

Dynamics of Computation in the Brain

76908

Solution EX #1

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Contents

1	Euler's Method for Numerical Integration	2
1.1	Analytical Part	2
1.1.1	Single-step Simulation Error	2
1.1.2	Fixed-time Simulation Error	2
1.2	Numerical Part	5
1.2.1	Numerical Simulations of $\mathbf{x}(t)$	5
1.2.2	Error Function	5
1.3	Qualitative Observation	6
2	Differential equation with time-dependent input	6

1 Euler's Method for Numerical Integration

$$\begin{aligned} \dot{x} &= f(x) \\ x(t + \Delta t) &= x(t) + f(x(t)) \Delta t \\ x &= x \end{aligned}$$

1.1 Analytical Part

$$\dot{x}(t) = jx(t) \quad x(t)j$$

1.1.1 Single-step Simulation Error

(a) The approximated solution after a single-step is:

$$x(0 + \Delta t) = x(0) + f(x(0)) \Delta t = x(0) + x(0) \Delta t$$

Note $x(0) = x_0$ the starting condition for the solution and we get:

$$x(\Delta t) = x_0 + x_0 \Delta t$$

(b) The analytical solution as we know is $x(t) = x_0 e^{jt}$. The single-step error is:

$$\begin{aligned} x(\Delta t) - jx(\Delta t) \Delta t &= jx_0 e^{j\Delta t} - x_0 + x_0 \Delta t \\ &= jx_0 j e^{j\Delta t} - 1 + \Delta t \end{aligned}$$

Using the fact that $e^x = \sum_{i=0}^{\infty} \frac{x^i}{i!}$ (Tylor expansion of e^x at 0), we get:

$$x(\Delta t) - jx_0 \Delta t = jx_0 j \left(1 + \Delta t + \frac{j^2 \Delta t^2}{2} + O(\Delta t^3) \right) - 1 + \Delta t = jx_0 j \left(\frac{j^2 \Delta t^2}{2} + O(\Delta t^3) \right)$$

$$jx_0 j \frac{j^2 \Delta t^2}{2}$$

1.1.2 Fixed-time Simulation Error

(a) Given t_1 and Δt , let n be the maximal integer such that: $n \Delta t < t_1$ (less formally, this means $t_1 = n \Delta t$ up to a small residual). We then get:

$$x(0) = x_0; \quad x(\Delta t) = x_0 + x_0 \Delta t = x_1; \quad \dots; \quad x(n \Delta t) = x_{n-1} + x_{n-1} \Delta t = x_n = x(t_1)$$

So, for $1 \leq i \leq n$:

$$\frac{x_i}{x_{i-1}} = \frac{x_{i-1} + x_{i-1} \Delta t}{x_{i-1}} = 1 + \Delta t$$

And now we can get a closed formula:

$$x(i, t) = x_i = x_0(1 - t)^i$$

Specifically:

$$x(t_1) = x_0(1 - t)^n$$

(b) First, note that $0 < t < 1$, so we get $0 < 1 - t < 1$ and thus $0 < (1 - t)^n < 1$. Ergo, we only need to consider what happens to $q := 1 - t$ in the ray $(-1; 1)$. Given a fixed n , this will singularly determine the different qualitative outcomes. Moreover, note $t_1 \neq 1$ i.e. $n \neq 1$: Thus, it suffices to consider the asymptotic behavior of q^n . We'll look at 3 regimes: $(-1; 1); (-1; 0); [0; 1)$:

$$\begin{aligned} & \begin{matrix} \infty \\ \approx 0 \end{matrix} \quad q < 1 \quad q^n \xrightarrow[n \rightarrow \infty]{} 0 \\ & \begin{matrix} \infty \\ \approx \end{matrix} \quad 1 < q < 0 \quad q^n \xrightarrow[n \rightarrow \infty]{} 0 \\ & \begin{matrix} \infty \\ \approx \end{matrix} \quad q = 1 \quad q^n \text{ diverges} \end{aligned}$$

I.e., for $0 < q < 1$, q^n will monotonically decrease to 0. For $-1 < q < 0$, q^n will still converge to 0 but will do it in an alternating fashion where the sign of q^n will oscillate between + and -. Similar oscillations will occur for $q < -1$ however, in this case there will be no convergence. In the special case of $q = -1$, q^n will oscillate between -1, otherwise, between -1 . Now:

$$\begin{aligned} & 0 < 1 - t < 1, \quad -1 < 1 - t < 0, \quad 1 - t > 0, \quad \frac{1}{2} < 1 - t < 1 \\ & 1 < 1 - t < 2, \quad 2 < 1 - t < 1, \quad 2 > 1 - t > 1, \quad \frac{2}{3} > 1 - t > \frac{1}{2} \\ & 1 < t < 1, \quad t < 2, \quad t > 2, \quad t > \frac{2}{3} \end{aligned}$$

Thus	∞	we're	left	with:
	$\geq \frac{1}{2}$	$t > 0$	$(0 < 1 - t < 1)$	<i>monotonical convergence</i>
	$\geq \frac{2}{3}$	$t > \frac{1}{2}$	$(1 < 1 - t < 2)$	<i>alternating convergence</i>
	$\geq t \geq \frac{2}{3}$	$(2 < 1 - t)$		<i>divergence</i>

(c) The error is:

$$x(t_1) - x(t_1)j = x_0 e^{-t_1} - x_0(1 - t)^n j = x_0 j e^{-t_1} (1 - t)^n j$$

Assume for simplicity $x_0 j = 1$:

$$(t_1) = j e^{-t_1} - e^{n \ln(1 - t)} j = j e^{-t_1} - e^{n \ln(1 - t)} j$$

We use Taylor's expansion around 0 of $\ln(1 + x) = x - \frac{x^2}{2} + o(x^3)$. For this to work, we'll add the condition that $(1 - t) > 0$ such that $\ln(1 - t)$ is defined. Also, remember $n = \frac{t_1}{t}$ so:

$$(t_1) = j e^{-t_1} - e^{\frac{t_1}{t} \ln(1 - t)} j = j e^{-t_1} - e^{-t_1 \frac{1}{2} t_1} j = e$$

