Algorithms and Complexity, weeks 1-5 key points

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March 9, 2021

Turing machine basics I

- Turing machines are precise models of computation
- First tape of a Turing machine is always a read-only input tape.
- ▶ The k^{th} tape is always the output tape
- The output tape is also considered a work tape
- The alphabet of a TM is denoted as Γ, it is finite.
- ► Each tape must always start with the left-of-tape symbol, >
- ▶ $\{0,1\}^*$ is the set of bitstrings, with ε denoting the empty string.

Turing machine basics II

In a single stage of computation a TM may:

- reads the character at each tape head
- writes a character at each work tape head
- may move each tape head to the left or to the right. note: our tapes are not recursive, if a head on the leftmost cell moves left, it stays put

what does it mean to say that M computes f?

It means that for every bitstring $x \in \{0,1\}^*$, if we start in state $q_{\mathtt{start}}$ with the initial configuration showing x (meaning x appears on the input tape and and the work tapes are blank), when we run M, we eventually reach $q_{\mathtt{halt}}$ with the output tape showing \triangleright on the leftmost cell and then the bitstring f(x) followed by all blanks.

Computable functions

Basics

Definition

(Computable functions) We say a function $f:\{0,1\}^* \to \{0,1\}^*$ is **computable** if there exists some Turing machine that computes it and **non-computable** if there isn't.

No variation of Turing machine affects this fact, giving us:

Thesis

(Church's Thesis) any algorithm that computes a function from bitstrings to bitstrings can be converted into a Turing machine that computes the same function

Boolean functions, languages and decidability I

Definition

A language can be defined as any set of words

Definition

A **boolean function** is a function of the form:

 $f:\{0,1\}^* \to \{0,1\}$. Noting that the output is a single bit rather than a bitstring.

There is a one-to-one correspondence between languages and boolean functions.

- For a given boolean function f the corresponding language is the set of bitstrings x s.t. f(x) = 1
- For a language L, the corresponding boolean function sends x to 1 if $x \in L$ and to 0 otherwise.

Boolean functions, languages and decidability II

This allows us to treat boolean functions, languages and decision problems as essentially the same thing.

A decision problem is said to be **decidable** when the corresponding boolean function is **computable**. I.e. given a language L, for L to be decidable there must exist some Turing machine that will start with a bitstring x and will run continuously until it halts and upon halting there will be a 1 on the output tape if $x \in L$ or 0 if it is not in the language.

Data Representation

- ▶ We can encode many real-life data types as bitstrings, but not all. (e.g. Real numbers cannot)
- We can encode multiple inputs as a single bitstring.

Code as Data

- ▶ We can not only encode many data types as bitstrings, we can encode program code or even other Turing machines as bitstring inputs to a TM as our TMs are essentially 6-tuples (see full notes for formal definition).
- We can therefore say that for **any** bitstring α we can construct a corresponding TM: M_{α}

The Universal Turing Machine, \mathcal{U}

 $\mathcal U$ is a Turing machine interpreter written as a Turing machine. It takes 2 inputs (encoded as a single input): α and x, where α is the bitstring describing the machine to be interpreted and x is the bistring input.

We define $\mathcal U$ as having 4 tapes and the basic alphabet of $\{\rhd,\Box,0,1\}$. Intuitively, $\mathcal U$ works by simulating the M_α by providing it with the 3 non-input tapes to M_α as its input, work and output tape respectively.

Diagonalisation & the Halting problem I

Problem

(The halting problem) the set of pairs $\langle \alpha, x \rangle$ (encoded as a single bitstring) such that the machine M_{α} executed on input x halts.

Diagonalisation & the Halting problem II

Turing's proof is as follows:

Proof.

Suppose that N is a machine that solves the halting problem.

We can convert it into a machine N' that, given x, runs forever if $\langle x, x \rangle \in \mathtt{HALT}$ (i.e. the machine M_x executed on x halts), and halts otherwise.

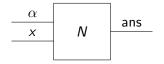
We know $N'=M_{\alpha}$ for some α , i.e. there exists some bitstring α that represents our new machine, as we know every machine can be represented as a bitstring.

Running N' on α halts if it runs forever and runs forever if it halts. We have derived a contradiction.



Diagonalisation & the Halting problem III

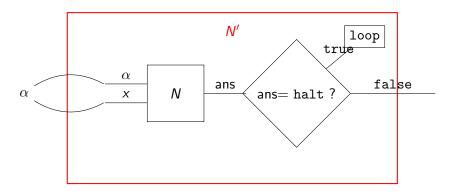
More intuitively, we can consider the described machine N as:



Where ans is whether N halts.

We can then construct the wrapper N' as:

Diagonalisation & the Halting problem IV



Where the outermost α is the bitstring of N'

You can clearly see that if N were to halt then N' would hang. We can therefore derive a contradiction as if we pass N' into N' it would have to half if it hangs and vice versa!

Upper bound notation

- ▶ If we have two function $f : \mathbb{N} \to \mathbb{N}$ and $g : \mathbb{N} \to \mathbb{N}$
- ▶ We say that f(n) is O(g(n)) is f is **no bigger** than g up to a constant factor, i.e. given a constant c and a value n_0 s.t. $\forall n, n \geq n_0$ we have:

$$f(n) \leq c \cdot g(n)$$

▶ We say that f(n) is o(g(n)) if f is **not** as **big** as g, even up to any constant factor. Or, if, **for** any $\varepsilon > 0$, there is a n_0 s.t. $\forall n, n \ge n_0$ we have:

$$f(n) \leq \varepsilon \cdot g(n)$$

Whenever f(n) is o(g(n)) is it also O(g(n)), this is the case if you take c to be 1



Lower bound notation

- ▶ If we have two function $f : \mathbb{N} \to \mathbb{N}$ and $g : \mathbb{N} \to \mathbb{N}$
- ▶ We say that f(n) is $\Omega(g(n))$ when g(n) is O(f(n))
- ▶ We say that f(n) is $\omega(g(n))$ when g(n) is o(f(n))
- ▶ We say that f(n) is $\Theta(g(n))$ when it is **both** O(g(n)) and $\Omega(g(n))$

This informally means f(n) and g(n) are the same, up to a constant factor

Time complexity

Definition

Worst case running time:

The running time of a machine M is the time taken from the input state, where x sits on the input tape and the other tapes are blank, to reach the halt state (q_{halt}) .

For any number n, we define $WT_M(n)$ to be the **worst case** running time for an input of length n.

Definition

DTIME classes

DTIME is a set of complexity classes.

A complexity class can be thought of as a set of decision problems (or languages or boolean functions...)

DTIME(n^2) is an example of a complexity class. A function $f:\{0,1\}^* \to \{0,1\}$ is in DTIME(n^2) when there is some machine that decides it and has worst case running time in $O(n^2)$

Polynomial Time

We can define the complexity (super) class of **polynomial time decision problems** as:

$$P \stackrel{\mathsf{def}}{=} \bigcup_{k>1} \mathsf{DTIME}(n^k)$$

From this definition, you can see that **any** decision problem in $\{\mathsf{DTIME}(n^k)\}_{k=0}^\infty$ is also in P