

***CS 407 Theory of Computation  
Spring 2021***

***Main Text :***

*Elements of Theory of Computation, Papadimitriou & Lewis, Prentice Hall 1998*

***Auxiliary Texts :***

*1- Introduction to the Theory of Computation, Sipser, 1997 PWS*

*2- Computers and Intractability, Garey & Johnson, Freeman 2000*

## *What is this course about ?*

*It is about problems and their solutions*

*How do human species express themselves formally ?  
(In particular problems and solutions)*

*As a sequence of symbols from an alphabet written from left to right  
(or right to left or top to bottom etc. ). Any such set of sequences is called a (written) language.*

*PART 1 (Problems of solvability or decidability)*

*Can we quantify the total number of possible problems (languages)  
and the total number of candidate solutions (languages) ?*

*What if the number of problems by far outnumber the number of solutions ?*

*PART 2 (Problems of computational complexity and intractability)*

*How do we measure the complexity of a problem instance and its  
solution in terms of the resources (time and space) it uses as a function of  
the problem instance size ?*

*What if the solution resource size explodes beyond imagination as the problem size grows ?*

Can we write a **universal debugger (UD)** ?

**UD** is a computer program that takes **any** program **P** as an input and decides whether **P** gets stuck (halts in an undesirable state) . **Answer** : Impossible !!!

It is stipulated (with little justification) that the memory consists of images (pictures, sounds, smells, touches and all possible patterns of sense) that are stored in terms of a subgraphs of nodes (neurons) that are interconnected in a specific way by edges in the brain which itself consists of a much larger graph containing all the past knowledge of the individual.

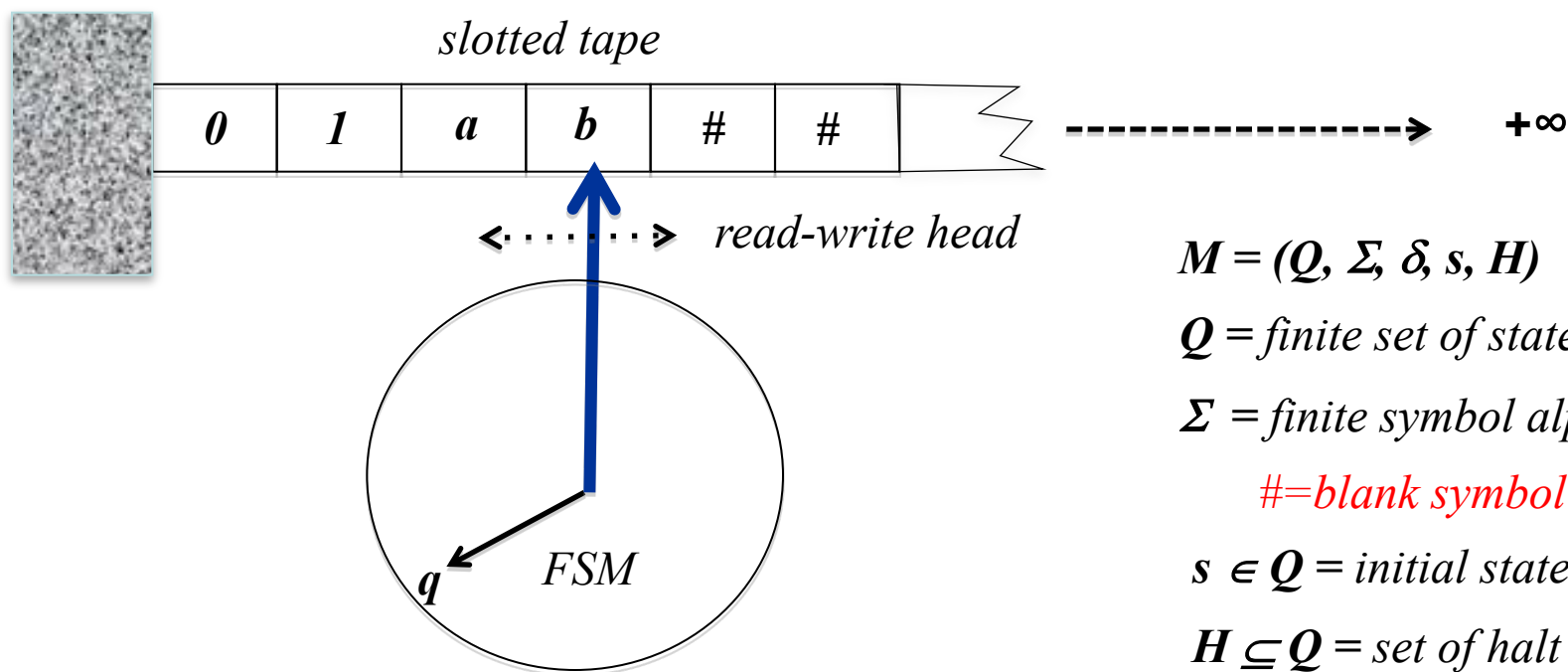
Given a possible subgraph with **m** nodes and a total graph with **n** nodes (**m**  $\leq$  **n**) what is the computational effort of determining whether the total graph contains the subgraph ? **Answer** : possibly  $2^{K.n}$  = **practically infinite** !!!

Three key concepts of the course :

**DECIDABILITY, RECURSION** and **NP-COMPLETENESS**

# Introduction to Turing Machines

*Turing Machine  $M$*



$$M = (Q, \Sigma, \delta, s, H)$$

$Q$  = finite set of states

$\Sigma$  = finite symbol alphabet

$\#$  = blank symbol

$s \in Q$  = initial state

$H \subseteq Q$  = set of halt states

usually  $H = \{h_{\text{YES}}, h_{\text{NO}}\}$

$\delta: Q - H \times \Sigma \rightarrow Q \times \{\rightarrow(\text{right move}), \leftarrow(\text{left move}), \Sigma(\text{write})\}$

$\delta$  = transition function

## *Instantaneous Description (ID) of a TM*

$(q, u \underline{a} v) : q = \text{current state of the FSM},$

$a = \text{the symbol under the head} ; u \in \Sigma^* = \text{the string to the **left** of the head}$

$v \in \Sigma^* = \text{the string to the **right** of the head}$

$(q, u \underline{a} v) \in Q \times (\Sigma^* \times \Sigma \times (\Sigma^* \cdot (\Sigma - \{\#\}) \cup \epsilon))$

*In short :*  
 $(s, \underline{\#} w)$

*Start convention :*  $(s, e \underline{\#} w) ; \text{ where } w \in \Sigma_0^* ; \Sigma_0 \subseteq \Sigma - \{\#\} \text{ the input alphabet}$

*Computational notation :*  $(q, u \underline{a} v) \vdash_M^* (p, x \underline{b} y) , \text{ a finite step } (*) \text{ computation}$

## *Tabular Representation of the Transition Function*

<i>current state</i>	<i>symbol under head</i>	<i>next state</i>	<i>action</i>
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*no. of rows* =  $|Q-H|. |\Sigma|$

