

25.09.2020

Digital Image Processing (CSE/ECE 478)

Lecture-13: Morphological Operations, Intro to Geometric Operations

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Announcements

- Projects
 - Form group(s) of ≥ 1 and ≤ 3
 - List will be announced at 9pm on 16th September
 - Read guidelines re: project preferences carefully

Binary Images

Structuring Elements

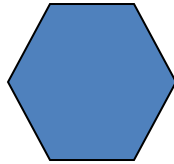
A **structuring element** = a shape mask

They can be any shape and size that is digitally representable, and each has an **origin**.

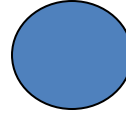


box

`box(length,width)`

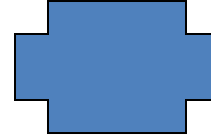


hexagon



disk

`disk(diameter)`



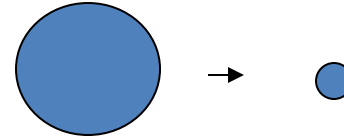
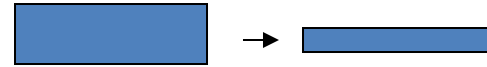
something

Erosion

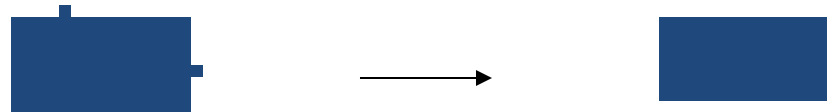
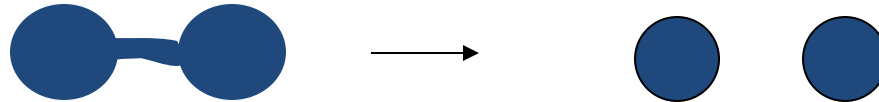
Erosion **shrinks** the connected sets of 1s of a binary image.

It can be used for

1. shrinking features



2. Removing bridges, branches and small protrusions

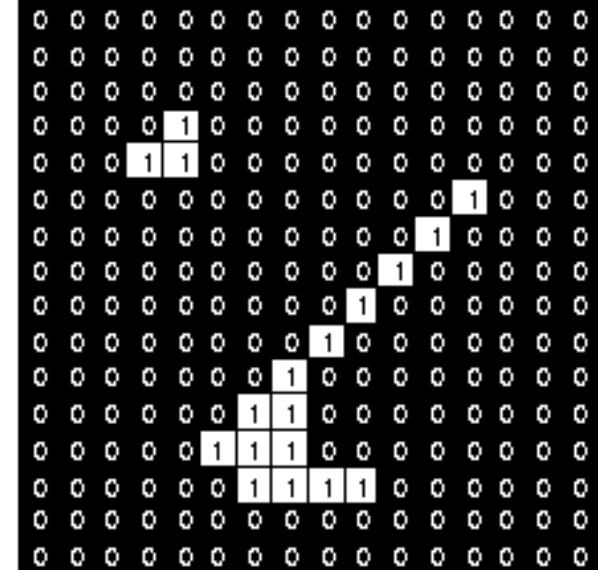
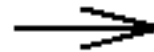
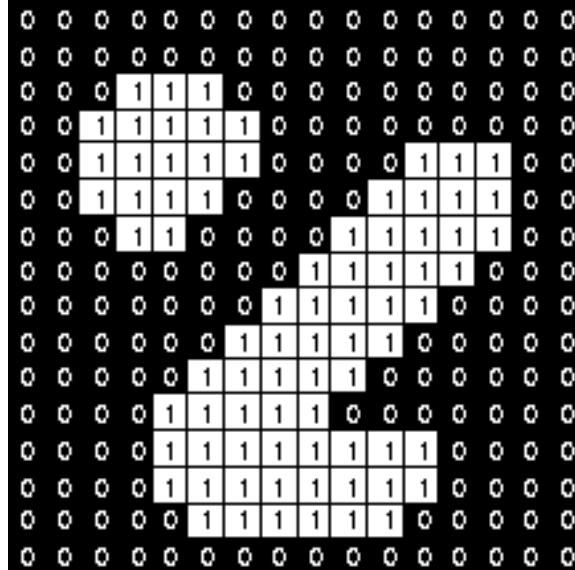


Erosion : Operation (**min** filter)

1	1	1
1	1	1
1	1	1

Set of coordinate points =

{ (-1, -1), (0, -1), (1, -1),
(-1, 0), (0, 0), (1, 0),
(-1, 1), (0, 1), (1, 1) }

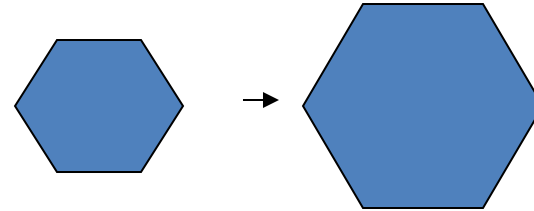


Dilation

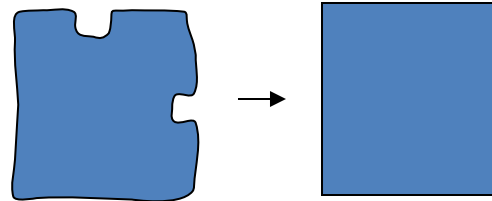
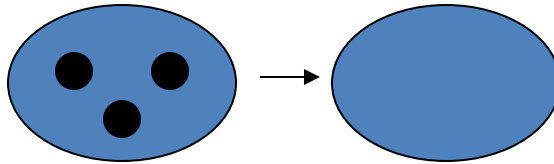
Dilation **expands** the connected sets of 1s of a binary image.

It can be used for

1. growing features

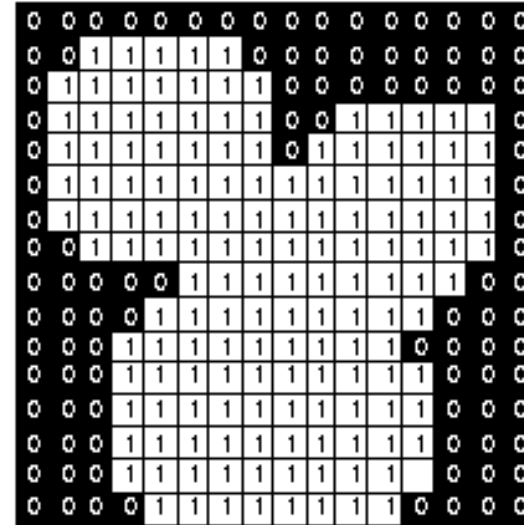
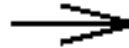
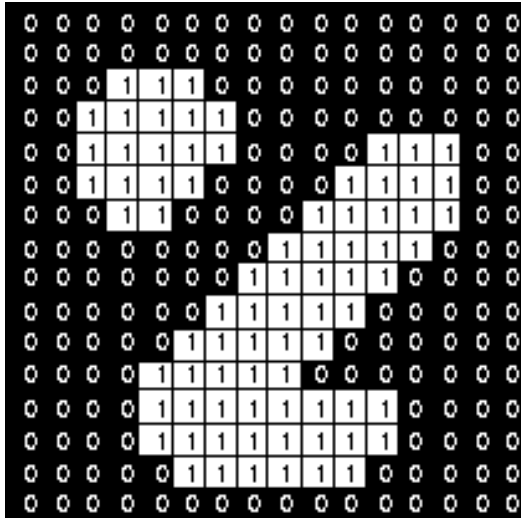


2. filling holes and gaps



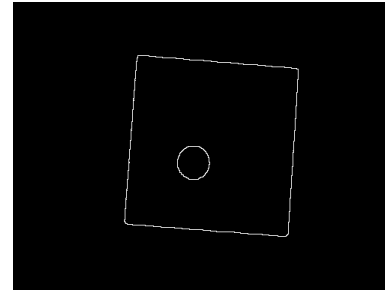
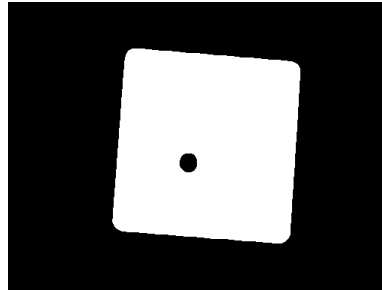
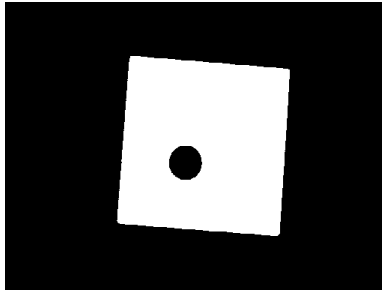
Dilation (max filter)

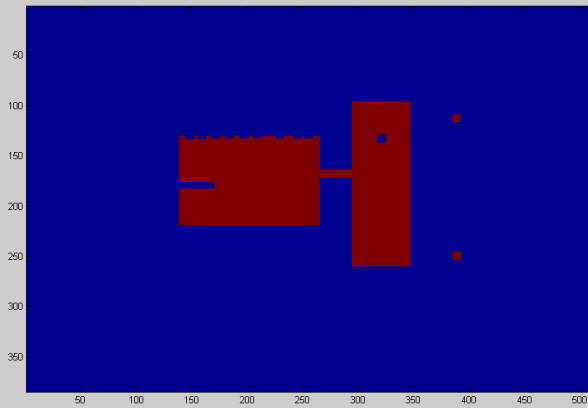
1	1	1
1	1	1
1	1	1



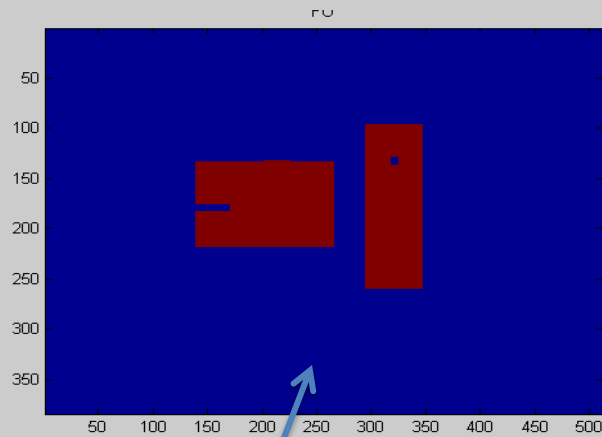
Boundary Detection

1. Dilate input image
2. Subtract input image from dilated image
3. Boundaries remain!

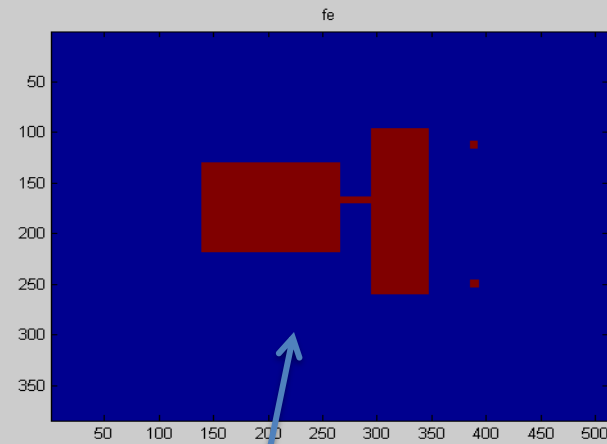




ORIGINAL



OPENING

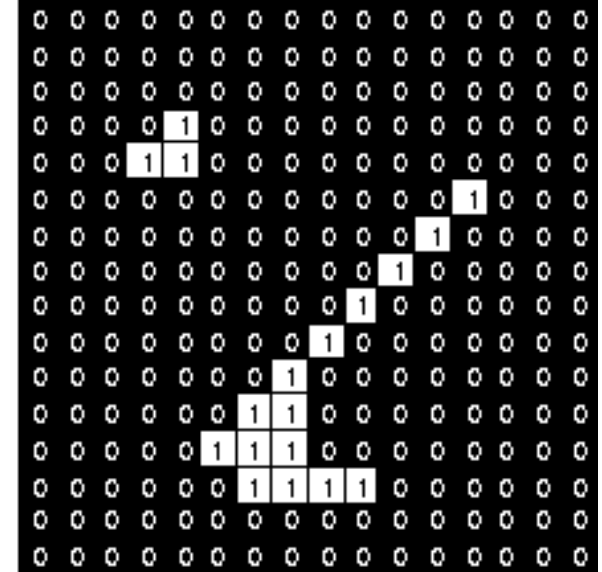
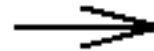
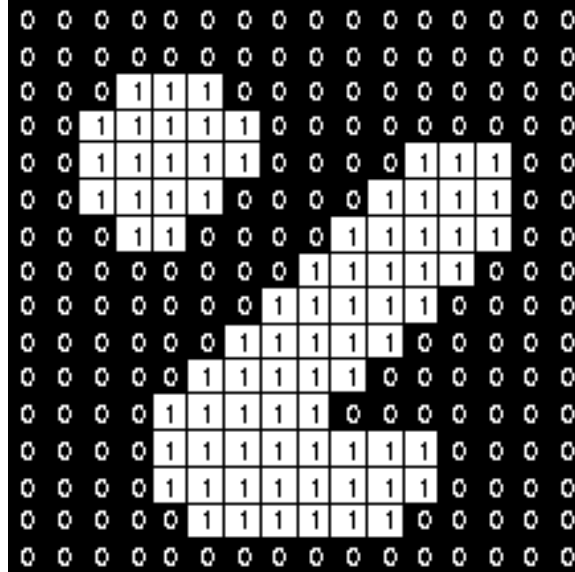


CLOSING

Erosion

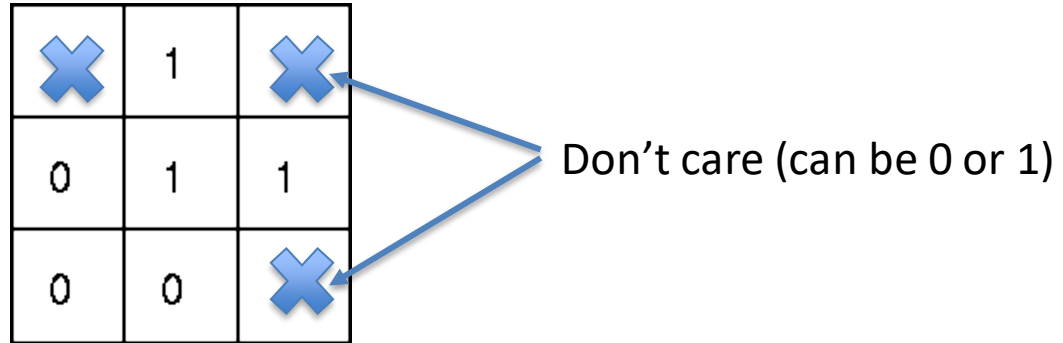
- Simple application of **pattern matching**
 - Fixed template**

