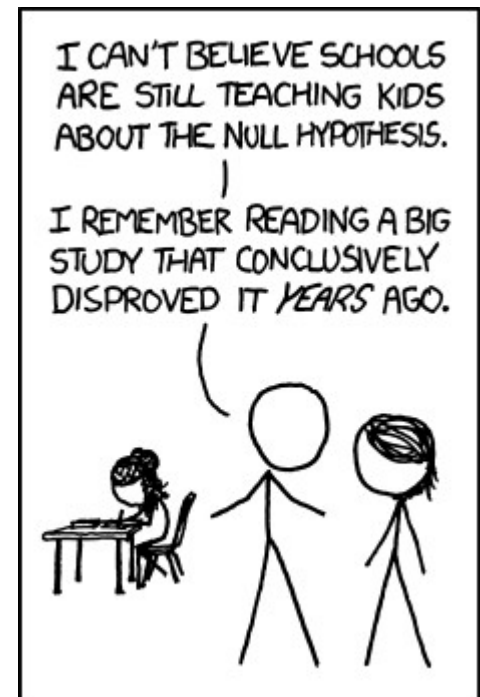


# Modern Particle Physics Experiments



Many aspects of particle physics are of stochastic nature, e.g.:

- **outputs of measurements**

The experiment results are test for various theoretical explanations.

How can we decide between theories?

→ use statistical hypothesis testing paradigm

“theory” – can be a different explanation of some phenomena:

- “SUSY particles exist” vs “SUSY particles do not exist”

or a statement about a value of some parameter:

- “electron neutrino mass is lower than  $0.9 \text{ eV}/c^2$ ” vs

“electron neutrino mass is lower than  $0.1 \text{ eV}/c^2$ ”

There is an everlasting confusion about answer of question

**“Probability of what?”** Two points of view exist:

- frequentist (“classic”): **probability = a fraction of desired outcomes out of many (imagined) trials**
- one **can not** talk about “probability that a theory is correct”, or “mass of particle X is within limits” as many trials on those would require many Universes
- one **can talk** about “probability that given (random) range contains a true value”

Let us use standard ruler, with 0.1cm ticks, to measure length of a pensil.

**Measurement tool reading:** 15 cm

**Measurement uncertainty:**  $0.1/\sqrt{12} = 0.03$  cm

**What is the length of a pensil?**  $15 \pm 0.03$  cm

The full sentence: “There is gaussian  $1\sigma$  probability (68.2%) that a range  $[15-0.03, 15+0.03]$  cm covers the true length of a pensil”.

**Never, say:** “The probability that the length of a pensil ...” as there is only one pencil.

Assume some experiment result:  $x_0$

Assume statistical model, or

hypothesis  $H(\theta)$ , for probability  
density function (pdf) of  $x$ :  $P(x|H) = P(x|\theta)$

**Likelihood:** the value of the  
probability for given experiment  
result (this is **not a probability!**):

$$\mathcal{L}(x_0, \theta) = P(x_0|H) = P(x_0|\theta)$$

Assume some there are two models, or hypotheses:

