

Orientation Sensor

Non-Visible component

Category	Requires	Version
Sensors	API 19, Android 4.4 - 4.4.4 KitKat	2

Overview

Non-visible component providing information about the device's physical orientation in three dimensions:

- **Roll:** 0 degrees when the device is level, increases to 90 degrees as the device is tilted up on its left side, and decreases to -90 degrees when the device is tilted up on its right side.
- **Pitch:** 0 degrees when the device is level, up to 90 degrees as the device is tilted so its top is pointing down, up to 180 degrees as it gets turned over. Similarly, as the device is tilted so its bottom points down, pitch decreases to -90 degrees, then further decreases to -180 degrees as it gets turned all the way over.
- **Azimuth:** 0 degrees when the top of the device is pointing north, 90 degrees when it is pointing east, 180 degrees when it is pointing south, 270 degrees when it is pointing west, etc.

These measurements assume that the device itself is not moving.

Events

Orientation Changed

Default OrientationChanged event handler

This event is signalled when the device's orientation has changed. It reports the new values of azimuth, pitch, and roll, and it also sets the Azimuth, Pitch, and roll properties.

Azimuth is the compass heading in degrees, pitch indicates how the device is tilted from top to bottom, and roll indicates how much the device is tilted from side to side.

Params	
azimuth	Number
pitch	Number
roll	Number

Properties

Angle

Number — Read - Blocks

Angle property getter method (read-only property). Specifically, this provides the angle in which the orientation sensor is tilted, treating

Available

Boolean — Read - Blocks

Available property getter method (read-only property).

Azimuth

Number — Read - Blocks

Azimuth property getter method (read-only property)

To return meaningful values the sensor must be enabled.

Enabled

Boolean — Default: *True* — Read Write - Designer Blocks

Enabled property getter method.

Magnitude

Number — Read - Blocks

Magnitude property getter method (read-only property). Specifically, this returns a number between 0 and 1, indicating how much the device is tilted. For the angle of tilt, use

Pitch

Number — Read - Blocks

Pitch property getter method (read-only property)

To return meaningful values the sensor must be enabled.

Roll

Number — Read - Blocks

Roll property getter method (read-only property)

To return meaningful values the sensor must be enabled.