

Finite-Difference modelling

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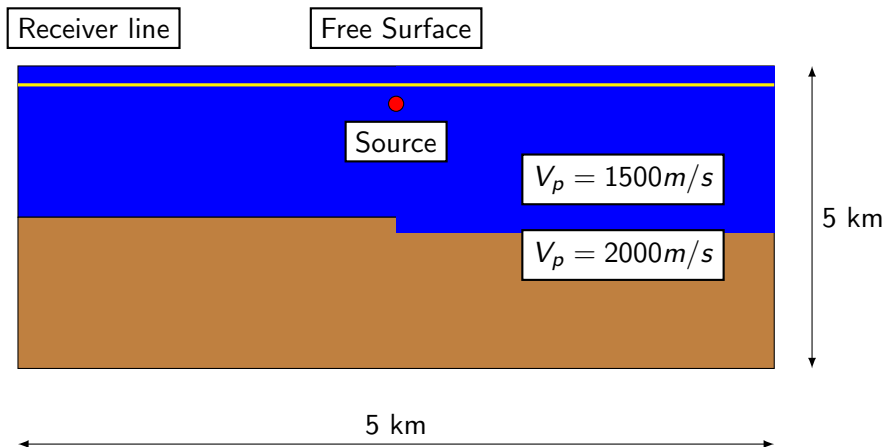
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Content

1. Why do we need Finite Difference modelling?
2. Newton and Hook's law
3. Finite Difference Grids
4. The Finite Difference Method

Diffracted waves



Diffracted waves

Movie-3

Newton's and Hook's laws

Seismic waves can be completely described by Newton's law

$$\partial_t v(x, t) = \rho^{-1}(x) \partial_x \sigma(x, t) + f(x, t),$$

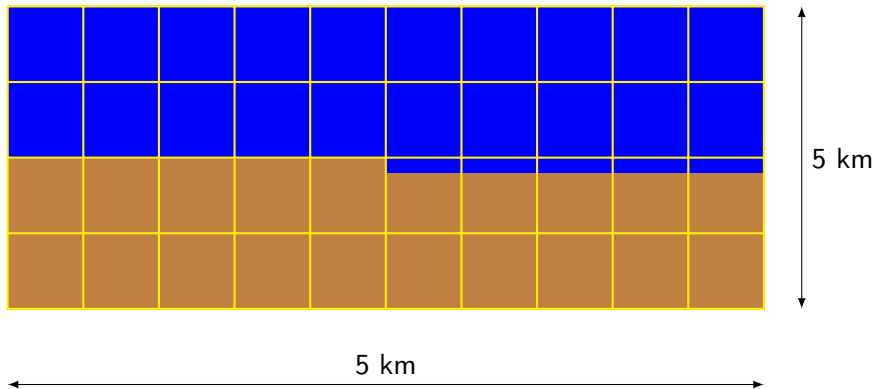
and Hook's law

$$\partial_t \sigma(x, t) = \kappa(x) \partial_x v(x, t).$$

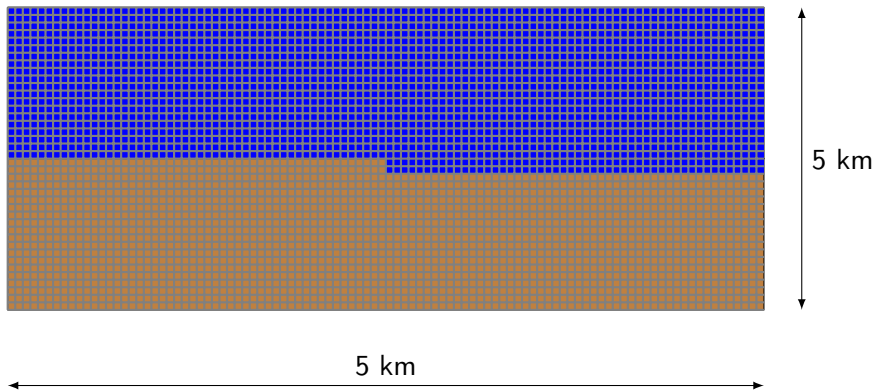
Here :

- ▶ $\rho(x)$: Density
- ▶ $v(x, t)$: Particle velocity
- ▶ $\sigma(x, t)$: Stress
- ▶ $f(x, t)$: External force (Source of energy)
- ▶ $\kappa(x)$: Bulk modulus (Stiffness)