$H_0$  – null hypothesis

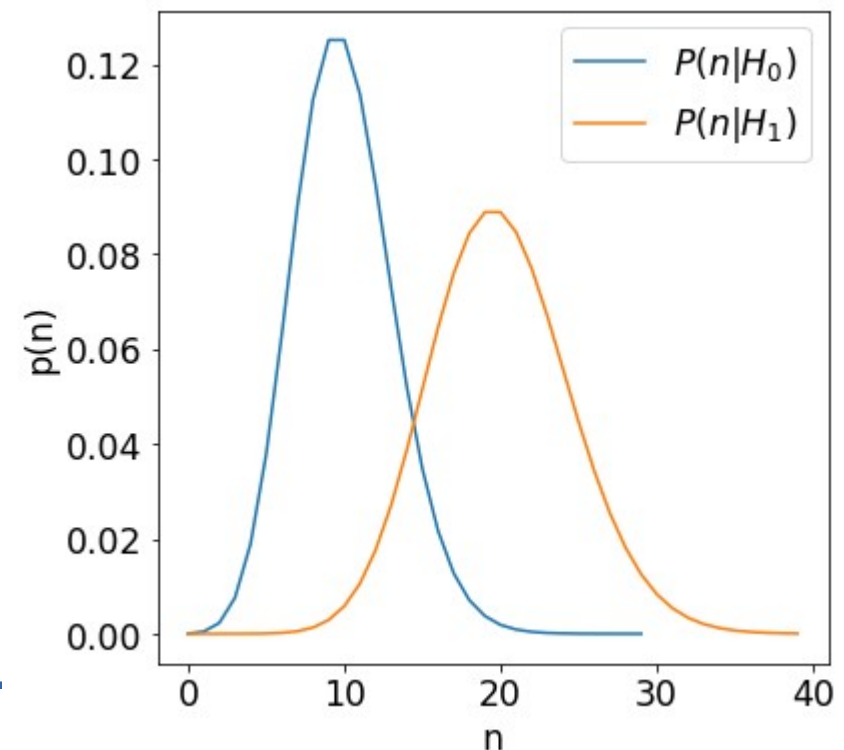
$H_1$  – alternative hypothesis

Hypotheses provide statistical models for experiment outcome:

$$P(x|H_0)$$

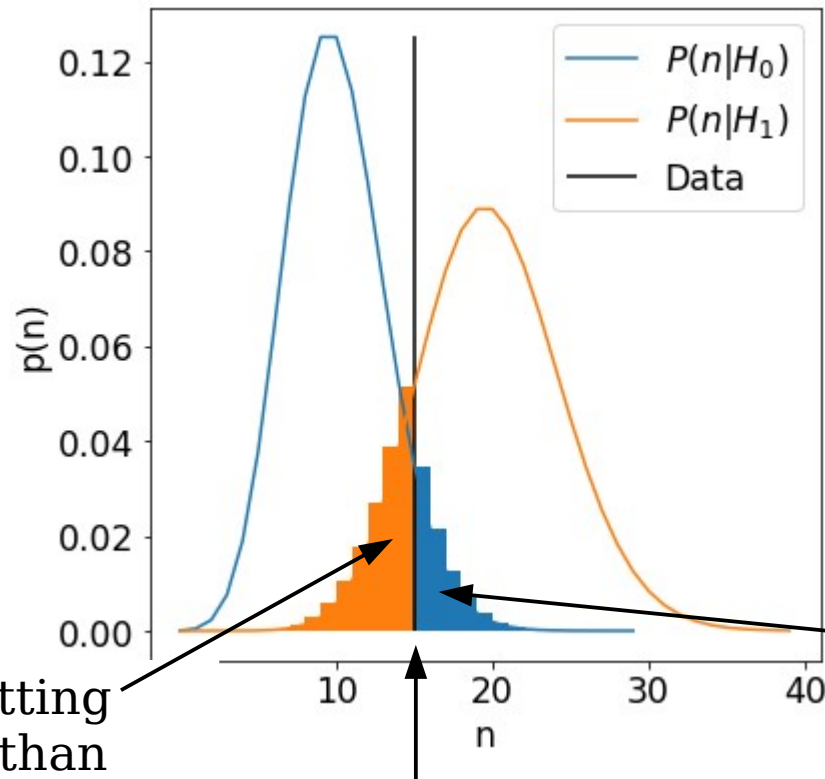
$$P(x|H_1)$$

**Question:** can we reject  $H_0$  given the observed experiment outcome?



## Definitions:

- $\alpha$  (Type I error) – probability of rejecting  $H_0$  when it is true.  $\alpha$  is called a **significance of the test**.
- $\beta$  (Type II error) – probability of accepting  $H_0$  when it is false



