



A PSF photometry tool for NASA's Kepler, K2, and TESS missions

José Vinícius de Miranda Cardoso^{1,2,4}, Geert Barentsen^{1,2}, Ben Montet^{3,*},
Ann Marie Cody^{1,2}, Christina Hedges^{1,2} and Michael Gully-Santiago^{1,2}

¹NASA Ames Research Center, Mountain View, CA, USA

²Bay Area Environmental Research Institute, Petaluma, CA, USA

³Department of Astrophysics, University of Chicago, IL, USA

⁴Federal University of Campina Grande, Campina Grande, Brazil

*NASA Sagan Fellow

Introduction

- NASA's Kepler and K2 missions have been delivering high-precision time series data for a wide range of stellar types
- However, both the official and community developed pipelines [1–3] tend to focus on studying isolated stars using simple aperture photometry, hence performing sub-optimally in crowded fields
- Although Point Spread Function (PSF) photometry methods are well known [4, 5], as of now, there exist no open source tool that takes into account the caveats inherent in Kepler and K2 data
- To address this issue, we present an open source PSF photometry toolkit for Kepler and K2 and extensible to TESS, as part of the K2 Guest Observer Office data analysis tool, PyKE

Methods

Fitting multiple PSFs jointly

Consider an experiment that outputs an image with m (m known) stellar objects as a collection of n independent *non-identically* distributed random variables $\mathbf{Y} \triangleq \{Y_i\}_{i=1}^n$ (pixels), each of which has expected value $\mathbb{E}[Y_i] = \sum_{j=1}^m \lambda_i(\boldsymbol{\theta}_j)$, where λ_i is the PSF model at the i -th pixel, $\boldsymbol{\theta}_j$ is a random vector that encodes the information about flux and center position of the j -th star. Hence, the likelihood function can be written as

$$P(\mathbf{Y} = \mathbf{y} | \{\boldsymbol{\theta}_j\}_{j=1}^m = \{\boldsymbol{\theta}_j\}_{j=1}^m) = \exp\left(-\sum_{i=1}^n \sum_{j=1}^m \lambda_i(\boldsymbol{\theta}_j)\right) \prod_{i=1}^n \frac{\left(\sum_{j=1}^m \lambda_i(\boldsymbol{\theta}_j)\right)^{y_i}}{y_i!}. \quad (1)$$

Perhaps of more practical interest is the log likelihood function

$$\log P(\mathbf{Y} = \mathbf{y} | \{\boldsymbol{\theta}_j\}_{j=1}^m = \{\boldsymbol{\theta}_j\}_{j=1}^m) = \sum_{i=1}^n \left(-\sum_{j=1}^m \lambda_i(\boldsymbol{\theta}_j) + y_i \log \sum_{j=1}^m \lambda_i(\boldsymbol{\theta}_j)\right). \quad (2)$$

Hence, the Maximum Likelihood Estimator (MLE) can be formulated as the following optimization problem

$$\boldsymbol{\theta}^*(\mathbf{y}) = \arg \min_{\boldsymbol{\theta} \in \Lambda} \sum_{i=1}^n \left(\sum_{j=1}^m \lambda_i(\boldsymbol{\theta}_j) - y_i \log \sum_{j=1}^m \lambda_i(\boldsymbol{\theta}_j)\right). \quad (3)$$

Furthermore, prior probability densities (often taken to be uniform on Λ) on the stars positions, fluxes, and sky background, are used.