1	1	1
1	1	1
1	1	1



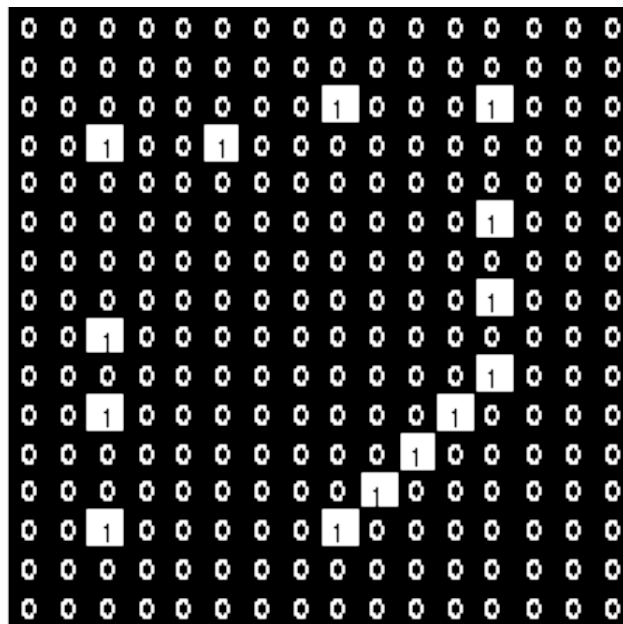
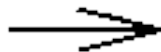
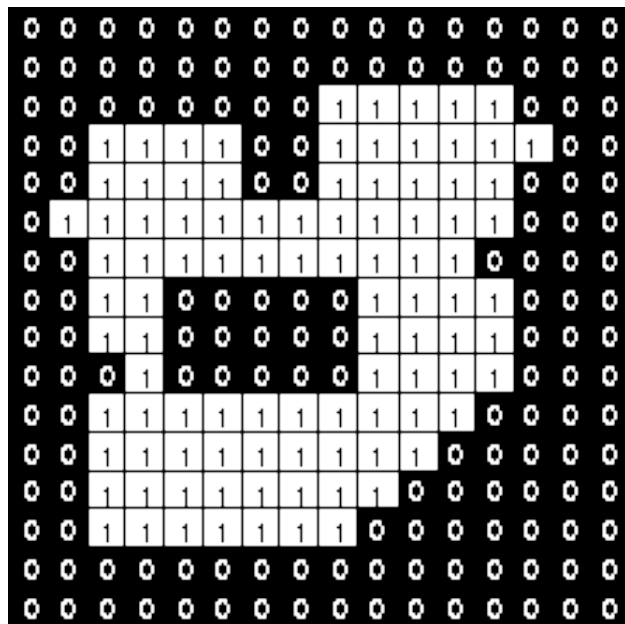
Hit-and-miss Transform

- Look for particular patterns of foreground and background pixels.



- If matched, set pixel = 1

Example: Find right-angled convex corners



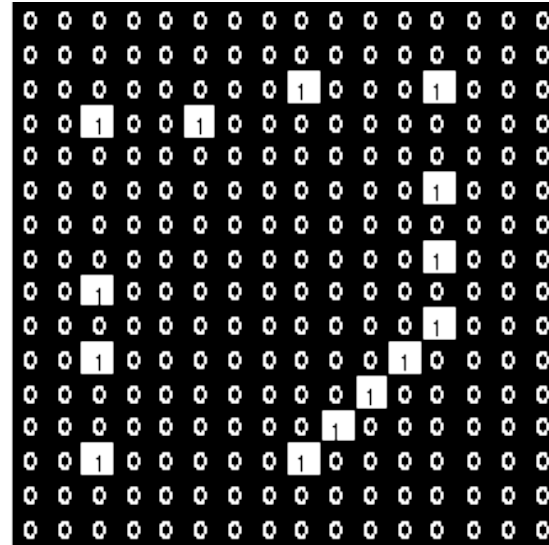
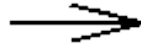
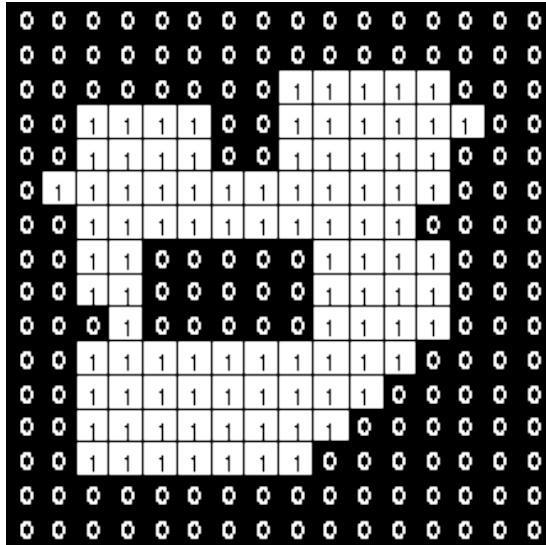
Example: Find right-angled convex corners

	1	
0	1	1
0	0	

	1	
1	1	0
	0	0

	0	0
1	1	0
	1	

0	0	
0	1	1
	1	



Sample HAM transforms

1)

0	0	0
0	1	0
0	0	0

Locate isolated
points

Sample HAM transforms

1)

0	0	0
0	1	0
0	0	0

Locate isolated
points

2)

0	1	0
0	0	0

Locate end points
on thin lines

Sample HAM transforms

1)

0	0	0
0	1	0
0	0	0

Locate isolated
points

2)

0	1	0
0	0	0

Locate end points
on thin/tapering
structures

3a)

	1	
	1	
1		1

3b)

1		
	1	
1		1

3c)

*	0	1
1	1	0
*	1	*

Locate triple junctions

Distance Transform

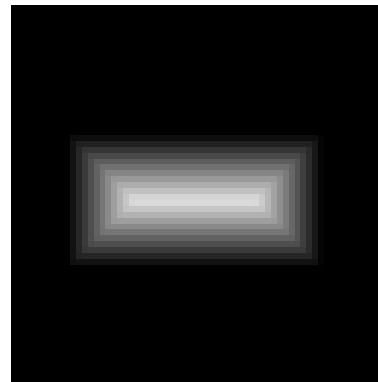
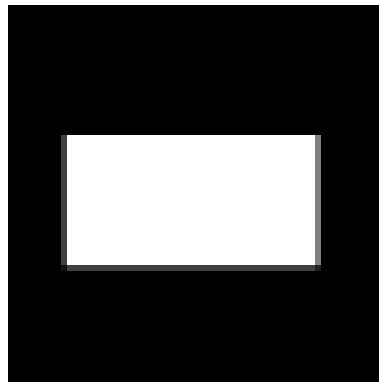
(with chessboard distance metric)

0	0	0	0	0	0	0	0	0	0	0	0	0
0	1	1	1	1	1	1	0	0	0	0	0	0
0	1	1	1	1	1	1	0	0	0	0	0	0
0	1	1	1	1	1	1	0	0	0	0	0	0
0	1	1	1	1	1	1	0	0	0	0	0	0
0	1	1	1	1	1	1	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0

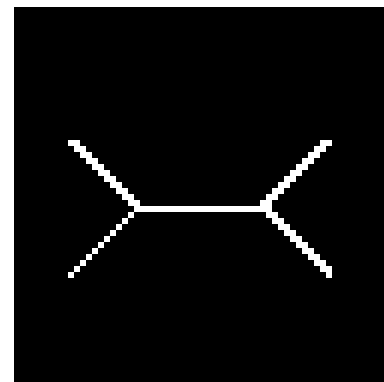
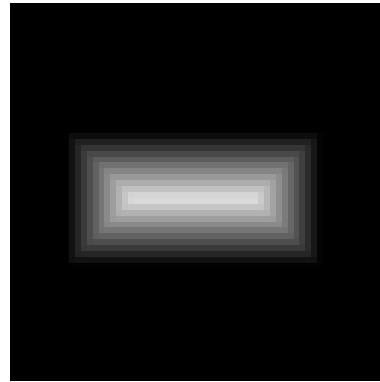
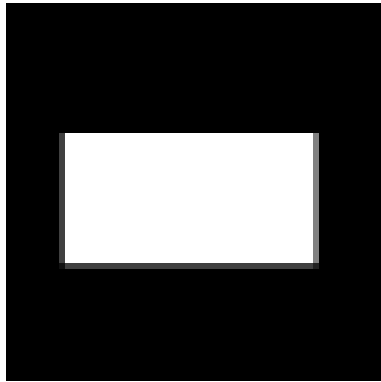
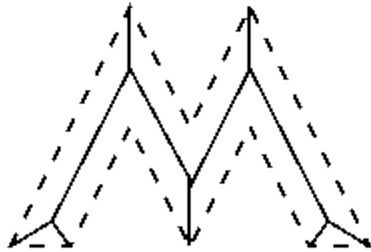
0	0	0	0	0	0	0	0	0	0	0	0	0
0	1	1	1	1	1	1	0	0	0	0	0	0
0	1	2	2	2	2	1	0	0	0	0	0	0
0	1	2	3	2	2	1	0	0	0	0	0	0
0	1	2	2	2	2	1	0	0	0	0	0	0
0	1	1	1	1	1	1	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0

Binary Image

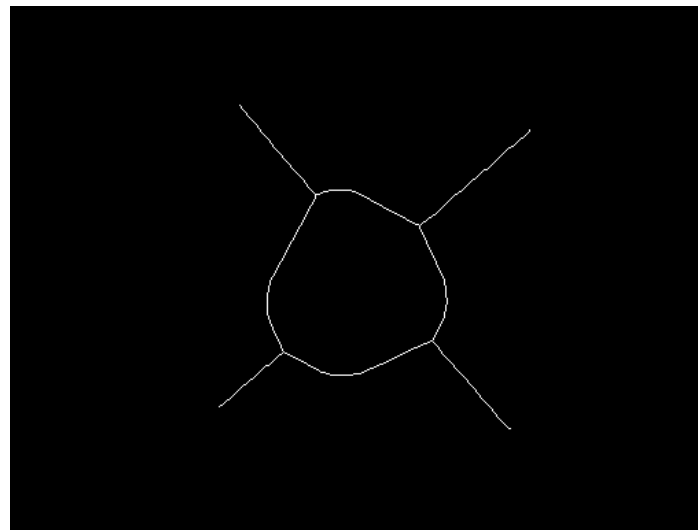
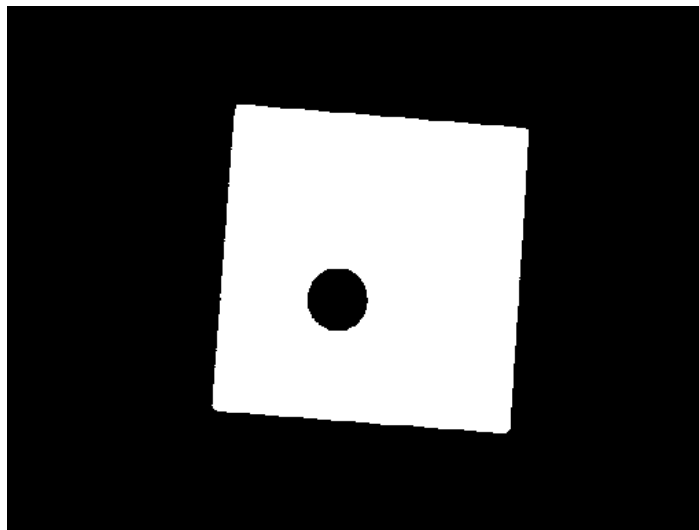
Distance transformation



Skeletonization



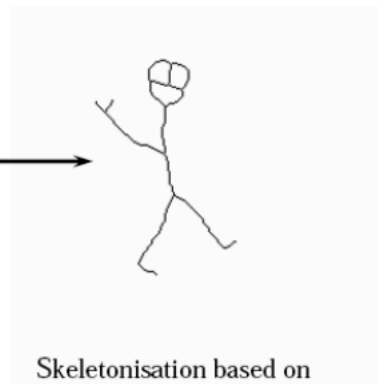
Skeletonization - Example



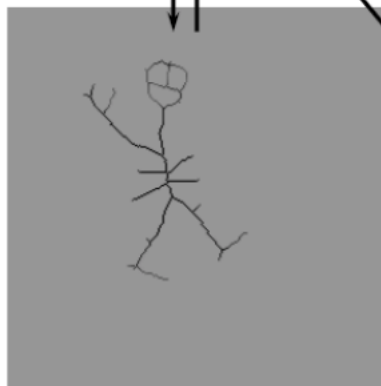
Skeleton



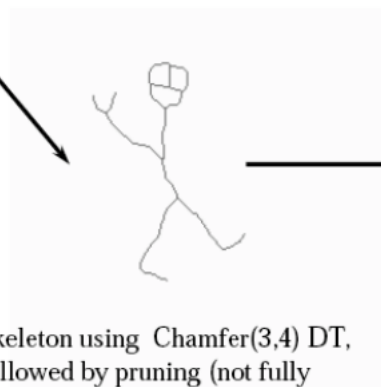
Skeleton



Skeletonisation based on thinning (not reversible)



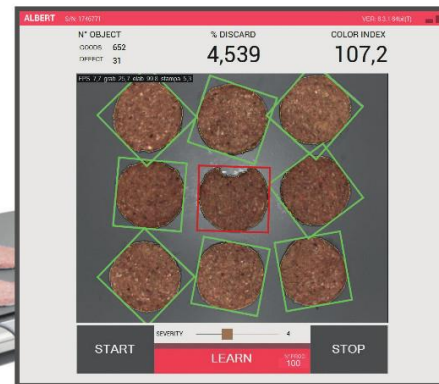
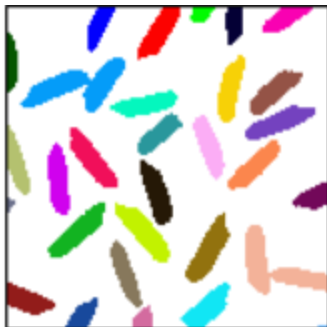
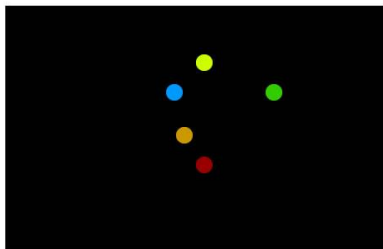
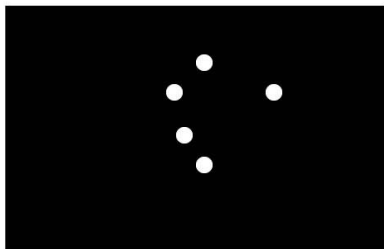
Skeleton using Chamfer(3,4) DT, no pruning (fully reversible)

