

偏微分方程式と物理現象

Partial Differential Equations for Science and Engineering

#### Outline of Class

#### Instructor

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Field: Urban meteorology and hydrology

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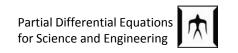
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#### Recommended Textbook

Advanced Engineering Mathematics by Erwin Kreyszig (Available in Tokyo Tech library)



#### Outline of Class

- Fundamental knowledge of PDE, Analytical and Numerical Solutions.
- ➤ Lectures and exercises on problems in Science and Engineering, deriving the PDE for physical phenomena, properties of PDE, methods for obtaining analytical and numerical solutions.
- Acquire the ability to perform numerical analyses by combining lectures with computational exercises.

#### Outline of Class

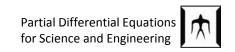
#### Schedule:

> Lecture 1 Definition and types of PDE Lecture 2 Modeling of flow phenomena with the hyperbolic PDE > Lecture 3 Analytical solution of the hyperbolic PDE (D'Alembert Solution) Analytical solution of the hyperbolic PDE (Fourier series) Lecture 4 > Lecture 5 Modeling of diffusion phenomena with the parabolic PDE > Lecture 6 Analytical solution of the parabolic PDE Lecture 7 Derivation and solution of elliptical equation Poisson > Lecture 8 Test level of understanding (Exercise Problems for Lecture 1-7) Introduction to Numerical analysis Lecture 9 Lesson 10-11 Numerical solution of PDE – Parabolic equation ➤ Lesson 12-13 Numerical solution of PDE – Combined Parabolic/Hyperbolic ➤ Lesson 14•15 Numerical solution of PDE – Hyperbolic equation

## Grading System

Term-end Report

mid-term examination (45%), term-end report (45%), short exercises (10%)



# Today's Objectives

Schedule and Strategy

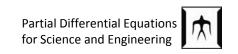
• Finite Difference Method

• Basic algorithm structure, outputting, and animation using python and ffmpeg.

# SCHEDULE & STRATEGY

# Style

- Sit and work together with assigned group to building the models in groups. May freely consult with other groups (free discussion) and myself.
- Tasks are given on the day.
- Concepts on numerical methods are taught on Mondays, computer programming on Thursdays.
- Compile a full report of tasks by November 27, 2017. (English language)
- Submission style: Print-outs and Soft-copies (zipped pdf and animations).
- Submission deadline: November 27, 2017, 17:15





Group		
1 Kiyo Kei	Ratchatawijin Maythawee	
2 Thumwanit Napat	Chin Riyu	
3 Zhou Lijun	Lerdbussarakam Tanad	Shagdar Zolbayar
4 Tsamara Tsani	Ka Kinzei	
5 Pongpattanayok Supatat	Jiang Lechuan	
6 Tumurbaatar Uyanga	Kiyo Yu	
7 Kadohiro Yasuki	Dolgormaa Banzragch	
8 Ka Jiyuntaku	Rudjito Rezkita Ramadhani	
9 Nasution Ghiffari Aby Malik	Kobayashi Yuki	
10 Chaijirawiwat Chawit	Chin Keitoku	
11 Sato Yaoki	Purevsuren Norovsambuu	
12 Do Khanh N	Kazama Tomohiro	

## Target PDEs

- 2-D diffusion phenomena
  - November 2, 2017 (Thursday)
- 2-D Burger's equation
  - November 9, 2017 (Thursday)
- 1-D Advection (Stability tests)
  - November 16, 2017 (Thursday)

# FINITE DIFFERENCE METHOD

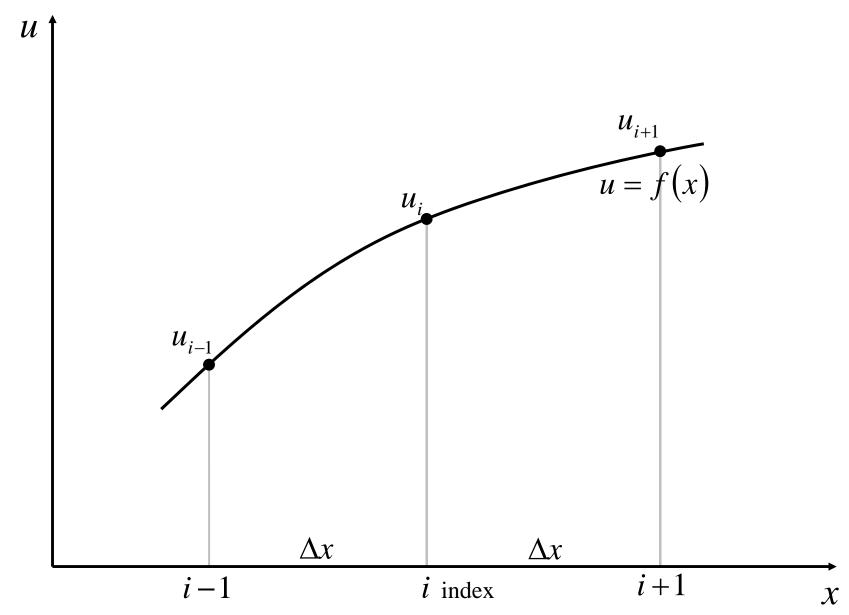
# Discretization of Differential Equations