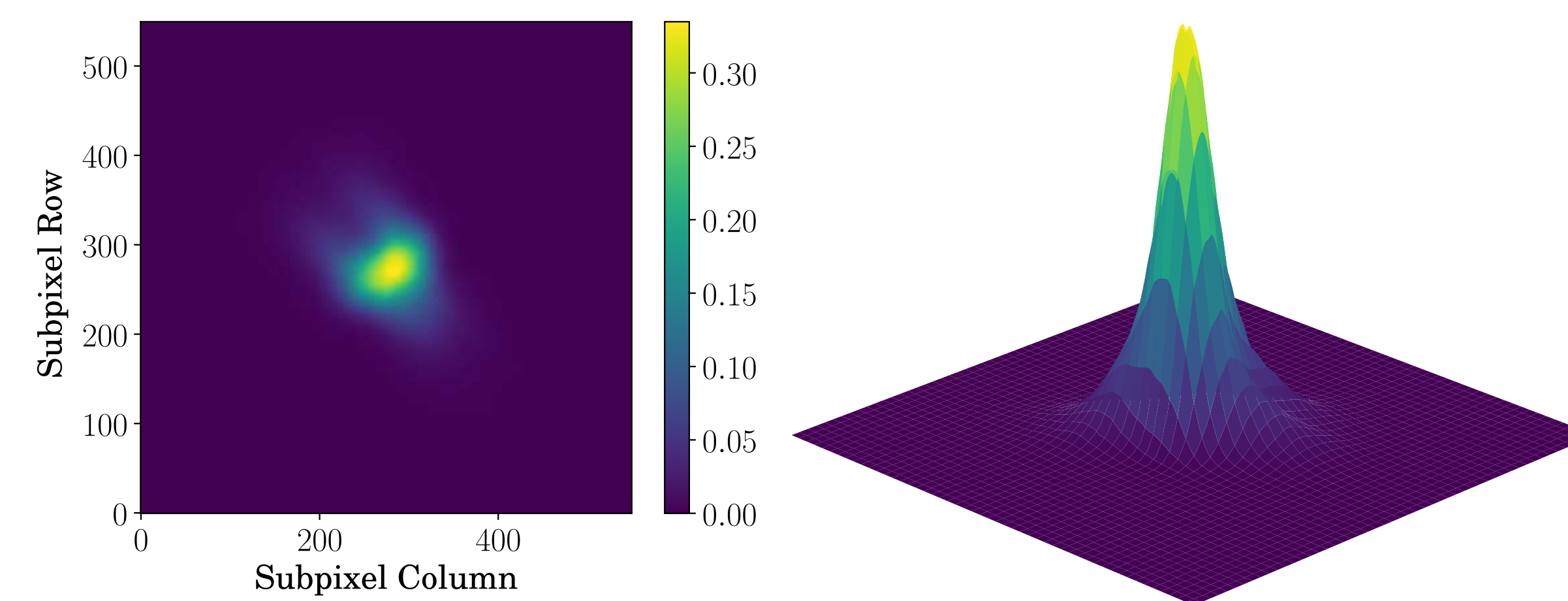
Estimating uncertainties using the Cramér-Rao Lower Bound

Uncertainties on the fitted values are computed using the Cramér-Rao Lower Bound. Mathematically,

$$\text{cov}(\boldsymbol{\theta}^*(\mathbf{Y})) \leq \left(\mathbb{E}_{\boldsymbol{\theta}} \left[\nabla_{\boldsymbol{\theta}} \log p(\mathbf{Y}|\boldsymbol{\theta}) [\nabla_{\boldsymbol{\theta}} \log p(\mathbf{Y}|\boldsymbol{\theta})^T]\right]\right)^{-1} \Big|_{\boldsymbol{\theta}=\boldsymbol{\theta}^*(\mathbf{y})} \quad (4)$$

