

## 2 Point Estimation for Parametric Families of Probability Distributions

### 2.1 Parametric Families

We now shift gears to discuss the statistical idea of point estimation. We will be consider the problem of *parametric* point estimation, so we will first need to understand what is a parametric family of probability distributions.

Here a *parameter space*  $\Theta$  will be a subset of  $\mathbb{R}^k$  for some  $k$ .

**Definition 2.** A *parametric* family of probability distributions is a collection of probability density functions (or probability mass functions) on  $\mathbb{R}^n$  indexed by the parameter space  $\Theta$ , that is, a collection of densities of the form  $\{f(x; \theta) : \theta \in \Theta\}$ .

Given a parametric family, each  $\theta \in \Theta$  uniquely specifies a probability density function  $f(x; \theta)$ .

**Example 1 (Normal family).** The family of normal probability densities has parameter space  $\Theta = \mathbb{R} \times (0, \infty)$ . In this case, the parameter is the ordered pair  $\theta = (\mu, \sigma^2)$ , and the density specified by  $\theta$  is (in the case of an i.i.d. sample  $(X_1, \dots, X_n)$  of size  $n$ )

$$f(x; \mu, \sigma^2) = \frac{1}{(2\pi\sigma^2)^{n/2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2}.$$

Suppose that the distribution of the random vector  $\mathbf{X}$  has a density belonging to a parametric family, that is,  $\mathbf{X} \sim f(x; \theta)$  for some  $\theta \in \Theta$ . Given a function  $g : \mathbb{R}^n \rightarrow \mathbb{R}$ , we write  $E_\theta(g(\mathbf{X}))$  to indicate that we are taking an expectation with respect to the density  $f(\mathbf{x}; \theta)$ . Similarly, we write  $P_\theta(\mathbf{X} \in A)$  to indicate we are computing a probability using the density  $f(\mathbf{x}; \theta)$ . To be precise,

$$P_\theta(\mathbf{X} \in A) = \int_A f(\mathbf{x}; \theta) d\mathbf{x}$$
$$E_\theta(g(\mathbf{X})) = \int_{\mathbb{R}^n} g(\mathbf{x}) f(\mathbf{x}; \theta) d\mathbf{x}.$$

A parametric family can have more than one parameterization. For example, we can parameterize the exponential family by

$$\mu \mapsto \frac{1}{\mu} e^{-x/\mu} \mathbf{1}\{x \geq 0\}, \quad \mu > 0.$$

Alternatively, it is sometimes parameterized by

$$\lambda \mapsto \lambda e^{-\lambda x} \mathbf{1}\{x \geq 0\}, \quad \lambda > 0.$$

When we talk about a parametric family of probability distributions, we should be sure to specify explicitly which parameterization we are using.

## 2.2 Statistical Inference

The problem of parametric statistical inference is the following: We observe data  $\mathbf{X} = (X_1, \dots, X_n)$  which has a joint density belonging to some parametric family  $\{f(x; \theta) : \theta \in \Theta\}$ . More exactly, the joint density of  $\mathbf{X}$  is  $f(x; \theta_0)$ , where  $\theta_0 \in \Theta$ . We often say that  $\theta_0$  is the “true” parameter value, in that the observed random variables in fact came from a distribution having density  $f(x; \theta_0)$ . The situation is that *we do not know the value of  $\theta_0$* , but we would like to *infer* information about  $\theta_0$ , based on  $\mathbf{X}$ .

It is intuitively clear that the data  $\mathbf{X}$  contains information about the value of  $\theta_0$ . An illustrative example is the following:

**Example 2.** Let  $\mathbf{X} = (X_1, \dots, X_n)$  be an i.i.d. sample from a uniform random variable on the interval  $[\theta_0, \theta_0 + 1]$ . Thus, we have the family of densities

$$\begin{aligned} f(\mathbf{x}; \theta) &= \prod_{i=1}^n \mathbf{1}\{\theta \leq x_i \leq \theta + 1\} \\ &= \mathbf{1}\left\{\theta \leq \min_{1 \leq i \leq n} x_i \leq \max_{1 \leq i \leq n} x_i \leq \theta + 1\right\}, \end{aligned}$$

where  $\theta \in \mathbb{R}$ . If we observe  $\min_{1 \leq i \leq n} X_i = a$  and  $\max_{1 \leq i \leq n} X_i = b$ , then it must be that  $\theta_0 < a < b < \theta_0 + 1$ . In particular,  $b - 1 < \theta_0 < a$ , and we have narrowed down the possible values of  $\theta_0$  to those in an interval of length at most 1.