$\alpha$  - probability of getting this, or more events than some threshold, when  $H_0$  when is true

$\beta$  - probability of getting this, or less events than some threshold, when  $H_1$  when is true

the decision threshold

## Optimization task:

- minimize  $\beta$  (Type II error) for given value of  $\alpha$  (Type I error)

## Solution:

- do not look at observable (e.g. event count) p.d.f, but at the p.d.f for the observable likelihood ratio:

$$\lambda = \frac{\mathcal{L}(x_0|H_0)}{\mathcal{L}(x_0|H_1)}$$

- or more computationally convenient:

$$t = -2 \ln \frac{\mathcal{L}(x_0|H_0)}{\mathcal{L}(x_0|H_1)}$$



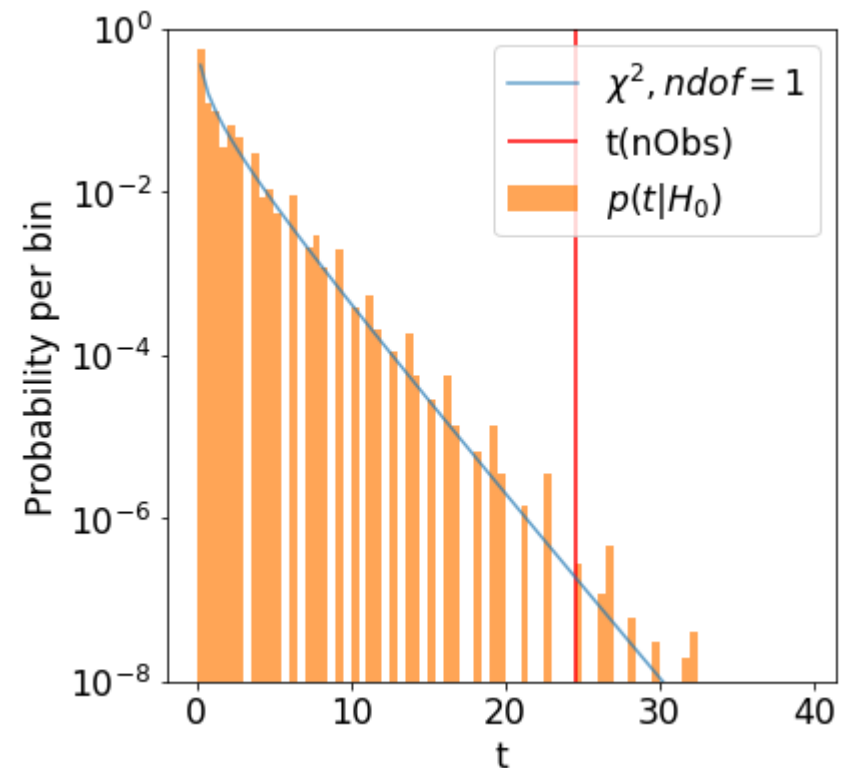
## Algorithm:

- choose the  $\alpha$  value (Type I error) **before** the experiment.
- calculate the likelihood ratio distribution, and find  $t_0$ :

$$t_0 : \int_{t_0}^{\infty} P(t|H_0) dt = \alpha$$

(luckily, often the distribution of  $t$  can be approximated by Gaussian distribution, and one can use analytical approximations)

- look at the data, and calculate  $t_{\text{DATA}}$
- reject  $H_0$  if  $t_{\text{DATA}} > t_0$



**Wilks theorem:** in the limit of large amount of data the likelihood ratio for data drawn from  $H_0$  model approaches the  $\chi^2$  distribution with number of degrees of freedom (“dof”, or “ndof”) equal to difference of number of free parameters in  $H_0$  and  $H_1$ :

$$P(t|H_0) \rightarrow \chi^2_{dof H_1 - dof H_0}$$

If there is only one free parameter (e.g. the number of signal events,  $S$ ) we have:

$$P(t|H_0) \rightarrow \chi^2_1$$

$$p_0 = \int_{t_{obs}}^{\infty} P(t|H_0) dt = 2(1 - \Phi(\sqrt{t_{obs}}))$$

↑  
often called  
p-value

↑  
Gaussian  
cumulative  
probability  
function (cdf)

