DUMP S (string),

DUMP L (program lines), DUMP B (bytecodes)

END Quit antBASIC.

FILES List files.

example: current working directory) FILES, specified directory) FILES "path-

name"

FREE Display memory usage.

HELP Display help information.

LIST List all or part of program.

example: all) LIST, single line) LIST 100, multiple lines) LIST 210, 330

LOAD Load a source file into memory.

example: LOAD "example/hello.bas"

MERGE Merge an additional file into memory.

example: MERGE "mylib/addon.bas"

NEW Clear program.

RENUM Renumber program lines.

example: default [start 100, step 10]) RENUM, define start) RENUM 1000, specify

start and step) RENUM 5000,5

RUN Start-up program. *CONTROL-C* aborts the program.

SAVE Save program as a text file.

example: SAVE "myprogram.bas"

ENVIRONMENT VARIABLE

ANT MICROWAIT

There are two types of wait functions, **MSLEEP()** and **USLEEP()**, in antBASIC. The former is a delay in *seconds*, while the latter is in *micro-seconds*. By default, both functions use the *usleep system call* internally, but a delay in the order of micro-seconds can lead to time variability.

If more precise control in micro-seconds is required, set the **ANT_MICROWAIT** environment variable. Then the USLEEP() function does not use the usleep system call but uses a simple loop for the number of times specified by ANT_MICROWAIT.

antcalib is a utility for estimating the number of loops required for a microsecond delay. The first argument specifies the number of loops, and the second argument specifies the number of loop calls.

```
$ ./antcalib 220 10000000
Loopcount = 220
Number of loops = 10000000

Elapsed time --> 10 sec 9327 usec
Mean time --> 1.000933 usec/loop
```

On a *Raspberry pi 400*, the loop count is around 220. Once the loop count is determined, add the export command to the ~/.bashrc.

```
export ANT_MICROWAIT=220
```

READLINE LIBRARY

Default Makefile will build an antBASIC binary linked with the **GNU Readline library**. This binary allows the user to do editing lines before sending them to antBASIC.

HOME PAGE & SOURCE REPOSITORY

```
https://baremetalhack.com
https://github.com/baremetalhack/antBASIC
```

FEEDBACKS

I'm looking forward to your comments and improvement reports. antbasic@baremetalhack.com

AUTHOR

Doctor BMH Wataru Nishida, *M.D.*, *Ph.D.*

PUBLICATION DATE

April 30rd, 2022 Published from *Japan*

COPYRIGHT

Public domain, CC0, Zero is Infinite