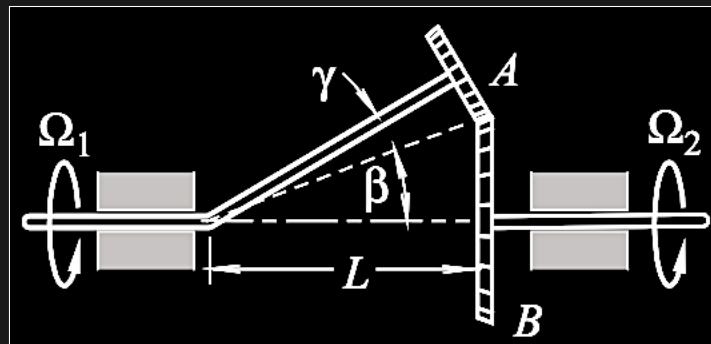


September 22, 2024

MODULE 4 — Assignment

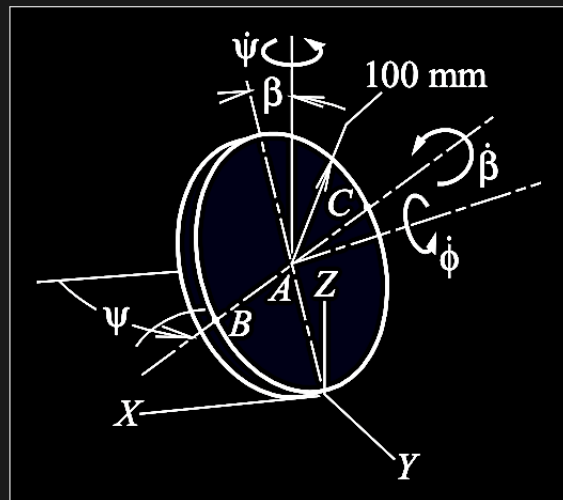
EXERCISE 4.39

Gear A spins relative to its shaft, which rotates at variable rate Ω_1 about the horizontal axis. Gear B rotates at the variable rate Ω_2 . Determine the angular velocity and angular acceleration of gear A.

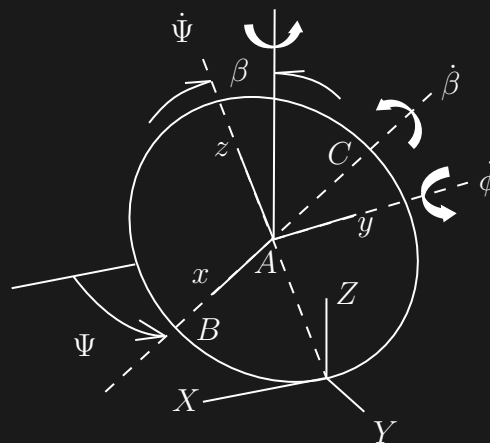


EXERCISE 4.44

The disk rolls without slipping over the horizontal XY plane. At the instant when $\beta = 36.87^\circ$, the X and Y components of the velocity of point B on the horizontal diameter of the disk are 8 m/s and -4 m/s, respectively, and the corresponding velocity components of center A at this instant are 4 m/s and 2 m/s. Determine the precession angle Ψ between the horizontal diameter BAC and the X axis, and also evaluate the precession, nutation, and spin rates.



In the following sketch, we will define two coordinate frames, $\{XYZ\}$ and $\{xyz\}$:



The transformation to convert $\{XYZ\}$ to $\{xyz\}$ is:

$$\begin{aligned}
 R &= \begin{bmatrix} \cos(\Psi) & -\sin(\Psi) & 0 \\ \sin(\Psi) & \cos(\Psi) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos(\beta) & -\sin(\beta) \\ 0 & \sin(\beta) & \cos(\beta) \end{bmatrix} \\
 &= \begin{bmatrix} \cos(\Psi) & -\sin(\Psi) \cos(\beta) & \sin(\Psi) \sin(\beta) \\ \sin(\Psi) & \cos(\Psi) \cos(\beta) & -\cos(\Psi) \sin(\beta) \\ 0 & \sin(\beta) & \cos(\beta) \end{bmatrix}
 \end{aligned}$$

From this we see that:

$$\begin{aligned}
 \bar{i} &= \begin{bmatrix} \cos(\Psi) \bar{I} \\ \sin(\Psi) \bar{J} \end{bmatrix} \\
 \bar{j} &= \begin{bmatrix} -\sin(\Psi) \cos(\beta) \bar{I} \\ \cos(\Psi) \cos(\beta) \bar{J} \\ \sin(\beta) \bar{K} \end{bmatrix} \\
 \bar{k} &= \begin{bmatrix} \sin(\Psi) \sin(\beta) \bar{I} \\ -\cos(\Psi) \sin(\beta) \bar{J} \\ \cos(\beta) \bar{K} \end{bmatrix}
 \end{aligned}$$

Submitted by Austin Barrilleaux on September 22, 2024.