The Kepler Pixel Response Function Model

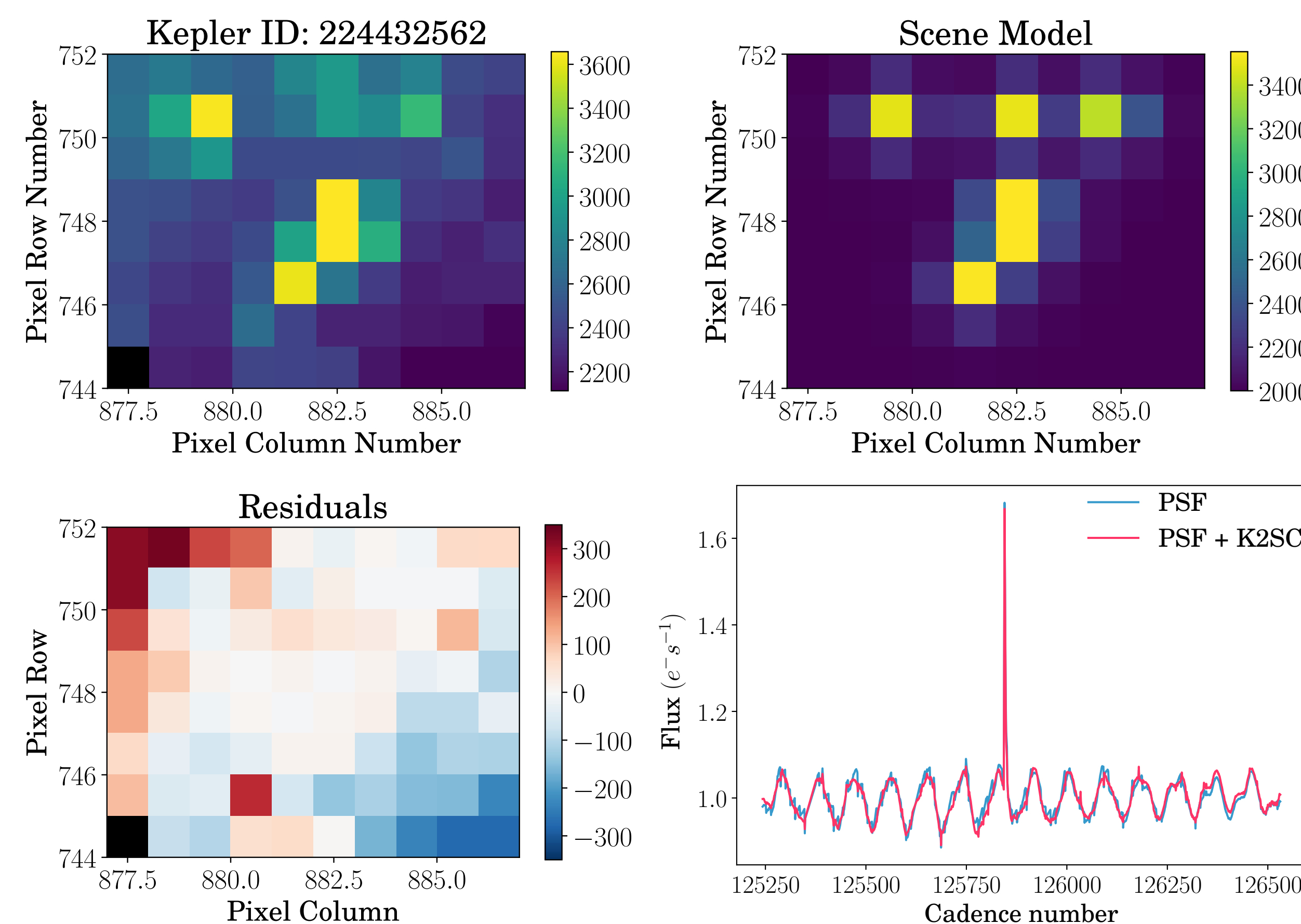
- Kepler's pixel response function (PRF) has been shown to be nonsymmetric and spatially variable across the detector [6]
- The PRF model used in PyKE is constructed following a similar procedure as stated by Bryson *et al.* [6]