- Finite Difference Method (FDM) (1910~present)
  - Formulation is easy.
  - Widely popular.
  - Mesh must be structured.
  - Neumann boundary conditions are approximated.
- Finite Element Method (FEM) (1956~present)
  - More time consuming for solving non-linear PDEs.
  - On-going development and gaining popularity.
  - Good for complex geometries and unstructured meshes.
  - Neumann boundary conditions are enforced.
- Finite Volume Method (recent)
  - Derived from either FDM or FEM

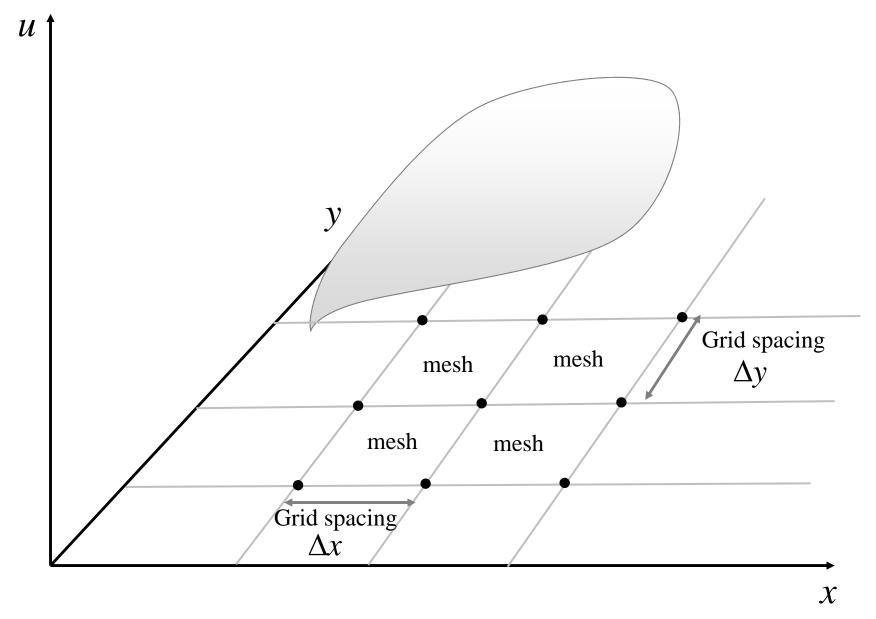
#### Basic idea of FDM

Derivatives in differential equations are written in terms of *discrete* quantities of dependent and independent variables, resulting in *simultaneous* algebraic equations with all unknowns prescribed at *discrete mesh points* for the entire *domain*.

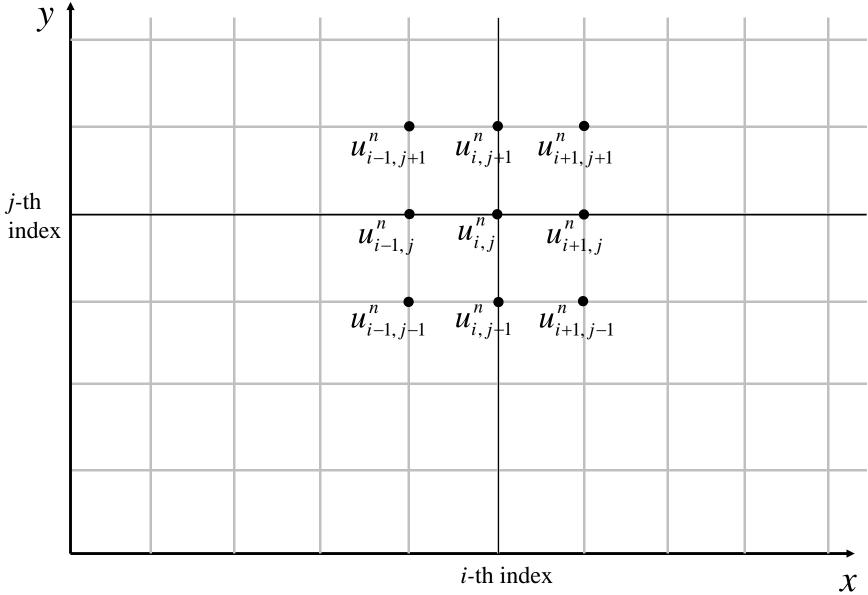
## Discretizations in FDM



## Discretizations in FDM for 2D







Consider a function u(x) and its derivative at point x,

$$\frac{\partial u(x)}{\partial x} = \lim_{\Delta x \to 0} \frac{u(x + \Delta x) - u(x)}{\Delta x}$$

