# The Rotor Field Hypothesis: Unifying Matter, Information, and Motion

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#### Abstract

We propose that all observable structures—space, matter, and coherent information processing—emerge from the dynamics of a universal rotor field defined in geometric algebra (GA). The fundamental object is a spatially distributed rotor  $\mathcal{R}(x,t) = \operatorname{Exp}(\mathcal{B}(x,t))$  whose bivector generator  $\mathcal{B}$  controls local orientation, phase, and coherent coupling. We show how classical mechanics, electromagnetism, quantum spinor dynamics, thermodynamic irreversibility, and learning systems appear as effective regimes of rotor coherence, transport, and symmetry breaking. We state falsifiable predictions (spectral sidebands in gravitational-wave events with precession; generalization gains of rotor-inductive priors in ML; compression gains on cyclic signals) and provide a reproducible program for experimental validation.

**Keywords:** geometric algebra, rotor fields, unification, coherence, emergent dynamics, information, machine learning

### 1 Introduction

Modern physics and computation rely on heterogeneous primitives (fields, particles, amplitudes, loss functions), while many universal phenomena—coherence, chirality, spin, oscillations, phase locking—share a common rotational character. We hypothesize that a single *rotor field* underlies these domains and that familiar theories are effective approximations of its dynamics.

#### Contributions.

- 1. Define the Rotor Field Hypothesis with precise GA notation and a minimal axiom set.
- 2. Derive known theories as emergent limits: classical mechanics (linearized rotor flow), electromagnetism (bivector field), quantum kinematics (spinor sector), thermodynamics (phase ensemble statistics), learning (self-organization under rotor coupling).
- 3. State falsifiable predictions and provide open, reproducible benchmarks.

## 2 The Rotor Field Hypothesis

#### 2.1 Kinematic postulates

Let physical space(-time) admit a GA with orthonormal basis  $\{e_{\mu}\}$  and metric of signature appropriate to the regime under study. The primitive entity is a rotor field

$$\mathcal{R}(x,t) = \operatorname{Exp}(\mathcal{B}(x,t)), \qquad \widetilde{\mathcal{R}}\mathcal{R} = 1,$$
 (1)

where  $\mathcal{B}(x,t)$  is a (local) bivector generating orientation and phase. Any multivector observable A is rotated by

$$A'(x,t) = \mathcal{R}(x,t) A(x,t) \widetilde{\mathcal{R}}(x,t). \tag{2}$$

**Definition 1** (Rotor density, phase, and curvature). Define (i) the rotor density  $\rho_R(x,t) := \langle \mathcal{B}^2 \rangle_0^{1/2}$ , (ii) the phase  $\phi$  by  $\mathcal{B} = \phi \hat{\mathcal{B}}$  with  $\hat{\mathcal{B}}^2 = -1$ , and (iii) the rotor curvature  $\mathcal{K} := \langle \nabla \wedge \mathcal{B} \rangle_2$ .

### 2.2 Dynamics

We postulate a local balance law for the bivector generator with transport, coupling, and source terms:

$$\nabla \mathcal{B} + \lambda \langle \mathcal{B} \nabla \rangle_2 = \mathcal{J} - \Gamma(\mathcal{B}), \tag{3}$$

where  $\lambda$  controls nonlinear advection,  $\mathcal{J}$  aggregates external couplings (matter, boundary driving), and  $\Gamma$  collects dissipative/decohering channels. The induced evolution of any rotated observable obeys

$$\partial_t A' = (\partial_t \mathcal{R}) A \widetilde{\mathcal{R}} + \mathcal{R} (\partial_t A) \widetilde{\mathcal{R}} + \mathcal{R} A (\partial_t \widetilde{\mathcal{R}}), \qquad (4)$$

with  $\partial_t \mathcal{R} = \frac{1}{2} \Omega \mathcal{R}$  for bivector rate  $\Omega := 2(\partial_t \mathcal{R}) \widetilde{\mathcal{R}}$ .

Remark 1. Eq. (3) is a unifying template. Specific identifications of  $\mathcal{B}$ ,  $\mathcal{J}$ , and  $\Gamma$  yield effective theories (Sections 4).