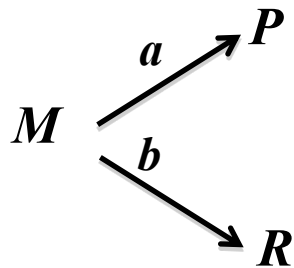
*Example : Clean-up TM :  $(s, \# w) \vdash^* (h, \#)$*

<i>Current state</i>	<i>Symbol under head</i>	<i>Next state</i>	<i>Action</i>
$s$	$\#$	$q_f$	$\rightarrow$
$s$	$0$	$x$	$x$
$s$	$1$	$x$	$x$
$q_f$	$\#$	$q_{b1}$	$\leftarrow$
$q_f$	$0$	$q_f$	$\rightarrow$
$q_f$	$1$	$q_f$	$\rightarrow$
$q_{b1}$	$\#$	$h$	$\rightarrow$
$q_{b1}$	$0$	$q_{b2}$	$\#$
$q_{b1}$	$1$	$q_{b2}$	$\#$
$q_{b2}$	$\#$	$q_{b1}$	$\leftarrow$
$q_{b2}$	$0$	$x$	$x$
$q_{b2}$	$1$	$x$	$x$

*Don't care combinations*

## The Composite Turing Machine

$M \cdot N$  = If and when the TM  $M$  halts then control is passed to TM  $N$  sharing the same tape.



= If and when the TM  $M$  halts then control is passed to TM  $P$  or  $R$  if current tape slot under the head has the symbol  $a$  or  $b$  respectively.

## Basic Turing Machines

$R(L)$  = TM that moves one slot right(left) and halts.

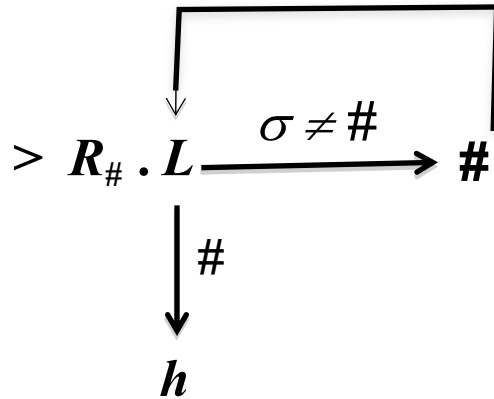
$\sigma$  = TM that writes on the current tape slot the symbol  $\sigma$  and halts.

$R_A(L_A)$  = TM that keeps on moving the head **right (left)** as long as the symbol under the head is **NOT** in  $A \subseteq \Sigma$  (a short hand notation is used as # instead of  $\{\#\}$  as an instance of the set  $A$ )

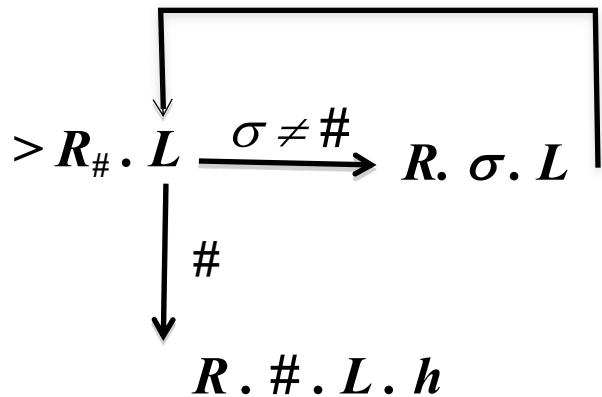
$h, h_{YES}, h_{NO}$  = TM that is in halted state : neutral, YES or NO!



## Clean-up TM revisited



*Example : The right shift machine RS :  $(s, \underline{\#} \ w) \vdash_{RS}^* (h, \underline{\#} \ \# \ w)$*



*verification example : take  $w = 010$*

$(\underline{\#}010) \ R_{\#} \rightarrow (\#010\underline{\#}) \ L \rightarrow (\#010\underline{0}) \ R \rightarrow (0 \text{ remembered})$

$(\#010\underline{\#}) \ 0 \rightarrow (\#010\underline{0}) \ L \rightarrow (\#01\underline{00}) \ L \rightarrow (\#0\underline{1}00) \ R \rightarrow (1 \text{ remembered})$

$(\#01\underline{00}) \ 1 \rightarrow (\#01\underline{1}0) \ L \rightarrow (\#0\underline{1}10) \ L \rightarrow (\#\underline{0}110) \ R \rightarrow (0 \text{ remembered})$

$(\#0\underline{1}10) \ 0 \rightarrow (\#\underline{0}110) \ L \rightarrow (\#\underline{00}10) \ L \rightarrow (\underline{\#}0010) \ R \rightarrow (\# \text{ detected})$

$(\#\underline{00}10) \ \# \rightarrow (\underline{\#}\underline{\#}010) \ L \rightarrow (\underline{\#}\underline{\#}010) \ h$

## *Tabular Representations*

*Clean-up machine C :  $(s, \underline{\#} w) \vdash_{LS}^* (h, \underline{\#})$*

<i>Label</i>	<i>Condition</i>	<i>Next TM</i>
<b>&gt;</b>	-	$R_{\#} L B$
<b>B</b>	$\sigma \neq \#$	$\# L B$
	$\sigma = \#$	$h$

*Right Shift Machine RS :  $(s, \underline{\#} w) \vdash_{RS}^* (h, \underline{\#} \# w)$*

<i>TM</i>	<i>Condition</i>	<i>Next TM</i>
<b>&gt;</b>	-	$R_{\#} L B$
<b>B</b>	$\sigma \neq \#$	$R \sigma L L B$
	$\sigma = \#$	$R \# L h$

## *Tabular Representations (Cont')*

*Left Shift Machine LS :  $(s, \# w \underline{\#}) \vdash_{RS}^* (h, w \underline{\#})$*

<i>TM</i>	<i>Condition</i>	<i>Next TM</i>
<i>&gt;</i>		<i>L<sub>#</sub> R <b>B</b></i>
<i><b>B</b></i>	$\sigma \neq \#$	<i>L <math>\sigma</math> R R <b>B</b></i>
	$\sigma = \#$	<i>L # h</i>

## *Basic Definitions on Turing machines*

A TM  $M$  with  $H = \{h_{YES}, h_{NO}\}$  is said to **DECIDE** a language  $L \subseteq \Sigma_0^*$  if:

$(s, \# w) |_{--M}^* (h_{YES}, u \underline{a} v)$ , if  $w \in L$

$(s, \# w) |_{--M}^* (h_{NO}, u \underline{a} v)$ , if  $w \notin L$

A TM  $M$  with  $H = \{h\}$  is said to **compute** a function  $f: \Sigma_0^* \rightarrow \Sigma_0^*$  if:

$(s, \# w) |_{--M}^* (h, u \underline{a} v)$ , iff  $u = e$ ;  $a = \#$  and  $v = f(w)$

A TM  $M$  with  $H = \{h\}$  is said to **SEMIDEcide (ACCEPT)** a language  $L \subseteq \Sigma_0^*$  if:

$(s, \# w) |_{--M}^* (h, u \underline{a} v)$ , iff  $w \in L$

Let  $\Sigma = \{a, b, c, x, \#\}$  (semidecides)

