

## Examples: Interior

Quiz: Find the **interior** of the following sets as a subset of  $\mathbb{R}$ .

1.  $\{x \mid -1 \leq x \leq 1\}$
2.  $\{1/n \mid n \in \mathbb{N}\}$

Quiz: Find the **closure** of the following sets as a subset of  $\mathbb{R}$ .

1.  $\{x \mid 1 < x < 2\}$
2.  $\{1, 2, 3\}$



$1 \in \text{Int}(\{1, 2, 3\})$   
 $\text{Int}(\{1, 2, 3\}) = \{1\}$

$S \cup B \cap S$

$\text{Int}(\{1, 2, 3\}) \cap \{1, 2, 3\} = \{1\}$

$\{1, 2, 3\} \cup \{1, 2, 3\}$

pts in this set  
s.t.  $\text{Int}(\{1, 2, 3\}) \cap \{1, 2, 3\} \neq \emptyset$

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**Quiz:** Find the **boundary** of the following sets as a subset of  $\mathbb{R}$ .

1.  $\{x \mid -1 < x < 1\}$
  2.  $\mathbb{Q}$
- Handwritten notes:*  $\{-1, 1\}$  (with arrows pointing to the first set),  $\text{Boundary}(\mathbb{Q}) = \mathbb{R}$  (with an arrow pointing to the second set).

*Handwritten notes:*

$$B_{\epsilon}(x) \cap \mathbb{Q} \neq \emptyset$$
$$B_{\epsilon}(x) \cap \mathbb{Q}^c \neq \emptyset$$

( $\epsilon > 0$ )

## Supporting Hyperplanes

**Supporting Hyperplane:** Suppose  $C \subseteq \mathbb{R}^n$ , and  $x_0$  is a point in its boundary  $\text{bd } C$ , i.e.,

$$x_0 \in \text{bd } C = \text{cl } C \setminus \text{int } C$$

If  $a \neq 0$  satisfies  $a^T x \leq a^T x_0$  for all  $x \in C$ , then the hyperplane  $\{x \mid a^T x = a^T x_0\}$  is called the **supporting hyperplane** to  $C$  at the point  $x_0$ . This is same as saying that the point  $x_0$  is separated by the hyperplane  $\{x \mid a^T x = a^T x_0\}$ . The geometric interpretation is that the hyperplane  $\{x \mid a^T x = a^T x_0\}$  is tangent to  $C$  at  $x_0$ , and the halfspace  $\{x \mid a^T x \leq a^T x_0\}$  contains  $C$ .

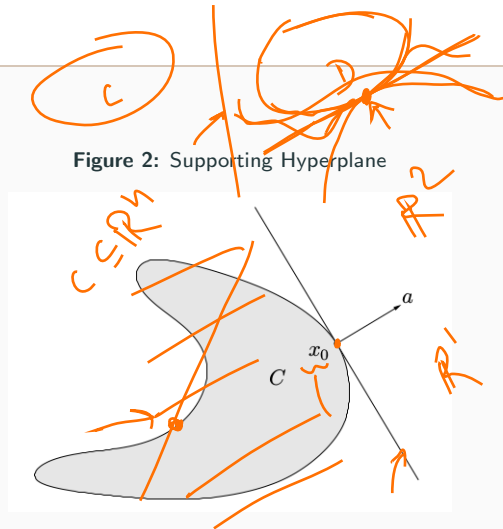


Figure 2: Supporting Hyperplane

# History of Supporting Hyperplane

- Hermann Minkowski introduced separating and supporting hyperplane theorem
- He also extensively used convex sets and convex functions
  - Convex sets were first used by Archimedes, a Greek mathematician
- Photo on the right during Mathematics prize by French academy of sciences
- Minkowski used so called convex bodies concept to prove many results in number theory
  - See “Geometry of numbers” by H. Minkowski

**Figure 3:** Hermann Minkowski, 1883



### Die nirgends concaven Flächen.

1. Es sei ein Punkt  $e$  und eine Punktmenge  $F$  mit folgenden Eigenschaften gegeben:

(A.) In jeder Richtung von  $e$  aus soll mindestens ein Punkt von  $F$  liegen (es ist ein Punkt mit bestimmten endlichen Coordinaten und verschieden von  $e$  gemeint, denn zu einer Richtung bedarf es zweier verschiedener Punkte, vgl. 2).