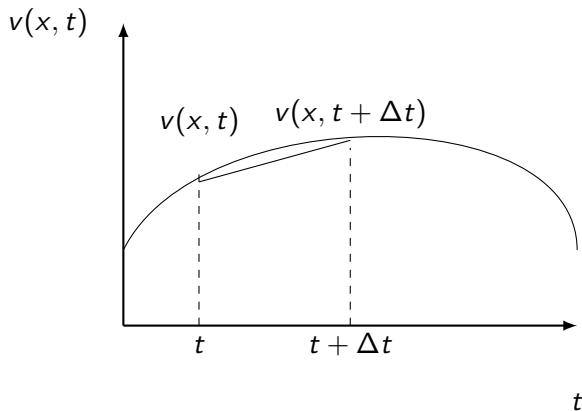
Gridded Models



Gridded Models



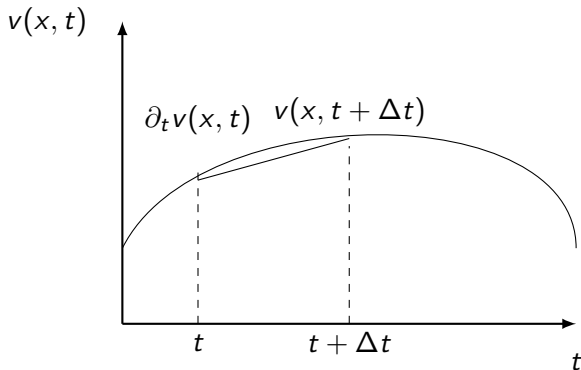
Time derivative of $v(x,t)$



$$\partial_t v(x,t) \approx \frac{v(x,t + \Delta t) - v(x,t)}{\Delta t}$$

$\partial_t v(x,t)$ is the slope of the line above.

Predict ahead in time



$$v(x, t + \Delta t) \approx v(x, t) + \partial_t v(x, t) \Delta t$$

It is possible to predict future values of $v(x, t)$ if the derivative (slope) is known.

Finite Difference solution

Seismic waves can be completely described by Newton's law

$$\partial_t v(x, t) = \rho^{-1} \partial_x \sigma(x, t) + f(x, t),$$

If we know $\sigma(x, t)$ and $v(x, t)$ we can compute $v(x, t + \Delta t)$ by using the formula from the previous slide:

$$v(x, t + \Delta t) \approx v(x, t) + \Delta t [\rho^{-1} \partial_x \sigma(x, t) + f(x, t)].$$

The derivative of σ on the right hand side can be computed by the same formula

$$\partial_x \sigma(x, t) \approx \frac{\sigma(x + \Delta x, t) - \sigma(x, t)}{\Delta x}$$

Finite Difference solution

Seismic waves can be completely described by Newton's law

$$\partial_t \sigma(x, t) = \rho^{-1} \partial_x v(x, t),$$

If we know $\sigma(x, t)$ and $v(x, t)$ we can compute $\sigma(x, t + \Delta t)$ by using the formula from the previous slide:

$$\sigma(x, t + \Delta t) \approx \sigma(x, t) + \Delta t [\kappa(x) \partial_x v(x, t)].$$

The derivative of v on the right hand side can be computed by the same formula

$$\partial_x v(x, t) \approx \frac{v(x + \Delta x, t) - v(x, t)}{\Delta x}$$

Initial conditions

By repeating the formulas on the previous slides we can compute the particle velocity and stress at any future time t .

The computation is started by assuming that the particle velocity and stress is zero at the beginning, only the external force f (source) is acting.

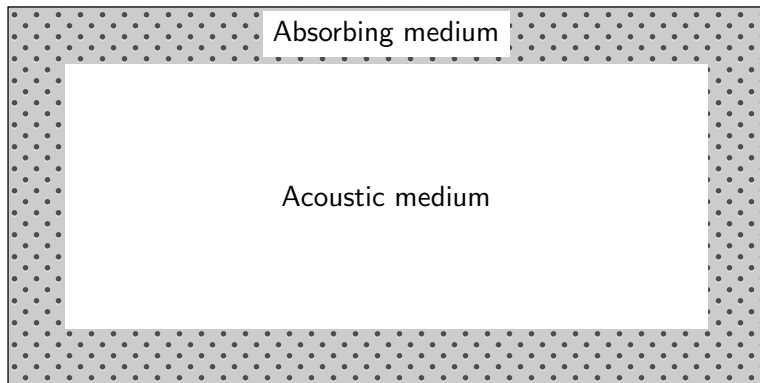
Outer Boundaries

Fig-1

Outer Boundaries

Fig-1

Perfectly Matched Layer (PML)



Fibrous Sound absorbing material

β : 0.5

Porosity

ρ_f : 1000 kg/m^3

Fluid density

ρ_s : 2600 kg/m^3

Fiber density

η : $10^{-3} \text{ kg/m} \times \text{s}$

Viscosity

κ : $0.5 \times 10^{-7} \text{ m}^2$

Permeability

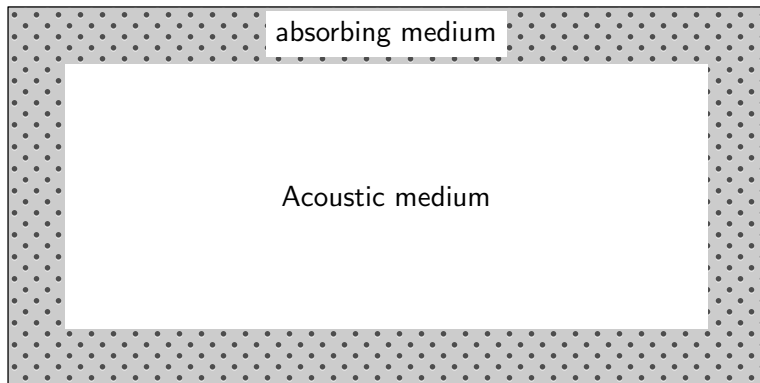
α : 1.2

Tortuosity

Gives $Q \approx 1.0$ Wave velocity: 1500 m/s



Perfectly Matched Layer (PML)



Perfectly Matched Layer (PML)