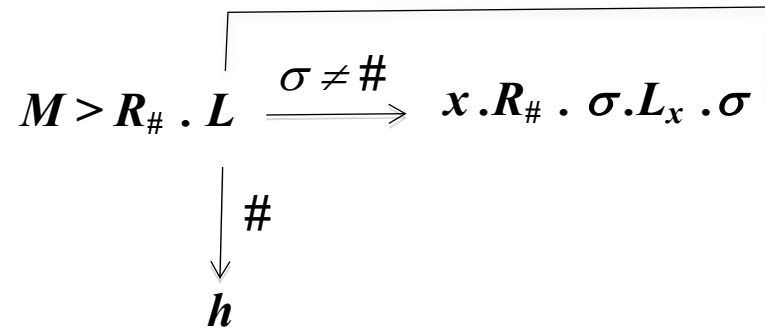


*Verification  $w = aabcc$*

$$\begin{aligned}
(\#aabc) R_{\{a,b,c,\#\}} &\rightarrow (\#aabc) x \rightarrow (\#xabc) R_{\{b,c,\#\}} \rightarrow (\#xabc) x \rightarrow (\#xaxc) R_{\{c,a,\#\}} \rightarrow (\#xaxc) x \rightarrow (\#xaxxc) R_{\{\#,a,b\}} \rightarrow (\#xaxxc\#) L_{\#} \rightarrow \\
(\#xaxxc) R_{\{a,b,c,\#\}} &\rightarrow (\#xaxxc) x \rightarrow (\#xxxxc) R_{\{b,c,\#\}} \rightarrow (\#xxxxc) (c \text{ detected}) \rightarrow h_{NO}
\end{aligned}$$

*Example : a TM  $M$  that computes the function*

$$f(w) = w.w^R ; (s, \# w) \vdash_M^* (h, \# w.w^R)$$



Label	Condition	Next TM
$>$	-	$R_{\#} L \textcolor{red}{B}$
$\textcolor{red}{B}$	$\sigma \neq \#$	$x R_{\#} \sigma L_x \sigma L \textcolor{red}{B}$
	$\sigma = \#$	$h$

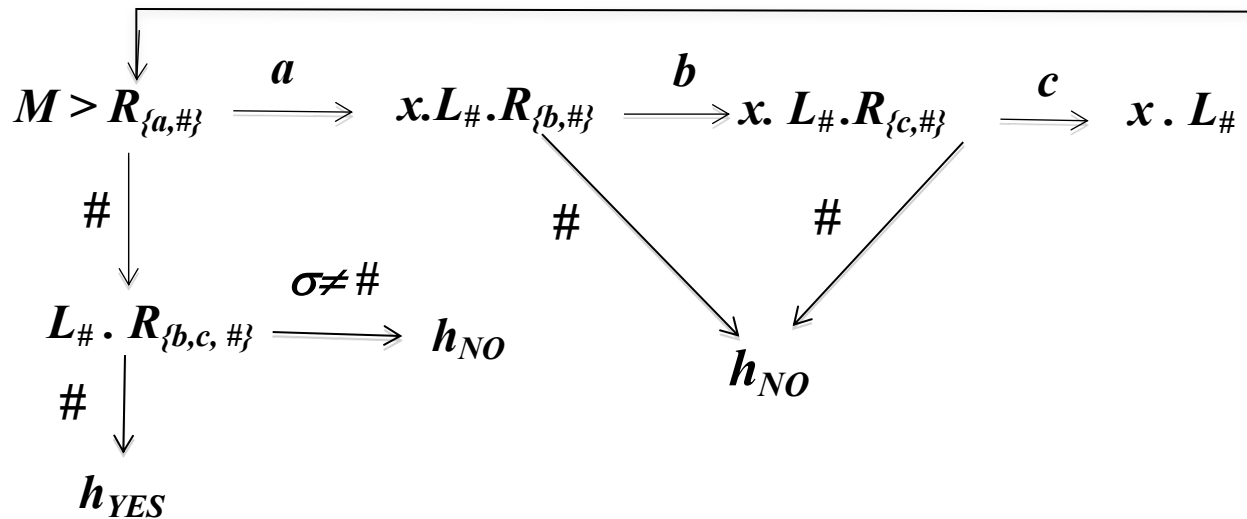
where  $w \in \Sigma_0^*$ ,  $x \notin \Sigma_0$  and  $\Sigma = \Sigma_0 \cup \{x, \#\}$

*Verification  $w = ab$  ;  $f(w) = abba$*

$(\# \underline{a} b) R_{\#} \rightarrow (\# \underline{a} b \#) L \rightarrow (\# \underline{a} b) x \rightarrow (\# \underline{a} x) (b \text{ remembered}) R_{\#} \rightarrow (\# \underline{a} x \#) b \rightarrow (\# \underline{a} x b) L_x \rightarrow (\# \underline{a} x b) \textcolor{red}{b} \rightarrow (\# \underline{a} b b) L \rightarrow$   
 $(\# \underline{a} b b) x \rightarrow (\# \underline{a} b b) (a \text{ remembered}) R_{\#} \rightarrow (\# \underline{a} b b \#) a \rightarrow (\# \underline{a} b b a) L_x \rightarrow (\# \underline{a} b b a) \textcolor{red}{a} \rightarrow (\# \underline{a} b b a) L \rightarrow (\# \underline{a} b b a) (\# \text{ detected}) h$

Example : A TM  $M$  that **decides** the language  $L = \{\omega \in \{a,b,c\}^* \mid \#as = \#bs = \#cs\}$