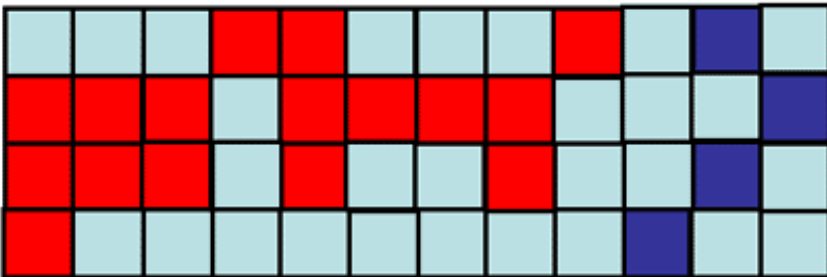
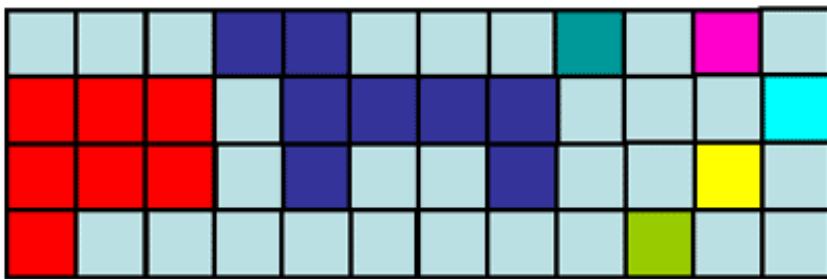
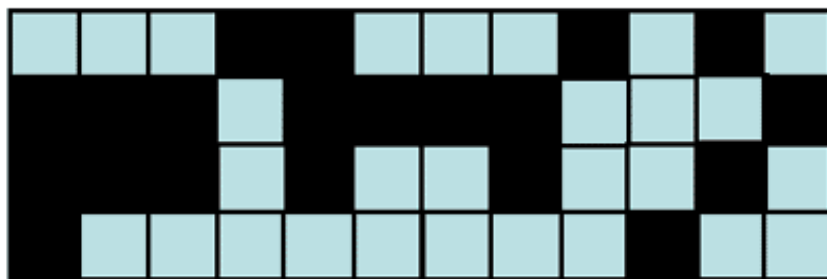


Skeleton using Chamfer(3,4) DT, followed by pruning (not fully reversible)

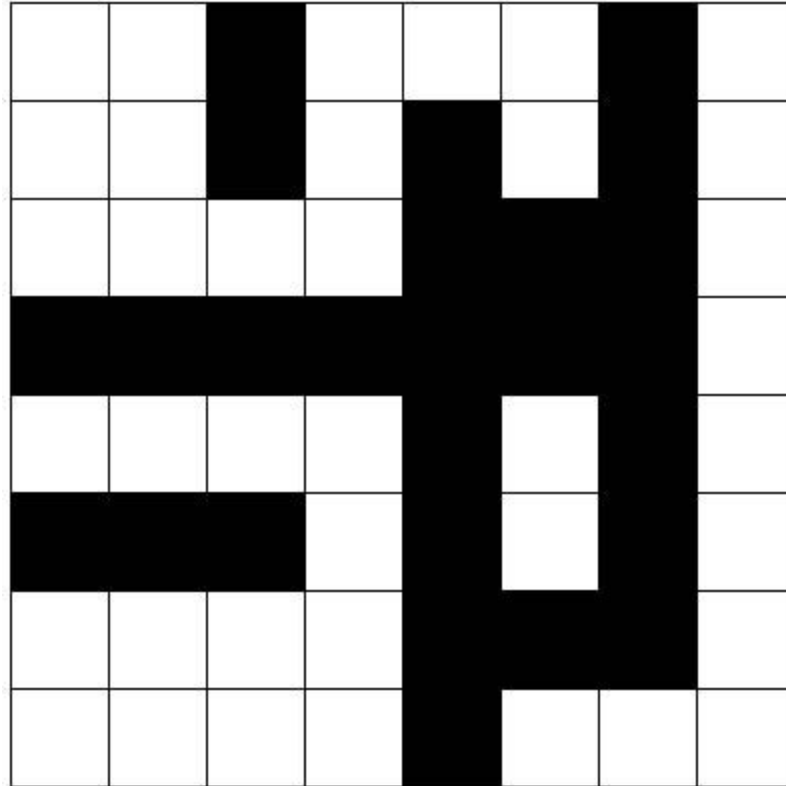


Components

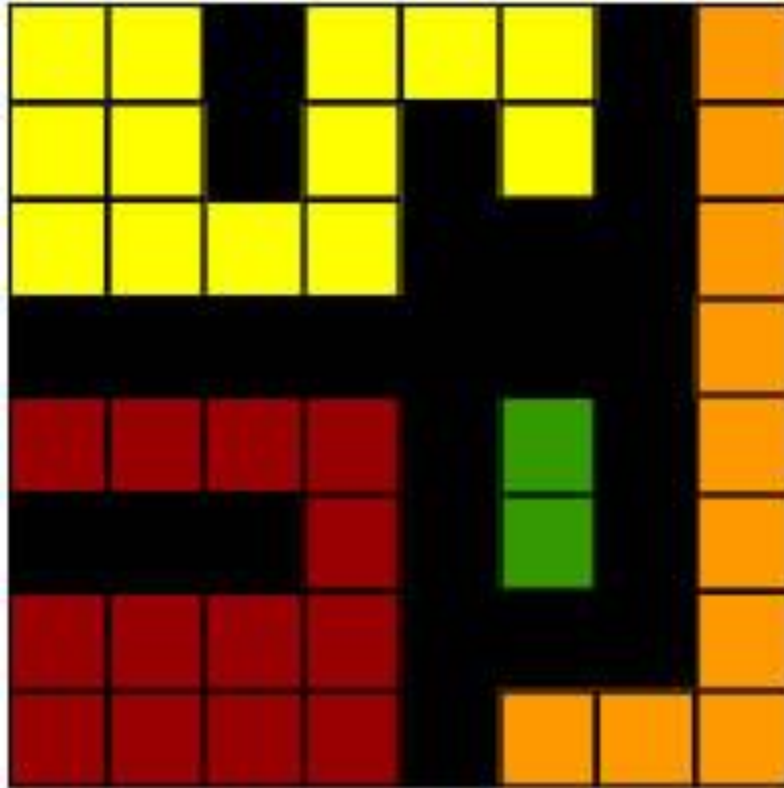




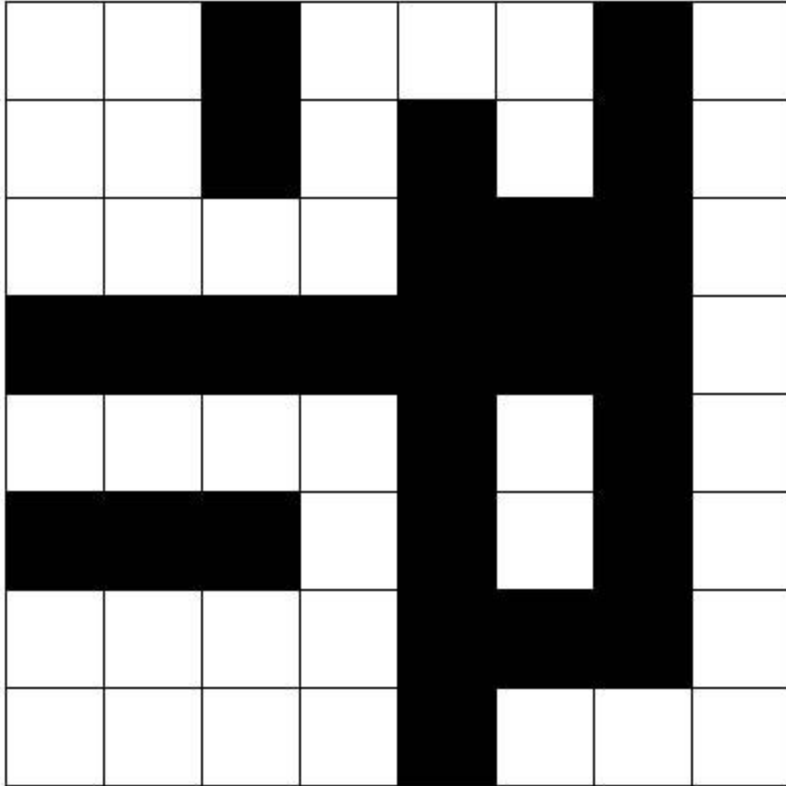
Two-Pass Algorithm for Connected Component Labelling



Two-Pass Algorithm for CCL

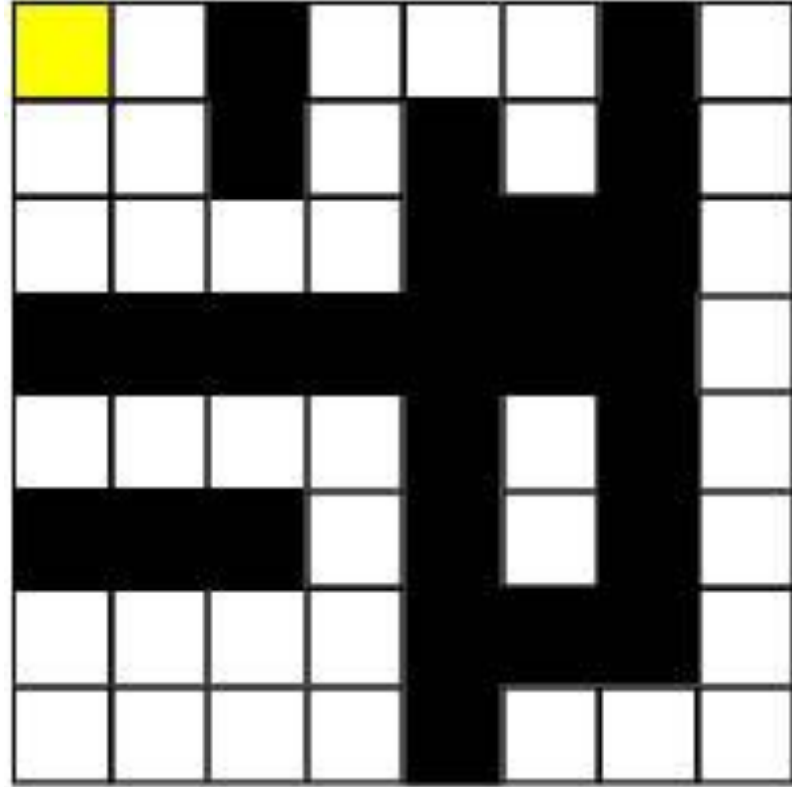
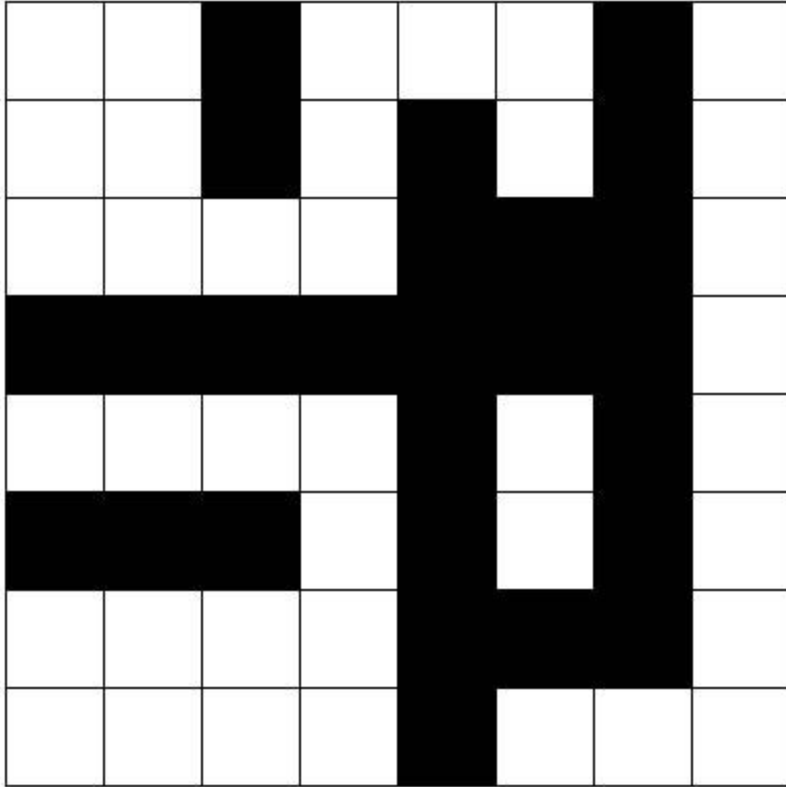


