

# Finite-Difference modelling

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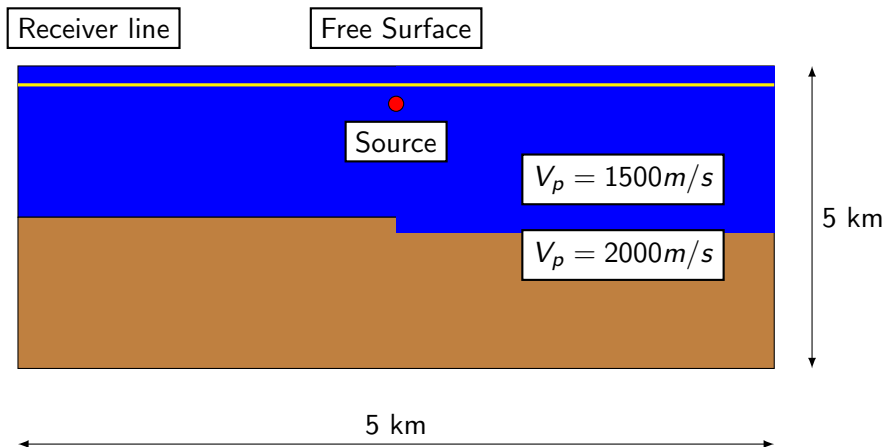
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UNIS, Svalbard April 2024

# Content

1. Why do we need Finite Difference modelling?
2. Newton and Hook's law
3. Finite Difference Grids
4. The Finite Difference Method

# Diffracted waves



# Diffracted waves

Movie-3

# Newton's and Hook's laws

Seismic waves can be completely described by Newton's law

$$\partial_t v(x, t) = \rho^{-1}(x) \partial_x \sigma(x, t) + f(x, t),$$

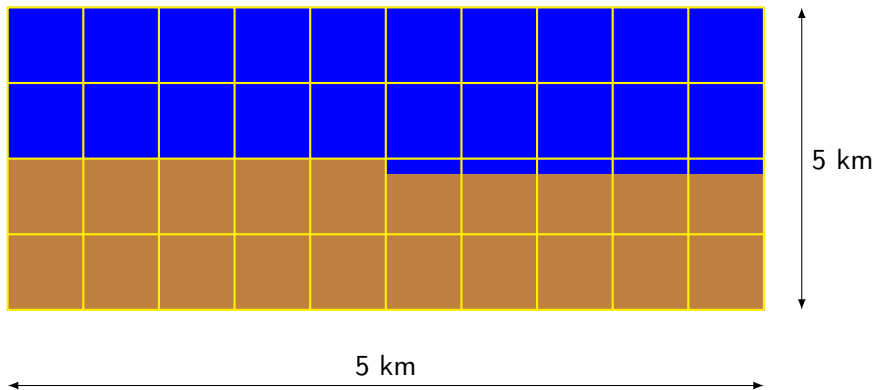
and Hook's law

$$\partial_t \sigma(x, t) = \kappa(x) \partial_x v(x, t).$$

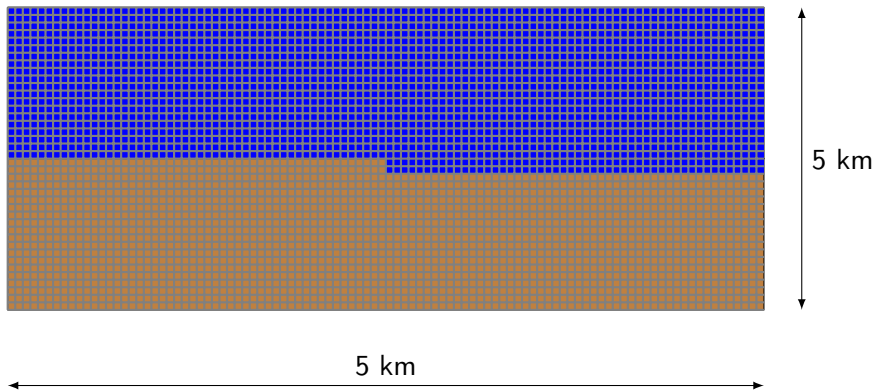
Here :

- ▶  $\rho(x)$  : Density
- ▶  $v(x, t)$  : Particle velocity
- ▶  $\sigma(x, t)$  : Stress
- ▶  $f(x, t)$  : External force (Source of energy)
- ▶  $\kappa(x)$  : Bulk modulus (Stiffness)