Let  $\Sigma = \{a,b,c,x,\#\}$

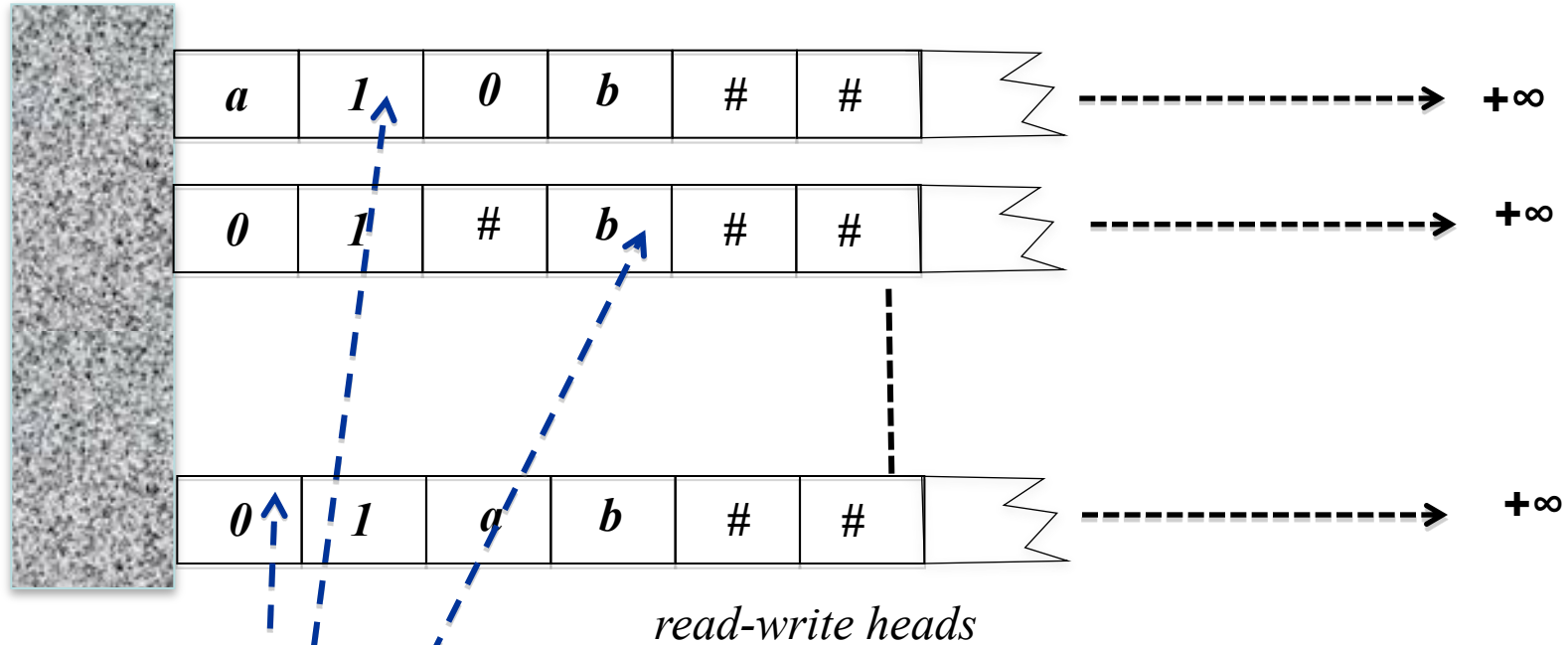


Verification  $w = \text{acabbc}$  ( $w = \text{acabbcb}$ )

$(\# \underline{a} c a b b c b) R_{\{a,\#\}} \rightarrow (\# \underline{a} c a b b c b) x \rightarrow (\# x \underline{c} a b b c b) L_{\#} \rightarrow (\# x \underline{c} a b b c b) R_{\{b,\#\}} \rightarrow (\# x c a \underline{b} b c b) x \rightarrow (\# x c a x \underline{b} c b) L_{\#} \rightarrow (\# x c a x b c \underline{b}) R_{\{c,\#\}} \rightarrow (\# x \underline{c} a x b c b) x \rightarrow$   
 $(\# x x \underline{a} x b c b) L_{\#} \rightarrow (\# x x a x b c \underline{b}) R_{\{a,\#\}} \rightarrow (\# x x a x b c b) x \rightarrow (\# x x x \underline{x} b c b) L_{\#} \rightarrow (\# x x x x b c \underline{b}) R_{\{b,\#\}} \rightarrow (\# x x x x \underline{b} c b) x \rightarrow (\# x x x x x \underline{c} b) L_{\#} \rightarrow (\# x x x x x c b) R_{\{c,\#\}} \rightarrow$   
 $(\# x x x x x c \underline{b}) x \rightarrow (\# x x x x x x \underline{b}) L_{\#} \rightarrow (\# x x x x x x b) R_{\{a,\#\}} \text{ (#detected)} \rightarrow (\# x x x x x x b \underline{\#}) L_{\#} \rightarrow (\# x x x x x x b) R_{\{b,c,\#\}} \rightarrow (\# x x x x x x b \underline{\#}) \text{ (# detected)} h_{YES}$   
 $(\# x x x x x x \underline{b}) \text{ (b detected)} h_{NO}$

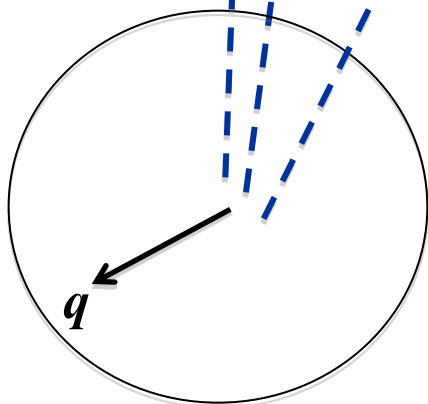
# Multitape TM

$k$  slotted tapes ;  $k$  heads



$$\delta: Q \times H \times \Sigma^k \rightarrow Q \times \{\rightarrow(\text{right move}), \leftarrow(\text{left move}), \Sigma(\text{write})\}^k$$

FSM





## *Instantaneous Description (ID) of a Multitape TM*

$(q ; u_1 \underline{a}_1 v_1 , \dots , u_k \underline{a}_k v_k) : q = \text{current state of the FSM},$

$a_j = \text{the symbol under head } j; u_j \in \Sigma^* = \text{the string to the left of head } j$

$v_j \in \Sigma^* = \text{the string to the right of head } j$

$(q ; u_1 \underline{a}_1 v_1 , \dots , u_k \underline{a}_k v_k) \in Q \times (\Sigma^* \times \Sigma \times (\Sigma^* \cdot (\Sigma - \{\#\}) \cup e))^k$

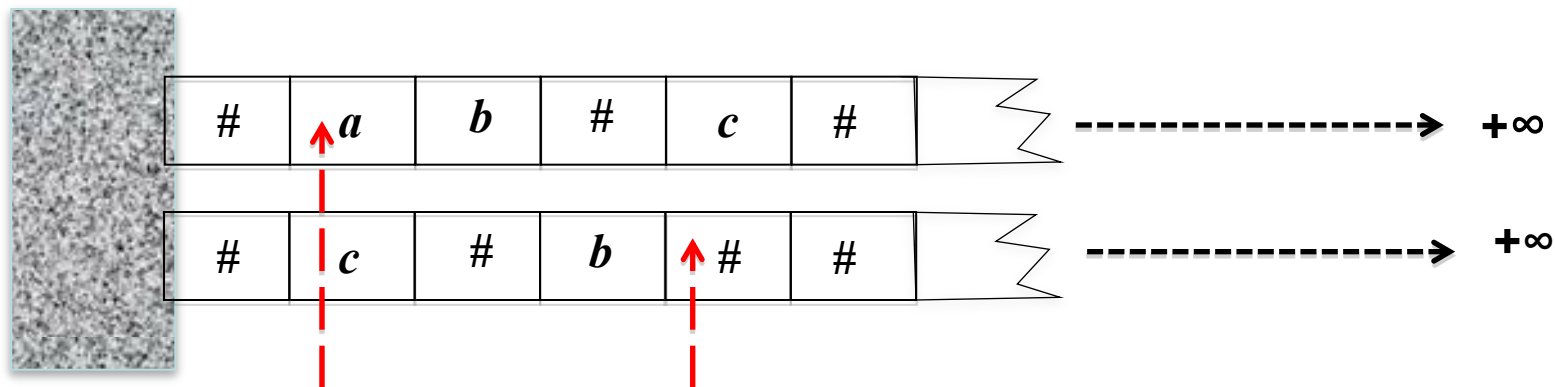
*Start convention* :  $(s, \# w, \dots, \#) ; \text{ where } w \in \Sigma_0^* ; \Sigma_0 \subseteq \Sigma \text{ is the input alphabet}$