Two-Pass Algorithm for Connected Component Labelling

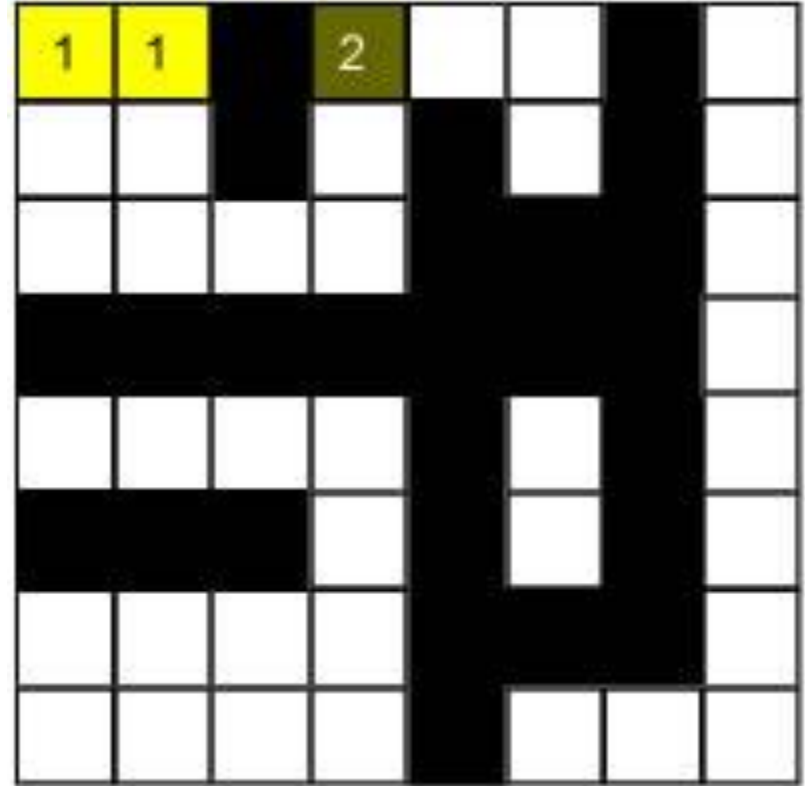
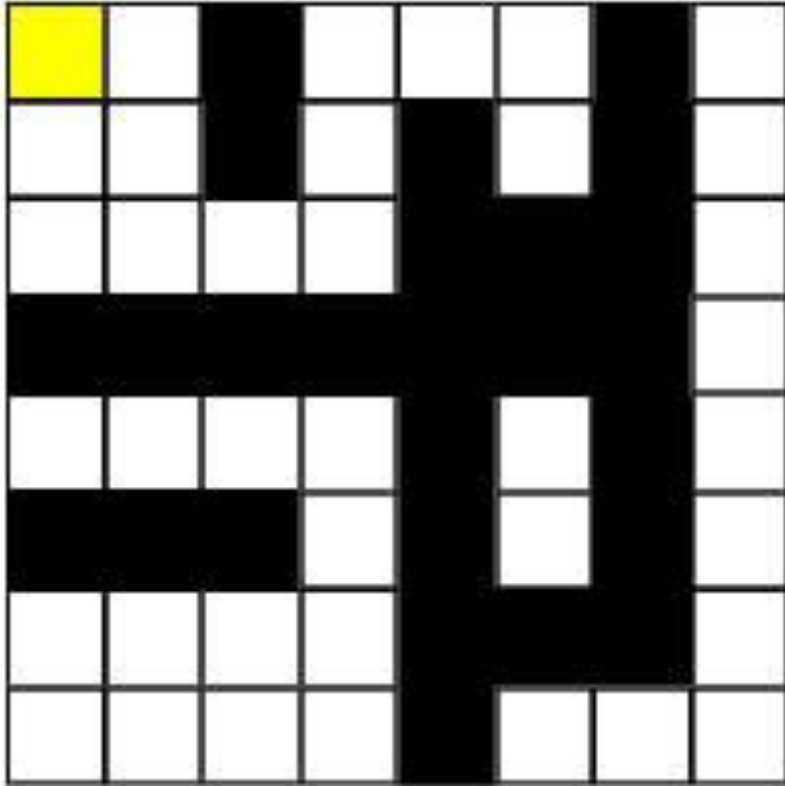


1	1	0	1	1	1	0	1
1	1	0	1	0	1	0	1
1	1	1	1	0	0	0	1
0	0	0	0	0	0	0	1
1	1	1	1	0	1	0	1
0	0	0	1	0	1	0	1
1	1	1	1	0	0	0	1
1	1	1	1	0	1	1	1

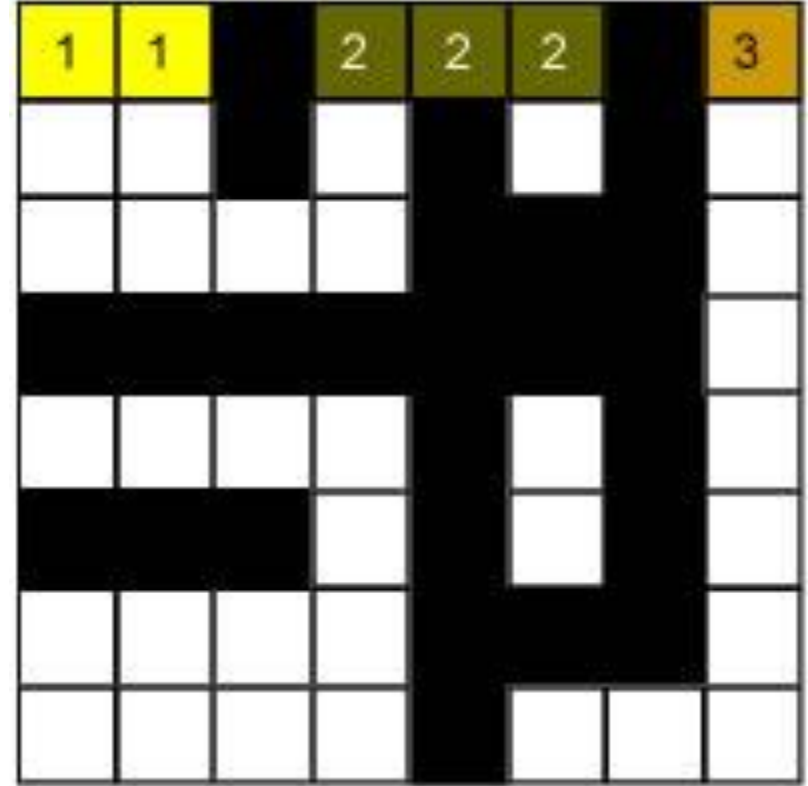
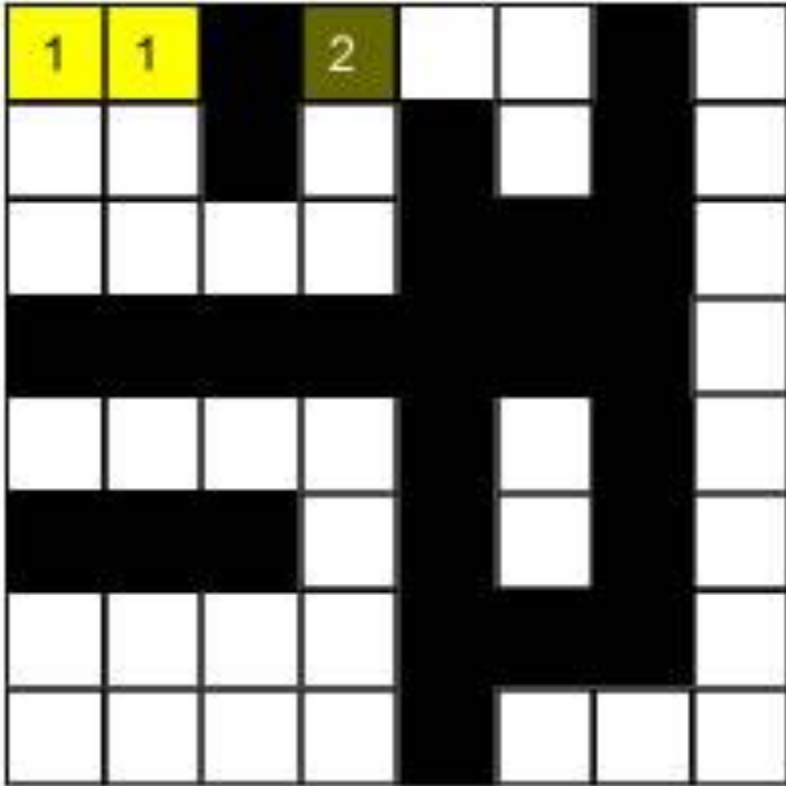
2PA: No top, left pixels → Create new label



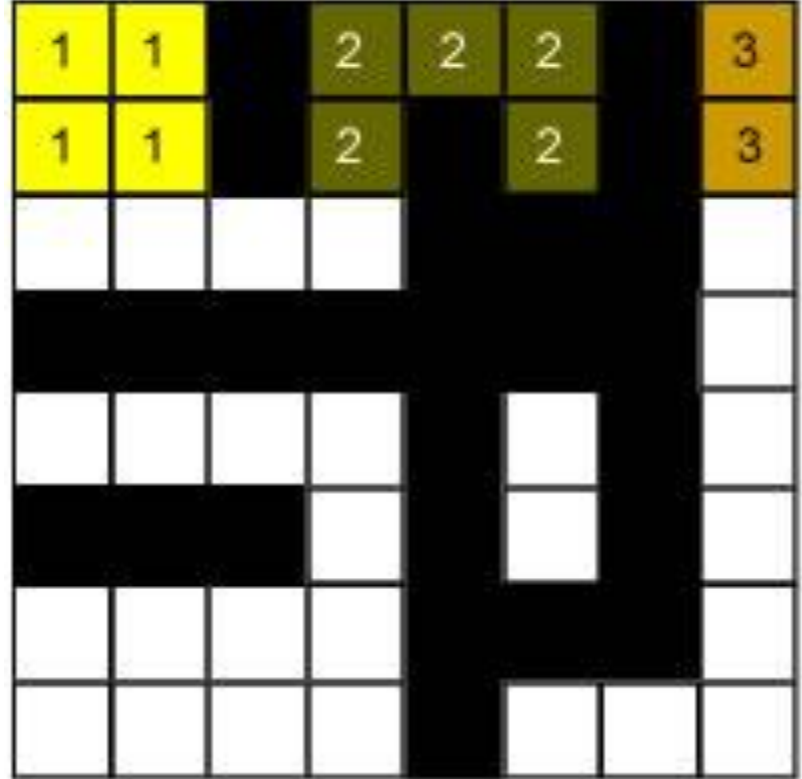
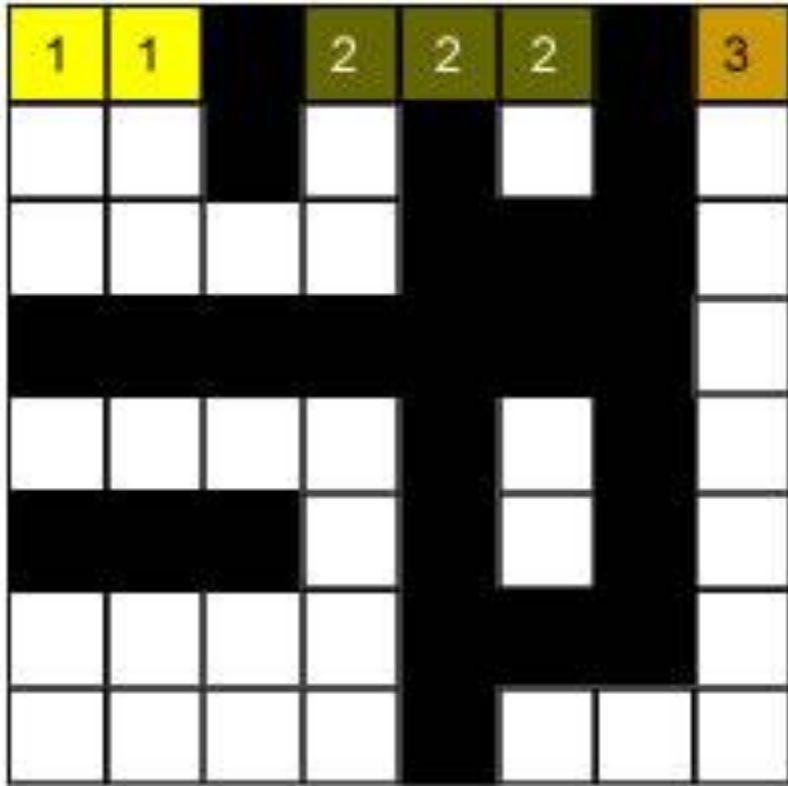
2PA: left pixel labeled → Copy label ; left pixel BG → new label



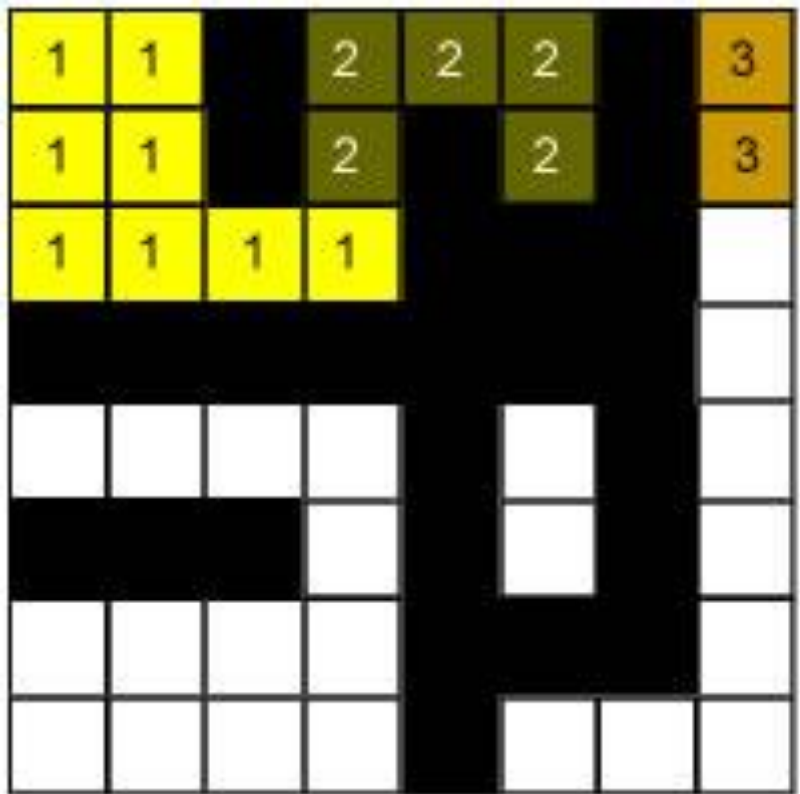
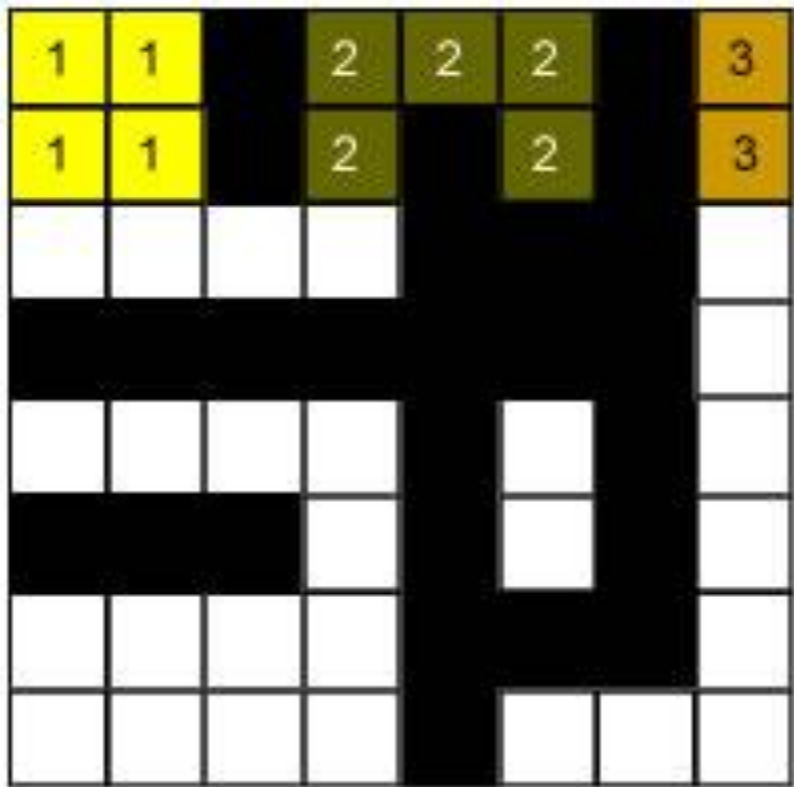
2PA: After row 1 is done