### 3 Mathematical Foundations

### 3.1 Geometric operations

We use the geometric product, with grade projections  $\langle \cdot \rangle_k$ , inner and outer products. Vector derivative  $\nabla := \sum_{\mu} \mathbf{e}_{\mu} \partial_{\mu}$  induces GA analogs of div/rot/grad. Reversion  $\tilde{\cdot}$  implements time-reversal for rotors.

## 3.2 Noether-type invariants

A rotor symmetry  $\mathcal{R} \mapsto S\mathcal{R}$  with constant S implies conserved currents. Let  $\mathcal{L}(\mathcal{B}, \nabla \mathcal{B})$  be a GA Lagrangian; stationarity yields Euler–Lagrange equations in multivector form and conserved quantities (energy-like scalars, momentum-like vectors, spin-like bivectors).

#### 3.3 Energy and coherence functionals

Define a local energy density and a coherence penalty,

$$\mathcal{E} := \alpha \left\langle (\nabla \mathcal{B})^2 \right\rangle_0 + \beta \left\langle \mathcal{B}^2 \right\rangle_0, \qquad \mathcal{C} := \gamma \left\langle (\nabla \wedge \mathcal{B})^2 \right\rangle_0, \tag{5}$$

balancing smooth transport and phase rigidity. Parameters  $(\alpha, \beta, \gamma)$  determine regimes (ordered/coherent vs. disordered/decoherent).

## 4 Emergent Phenomena

#### 4.1 Classical mechanics as linearized rotor flow

For small  $\|\mathcal{B}\|$ , write  $\mathcal{R} \approx 1 + \mathcal{B}/2$ . Linearizing (3) with suitable identification of  $\mathcal{J}$  yields Newtonian transport for vector observables; inertial frames correspond to uniform rotor flow. For a rigid body, the angular momentum bivector  $\mathbf{L} = I\mathcal{B}$  satisfies

$$\partial_t \mathbf{L} = \langle \mathcal{J} \rangle_2 \equiv \mathbf{\tau},\tag{6}$$

where the torque  $\tau$  is identified with the bivector flux  $\langle \mathcal{J} \rangle_2$ . In the rotor representation, Euler's equations emerge from the commutator  $[\mathcal{B}, I\mathcal{B}]$  under body-fixed coordinates, with precession naturally encoded in rotor composition.

### 4.2 Electromagnetism as a bivector field

Let the electromagnetic field be the bivector  $F := \langle \nabla \wedge A \rangle_2$  with potential A. In rotor form,

$$F = \mathcal{R}F_0 \widetilde{\mathcal{R}}, \qquad \nabla F = J, \tag{7}$$

so sources J couple to rotor curvature K. Plane waves are constant- $\mathcal{B}$  rotor transports; polarization is encoded by  $\hat{\mathcal{B}}$ . The TE (transverse electric) and TM (transverse magnetic) modes emerge from grade decomposition: writing  $F = \mathbf{E} + I\mathbf{B}$  with pseudoscalar I, the TE mode corresponds to  $\langle F \rangle_1$  (electric vector part) perpendicular to propagation, while TM has  $\langle F \rangle_2$  (magnetic bivector) perpendicular. Under rotor transformation, TE/TM swap via duality  $F \mapsto IF$ .

## 4.3 Quantum kinematics (spinor sector)

Spinors arise as minimal left ideals; a Pauli/Dirac spinor corresponds to restricting  $\mathcal{R}$  to a representation sector. The phase evolution  $\partial_t \phi$  gives the quantum phase; interference appears as rotor composition. For a spin- $\frac{1}{2}$  particle in a magnetic field  $\mathbf{B}$ , the rotor  $\mathcal{R} = \exp\left(\frac{1}{2}\mathbf{B} \cdot \boldsymbol{\sigma}t\right)$  with Pauli bivectors  $\boldsymbol{\sigma}$  yields the Pauli equation:

$$i\hbar \,\partial_t \psi = -\frac{\mu}{2} \, \boldsymbol{B} \cdot \boldsymbol{\sigma} \, \psi, \tag{8}$$

where  $\psi$  is the spinor wavefunction. Rotor composition  $\mathcal{R}_1\mathcal{R}_2$  captures multi-particle entanglement and geometric phases.

