

Report: Torque in a Variable Reluctance Machine

Barış Kuseyri

8 March 2020

Contents

1	Introduction	ii
2	Method	ii
3	Modelling	ii
3.1	Analytical Modelling	ii
3.2	FEA Modelling: 2D - Linear Materials	ii
3.3	FEA Modelling: 2D - Nonlinear Materials	ii
3.4	Control Method	ii
3.5	Analytical Modelling	ii
3.6	Motion Animation	ii
3.7	FEA Modelling: 3D	ii
4	Results	ii
5	Evaluation	ii

1 Introduction

This report examines a basic variable reluctance machine. A set of values, dimensions vsvs are given. From these values an analytical model of the machine is obtained. This model includes an analytical formula for the reluctance and the inductance of the system as a fuction of rotation of the variable reluctance machine. Then, torque characteristics are plotted, while machine coil is under DC excitation.

2 Method

3 Modelling

3.1 Analytical Modelling

3.2 FEA Modelling: 2D - Linear Materials

3.3 FEA Modelling: 2D - Nonlinear Materials

3.4 Control Method

$$T = \frac{1}{2} * i^2 * \frac{dL(\theta)}{d(\theta)} \quad (1)$$

$$i(t) = I_m * \sin(w_r t) \quad (2)$$

$$\delta = \sqrt{\frac{2\rho}{\omega\mu}} \quad (3)$$

3.5 Analytical Modelling

3.6 Motion Animation

3.7 FEA Modelling: 3D

4 Results

5 Evaluation