*Computational notation* :

$(q ; u_{11} \underline{a}_{11} v_{11} , \dots , u_{k1} \underline{a}_{k1} v_{k1}) \vdash_M^* (p ; u_{1m} \underline{a}_{1m} v_{1m} , \dots , u_{km} \underline{a}_{km} v_{km}) ,$

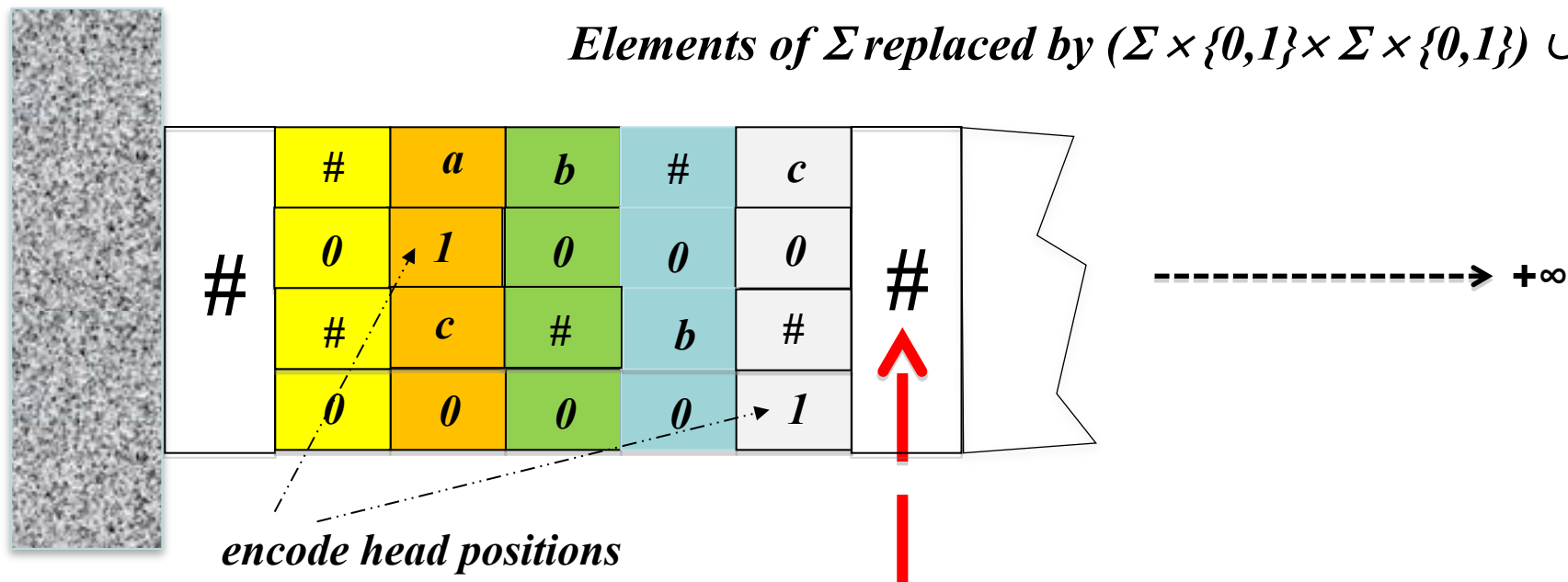
*An (m-step) finite step (\*) computation*

## Simulating A Multitape TM on a single tape one



Each step of the computation of the 2 tape TM is accomplished by finite-steps (scans) of the single tape TM

Elements of  $\Sigma$  replaced by  $(\Sigma \times \{0,1\} \times \Sigma \times \{0,1\}) \cup \#$



## *Fact*

### *Every multitape TM can be simulated by a standard TM*

*For a given  $k$ -tape TM  $M_k$  there is a corresponding standard TM  $M$  such that :*

- If  $M_k$  **decides** a language  $L$  then  $M$  **decides** the language  $L$*
- If  $M_k$  **semidecides** a language  $L$  then  $M$  **semidecides** the language  $L$*
- If  $M_k$  **computes** a function  $f: (s, \underline{\#} w, \dots, \underline{\#}) \vdash_{M_k}^* (h, \underline{\#} f(w), \dots, \underline{\#})$*

*Then  $M$  **computes** the function  $f$ ,  $(s, \underline{\#} w) \vdash_M^* (h, \underline{\#} f(w))$*

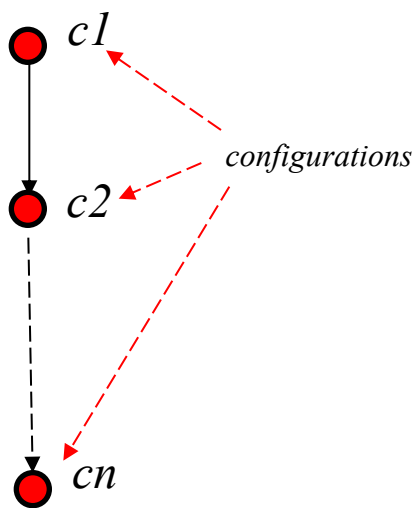
## *Nondeterministic TM (NDTM)*

*The only difference is in the transition function :*

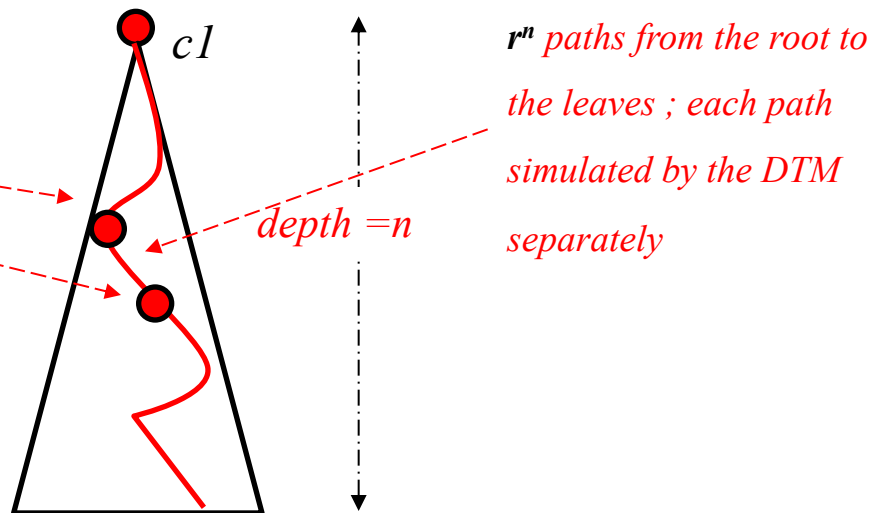
$$\delta: Q-H \times \Sigma \rightarrow 2^Q \times \{\rightarrow(\text{right move}), \leftarrow(\text{left move}), \Sigma(\text{write})\}$$

*At each configuration a NDTM can have at most  $r = |Q| \cdot (2 + |\Sigma|)$  next configurations.*

*DTM computations = linear*



*NDTM computations = tree*



## *Nondeterministic TM (NDTM)*

$$\delta: Q \times \Sigma \rightarrow 2^Q \times \{\rightarrow(\text{right move}), \leftarrow(\text{left move}), \Sigma(\text{write})\}$$

*Every nondeterministic TM can be simulated by a standard TM !*

### *Definitions*

A nondeterministic TM  $M$  is said to **decide** a language  $L$  if

1- There is an integer  $K$  such that there is no configuration  $C$  such that

$(s, \# w) \vdash_M^K C$  (i.e. all computations **halt** before  $K$  steps !)