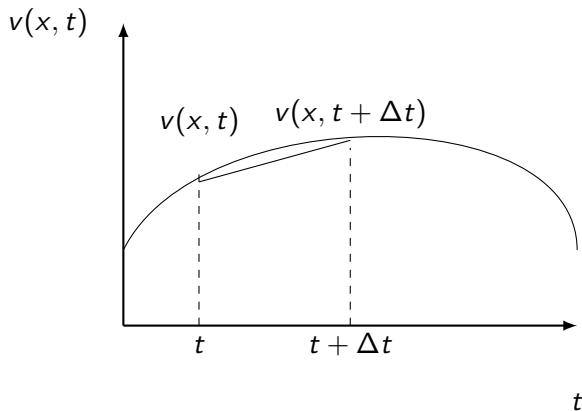
## Gridded Models



# Gridded Models



## Time derivative of $v(x,t)$

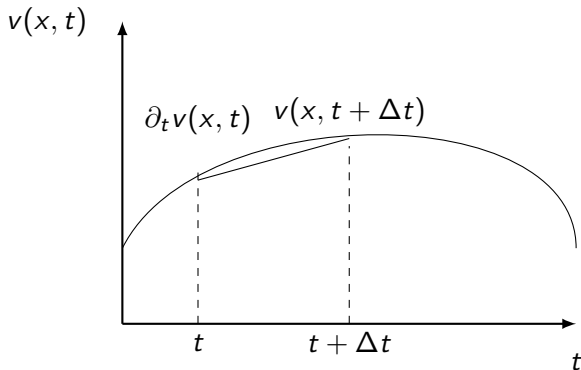


$$\partial_t v(x,t) \approx \frac{v(x,t + \Delta t) - v(x,t)}{\Delta t}$$

$\partial_t v(x,t)$  is the slope of the line above.



## Predict ahead in time



$$v(x, t + \Delta t) \approx v(x, t) + \partial_t v(x, t) \Delta t$$

It is possible to predict future values of  $v(x, t)$  if the derivative (slope) is known.

## Finite Difference solution

Seismic waves can be completely described by Newton's law

$$\partial_t v(x, t) = \rho^{-1} \partial_x \sigma(x, t) + f(x, t),$$

If we know  $\sigma(x, t)$  and  $v(x, t)$  we can compute  $v(x, t + \Delta t)$  by using the formula from the previous slide:

$$v(x, t + \Delta t) \approx v(x, t) + \Delta t [\rho^{-1} \partial_x \sigma(x, t) + f(x, t)].$$

The derivative of  $\sigma$  on the right hand side can be computed by the same formula

$$\partial_x \sigma(x, t) \approx \frac{\sigma(x + \Delta x, t) - \sigma(x, t)}{\Delta x}$$

## Finite Difference solution

Seismic waves can be completely described by Newton's law

$$\partial_t \sigma(x, t) = \rho^{-1} \partial_x v(x, t),$$

If we know  $\sigma(x, t)$  and  $v(x, t)$  we can compute  $\sigma(x, t + \Delta t)$  by using the formula from the previous slide:

$$\sigma(x, t + \Delta t) \approx \sigma(x, t) + \Delta t [\rho^{-1} \partial_x v(x, t)].$$

The derivative of  $v$  on the right hand side can be computed by the same formula

$$\partial_x v(x, t) \approx \frac{v(x + \Delta x, t) - v(x, t)}{\Delta x}$$

## Initial conditions

By repeating the formulas on the previous slides we can compute the particle velocity and stress at any future time  $t$ .

The computation is started by assuming that the particle velocity and stress is zero at the beginning, only the external force  $f$  (source) is acting.

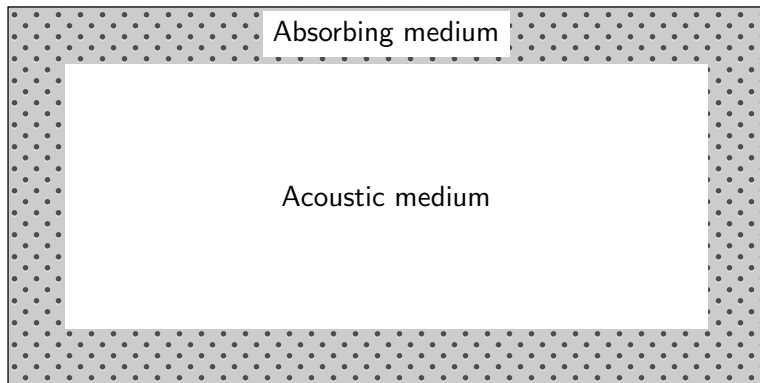
# Outer Boundaries

Fig-1

# Outer Boundaries

Fig-1

# Perfectly Matched Layer (PML)



# Fibrous Sound absorbing material

$\beta$ : 0.5

Porosity

$\rho_f$ :  $1000 \text{ kg/m}^3$

Fluid density

$\rho_s$ :  $2600 \text{ kg/m}^3$

Fiber density

$\eta$ :  $10^{-3} \text{ kg/m} \times \text{s}$

Viscosity

$\kappa$ :  $0.5 \times 10^{-7} \text{ m}^2$

Permeability

$\alpha$ : 1.2

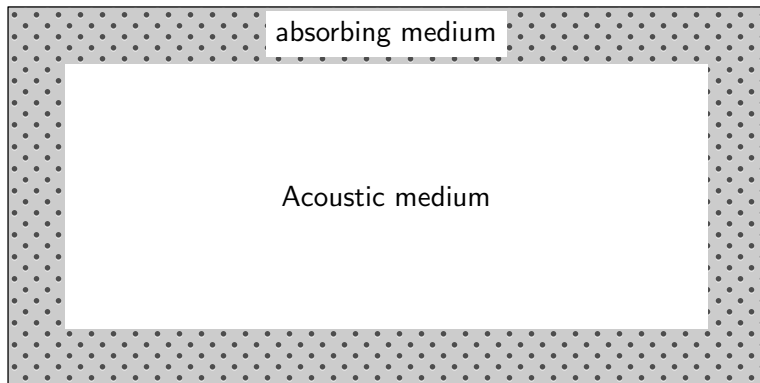
Tortuosity

Gives  $Q \approx 1.0$  Wave velocity:  $1500 \text{ m/s}$





# Perfectly Matched Layer (PML)



## Perfectly Matched Layer (PML)

