24 November, 2016

ANSWERS

(a)
$$(4 \text{ pts})$$
 $(q_0, e, Z_0) \rightarrow (q_0, SZ_0)$; $(q_0, e, S) \rightarrow (q_0, ACB)$; $(q_0, e, A) \rightarrow (q_0, 0A1)$
 $(q_0, e, A) \rightarrow (q_0, e)$; $(q_0, e, B) \rightarrow (q_0, 1B0)$; $(q_0, e, B) \rightarrow (q_0, e)$;
 $(q_0, e, C) \rightarrow (q_0, 1C)$; $(q_0, e, C) \rightarrow (q_0, e)$;
 $(q_0, 0, 0) \rightarrow (q_0, e)$; $(q_0, 1, 1) \rightarrow (q_0, e)$; $(q_0, e, Z_0) \rightarrow (q_0, e)$ or (f, Z_0)

(b) (6 pts) The PDAs that accept the languages L_1 and L_2 are given below

for L_1 (both f and g are final states):

$$(q_0, 0, Z_0) \to (f, Z_0); (f, 0, Z_0) \to (f, 0Z_0); (f, 0, 0) \to (f, 00); (f, 1, 0) \to (g, e);$$

 $(g, 1, 0) \to (g, e)$

for L_2 : the PDA in part (a) since $L_2 = L_G$