## 2.3 Point Estimation Set-Up

In the context of point estimation, we may be interested in a function  $\tau : \Theta \rightarrow \mathbb{R}^p$ , and we wish to know  $\tau(\theta_0)$ . Again, we want to make an *estimate* of  $\tau(\theta_0)$  based on  $\mathbf{X}$ .

The notion of a *statistic* is elementary, but must be stated:

**Definition 3.** A *statistic* is a random variable  $T$  so that  $T = t(X_1, X_2, \dots, X_n)$  for some function  $t : \mathbb{R}^n \rightarrow \mathbb{R}^m$ .

Thus a statistic is any random variable which is a function of the sample  $(X_1, \dots, X_n)$ .

**Definition 4.** An *estimator* is any statistic  $T$  which is used to estimate the fixed vector  $\tau(\theta_0)$ . If we observe  $(X_1, \dots, X_n) = (x_1, \dots, x_n)$  for a (non-random) vector  $\mathbf{x} = (x_1, \dots, x_n)$ , then the value  $t(\mathbf{x})$  is an *estimate* of  $\tau(\theta_0)$  when  $\mathbf{X} = \mathbf{x}$ .

Notice that there is not much to the definition of an estimator, as any stupid statistic can qualify. For example, the statistic  $T \stackrel{\text{def}}{=} 1$  which is always equal to 1 can be claimed to be an estimator of  $\mu$  in Example 1. It is, however, a stupid estimator and others are better.

## 2.4 Some criterion

We briefly mention here some criterion to decide if an estimator is good. We will not say much here, but will return to this topic at a later point.

We would like an estimator  $T$  to be, “on average” centered around the number we are trying to estimate,  $\tau(\theta_0)$ .

**Definition 5.** An estimator  $T$  of  $\tau(\theta_0)$  is called *unbiased* for  $\tau(\theta_0)$  if

$$E_{\theta_0}(T) = \tau(\theta_0) \quad \forall \theta_0 \in \Theta. \quad (1)$$

We now suppose that for each  $n$ , we have a parametric family of densities  $\{f(x_1, \dots, x_n; \theta) : \theta \in \Theta\}$ , where the parameter space  $\Theta$  does not depend on  $n$ . This is the case when  $(X_1, \dots, X_n)$  is an i.i.d. sample from a parametric family of distributions on  $\mathbb{R}$ . The following definition applies in this situation.

**Definition 6.** Suppose that we have a sequence of estimators  $\{T_n\}_{n=1}^\infty$ , where  $T_n$  is an estimator based on a sample of size  $n$ . Then the sequence  $\{T_n\}$  is *consistent* of  $\tau(\theta_0)$  if  $T_n \xrightarrow{\text{Pr}} \tau(\theta_0)$  for all  $\theta_0 \in \Theta$ .

**Example 3.** Suppose that  $X_1, X_2, \dots, X_n$  is a random sample from a parametric family on  $\mathbb{R}$ . Suppose that for each  $\theta$ , the density  $f(x; \theta)$  has finite variance. Consider the function of  $\theta$  given by

$$\tau(\theta) = E_\theta(X_1) .$$

We note that this is indeed a function of  $\theta$ . Since the distribution of  $X_1$  has density  $f(x; \theta)$ , the expectation of  $X_1$  depends on  $\theta$ . By the Weak Law of Large Numbers, we have that

$$\frac{1}{n} \sum_{i=1}^n X_i \xrightarrow{\text{Pr}} \tau(\theta) ,$$

and so the sequence of estimators  $T_n \stackrel{\text{def}}{=} n^{-1} \sum_{i=1}^n X_i$  is consistent for  $\tau(\theta)$ .

We will return to these properties later.