The  $t$  variable is sensitive for both up- and downward fluctuations. In case of looking for a new signal, one is interested only in additional events on top of known background. In that case a modified variable is better:

$$q_0 = \begin{cases} -2 \ln \frac{\mathcal{L}(x_0 | H_0 = B)}{\mathcal{L}(x_0 | H_1 = \hat{S} + B)} & \hat{S} > 0 \\ 0 & \hat{S} < 0 \end{cases}$$

data best fit  $S$   
estimate

$$p_0 = \int_{q_0, obs}^{\infty} P(q | H_0) dt = 1 - \Phi(\sqrt{q_0, obs})$$

Gaussian  
cumulative  
probability  
function (cdf)

$$z = \Phi^{-1}(1 - p_0) = \sqrt{q_0}$$

Number of single  
sided Gaussian sigma  
corresponding to  $p_0$

## Poisson case:

$H_0$  - expected number of events is  $B$

$H_1$  - expected number of events is  $\mu_{H_1}$  - the data best fit value:  $\mu_{H_1} = nObs$

$$q_0(nObs) = -2 \ln \frac{\mathcal{L}(x_0|H_0)}{\mathcal{L}(x_0|H_1)} = -2 \ln \left( \frac{B^{nObs} e^{-B}}{nObs!} \bigg/ \frac{(\mu_{H_1})^{nObs} e^{-\mu_{H_1}}}{nObs!} \right) =$$

$$-2 \ln \left( \frac{B^{nObs}}{(nObs)^{nObs}} e^{-B+nObs} \right) = -2 [nObs (\ln(B) - \ln(nObs)) + nObs - B] =$$

$$2 [nObs (\ln(nObs) - \ln(B)) + B - nObs]$$

- if  $B$  is known, then  $S = nObs - B$
- if we plan an experiment for some known  $S$  and  $B$ , then expected  $nObs = S + B$

$$z \simeq \sqrt{q_0} = \sqrt{2[nObs[\ln(nObs) - \ln(B)] + B - nObs]} = |nObs = S + B| =$$

$$= \sqrt{2[(S+B)\ln(\frac{S+B}{B}) + B - B - S]} = \sqrt{2[(S+B)\ln(1+\frac{S}{B}) - S]} =$$

$$\sqrt{2[B(1+\frac{S}{B})\ln(1+\frac{S}{B}) - B\frac{S}{B}]} \simeq |x = \frac{S}{B}, S \ll B \rightarrow x \ll 1| \simeq$$

$$\sqrt{2B[(1+x)\log(1+x) - x]} \simeq \sqrt{2B[(1+x)(x - \frac{x^2}{2}) - x]} \simeq |\text{terms up to } x^2|$$

$$\sqrt{2B[x - \frac{x^2}{2} + x^2 - x]} = \sqrt{2B[\frac{x^2}{2}]} = \sqrt{\frac{S^2}{B}} = \frac{S}{\sqrt{B}}$$