2-  $w \in L$  **iff** there is at least one computation :  $(s, \# w) \vdash_M^* (h_{YES}, u \# v)$

A nondeterministic TM  $M$  is said to **semidecide** a language  $L$  if

1- There is no integer  $K$  that satisfies 1- above

2-  $w \in L$  **iff** there is a computation :  $(s, \# w) \vdash_M^* (h_{YES}, u \# v)$

A nondeterministic TM  $M$  is said to **compute** a function  $f$  if :

1- Condition 1- of decidability above holds

2-  $(s, \# w) \vdash_M^* (h_{YES}, u \# v)$  **iff**  $u=e$  ;  $a=\#$  ;  $v = f(w)$

**Example** A two-tape NDTM that decides the language

$L = (\omega \in \Sigma_0^* \mid \omega = u.u ; u \in \Sigma_0^*) ; \text{ start at } (s ; \# \omega, \#) ; d \notin \Sigma_0$

Immediately accept if  $\omega = e$  ; else move to **A**  $\longrightarrow$

Move head to a midpoint nondeterministically  
; copy first entry of 2nd half to 2<sup>nd</sup> tape 1<sup>st</sup> entry  
and replace it with **d** ; if  $\#$  is reached then reject !  $\longrightarrow$

Copy entire 2nd half of 1<sup>st</sup> tape to 2<sup>nd</sup> tape  
meanwhile replacing copied entries with **d**  $\longrightarrow$

Replace all **ds** with  $\#$  in tape 1 and after  
that move heads 1 and 2 to leftmost  $\#$  to  
make them ready for comparison  $\longrightarrow$

Compare contents of 1<sup>st</sup> tape and 2<sup>nd</sup> tape  
; if equal accept with  $h_{YES}$  ; if different reject  
with  $h_{NO}$  !  $\longrightarrow$

TM	Condition	Next TM
$> R^1$	$\sigma^1 = \#$	$h_{YES}$
	$\sigma^1 \neq \#$	<b>A</b>
<b>A</b> = $R^1$	$\sigma^1 = x \neq \#$	<b>A</b>
	$\sigma^1 = x \neq \#$	$R^2 . x^2 . d^1 . \mathbf{B}$
	$\sigma^1 = \#$	$h_{NO}$
<b>B</b> = $R^1 R^2$	$\sigma^1 = x \neq \#$	$x^2 . d^1 . \mathbf{B}$
	$\sigma^1 = \#$	<b>C</b>
<b>C</b> = $L^1$	$\sigma^1 = d$	$\#^1 . \mathbf{C}$
	$\sigma^1 \neq d$	$L_{\#}^1 . L_{\#}^2 . \mathbf{D}$
<b>D</b> = $R^1 R^2$	$\sigma^1 = \sigma^2 \neq \#$	<b>D</b>
	$\sigma^1 = \sigma^2 = \#$	$h_{YES}$
	else	$h_{NO}$

$L = (\omega \in \Sigma_0^* \mid \omega = u.u ; u \in \Sigma_0^*) ; \text{start at } (s ; \# \omega, \#) ; d \notin \Sigma_0$

$\omega = abab$  start at  $(\# a b a b, \#)$

$(\# a b a b, \#) \xrightarrow{R^1} (\# \underline{a} b a b, \#) \xrightarrow{R^1 A} (\# a \underline{b} a b, \#) \xrightarrow{R^1 R^2}$

$(\# a b \underline{a} b, \#) \xrightarrow{a^2 d^1} (\# a b \underline{d} b, \# \underline{a}) \xrightarrow{R^1 R^2}$

$(\# a b d \underline{b}, \# a \#) \xrightarrow{b^2 d^1} (\# a b d \underline{d}, \# a \underline{b}) \xrightarrow{R^1 R^2}$

$(\# a b d d \#, \# a b \#) \xrightarrow{L^1} (\# a b d \underline{d}, \# a b \#) \xrightarrow{\#^1}$

$(\# a b d \#, \# a b \#) \xrightarrow{L^1} (\# a b \underline{d}, \# a b \#) \xrightarrow{\#^1}$

$(\# a b \#, \# a b \#) \xrightarrow{L^1} (\# a \underline{b}, \# a b \#) \xrightarrow{L_{\#}^1 . L_{\#}^2}$

$(\# a b, \# a b) \xrightarrow{L^1} (\# a b, \# a b) \rightarrow \text{compare } h_{YES}$

TM	Condition	Next TM
$> R^1$	$\sigma^1 = \#$	$h_{YES}$
	$\sigma^1 \neq \#$	<b>A</b>
<b>A</b> = $R^1$	$\sigma^1 = x \neq \#$	<b>A</b>
	$\sigma^1 = x \neq \#$	$R^2 . x^2 . d^1 . \mathbf{B}$
	$\sigma^1 = \#$	$h_{NO}$
<b>B</b> = $R^1 R^2$	$\sigma^1 = x \neq \#$	$x^2 . d^1 . \mathbf{B}$
	$\sigma^1 = \#$	<b>C</b>
<b>C</b> = $L^1$	$\sigma^1 = d$	$\#^1 . \mathbf{C}$
	$\sigma^1 \neq d$	$L_{\#}^1 . L_{\#}^2 . \mathbf{D}$
<b>D</b> = $R^1 R^2$	$\sigma^1 = \sigma^2 \neq \#$	<b>D</b>
	$\sigma^1 = \sigma^2 = \#$	$h_{YES}$
	else	$h_{NO}$

## Example A two-tape TM that adds two “binary coded” integers

$(s; \# \omega_1 \# \omega_2, \#) \vdash (h, \# \text{ “}\omega_1 + \omega_2\text{”, } \#)$

Copy  $\omega_1$  into the 2<sup>nd</sup> tape and replace copied entries and # with 0s ; move heads 1 and 2 to rightmost least significant digits to start addition

Start addition of digits with the result replacing the content of 1<sup>st</sup> tape digit ; if there is a carry digit move to C ; else continue with B ; stop if # is reached in tape 2 with head 1 in leftmost #

