Welcome to instats

The Session Will Begin Shortly

(At the top of the hour, Eastern USA time)

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START

Nonlinear Time Series Analysis, Part I: Detecting Nonlinearity

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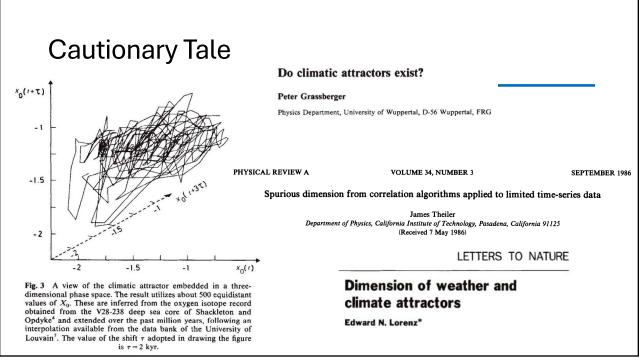
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Seminar Overview

- Day 1
 - Session 1: Introduction to Nonlinear Time Series (NTLS)
 - Session 2: Behaviors and State Spaces
- Day 2
 - Session 3: State Spaces (continued)
 - Session 4: Recurrences
- Dav 3
 - Session 5: Tests
 - Session 6: Singular Spectrum Analysis and Noise
- Day 4
 - Session 7: Surrogate Data
 - Session 8: Convergent Cross Mapping

Eliminate all other factors, and the one which remains must be the truth. Arthur Conan Doyle The Sign of the Four

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What must we eliminate?

- We try to eliminate the following possibilities
 - That our time series data are simply random (noise)
 - That the data may be equally well modeled by something other than a nonlinear system (nonlinearity)
 - The signal must be strong enough to be modeled
 - That the system changes over time in a way that different segments of the time series should be modeled with different models (nonstationary)
 - In the case of vector time-series data, that the various components belong to different, and unconnected, systems (separable)

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Procedure

- (Linear) Noise
 - Spectrum signal analysis (SSA; Session 6)
 - Brock-Dechert-Scheinkman (BDS) test
 - Surrogate test
 - Various entropy-related tests
 - Maximum characteristic Lyapunov exponent (MLCE)
- Nonlinearity
 - Nash-Sutcliff efficiency (NSE)
- Nonstationarity
 - · Nonlinear cross-prediction
- Separability
 - Convergent cross-mapping (CCM) session 8

Brock-Dechert-Scheinkman (BDS) Test

- Is the series signal or noise?
- H₀: The series is independent and identically distributed
- BDS test

 - $BSD(m,\epsilon)=\frac{\sqrt{n}\mathcal{C}(m)}{s}$ (n is the series length, C(m) is related to the correlation integral for various embedding dimensions, and s is the asymptotic standard deviation)
- Embed the series in *m* dimensions (try several)
- Consider various levels of "closeness"
- Tests.Rmd

Surrogate Test

- Is the series signal or noise?
- H_o: The series is independent and identically distributed
- We'll say much more about surrogates in session 7, so for now, we will just note that the one of the surrogate tests is a resampling alternative to the BDS test.

Entropy

• Surprise!

$$S = -\sum p_i \log(p_i)$$

- where:
 - p_i is the probability of an event
 - Log-base determines the units (nats for natural log, bits for log-base-2)

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Entropy: Alternate interpretation

- Uncertainty and information
- "I'm thinking of a number 1 and 128"
 - Uncertainty (in bits): $log_2(128) = 7$
 - We need 7 bits to write each of the 1st 100 integers
 - Optimal strategy: Guess the midpoint each time
 - · Gains 1 bit of information
 - Because 7 bits is the information we must gain to know the number, the optimal strategy for [1,100] takes at most 7 guesses
- Entropy calculations

Entropy Rate

- Many flavors of entropy; we want entropy rate
- Divide state space into boxes ("hypercubes") with edge ϵ
- Then
 - Deterministic: Entropy rate as E approaches zero approaches a constant
 - Stochastic: Entropy rate as ε approaches zero diverges

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Randomness v. (Deterministic) Chaos

- Randomness: No model
- Chaos: Model, but...
 - "Sensitive dependence on initial conditions" (SDIC)
 - Lyapunov exponent > 0
 - · Maximum characteristic Lyapunov exponent (MCLE)
- Lack of infinite precision in measurement limits forward prediction/modeling
- In R: Lyapunov.Rmd

Nonlinear Serial Dependence

- Reconstruct state space
- Nash-Sutcliffe coefficient of efficiency (NSE)
 - NSE > 0.65 is good evidence of a signal
- Simplex prediction
 - Essentially, fancy autoregression
 - · Weighted average of the predictions of nearby neighbors
- Aside: Autoregression
 - $x_{n+1} = \alpha_i x_n + \epsilon_i$
 - Not i.i.d., so NOT linear regression
- Tests.Rmd

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Nonstationarity Tests

- Linear TS
 - "Weak" stationarity: Mean and variance, for example, do not fluctuate
 - · Divide TS into segments and compare across segments
 - · Doesn't work for nonlinear
- Nonlinear TS: Cross-prediction stationarity test
 - Divide TS into segments and predict across segments
 - Matrix of NSE values
 - · Each segment predicts each other segment
 - · Entries should be large and roughly constant

And around again...

- Tests
 - Noise
 - Nonstationarity
 - Linearity
- Next session: Singular Spectrum Analysis
 - Removes (some) noise
 - Removes (some) nonstationarity
- Repeat tests
 - Why? Stay close to original data and make certain nothing changed

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Questions



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Next session @ UTC 1900