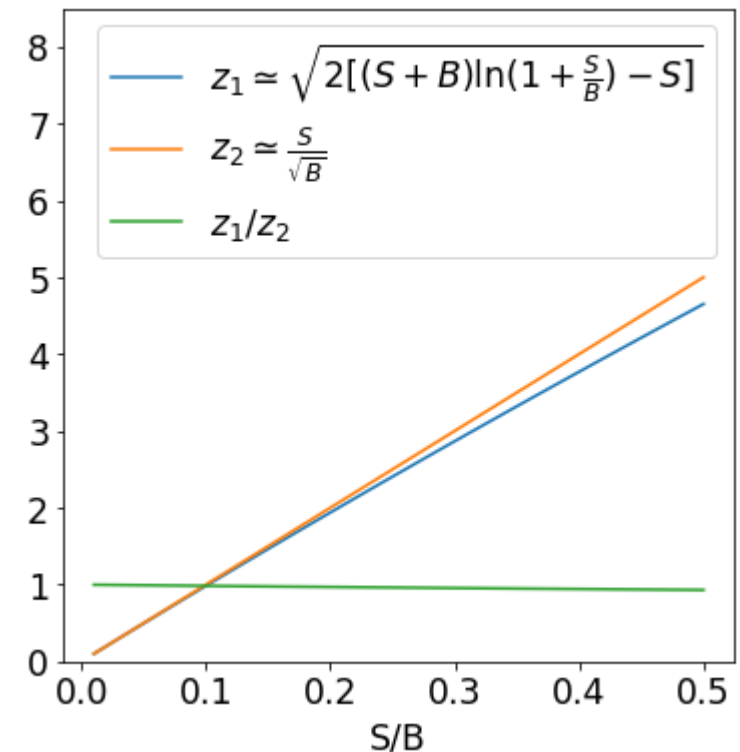
• large amount of data:  $z \simeq \sqrt{q_0} = \sqrt{2[nObs[\ln(nObs) - \ln(B)] + B - nObs]}$

• in addition  $S \ll B$ :  $z \simeq \frac{S}{\sqrt{B}}$

A dataset for which the best fit values reproduce the assumed values, e.g  $S_{\text{best fit}} = S$  is called

**“Asimov dataset”**

Similarly putting  $nObs = S + B$  is called using Asimov values for observation.



## Discovery:

$H_0$  – background only hypothesis (B)

$H_1$  – best fit signal + background hypothesis ( $\hat{S}+B$ )

test statistics -  $q_0$

Usual significance of the test: **“ $5\sigma$ ” -  $\alpha = 2.87 \cdot 10^{-7}$**

## Exclusion:

$H_0$  – nominal signal+background hypothesis (S+B)

$H_1$  – best fit signal +background hypothesis ( $\hat{S}+B$ )

test statistics -  $q_\mu$

Usual significance of the test: **“95 CL” -  $\alpha = 0.05$**

**Discovery:**

$$q_0 = \begin{cases} -2 \ln \frac{\mathcal{L}(x_0 | H_0 = B)}{\mathcal{L}(x_0 | H_1 = \hat{S} + B)} & \hat{S} > 0 \\ 0 & \hat{S} < 0 \end{cases}$$

**Exclusion:**

$$q_\mu = \begin{cases} -2 \ln \frac{\mathcal{L}(x_0 | H_0 = S + B)}{\mathcal{L}(x_0 | H_1 = \hat{S} + B)} & \hat{S} < S \\ 0 & \hat{S} > S \end{cases}$$