Carry account continues  $\rightarrow$  Carry account disappears  $\rightarrow$

Carry account is terminated ; result in tape 1  $\rightarrow$

Carry account propagates to left digits  $\rightarrow$

TM	Condition	Next TM
<b>A</b> = $R^1 R^2$	$\sigma^1 = x \neq \#$	$0^1 x^2 \text{A}$
	$\sigma^1 = \#$	$0^1 R^1 \# L^1 L^2 \text{B}$
<b>B</b>	$\sigma^1 \sigma^2 = 01 \vee 10$	$1^1 \#^2 L^1 L^2 \text{B}$
	$\sigma^1 \sigma^2 = 00$	$0^1 \#^2 L^1 L^2 \text{B}$
	$\sigma^1 \sigma^2 = 11$	$0^1 \#^2 L^1 L^2 \text{C}$
	$\sigma^2 = \#$	$L^1 \# h$
<b>C</b>	$\sigma^1 \sigma^2 = 01 \vee 10$	$0^1 \#^2 L^1 L^2 \text{C}$
	$\sigma^1 \sigma^2 = 00$	$1^1 \#^2 L^1 L^2 \text{B}$
	$\sigma^1 \sigma^2 = 11$	$1^1 \#^2 L^1 L^2 \text{C}$
	$\sigma^2 = \#$	<b>D</b>
<b>D</b>	$\sigma^1 = 0$	$1^1 L^1 \# h$
	$\sigma^1 = 1$	$0^1 L^1 \text{D}$



## *The Universal Turing Machine*

*Coding Alphabet* =  $\{ ( , ) , \$ , ' , ' , 0 , 1 , \# \}$

$\#$  = *blank character*

*Binary Encoding Convention :*

*States* :  $0 \rightarrow \text{HALT}_{\text{Yes}} ; 1 \rightarrow \text{HALT}_{\text{No}} ; \dots$

*Input/Action* :  $0 \rightarrow \text{Right Move} ; 1 \rightarrow \text{Left Move} ; \dots$

*Tape representation (xx denotes encoded character)*

*Tape 1 is input tape*  $\rightarrow \# \text{xx,xx}, \dots \text{xx} \$ \text{head position xx}, \dots \text{xx} \#$

*Tape 2 is transition table*  $\rightarrow \# (q_1, a_1, q'_1, \text{action}_1) \dots (q_n, a_n, q'_n, \text{action}_n) \#$

*Tape 3 is current state*  $\rightarrow \# \text{xx} \#$

## *How does the Universal Turing Machine work ?*

*Suppose that the TM  $M$  simulated by the UTM  $U$  makes the transition :  $(q, \sigma) \rightarrow (q', b)$  where :*

*;-  $q$  is the current state encoded as  $E(q)$  in **tape 3***

*;-  $\sigma$  is the current symbol under the head encoded as  $E(\sigma)$  just before the \$ symbol in **tape 1***

*;-  $q'$  is the next state dictated by the transition fn. (3<sup>rd</sup> element of the row)*

*;-  $b$  is the encoded next action again dictated by the transition fn. (4<sup>th</sup> element of the row) which is ' $\rightarrow$ ' or ' $\leftarrow$ ' (move the \$ mark in **tape 1**) , or some  $\sigma'$  to be printed as  $E(\sigma')$  before the \$ marked slot in **tape 1**.*

*The UTM simulation takes place in terms of two phases :*

*The **search phase** and the **action implementation phase***

***Search Phase :** Search among the encoded rows of the transition function until a row is found such that there is an exact match between the first two entries of this row and the encoded current state in **tape 3** and the encoded input before the \$ symbol in **tape 1**.*

***Action Implement Phase :** Replace the current state in **tape 3** with the next state (3rd element of the matching row); move the \$ mark in **tape 1** right or left ; or print  $E(\sigma')$  before the \$ marked slot in **tape 1** in accordance with the 4<sup>th</sup> entry of the matching row.*

## *The Halting Problem*

Consider the set of **all** Deterministic Turing Machines (DTMs) with an input alphabet  $\Sigma = \{\#, 0, 1\}$  and a single halt state  $h$ .

The transition function  $\delta : \{Q \setminus h\} \times \Sigma \rightarrow Q \times (\{\rightarrow, \leftarrow\} \cup \Sigma)$  of any such DTM is a finite table with  $(|Q|-1) \cdot |\Sigma|$  rows and 4 columns where  $|\Sigma| = 3$  !

Every row of the entire transition function can be encoded by **positive integers** as follows : integers  $j > 0$  and  $k > 0$  corresponds to elements of  $Q$  and  $\Sigma$  where  $j=1$  corresponds to the special halt state  $h$  and  $k = 3, \dots, |\Sigma|+2$  correspond to the inputs in  $\Sigma$ . The special integers 1 and 2 are reserved for encoding the actions for right and left motions of the head of the DTM respectively. Hence every row of the transition function  $\delta$  is represented by 4 positive integers that are separated by some symbol, such as a comma, acting a separator :  $i, j, k, m$ ,

*A binary encoding for a single row of the transition function is as follows :*

*$r = 0^i 1 0^j 1 0^k 1 0^m 1$ ; And the entire transition function  $\delta$  be encoded as  $E(\delta)$*

*which is a concatenation of  $R = (|Q|-1) \cdot |\Sigma|$  binary rows as :*

*$E(\delta) = r_1 . r_2 \dots r_R$  where  $r_j$  denotes the binary code for the  $j^{\text{th}}$  row of the transition function. Note that distinct encodings corresponding to different orders in which the rows are sequenced and different integer encodings for states all correspond to the same DTM.*

*Thus **every** DTM corresponds to **possibly different binary strings** each represented by some  $E(\delta)$ , depending on the permutation of the rows and the integer encodings of the states of the transition function.*

*Finally as a convention we choose the first block of zeros in the first chosen row as the encoding of the **initial state** .*

**Example : Clean-up TM :  $(s, \# w) \vdash^* (h, \#)$**

Current state	Symbol under head	Next state	Action
$s$	$\#$	$q_f$	$\rightarrow$
$s$	$0$	$q_f$	$\rightarrow$
$s$	$1$	$q_f$	$\rightarrow$
$q_f$	$\#$	$q_{b1}$	$\leftarrow$
$q_f$	$0$	$q_f$	$\rightarrow$
$q_f$	$1$	$q_f$	$\rightarrow$
$q_{b1}$	$\#$	$h$	$\rightarrow$
$q_{b1}$	$0$	$q_{b2}$	$\#$
$q_{b1}$	$1$	$q_{b2}$	$\#$
$q_{b2}$	$\#$	$q_{b1}$	$\leftarrow$
$q_{b2}$	$0$	$q_{b1}$	$\leftarrow$
$q_{b2}$	$1$	$q_{b1}$	$\leftarrow$

2, 3, 3, 1

2, 4, 3, 1

2, 5, 3, 1

3, 3, 4, 2

3, 4, 3, 1

3, 4, 3, 1

etc.

**0010001000101**

$\rightarrow \rightarrow 1$

$\leftarrow \rightarrow 2$

$\# \rightarrow 3$

$0 \rightarrow 4$

$1 \rightarrow 5$

Let  $L_{DTM} \subseteq \{0,1\}^*$  be the language corresponding to any legitimate encoding of the transition function of DTM with binary inputs with the conventions as described in the previous slides. Also note that for **distinct** binary strings  $u \in \{0,1\}^*$  the strings  $1u$  correspond to **distinct** positive numbers covering all the integers  $1,2,\dots$  as follows :

$1e \rightarrow 1$ ;  $10 \rightarrow 2$ ;  $11 \rightarrow 3$ ;  $100 \rightarrow 4$ ;  $101 \rightarrow 5 \dots$  etc.