Expanding  $u(x+\Delta x)$  using Taylor's series about u(x),

$$u(x + \Delta x) = u(x) + \Delta x \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)^2}{2} \frac{\partial^2 u(x)}{\partial x^2} + \frac{(\Delta x)^3}{3!} \frac{\partial^3 u(x)}{\partial x^3} + \dots$$

Substituting  $u(x+\Delta x)$  to the derivative function,

$$\frac{\partial u(x)}{\partial x} = \lim_{\Delta x \to 0} \left( \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)}{2} \frac{\partial^2 u(x)}{\partial x^2} + \dots \right)$$

Simplifying,

$$\frac{u(x + \Delta x) - u(x)}{\Delta x} = \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)}{2} \frac{\partial^2 u(x)}{\partial x^2} + \dots = \frac{\partial u(x)}{\partial x} + O(\Delta x)$$

Applying our pre-defined indexing,

$$\frac{u_{i+1} - u_i}{\Delta x} = \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)}{2} \frac{\partial^2 u(x)}{\partial x^2} + \dots = \frac{\partial u(x)}{\partial x} + O(\Delta x)$$

Re-arranging we get an approximation (forward difference),

$$\frac{\partial u(x)}{\partial x} = \frac{u_{i+1} - u_i}{\Delta x} + O(\Delta x)$$

Expanding  $u(x+\Delta x)$  using Taylor's series about u(x),

$$u(x + \Delta x) = u(x) + \Delta x \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)^2}{2} \frac{\partial^2 u(x)}{\partial x^2} + \frac{(\Delta x)^3}{3!} \frac{\partial^3 u(x)}{\partial x^3} + \dots$$

$$\boxed{\frac{u_{i+1} - u_i}{\Delta x} = \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)}{2} \frac{\partial^2 u(x)}{\partial x^2} + \dots = \frac{\partial u(x)}{\partial x} + O(\Delta x)}$$

Expanding  $u(x-\Delta x)$  using Taylor's series about u(x),

$$u(x - \Delta x) = u(x) - \Delta x \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)^2}{2} \frac{\partial^2 u(x)}{\partial x^2} - \frac{(\Delta x)^3}{3!} \frac{\partial^3 u(x)}{\partial x^3} + \dots$$

$$\frac{u_i - u_{i-1}}{\Delta x} = \frac{\partial u(x)}{\partial x} - \frac{(\Delta x)}{2} \frac{\partial^2 u(x)}{\partial x^2} + \dots = \frac{\partial u(x)}{\partial x} + O(\Delta x)$$

$$\frac{u_{i+1} - u_i}{\Delta x} = \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)}{2} \frac{\partial^2 u(x)}{\partial x^2} + \dots = \frac{\partial u(x)}{\partial x} + O(\Delta x)$$

$$\frac{u_i - u_{i-1}}{\Delta x} = \frac{\partial u(x)}{\partial x} - \frac{(\Delta x)}{2} \frac{\partial^2 u(x)}{\partial x^2} + \dots = \frac{\partial u(x)}{\partial x} + O(\Delta x)$$

Adding both equations,

$$\frac{u_{i+1} - u_{i-1}}{2\Delta x} = \frac{\partial u(x)}{\partial x} + \frac{(\Delta x)^2}{3!} \frac{\partial^3 u(x)}{\partial x^3} + \dots = \frac{\partial u(x)}{\partial x} + O(\Delta x^2)$$

Approximation for the 1st order,

$$\frac{\partial u(x)}{\partial x} = \frac{u_{i+1} - u_i}{\Delta x} + O(\Delta x)$$
 Forward Difference 
$$\frac{\partial u(x)}{\partial x} = \frac{u_i - u_{i-1}}{\Delta x} + O(\Delta x)$$
 Backward Difference

$$\frac{\partial u(x)}{\partial x} = \frac{u_{i+1} - u_{i-1}}{2\Delta x} + O(\Delta x^2)$$
 Central Difference