(overrides) left pixel BG → new label

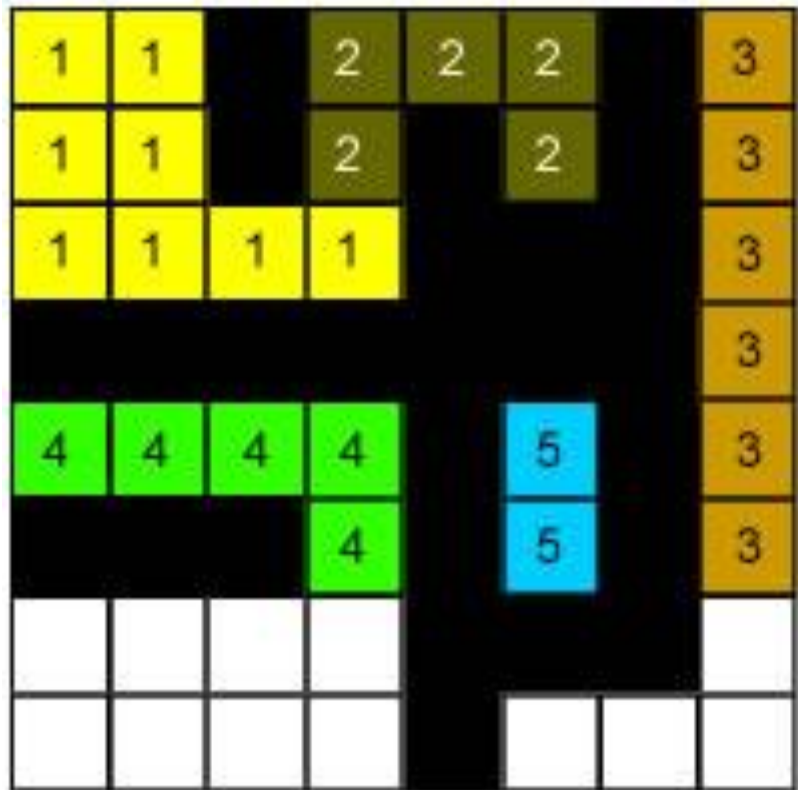
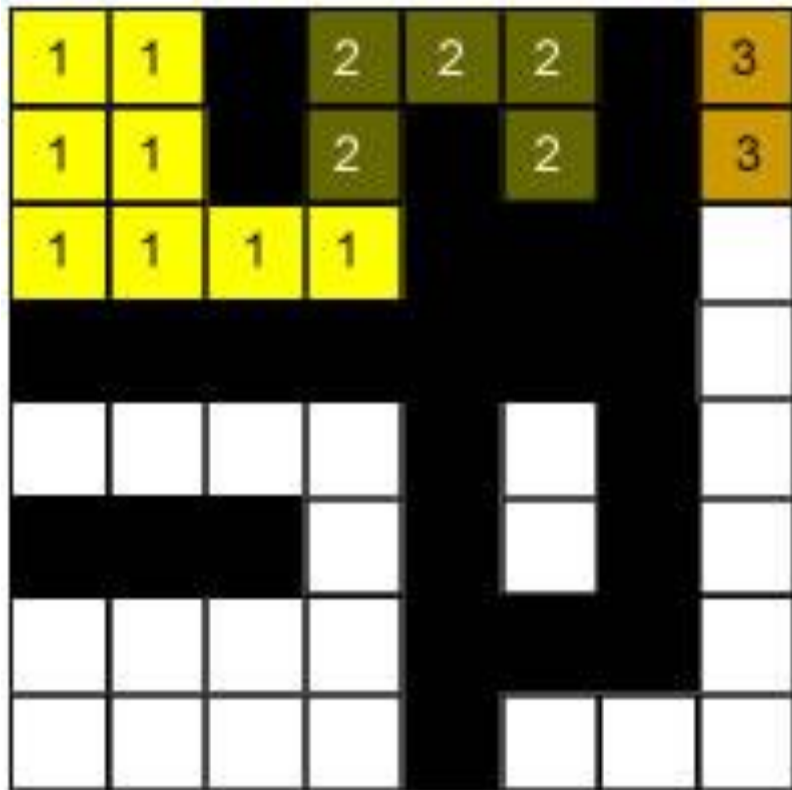


2PA: left/top pixel labeled, different labels → Copy smaller id label, record the association



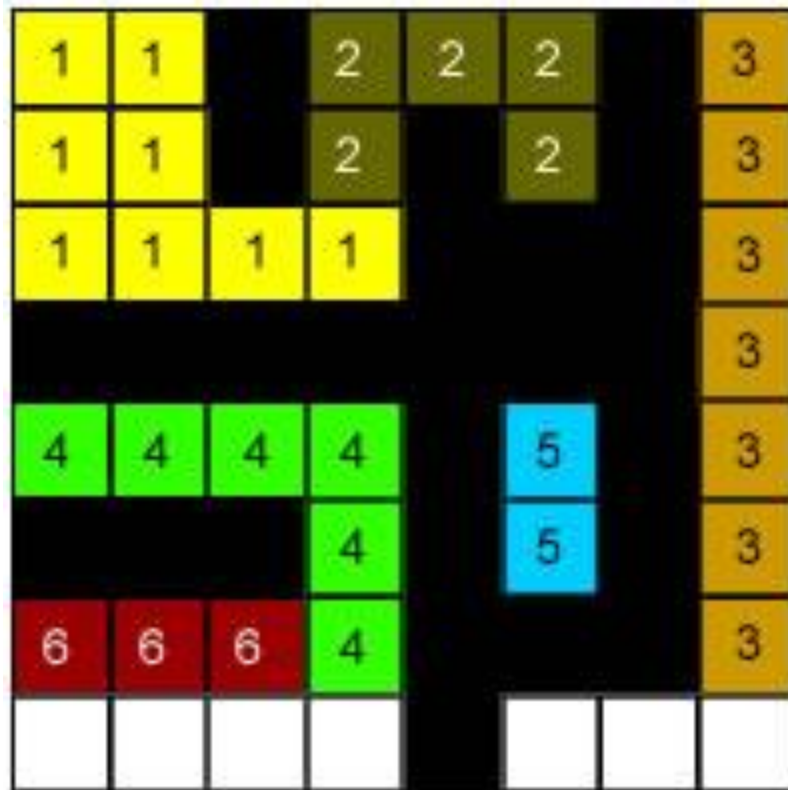
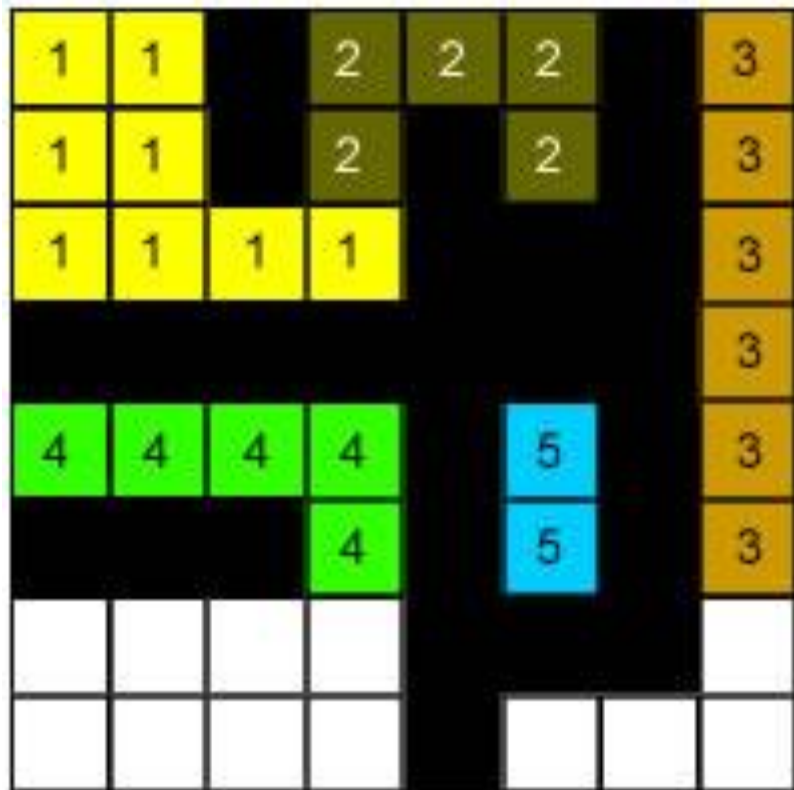
1
↑
2

2PA: left/top pixel labeled, different labels → Copy smaller id label, record the association



1
↑
2

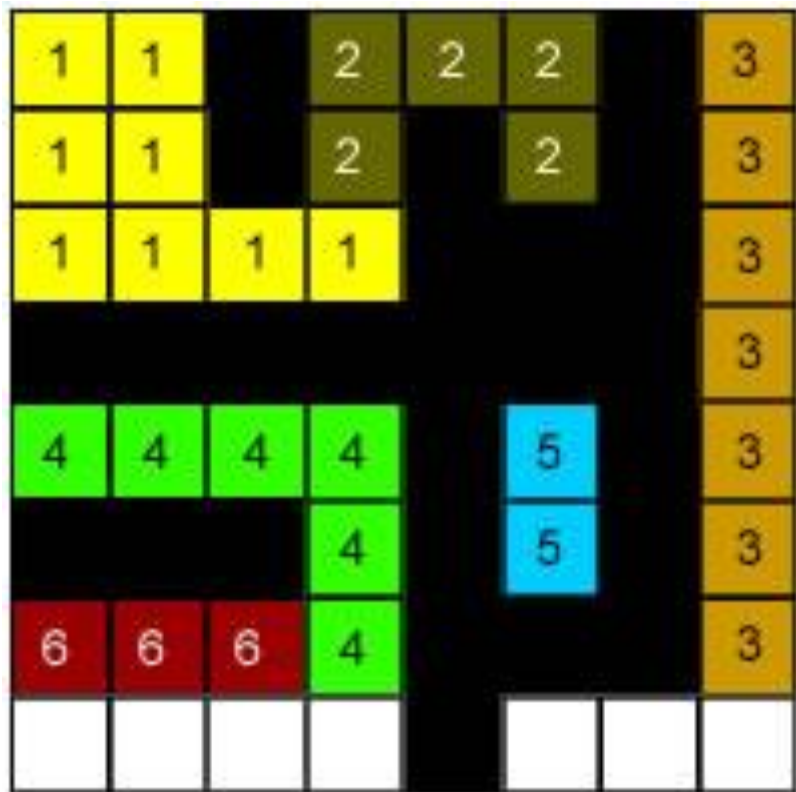
2PA



1
↑
2

4
↑
6

2PA: After first pass is complete

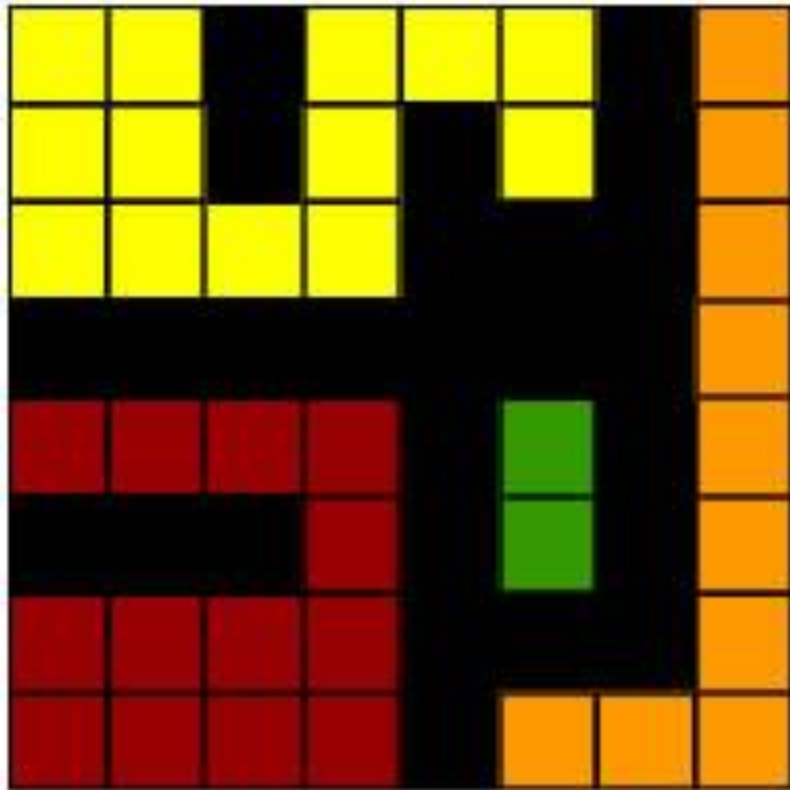


1
↑
2

4
↑
6

3
↑
7

2PA: After first pass is complete



1
↑
2

4
↑
6

3
↑
7

2PA: Second pass: Replace child label with root label.

Union-Find data structure ensures 'find'-ing root is $O(1)$.