In view of the definition above the infinite number of positive integers :

$1L_{DTM} \rightarrow 0 < x_1 < x_2 < \dots, < x_m < \dots$

cover all the DTMs, although a single DTM may correspond to more than one – but a finite number - of the integers above.

*In view of the definition  $L_{DTM}$  for each  $w \in L_{DTM}$  the unique DTM  $M$  can be written as a **function** of the string  $w$  as  $M = M(w)$*

*We extend the encoding of a DTM  $M$  in the following manner :*

*By the term **accept** for an input  $u \in \{0,1\}^*$  for a DTM  $M$  , it is meant that  $M$  eventually **halts** at its legitimate halt state  **$h$**  starting from the initial string  $u$  on its tape.*

*If  $w \in \{0,1\}^* \sim L_{DTM}$  -  $w$  does **not** correspond to a binary encoding of a DTM as explained above - we let  $M(w) := R$ , that is a DTM which moves its head right at each step irrespective of the tape input **hence** it does not halt and hence does **not accept any** input  $u \in \{0,1\}^*$  .*



We first define the following diagonal language  $D \subseteq \{0,1\}^*$

$D := (w \in \{0,1\}^* \mid M(w) \text{ **accepts** } w)$

The complement diagonal language is :

$D^c := (w \in \{0,1\}^* \mid M(w) \text{ **does not accept** } w)$

**Key question** : Is there a DTM that **semidecides the language**  $D^c$  ?

**Answer** : **NO ! WHY NOT ?**

Suppose there is a DTM  $M^*$  that semidecides  $D^c$

Let  $u^*$  be a binary encoding of  $M^*$  in  $L_{DTM}$  so that  $M(u^*) = M^*$

How does  $M(u^*)$  behave on  $u^*$  as its input ?

First note that there are only 2 possibilities : either  $u^* \in D^c$  or  $u^* \in D$

**CASE (1)  $u^* \in D^c$**

$M^*$  ACCEPTS  $u^*$  **because**  $M^*$  semidecides  $D^c$  and  $u^* \in D^c$

$M^*$  DOES NOT ACCEPT  $u^*$  **follows** from the definition of  $D^c$  and  $u^* \in D^c$

Logical contradiction : not possible

**CASE (2)  $u^* \in D$  (or  $u^* \notin D^c$ )**

$D^c := (w \in \{0,1\}^* \mid M(w) \text{ does not accept } w)$



$M^*$  DOES NOT ACCEPT  $u^*$  **because**  $M^*$  semidecides  $D^c$  and  $u^* \notin D^c$

$M^*$  ACCEPTS  $u^*$  **follows** from the definition of  $D^c$  and  $u^* \notin D^c$

Logical contradiction : not possible

**A Logical Contradiction is the end of rational thought ;**

**Hence no such DTM  $M^*$  encoded by  $u^*$  exists !**

*Is there a DTM  $M$  that decides  $D$  ? NO ! Why*

*If a DTM  $M$  decides  $D$  then :*

*for  $M'$  same as  $M$  except  $h_{YES}$  and  $h_{NO}$  interchanged then  $M'$  decides  $D^c$*

*But this contradicts the previous result since  $D^c$  is not even **semidecidable**  
hence certainly not **decidable** !*

*But if  $D$  is NOT **decidable** then  $H_0$  is not **decidable** where*

*$H_0 = (u \in \{0,1\}^* ; \{0,1\}^* \mid u = (u_1 ; u_2) ; M = M(u_1) \text{ and } M \text{ halts on } u_2 )$*

*Why ? Because  $D$  is the special case of  $H_0$  with  $u_2 = u_1$*

*$H_0$  is a **semidecidable language** semidecided by a universal TM.*

## The Anatomy of Problem Solvability

$$1L_{DTM} \rightarrow 0 < x_1 < x_2 < \dots, < x_m < \dots \rightarrow +\infty$$

Since every encoded DTM is represented by a positive integer we can list ALL DTMs as below :

$$T_1, T_2, \dots, T_m, \dots \rightarrow +\infty$$

For every DTM  $T_m$  there is a unique language  $L_m$  semidecided by it ( $u \in L_m \Leftrightarrow T_m$  halts on  $u$ )

$$L_1, L_2, \dots, L_m, \dots \rightarrow +\infty \rightarrow \text{ALL semidecidable languages in } \{0,1\}^*$$

Some of the  $L_j$  above have the desirable property that for some  $k > 0$   $L_j^c = L_k$

A special DTM composed using  $T_j$  and  $T_k$ , decides  $L_j$  by halting on ALL  $u$  in  $\{0,1\}^*$  :

At  $h_{YES}$  if  $u \in L_j$  and at  $h_{NO}$  if  $u \in L_j^c = L_k$

These composed DTMs with 2 halt states and the languages they decide are listed below:

$$M_1, M_2, \dots, M_m, \dots \rightarrow +\infty$$

$$N_1, N_2, \dots, N_m, \dots \rightarrow +\infty$$

$\Rightarrow$  Each  $M_p$  is called an **ALGORITHM** that solves the problem encoded by the decidable language  $N_p$

## *Integer Interpretation of Problems and Solutions*

$$lL_{DTM} \rightarrow 0 < x_1 < x_2 < \dots, < x_m < \dots \rightarrow +\infty$$

$T_1, T_2, \dots, T_m, \dots \rightarrow +\infty$  every DTM (semi-solution candidate) is identified with an integer

$$L_1, L_2, \dots, L_m, \dots \rightarrow +\infty$$

every **semidecidable** language (semi-solvable encoded problem) is identified with a subset of integers using the construct :  $1.L_m$

*Hence the set of DTMs and associated semidecidable languages are both COUNTABLE*

*But every language  $L$  (encoded problem) is in 1-to-1 correspondence with all the subsets of integers using the construct :  $1.L$*

*Fact : the **SET OF ALL SUBSETS** of integers is **NOT COUNTABLE** ! (see next slide)*

Hence : the **SET OF ALL LANGUAGES (ALL ENCODED PROBLEMS)** is **NOT COUNTABLE**

**CONCLUSION :**  $\text{DECIDABLE PROBLEMS} < \text{SEMIDECIDABLE PROBLEMS} < \text{ALL PROBLEMS}$

$\leftarrow \text{COUNTABLE} \rightarrow \quad \leftarrow \text{UNCOUNTABLE} \rightarrow$

*Proof (by contradiction) of*

*“ the **SET OF ALL SUBSETS** of integers is **NOT COUNTABLE** ! ”*

Suppose it is *countable* so that *all* subsets  $N$  are as counted as below :

$S_1, S_2, \dots, S_m, \dots$

Define  $D := (m \in N \mid m \in S_m) \subseteq N$  , so that the complement  $D^c = (m \in N \mid m \notin S_m) \subseteq N$

Since the above count covers *all subsets of*  $N$  we must have for some  $k$  :

$D^c = S_k$  . We ask the question whether  $k \in D^c$  . There are 2 cases :

**CASE1** :  $k \in D^c$  Then by definition  $k \notin S_k$  so that  $D^c \neq S_k$

**CASE2** :  $k \notin D^c$  (or  $k \in D$ ) Then again by definition  $k \in S_k$  so that again  $D^c \neq S_k$

Therefore the countability assumption above is false and the result follows.