#### 4.4 Thermodynamics and entropy

Ensembles of rotors with noise  $\Gamma$  yield entropy production via dephasing. Coarse-graining of  $\phi$  produces macroscopic irreversibility (H-theorem analogue) while microscopic dynamics stay reversible under reversion  $\tilde{\cdot}$ . Define the rotor entropy as the phase dispersion functional:

$$S[\rho_{\phi}] := -k_B \int \rho_{\phi}(\phi, x) \ln \rho_{\phi}(\phi, x) \,d\phi \,dx, \tag{9}$$

where  $\rho_{\phi}$  is the phase distribution. Under dissipation  $\Gamma$ , monotonicity  $\partial_t S \geq 0$  follows from the Fokker-Planck equation for  $\rho_{\phi}$  with  $\Gamma$  as a diffusion term, establishing the rotor H-theorem.

#### 4.5 Learning as self-organization

Learning systems implement gradient flows in rotor-coupled spaces. Rotor coherence acts as an *inductive bias*: it stabilizes cyclic/rotational patterns and symmetry constraints. In ML, rotor-regularized layers apply  $\mathcal{L}_{\text{reg}} = \alpha \|\mathcal{R}\mathbf{h} - \mathbf{h}'\|^2$  to enforce SO(3) equivariance and improve generalization on geometric datasets.

## 5 Predictions and Experimental Consequences

Gravitational-wave sidebands. Binary systems with strong precession exhibit spectral sidebands at  $f \pm \Omega_R$  from rotor-phase modulation, with phase-amplitude coupling tied to local rotor density  $\rho_R$ . We predict observable sidebands in LIGO/Virgo GWTC-3 events with  $\chi_{\rm eff} > 0.3$ , testable via matched-filter templates including rotor-phase terms. Synthetic benchmarks available at rotor-grav/waveforms/.

Rotor-inductive ML priors. Neural layers implementing rotor actions (GA rotors on feature blades) improve generalization on datasets with SO(2/3), SE(3) symmetries at fixed parameter counts; robustness to phase-like corruption increases. Benchmark datasets: ModelNet40 (3D shapes), QM9 (molecular properties), N-body dynamics. Protocol: train with/without rotor layers, 5-fold CV, report test accuracy  $\pm$  std; measure robustness via rotation/phase noise injection ( $\sigma_{\theta} \in [0, \pi/4]$ ).

Compression of cyclic signals. A rotor-aware codec surpasses baselines on signals with rotational/phase structure (periodic machinery, orbits, voiced audio) by factor  $\Delta$  bpb with interpretable bivector dictionaries. Metrics: compression ratio (bpb), reconstruction PSNR/SNR, bivector sparsity. Test corpora: LibriSpeech (voiced), machinery vibration logs, planetary ephemerides. Ablation: rotor dictionary size  $\{32, 64, 128\}$ , phase quantization  $\{8, 12, 16\}$  bits. Expected gain:  $\Delta \approx 0.5$ –1.2 bpb over Opus/FLAC.

## 6 Reproducibility Program

We release an open monorepo with:

- rotor-core/: GA primitives, tests, reference rotors;
- rotor-compress/: datasets, metrics, codec;
- rotor-ml/: PyTorch/JAX rotor layers, training scripts;
- rotor-grav/: waveform generator and comparison tools.

One-command replication (Makefile) and CI artifacts ensure exact reproduction. Repository: https://github.com/barthezslavik/rotor-field-hypothesis.

## 7 Discussion and Implications

The hypothesis reinterprets matter and information as manifestations of a single rotor substrate. It aligns with GA-based physics (Hestenes), informational views (Tegmark, Schmidhuber), while offering concrete, testable signatures across physics, chemistry, and learning systems. Open questions include metric emergence, coupling constants from rotor invariants, and cosmological boundary conditions.

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