Using the telemetr package

August 3, 2012

Testing With Random Data

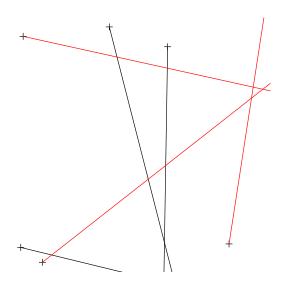
First we'll generate some random data. For each of two animals we'll get three bearings on a single day.

```
> set.seed(999)
> library(telemetr)
> library(ggplot2)
> m = telemetr:::makeMoreTriData(ntowers=3,animals=letters[1:2],dates=Sys.Date())
> summary(m)
Object of class SpatialPointsDataFrame
Coordinates:
    min
          max
x 0.0947 0.787
y 0.0700 0.853
Is projected: NA
proj4string : [NA]
Number of points: 6
Data attributes:
animal
                             thetaTrue
                                               bearing
                                                                theta
              :2012-08-03 Min. :-1.538
                                          Min. : 8.76 Min.
a:3
                                                                   :0.666
       Min.
       1st Qu.:2012-08-03 1st Qu.:-1.029
                                            1st Qu.: 64.51
                                                            1st Qu.:2.237
       Median :2012-08-03
                          Median :-0.152
                                            Median :103.06
                                                            Median :4.829
              :2012-08-03
                           Mean :-0.192
                                            Mean :102.22
       Mean
                                                           Mean
                                                                   :3.975
       3rd Qu.:2012-08-03
                           3rd Qu.: 0.469
                                            3rd Qu.:150.16
                                                            3rd Qu.:5.774
       Max.
              :2012-08-03
                          Max. : 1.336
                                            Max.
                                                   :180.93 Max. :6.066
```

We'll plot the bearings, colouring by animal:

```
> plot(m)
```

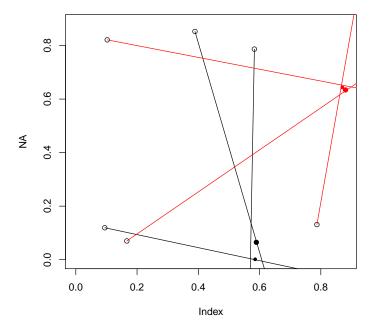
> telemetr:::drawVectors(~bearing|animal,m)



Now we locate using two methods:

```
> trmr = triang(~bearing|animal,m,method="rmr")
> tmle = triang(~bearing|animal,m,method="mle")

Next we plot the points and the location estimates:
> plot(NA,xlim=range(coordinates(m)[,1],coordinates(trmr[,1]),coordinates(tmle[,1])),
+ ylim=range(coordinates(m)[,2],coordinates(trmr[,2]),coordinates(tmle[,2])))
> points(m)
> telemetr:::drawVectors(~bearing|animal,m)
> points(trmr,pch=19,col=1:2)
> points(tmle,pch=20,col=1:2)
```



Testing with Lenth Data

The sample data from Lenth's Technometrics article was typed in and is available the samples folder. We read it in. One of the readings was used to test the robustness of the estimators, so we will add a flag column to the data. This table should be close to Lenth's table 1.

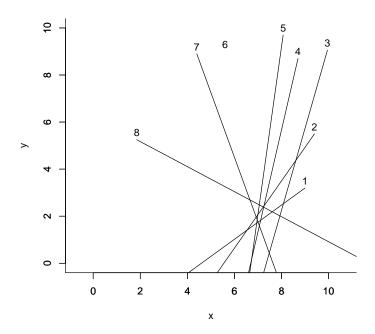
```
> lenth = read.table(system.file("samples","lenth.dat",package="telemetr"))
```

- > coordinates(lenth)=~x+y
- > lenth\$ok = 1
- > lenth\$ok[6]=0
- > lenth

```
coordinates bearing ok
1
      (9, 3.2)
                   234
    (9.4, 5.5)
                   215
                        1
 (9.95, 9.05)
                   196
                        1
    (8.7, 8.7)
                   193
                         1
5
   (8.07, 9.7)
                   188
      (5.6, 9)
                   250 0
    (4.4, 8.9)
                   160 1
8 (1.85, 5.25)
                   118 1
```