**Important:**

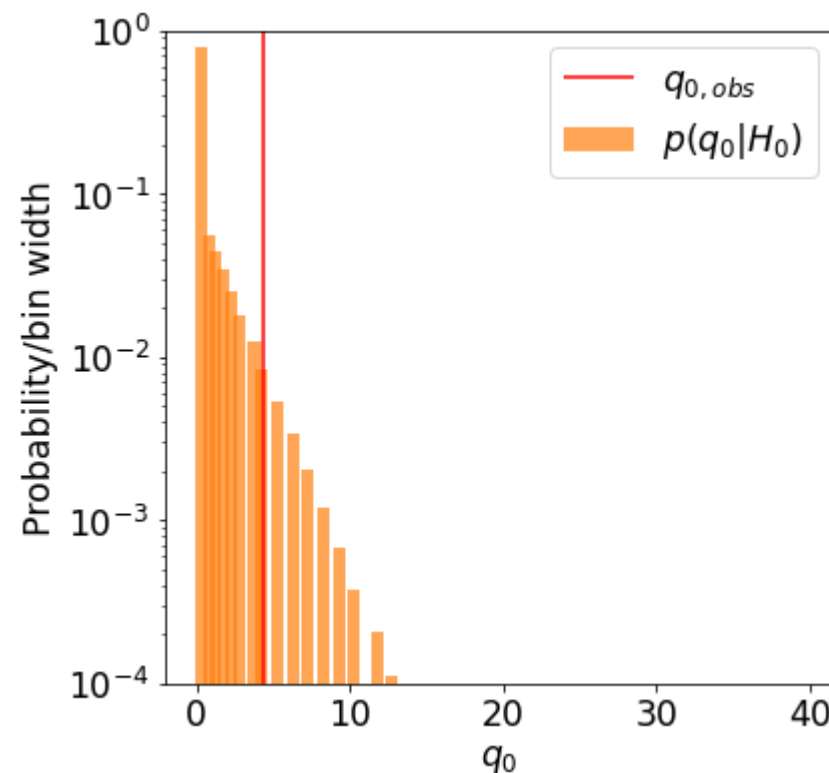
$\hat{S}$  is the best fit S value to the observed data!



## Assumptions and observations:

$$\alpha = 2.87 \cdot 10^{-7}, B = 20, N_{\text{data}} = 30$$

$$S_{\text{best fit}} = 10$$



## Can we reject the null hypothesis?

`q0_Obs: 4.33`

`MC estimate for  $p(q_0 > q_{0\_Obs})$ : 1.35E-02, single sided Gaussian sigma: 2.2`

`Gauss estimate for  $p(q_0 > q_{0\_Obs})$ : 1.87E-02, single sided Gaussian sigma: 2.1`

`alpha: 2.87E-07`

`Null hypothesis (B only) is NOT REJECTED`

## Assumptions:

$$\alpha = 2.87 \cdot 10^{-7}, B = 20, S = 10$$

**What would be significance for the nominal S?**

$$z \simeq \sqrt{q_0}, \quad q_{0,Asimov} = q_0(nObs = S + B)$$

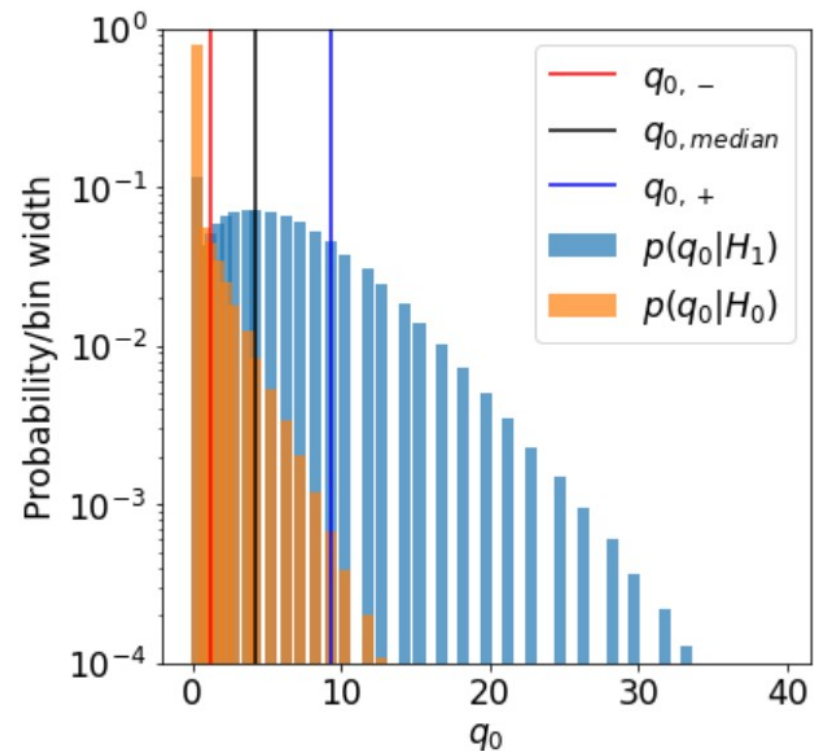
## What would we observe in experiment?