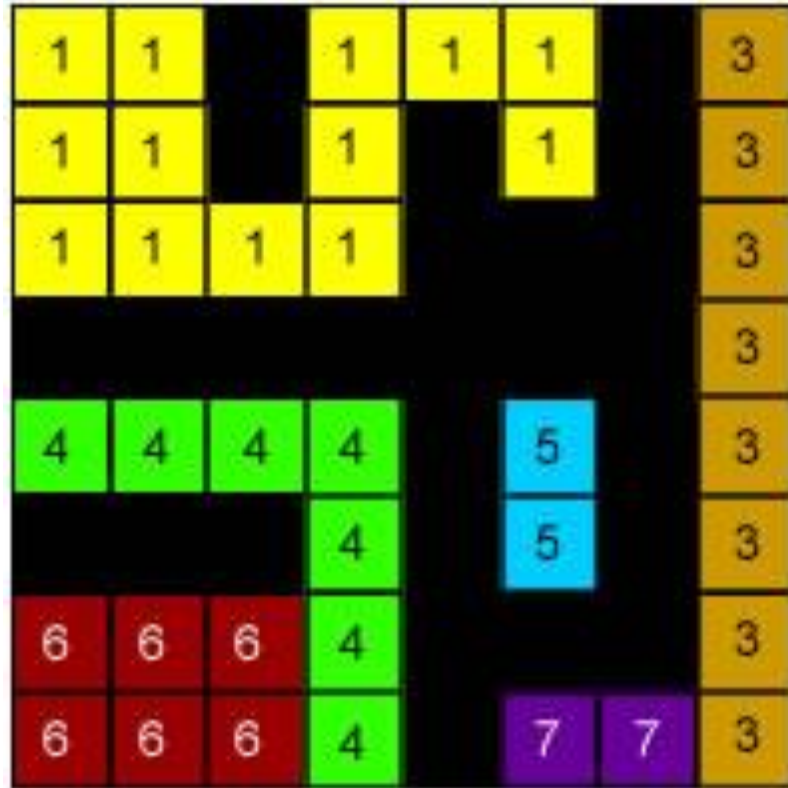
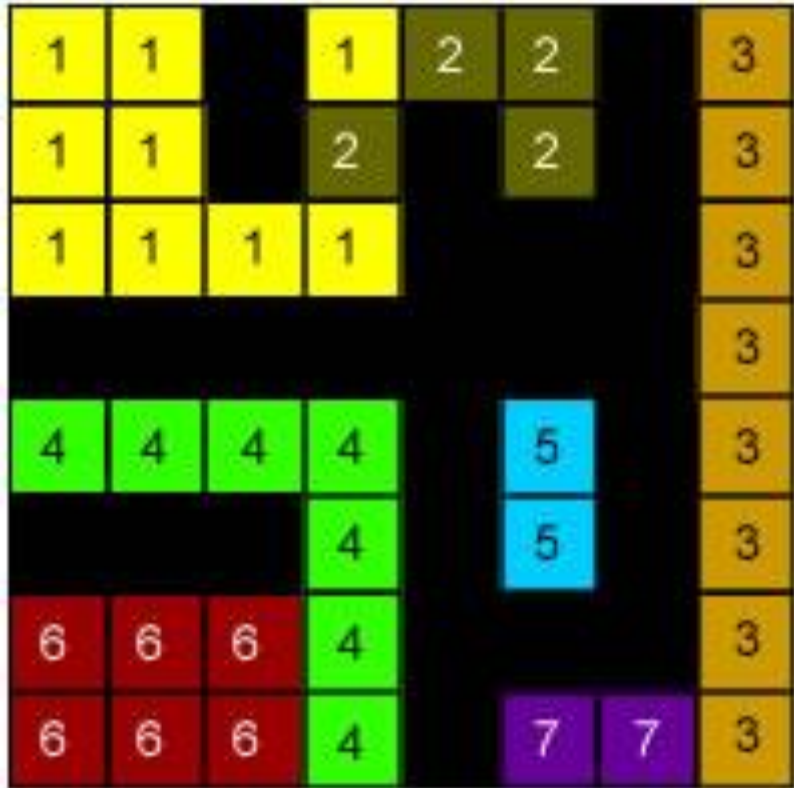
1
↑
2

4
↑
6

3
↑
7

2PA: Second pass: Replace child label with root label.

Union-Find data structure ensures 'find'-ing root is $O(1)$.



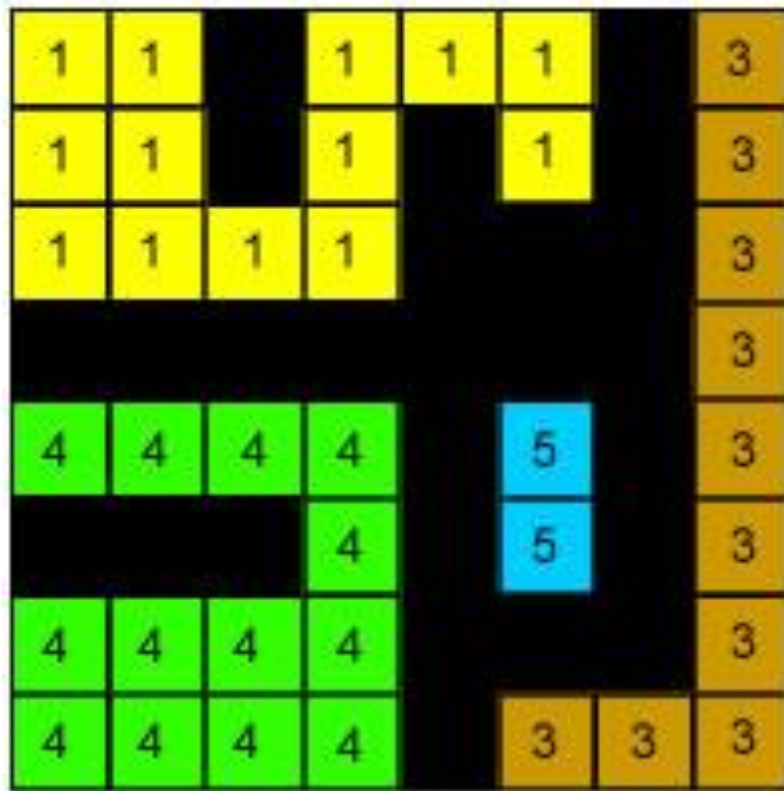
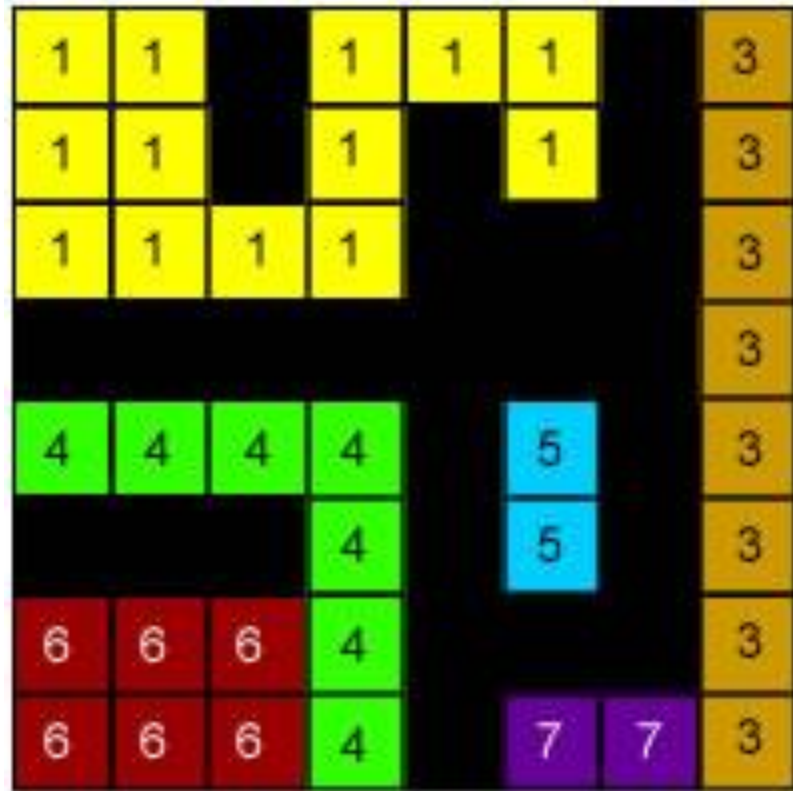
1
↑
2

4
↑
6

3
↑
7

2PA: Second pass: Replace child label with root label.

Union-Find data structure ensures 'find'-ing root is $O(1)$.

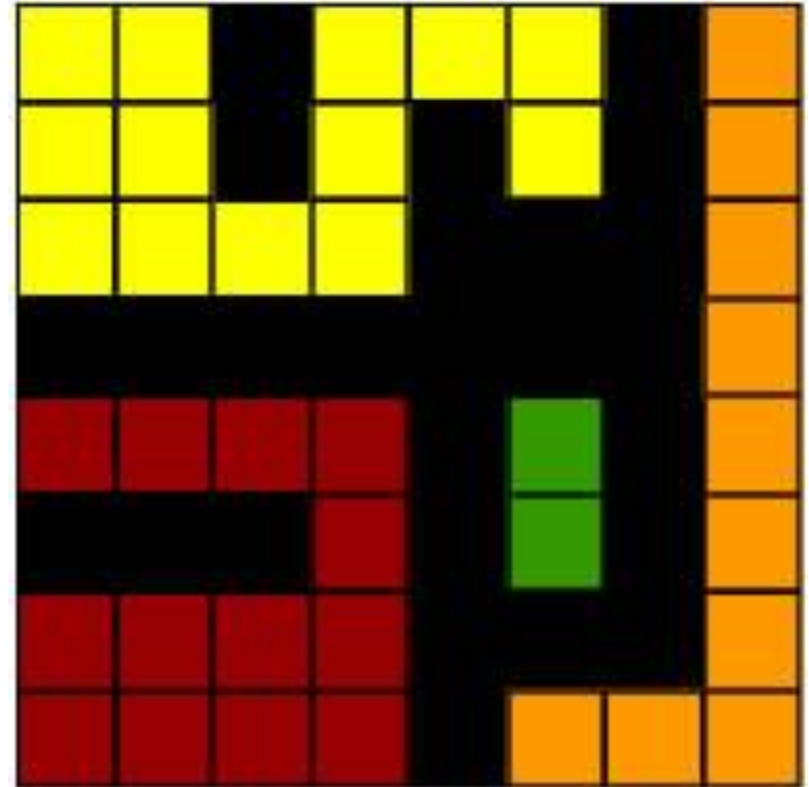
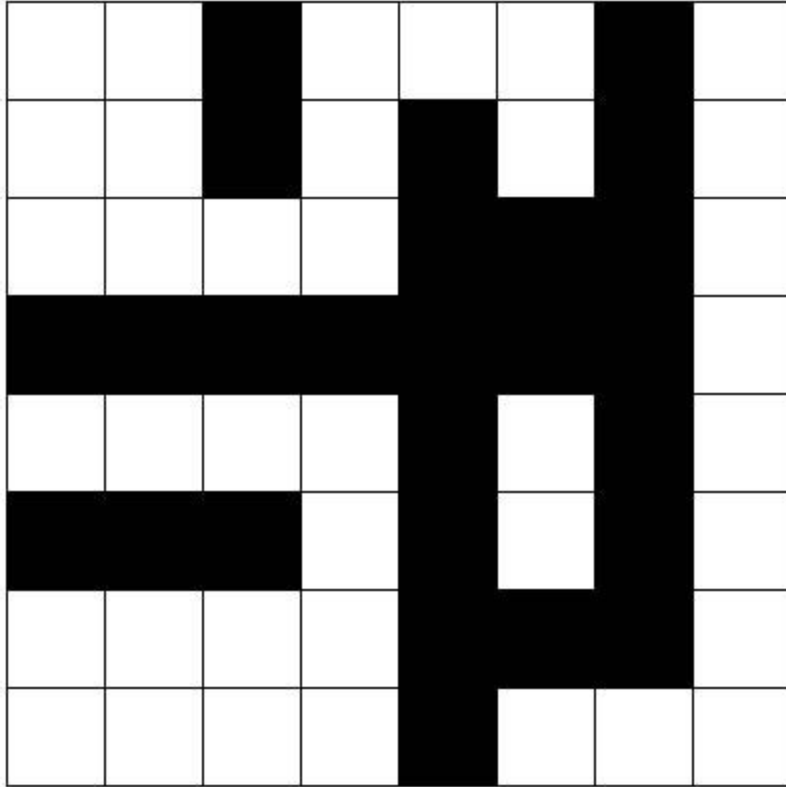


1
↑
2

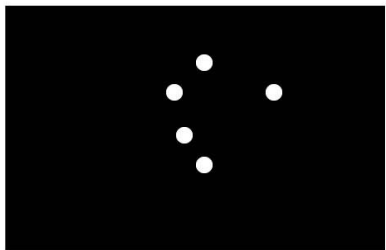
4
↑
6

3
↑
7

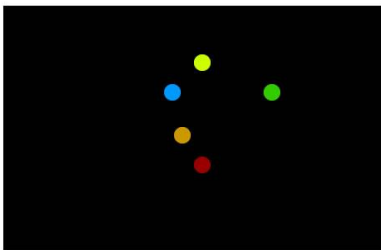
2PA-CCL (Rosenfeld&PFaltz 1968): Requires only two rows of image at a time



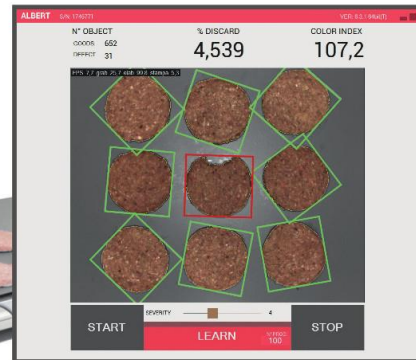
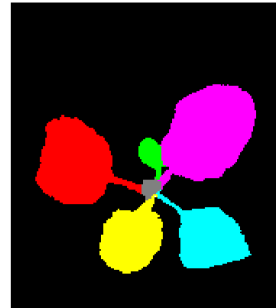
Connected Component Labeling