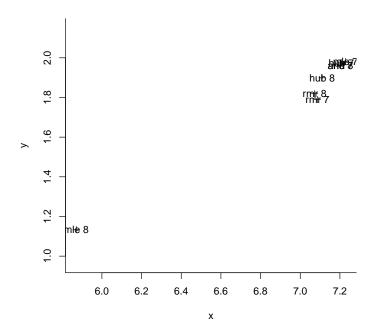
Now we loop over the methods and also whether to include the outlier or not. The resulting table should duplicate Lenth's table 2 once all the methods and error estimates are working:

```
> results = data.frame(method=NULL,x=NULL,y=NULL)
> for(subset in list(lenth$ok==1,TRUE)){
    for(method in c("mle", "hub", "and", "rmr")){
      tri = triang(~bearing,lenth,method=method,subset=subset)
      results=rbind(results,data.frame(
        npts=tri$npts,method=method,
        x=coordinates(tri)[,1],y=coordinates(tri)[,2]))
    }
+ }
> options(digits=3)
    results
   npts method
                 X
           mle 7.23 1.98
Х
x1
           hub 7.21 1.97
     7
          and 7.20 1.96
x2
xЗ
        rmr 7.09 1.79
x4
     8
         mle 5.87 1.13
x5
     8
          hub 7.11 1.90
           and 7.20 1.96
x6
      8
x7
           rmr 7.07 1.82
   Currently the point estimates are exact, or close to 1dp for most cases.
  The following plot emulates Lenth's figure 1:
> plot(coordinates(lenth),xlim=c(0,10),ylim=c(0,10),bty="1",type="n",asp=1)
> text(coordinates(lenth)[,1],coordinates(lenth)[,2]+.3,as.character(1:nrow(lenth)))
> axis(1)
> axis(2)
> drawVectors(~bearing,lenth,subset=lenth$ok==1)
```

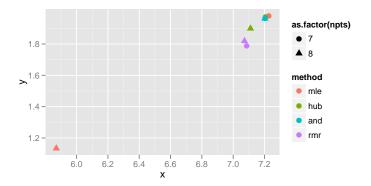


We can try and emulate Lenth's figure 3 but the labelling is problematic.

- > coordinates(results)=~x+y
- > plot(coordinates(results),type="n",asp=1,bty="1")
- > plot(results,add=TRUE)
- > text(coordinates(results),paste(results\$method,results\$npts))



Another option is to use ggplot to style the points:



Demo Data

Another batch of demo data was supplied with the Fortran source code. This consisted of a number of azimuths from three towers (although a tower location file with 8 towers was supplied, only three seem to be used in the data). This was converted into a spatial points data frame as azr in the package.

```
> data(azr)
> mlefits = triang(~bearing|animal,azr,method="mle")
> rmrfits = triang(~bearing|animal,azr,method="rmr")
> andfits = triang(~bearing|animal,azr,method="and")
> bb = bbox(rbind(coordinates(azr),
+ coordinates(mlefits),
+ coordinates(rmrfits),
+ coordinates(andfits)))
> par(mfrow=c(4,4))
> par(mar=c(0,0,2,0))
> colours=c("#1B9E77", "#D95F02", "#7570B3", "#E7298A")
> for(i in 17:32){
+ bb = bbox(rbind(coordinates(azr),coordinates(rmrfits[i,]),
+ coordinates(mlefits[i,]),coordinates(andfits[i,])))
```

```
plot(SpatialPoints(t(bb)),cex=0)
plot(azr[azr$animal==i,],add=TRUE)
drawVectors(~bearing|animal,azr,subset=azr$animal==i)
points(rmrfits[i,],pch=19,col=colours[1],cex=3)
points(mlefits[i,],pch=19,col=colours[2],cex=2)
points(andfits[i,],pch=19,col=colours[4],cex=1.5)
title(paste("Data ",i))
Data 17
                             Data 19
              Data 18
                                           Data 20
Data 21
              Data 22
                             Data 23
                                           Data 24
Data 25
              Data 26
                             Data 27
                                           Data 28
```

Data 30

Appendix

Data 29

On Finding the Source of a Signal Author(s): Russell V. Lenth Reviewed work(s): Source: Technometrics, Vol. 23, No. 2 (May, 1981), pp. 149-154

Data 31

Data 32