$q_0$  values fluctuate according to number of observed events (assuming S+B), so we define:

$q_{0,median}$  – 50% of experiments will observe this or greater value

$q_{0,-}$  – 84% of experiments will observe this or greater value

$q_{0,+}$  – 16% of experiments will observe this or greater value



## What significance of planned experiment we can expect?

Take the  $q_{0,-/median/+}$  values calculated for S+B data, and check  $p(q_{0,-/median/+} > t)$  assuming  $H_0$  (B only)

`q0 median from Asimov dataset = 4.33`

`MC estimate for p(q0>q0_Asimov) under H1: 4.52E-01 (expected: 0.50)`

`q0 minus = 1.25, q0 median = 4.25, q0 plus = 9.25`

`MC estimate for p(q0>q0_minus) under H1: 7.93E-01 (expected: 0.84)`

`MC estimate for p(q0>q0_median) under H1: 4.52E-01 (expected: 0.50)`

`MC estimate for p(q0>q0_plus) under H1: 1.57E-01 (expected: 0.16)`

<code>Gauss estimate for p(q0&gt;q0_minus):</code>	<code>1.32E-01,</code>	<code>single sided Gaussian sigma:</code>	<code>1.1</code>
<code>Gauss estimate for p(q0&gt;q0_median):</code>	<code>1.96E-02,</code>	<code>single sided Gaussian sigma:</code>	<code>2.1</code>
<code>Gauss estimate for p(q0&gt;q0_Asimov):</code>	<code>1.87E-02,</code>	<code>single sided Gaussian sigma:</code>	<code>2.1</code>
<code>Gauss estimate for p(q0&gt;q0_plus):</code>	<code>1.18E-03,</code>	<code>single sided Gaussian sigma:</code>	<code>3.0</code>

## Assumptions:

$$\alpha = 0.05, B = 200$$

**What minimal number of signal events can be rejected for 50% of hypothetical experiments?**

Expected answer:

Expected median exclusion on  $S = 25$

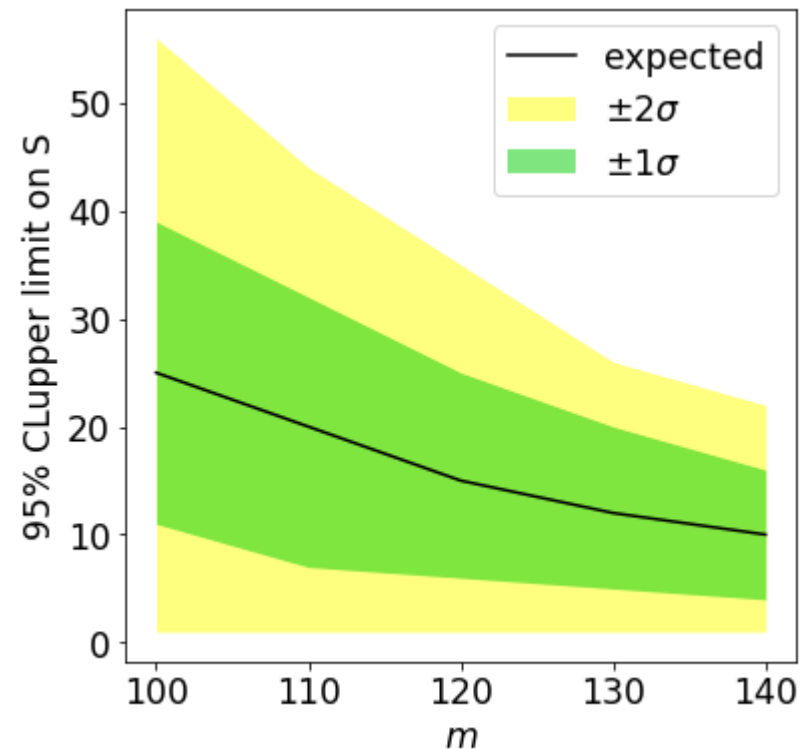
## Assumptions:

