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1  --Programmed by: Luis Barquero
2  --Purpose: Testbench will simulate the T-Bird light example, except there is the
   inclusion of the brakes
3      --The different states will be: Idle, Left Turn(no brakes), Right Turn(no brakes),
       Hazards, Left Turn(with brakes),
4      --
       Right Turn(with brakes).
5
6  library ieee;
7  use ieee.std_logic_1164.all;
8
9  entity tbird_testbench is
10 end tbird_testbench;
11
12 architecture behavior of tbird_testbench is
13
14     signal clk_sig : std_logic := '0';
15     signal rst_sig : std_logic := '0';
16     signal left_sig,right_sig,haz_sig,brakes_sig : std_logic;
17     constant Tperiod : time := 10 ns;
18
19     begin
20
21         process(clk_sig)
22         begin
23             clk_sig <= not clk_sig after Tperiod/2;
24         end process;
25
26         rst_sig <= '0', '1' after 2 ns, '0' after 4 ns;           --Reset Signal
27
28         --Left will be on from 20 to 60 ns(no brake), then it will be on from 140-240 (with
       brakes from 160-220).
29
30         left_sig <= '0', '1' after 20 ns, '0' after 60 ns, '1' after 140 ns, '0' after 240 ns;
31
32
33         --Right will be on from 60 to 100 ns(no brake), then it will be on from 240-340 (with
       brakes from 260-320).
34
35         right_sig <= '0', '1' after 60 ns, '0' after 100 ns, '1' after 240 ns, '0' after 340
       ns ;
36
37
38         --Hazard will be on from 100 to 140 ns.
39
40         haz_sig <= '0', '1' after 100 ns, '0' after 140 ns;
41
42
43         --Brakes will be on from 160 to 220 ns(for left turn with brakes), then it will be on
       from 260-320 (for right turn with brakes).
44
45         brakes_sig <= '0', '1' after 160 ns, '0' after 220 ns, '1' after 260 ns, '0' after
       320 ns;
46
47
48         -- this is the component instantiation for the
49         -- DUT - the device we are testing
50         DUT : entity work.tbird_lc(behavior)
51             port map(clk => clk_sig, rst => rst_sig,
52                     left => left_sig, right => right_sig,
53                     haz => haz_sig, brakes => brakes_sig);
54
55
56     end behavior;

```