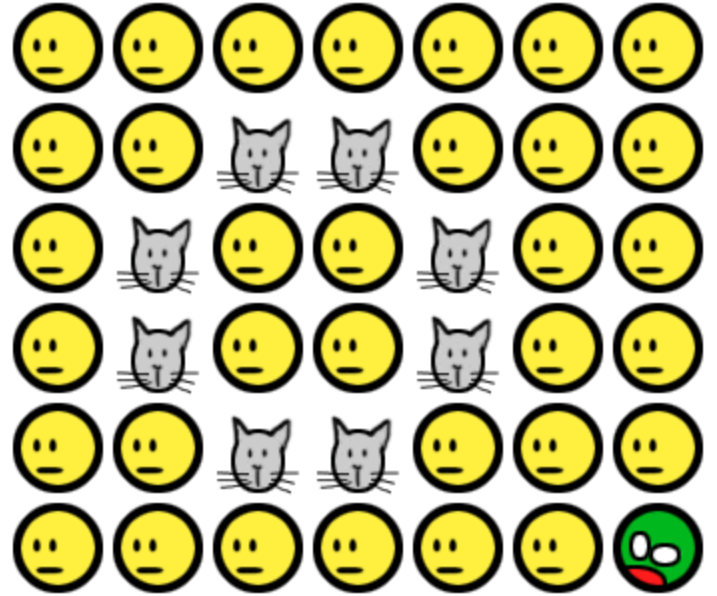
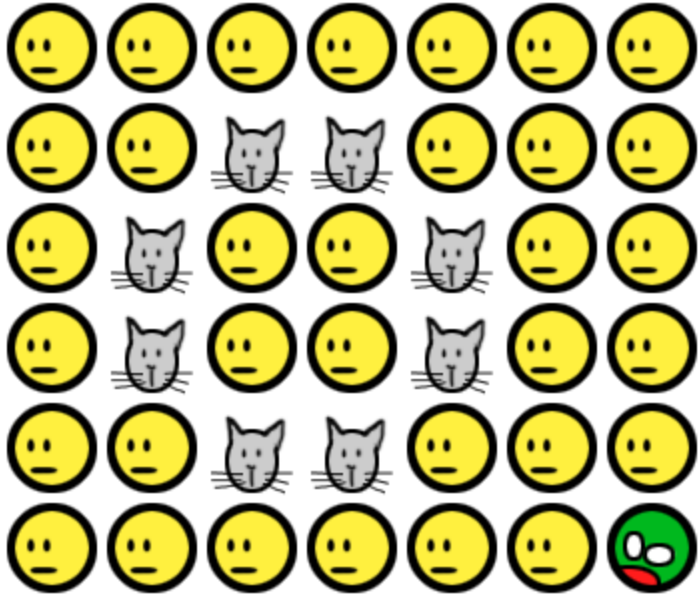


bwlabel

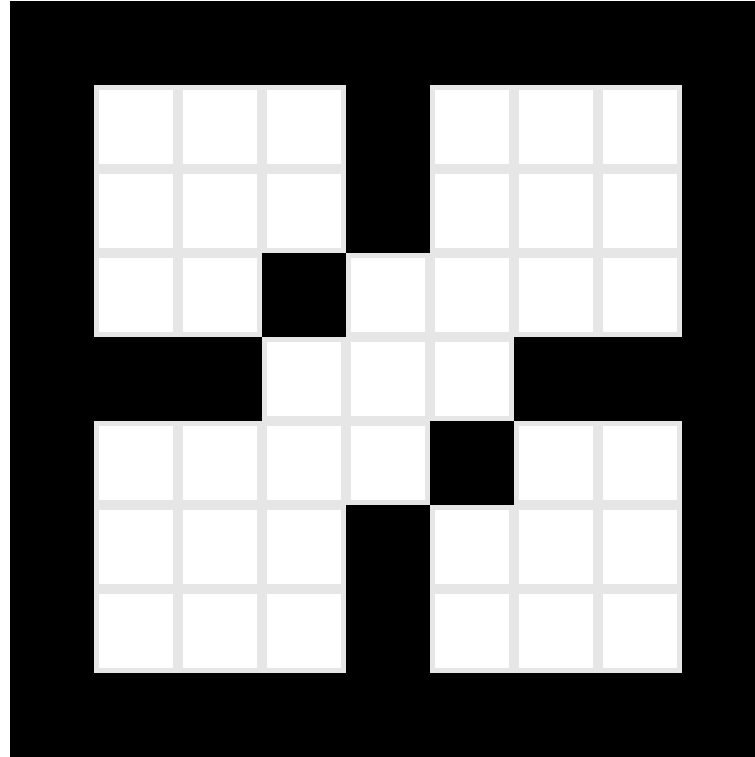
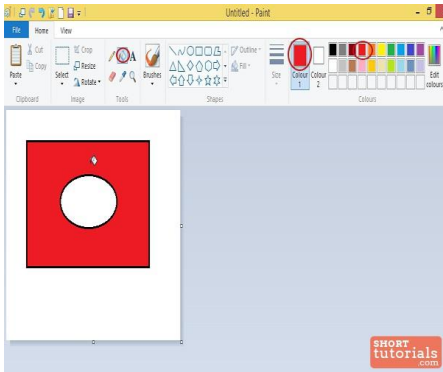


label2rgb

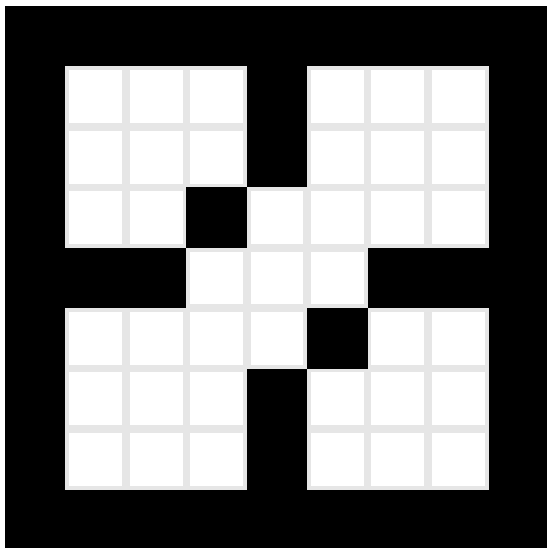




Flood-Fill



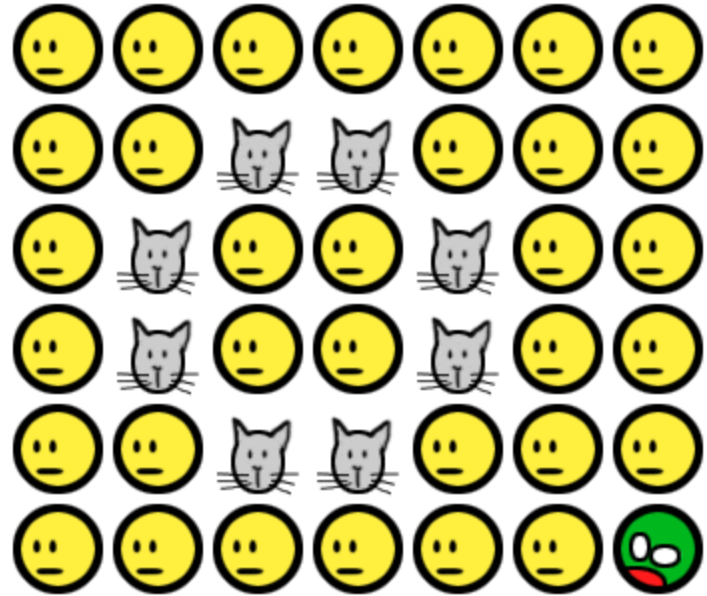
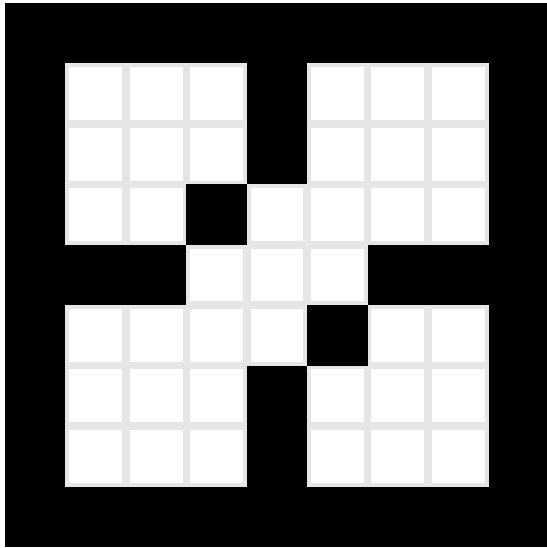
Flood-Fill Algorithm (4-conn)



```
void floodFill(int x, int y, int fill, int old)
{
    if ((x < 0) || (x >= width)) return;
    if ((y < 0) || (y >= height)) return;
    if (getPixel(x, y) == old) {
        setPixel(fill, x, y);
        floodFill(x+1, y, fill, old);
        floodFill(x, y+1, fill, old);
        floodFill(x-1, y, fill, old);
        floodFill(x, y-1, fill, old);
    }
}
```

Many/More efficient versions exist !

If 8-conn, all white pixels filled
(all humans eventually become zombie !)



Summary of Morphological Filtering

Operation	Equation	Comments
		(The Roman numerals refer to the structuring elements shown in Fig. 9.26).
Translation	$(A)_z = \{w w = a + z, \text{ for } a \in A\}$	Translates the origin of A to point z .
Reflection	$\hat{B} = \{w w = -b, \text{ for } b \in B\}$	Reflects all elements of B about the origin of this set.
Complement	$A^c = \{w w \notin A\}$	Set of points not in A .
Difference	$A - B = \{w w \in A, w \notin B\}$ $= A \cap B^c$	Set of points that belong to A but not to B .
Dilation	$A \oplus B = \{z (\hat{B})_z \cap A \neq \emptyset\}$	"Expands" the boundary of A . (I)
Erosion	$A \ominus B = \{z (B)_z \subseteq A\}$	"Contracts" the boundary of A . (I)
Opening	$A \circ B = (A \ominus B) \oplus B$	Smooths contours, breaks narrow isthmuses, and eliminates small islands and sharp peaks. (I)
Closing	$A \bullet B = (A \oplus B) \ominus B$	Smooths contours, fuses narrow breaks and long thin gulfs, and eliminates small holes. (I)

MATLAB codes

`circshift(A,z)`

`fliplr(flipud(B))`

`~A` or `1-A`

`A & ~B`

`imdilate(A,B)`

`imerode(A,B)`

`imopen(A,B)`

`imclose(A,B)`

Summary (Con'd)

Hit-or-miss transform	$A \odot B = (A \ominus B_1) \cap (A^c \ominus B_2)$ $= (A \ominus B_1) - (A \oplus \hat{B}_2)$	The set of points (coordinates) at which, simultaneously, B_1 found a match ("hit") in A and B_2 found a match in A^c .	<code>bwhitmiss(A,B)</code>
Boundary extraction	$\beta(A) = A - (A \ominus B)$	Set of points on the boundary of set A . (I)	<code>A & ~(imerode(A,B))</code>
Region filling	$X_k = (X_{k-1} \oplus B) \cap A; X_0 = p \text{ and } k = 1, 2, 3, \dots$	Fills a region in A , given a point p in the region. (II)	<code>region_fill.m</code>
Thinning	$A \otimes B = A - (A \oplus B)$ $= A \cap (A \oplus B)^c$ $A \otimes \{B\} =$ $(((\dots ((A \otimes B^1) \otimes B^2) \dots) \otimes B^n)$ $\{B\} = \{B^1, B^2, B^3, \dots, B^n\}$	<p>Thins set A. The first two equations give the basic definition of thinning.</p> <p>The last two equations denote thinning by a sequence of structuring elements. This method is normally used in practice. (IV)</p>	<code>bwmorph(A,'thin');</code>

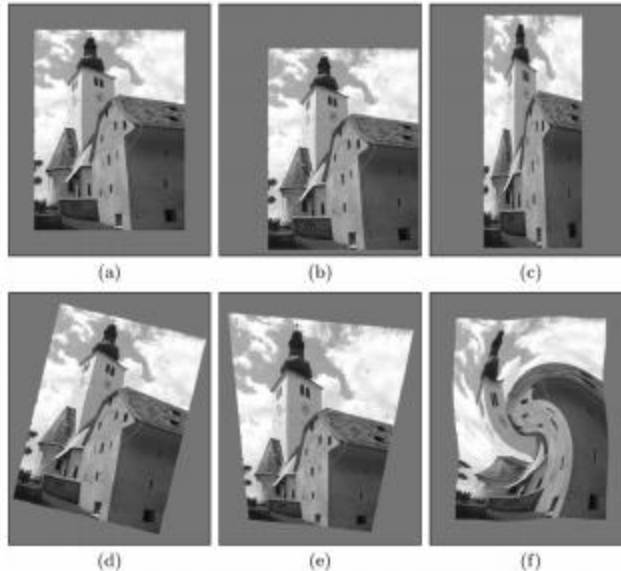
Morphological Filtering using MATLAB

- <https://in.mathworks.com/help/images/morphological-filtering.html>

GEOMETRIC OPERATIONS

Geometric Operations

- Filters, point operations change intensity
- Pixel position (and geometry) unchanged
- Geometric operations: change image geometry
- **Examples:** translating, rotating, scaling an image



**Examples of
Geometric
operations**

Geometric Operations

- Example applications of geometric operations:
 - Zooming images, windows to arbitrary size
 - Computer graphics: deform textures and map to arbitrary surfaces
- **Definition:** Geometric operation transforms image I to new image I' by modifying **coordinates of image pixels**

$$I(x, y) \rightarrow I'(x', y')$$

- Intensity value originally at (x, y) moved to new position (x', y')

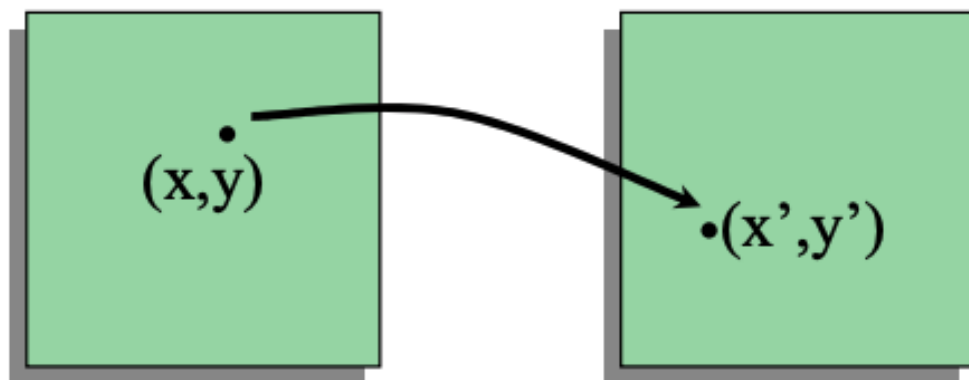
Example: Translation
geometric operation
moves value at
 (x, y) to $(x + d_x, y + d_y)$



$$x \rightarrow f_x(x, y) = x'$$

$$y \rightarrow f_y(x, y) = y'$$

$$I(x, y) = I'(f_x(x, y), f_y(x, y))$$



$I(x, y)$

$I'(x', y')$

Common Geometric Operations



- **Scale** - change image content size



- **Rotate** - change image content orientation



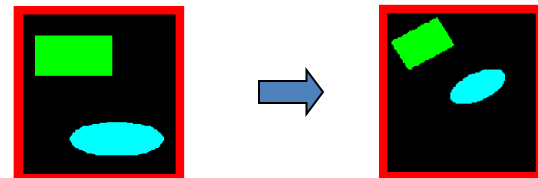
- **Reflect** - flip over image contents