An object of the PSF model can be instantiated as follows

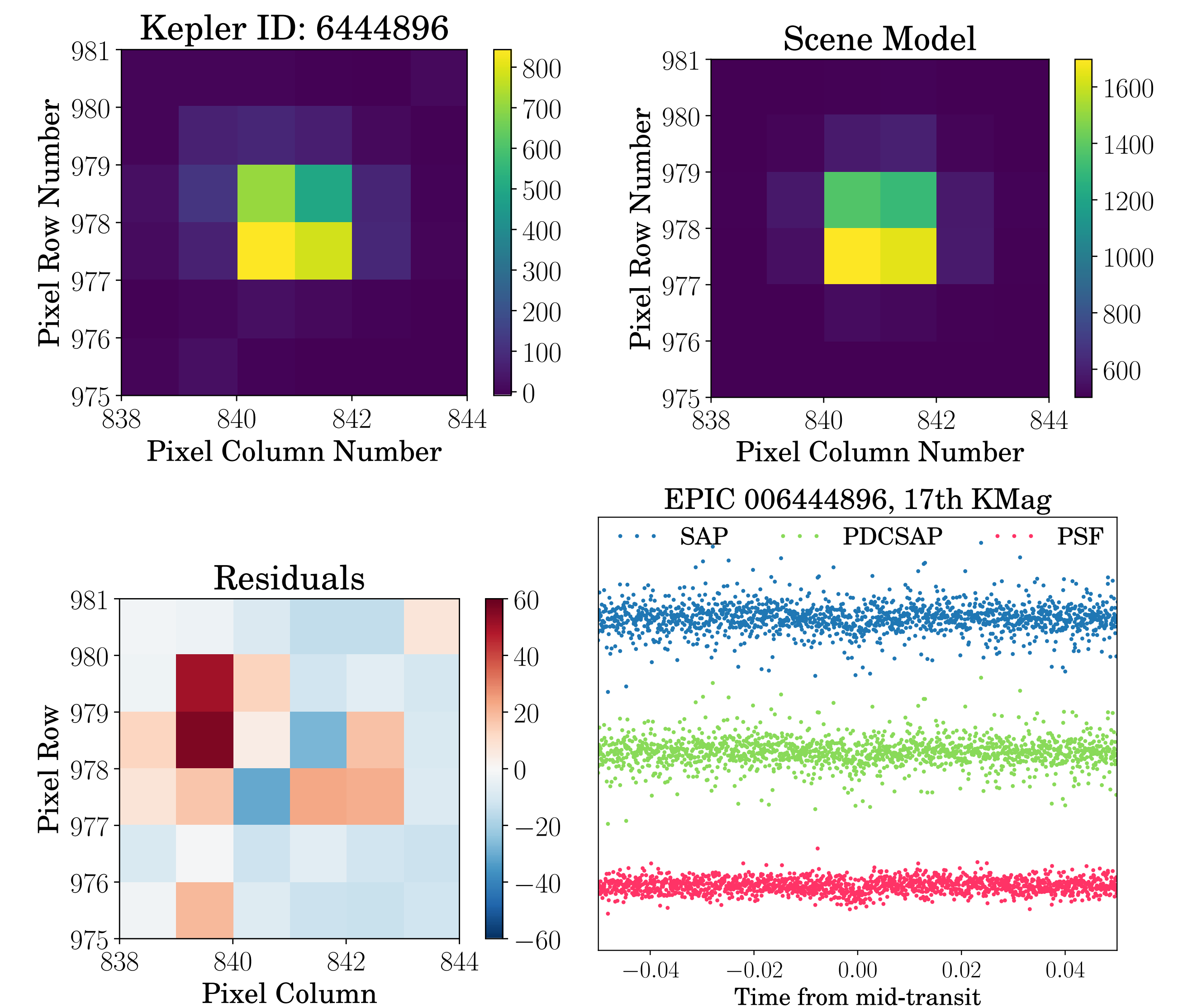
```
>>> from pyke import KeplerTargetPixelFile
>>> tpf = KeplerTargetPixelFile("ADDRESS_TO_TPF")
>>> prf = tpf.get_prf_model()
```

Crowded K2 Clusters



```
>>> from pyke.prif import SceneModel, PRFPhotometry
>>> scene = SceneModel(prfs=5*[prf])
>>> phot = PRFPhotometry(prior=prior, scene_model=scene)
>>> results = phot.fit(tpf.flux)
```

Kepler Faint Stars



Conclusions

- We have presented an open-source tool to perform PSF photometry on Kepler and K2 data which precisely and accurately estimates stellar positions and fluxes on the CCD
- Motion-dependent noise, primarily caused by the subpixel flat-field variations, which are not taken into account in the PSF model, is still present. Nevertheless, it can be easily removed by the procedures developed by detrending pipelines
- As future works, we intend to study novel ways to build the PSF model, especially by using data-driven approaches

References

- [1] Luger R. *et al.* *ArXiv e-prints:1702.05488*, February 2017.
- [2] Vanderburg A. *et al.* *PASP*, *arXiv:1408.3853*, 126:948, October 2014.
- [3] Aigrain S. *et al.* *MNRAS*, *arXiv:1603.09167*, 459:2408–2419, July 2016.
- [4] Anderson J. *et al.* *2000PASP..112.1360A*, 112:1360–1382, October 2000.
- [5] Libralato M. *et al.* *MNRAS*, *arXiv:1510.09180*, 456:1137–1162, February 2016.
- [6] Bryson S. T. *et al.* *APJL*, *arXiv:1001.0331*, 713:L97–L102, April 2010.