Approximation for the 2<sup>nd</sup> order,

$$\frac{\partial^2 u(x)}{\partial x^2} = \frac{u_{i+1} - 2u_i + u_{i-1}}{\Delta x^2} + O(\Delta x^2)$$

Considering the diffusion equation (w/ constant coefficient),

$$\frac{\partial u}{\partial t} - \alpha \frac{\partial^2 u}{\partial x^2} = 0$$

Utilizing the FTCS Method,

$$\frac{u_i^{n+1} - u_i^n}{\Delta t} = \alpha \frac{u_{i+1}^n - 2u_i^n + u_{i-1}^n}{\Delta x^2} + O(\Delta t, \Delta x^2)$$

$$u_i^{n+1} = u_i^n + \left(\frac{\alpha \Delta t}{\Delta x^2}\right) \left(u_{i+1}^n - 2u_i^n + u_{i-1}^n\right)$$

# Treatment of Boundary Conditions

Dirichlet conditions,

The *u* values at the boundaries are fixed for all *n*.

Neumann conditions,

The approximation for the derivate at the boundary is

$$\frac{u_{i+1}^n - u_0^n}{2\Delta x} = G$$

$$u_0^n = u_{i+1}^n - 2\Delta x(G) \quad \text{(Ghost point)}$$

Mission for the week

$$\frac{\partial T}{\partial t} - \alpha \left( \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) = 0$$

Construct a diffusion model for a 2-D heat plate with dimensions 100 m. by 100 m.

- 1. Desired initial condition (distributed).
- 2. Investigate w/ or without Dirichlet or Neumann Boundary Conditions.
- 3. Investigate various influences of  $d = \frac{\alpha \Delta t}{\Delta x^2}$ . What is happening when its values range from 0. to 1.0.
- 4. Visualize the results by animation.

# Python Programming (python.org)

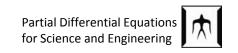
- High-level programming language for general purpose programming.
- Fewer lines of code compared to C++ and Java.
- Most linux operating systems have built-in Python.
- Compatible with various OS.
- Plotting can be done simultaneously within the program.
- Large resources online.
- Not named after a "snake".

# Summary of basic python structure in this class

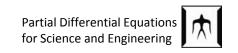
- 1. Import Statement (numpy, matplotlib)
- 2. Function Assignment (def)
- 3. The body Main function (def main())

# ffmpeg (ffmpeg.org)

- 1. Free software project that produces libraries and programs for handling multimedia data.
- 2. Fast video/audio conversion and editing tool.
- 3. Capable of creating high quality time-lapses.



# DEMONSTRATING PYTHON PROGRAM WITH ANIMATION



Given y(t,x) and the differential equation,

$$\frac{\partial y}{\partial t} = 1$$
 Dirichlet boundary condition 
$$y(0, x) = 0$$

Visualize the change of y from t = 0 to 10 at 0.1 t-intervals from the region x = 0 to 10 with 100 grid points.

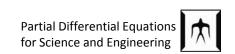
```
import numpy as np
    import matplotlib.pyplot as plt
     import os
                                Change work directory to location of script.
 4
    directory = os.path.dirname(os.path.realpath( file ))
    os.chdir(directory)
 6
   def get value(it):
 9
         y = t
10
         return t
                                                     Function declaration.
11
                                               Main body of the program.
12
   def main():
13
         t = np.arange(0.,10.,0.1)
                                               Setting boundaries,
         x = np.linspace(0.,10.,num=100)
14
                                               descritization
15
         y = np.copy(x)
         y[:] = 0.
16
         icount = 1
17
         for it in t:
18
19
             for i in range(0, y.shape[0]):
                                               Looping in time and space.
20
                  v[i] = get value(it)
21
             plt.clf()
22
             plt.plot(x,y)
                                                Plot settings.
             plt.xlim(0,10)
23
             plt.ylim(0,10)
24
             plt.savefig("test %03di.jpg"%(icount)) Save to file.
25
26
             icount+=1
27
   ⊟if
28
                        main ":
          name
29
         main()
                        Calls the main function. Complete program syntax.
```

ffmpeg command

ffmpeg -r 1 -start\_number 1 -i test\_%03d.jpg -vcodec libx264 trial.mp4

- -r [frames/images per second]
- -start\_number [initial file number]
- -I test\_%03d.jpg (test\_001.jpg,test\_002.jpg)
- -vcodec [codec for video]

trial.mp4 (output video in mp4 format).



#### Textbook reference

- Computational Fluid Dynamics by T.J. Chung
  - Downloadable via Tokyo Tech OPAC