- **Translate** - change image content position



- **Affine Transformation**
 - general image content linear geometric transformation



Simple Mappings

- **Translation:** (shift) by a vector (d_x, d_y)

$$\begin{aligned} T_x : x' &= x + d_x \\ T_y : y' &= y + d_y \end{aligned} \quad \text{or} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} d_x \\ d_y \end{pmatrix}$$



Simple Mappings

- **Translation:** (shift) by a vector (d_x, d_y)

$$\begin{aligned} T_x : x' &= x + d_x \\ T_y : y' &= y + d_y \end{aligned} \quad \text{or} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} d_x \\ d_y \end{pmatrix}$$

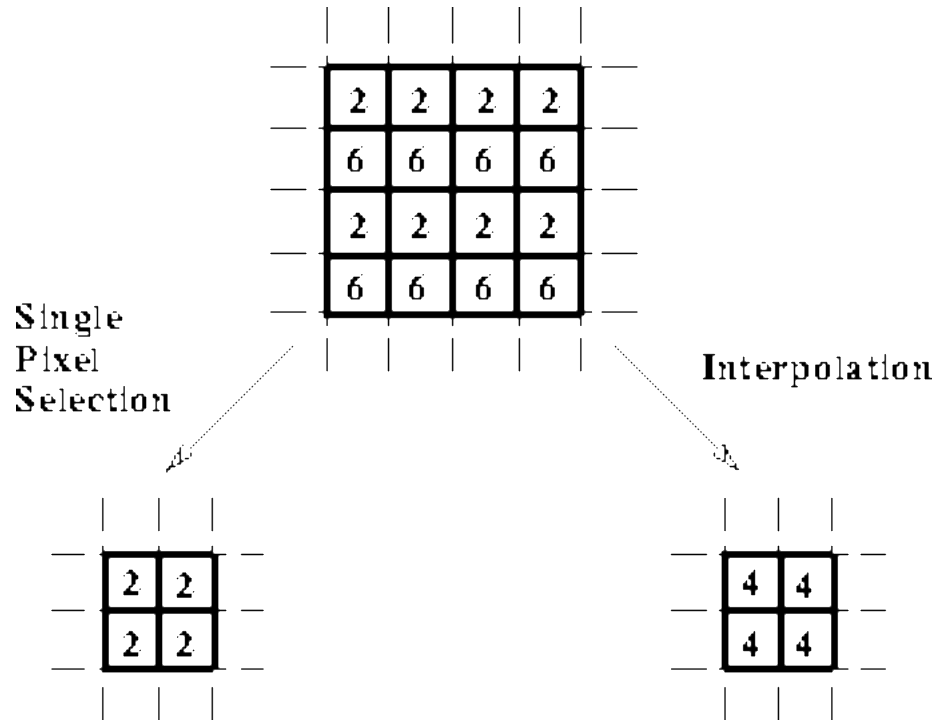


- **Scaling:** (contracting or stretching) along x or y axis by a factor s_x or s_y

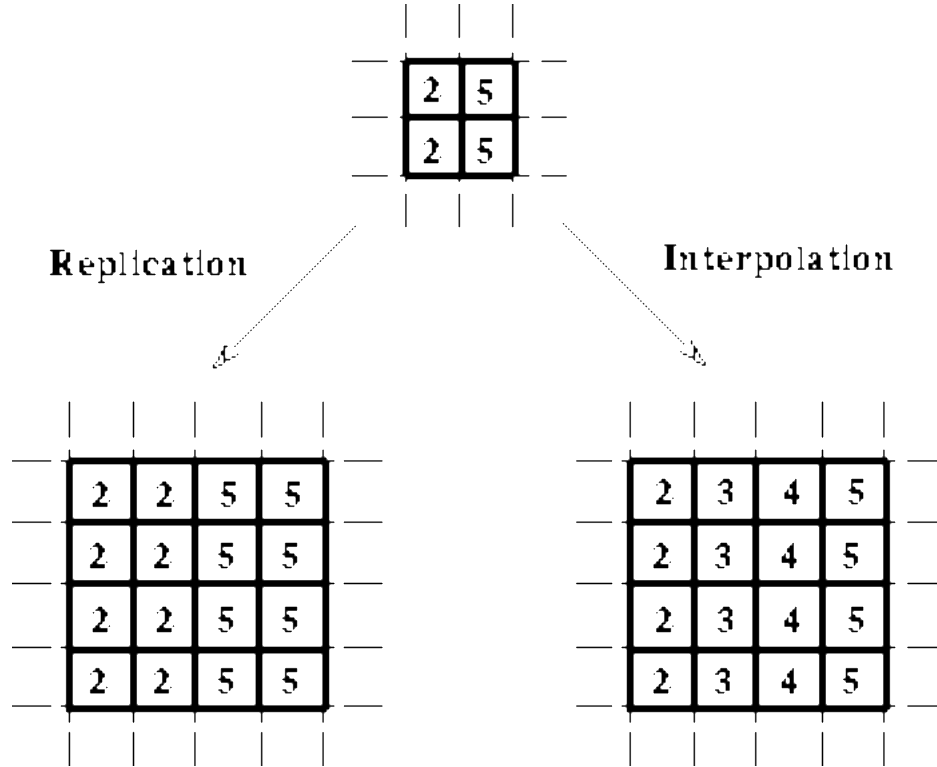
$$\begin{aligned} T_x : x' &= s_x \cdot x \\ T_y : y' &= s_y \cdot y \end{aligned} \quad \text{or} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} s_x & 0 \\ 0 & s_y \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$



Scaling (Shrink)



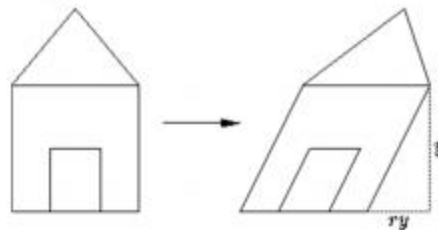
Scaling (Stretch)



Simple Mappings

- **Shearing:** along x and y axis by factor b_x and b_y

$$\begin{aligned} T_x : x' &= x + b_x \cdot y \\ T_y : y' &= y + b_y \cdot x \end{aligned} \quad \text{or} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 1 & b_x \\ b_y & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$



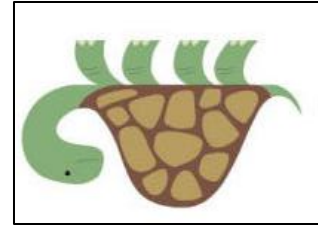
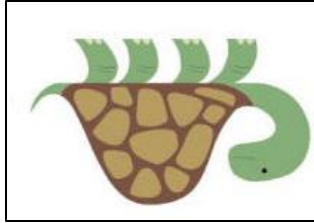
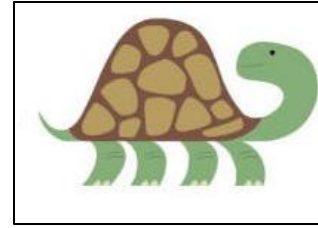
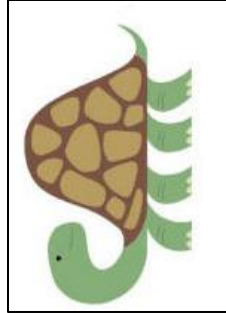
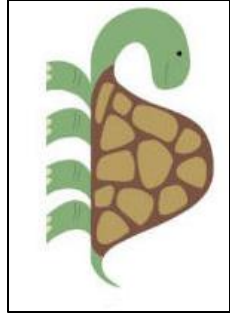
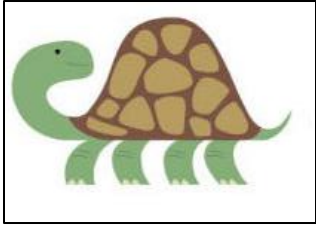
- **Rotation:** the image by an angle α

$$\begin{aligned} T_x : x' &= x \cdot \cos \alpha - y \cdot \sin \alpha \\ T_y : y' &= x \cdot \sin \alpha + y \cdot \cos \alpha \end{aligned}$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

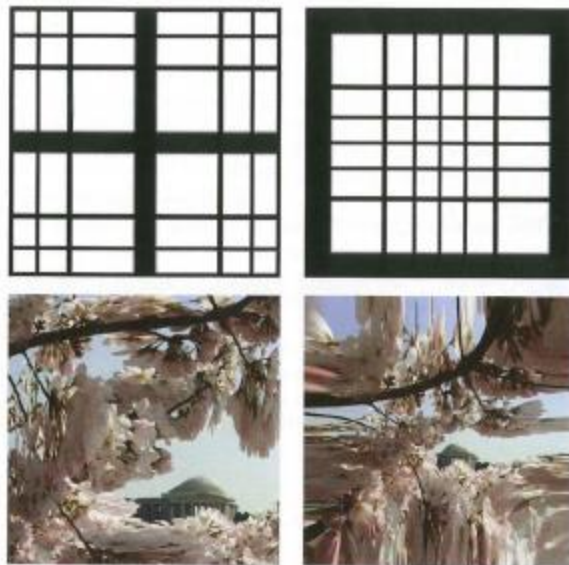


90, 180 rotations , Flipping



- **Image warping:** we can use a function to select which pixel somewhere else in the image to look up
- For example: apply function on both texel coordinates (x, y)

$$x' = x + y * \sin(\pi * x)$$



Homogeneous Coordinates

- Notation useful for converting scaling, translation, rotating into point-matrix multiplication
- To convert ordinary coordinates into homogeneous coordinates

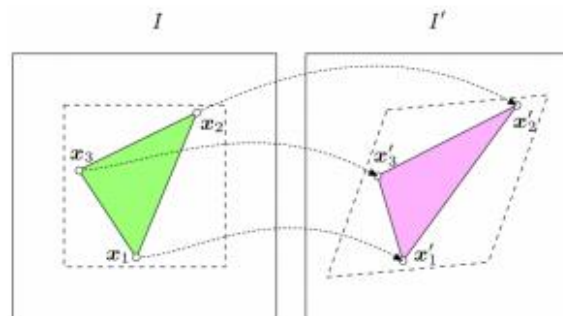
$$\mathbf{x} = \begin{pmatrix} x \\ y \end{pmatrix} \quad \text{converts to} \quad \hat{\mathbf{x}} = \begin{pmatrix} \hat{x} \\ \hat{y} \\ h \end{pmatrix} = \begin{pmatrix} h x \\ h y \\ h \end{pmatrix}$$

Affine (3-Point) Mapping

- Can use homogeneous coordinates to rewrite translation, rotation, scaling, etc as vector-matrix multiplication

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

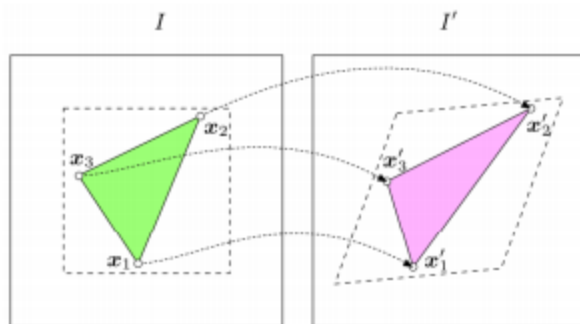
- **Affine mapping:** Can then derive values of matrix that achieve desired transformation (or combination of transformations)



- Inverse of transform matrix is **inverse mapping**

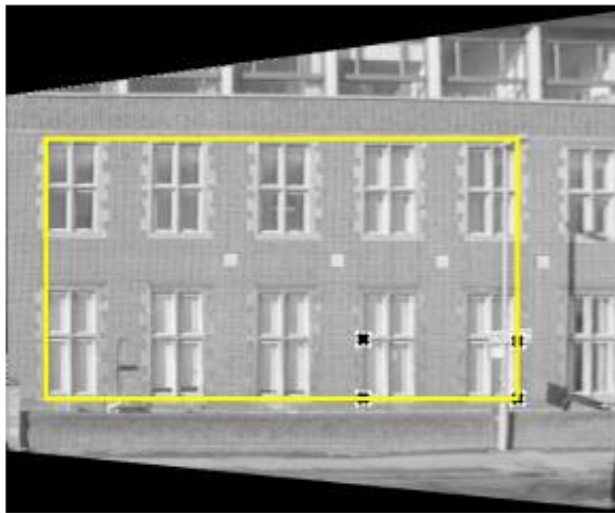
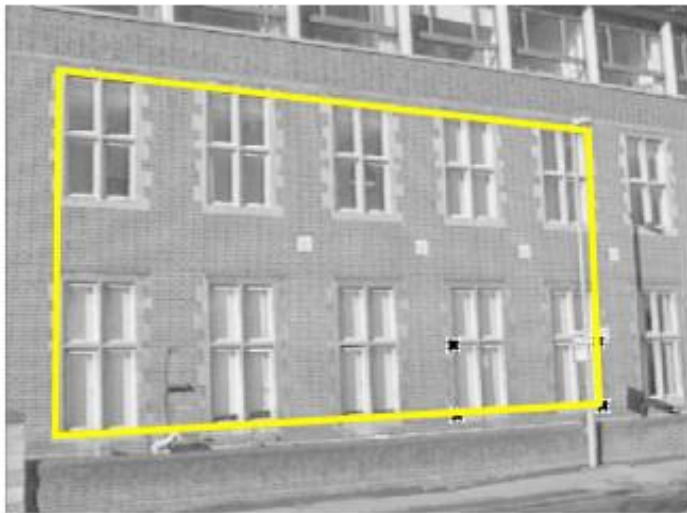
Affine (3-Point) Mapping

- What's so special about affine mapping?



- Maps
 - straight lines \rightarrow straight lines,
 - triangles \rightarrow triangles
 - rectangles \rightarrow parallelograms
 - Parallel lines \rightarrow parallel lines
- Distance ratio on lines do not change

Homography



from Hartley & Zisserman

$$\begin{pmatrix} x'_1 \\ x'_2 \\ x'_3 \end{pmatrix} = \begin{bmatrix} h_{11} & h_{12} & h_{13} \\ h_{21} & h_{22} & h_{23} \\ h_{31} & h_{32} & h_{33} \end{bmatrix} \times \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

References

- G&W, 3rd Ed., 9.1-9.3, 9.6
- Grayscale Morphology:

<http://people.ciirc.cvut.cz/~hlavac/TeachPresEn/11ImageProc/71-06MatMorfolGrayEn.pdf>

Scribe List

2018102018
2018102019
2018102022
2018102027
2018102028
2018102031