- experiment is looking for a particle of unknown mass:  $100 < m_x < 150$
- expected background is:  $B(m_x) = 200 \cdot e^{-(X-100)/20}$

## Task:

Plot excluded number of signal events for 97.6%, 84%, 50%, 16% 2.4% of experiments, as a function of  $m_x$

## Expected result:



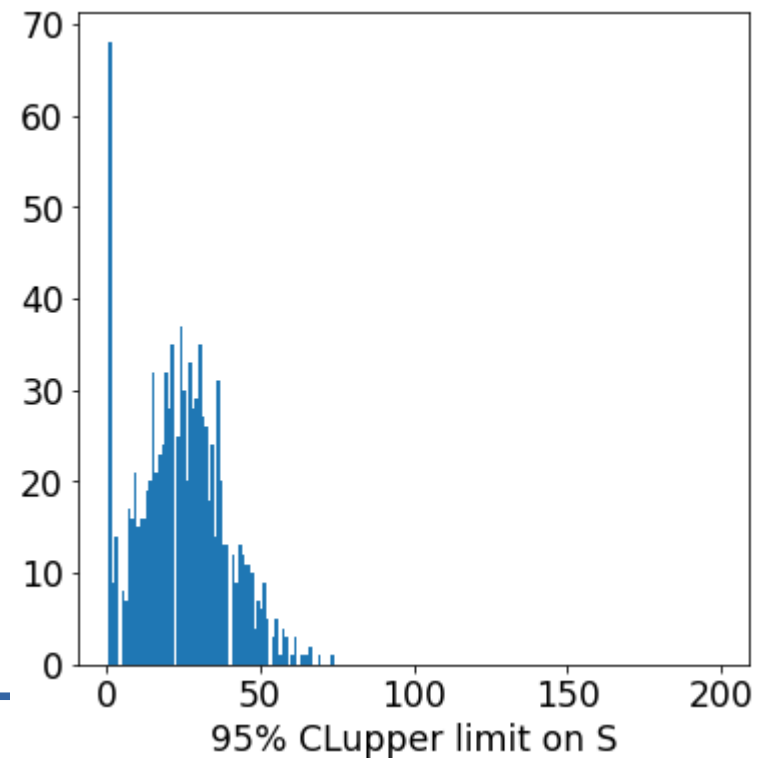
## Hints:

- generate 1000 pseudo experiments according to  $H_1$  - the number of observed events in each pseudo experiment follows  $\text{Poisson}(B)$
- for each pseudo experiment test many  $S$  hypotheses, until  $S$  is excluded.

The upper limit should be calculated using  $H_0 = S + B$ ,

where **B is the nominal B**

- create a histogram of excluded  $S$  values
- from histogram find the  $\pm 2\sigma$ ,  $\pm 1\sigma$  and median values of  $S$



## **Review articles of probability and statistics on PDG portal:**

- *The Review of Particle Physics*

## **Lectures on Statistics:**

- B. Cousins, *Lectures on Statistics: in Theory: Prelude to Statistics in Practice*

## **More details on asymptotic formulas:**

- G. Cowan, et al, *Asymptotic formulae for likelihood-based tests of new physics*



- Bayesian: **probability = a subjective degree of belief**
  - one **can talk** about probability of whatever, since this is your degree of belief that given statement is true
  - can be coherent between different people, give rigid prescription of assigning the probability

Bayesian reasoning usually uses the Bayes theorem:

$$P(B|A) = \frac{P(A|B)P(B)}{P(A)}$$

posterior probability  $\nearrow$   $P(B|A)$   $\nwarrow$  prior probability