18.

### Die überall convexen Flächen.

Eine nirgends concave Fläche soll als überall convex bezeichnet werden, wenn jede Stützebene an die Fläche mit derselben nur einen Punkt gemein hat. Diese Bedingung lässt sich noch anders ausdrücken.

Es sei  $F$  eine nirgends concave Fläche um einen Punkt  $e$ . Existirt eine Stützebene an  $F$ , welche zwei verschiedene Punkte von  $F$  ent-

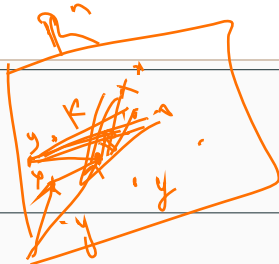
Figure 4: Convex and Strictly Convex from the article: Geometry of numbers

## Dual Cones and Generalized Inequalities

**Dual Cone:** Let  $K$  be a cone. The set

$$K^* = \{y \mid x^T y \geq 0 \text{ for all } x \in K\}$$

is called the dual cone of  $K$ .



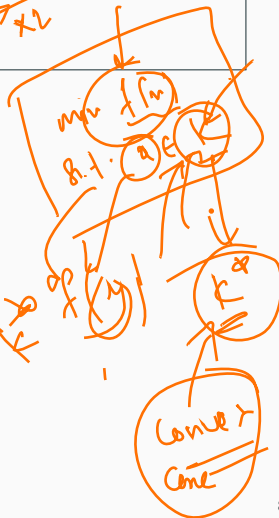
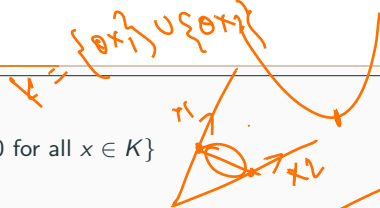
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- $K^*$  is a cone, and is always convex, even when the original cone  $K$  is not
- Proof on chalkboard



Handwritten proof for the dual cone:

$$\begin{aligned}
 & \text{Let } x_1 \in K, x_2 \in K \\
 & \theta_1 x_1 + \theta_2 x_2 \in K \\
 & \theta_1 x_1^T x + \theta_2 x_2^T x \geq 0 \quad \forall x \in K \\
 & \Rightarrow (\theta_1 x_1 + \theta_2 x_2)^T x \geq 0 \quad \forall x \in K \\
 & \Rightarrow \theta_1 x_1 + \theta_2 x_2 \in K^*
 \end{aligned}$$

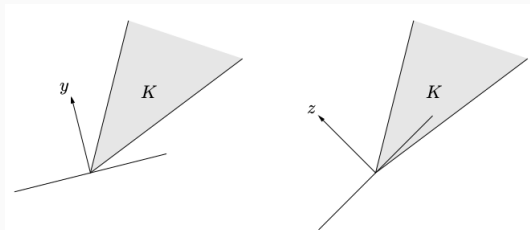
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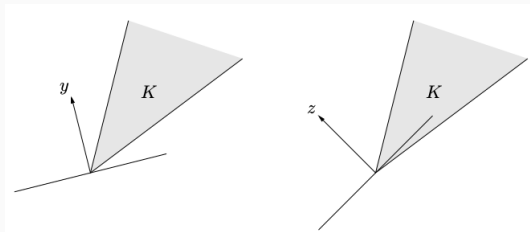
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$$u^T y \leq 0$$



$$\bullet \quad x^T y \geq 0 \iff y^T x \geq 0 \iff y^T x \geq y^T 0 \iff (-y)^T x \leq (-y)^T 0$$

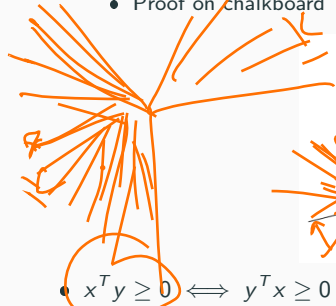
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$$x^T y \geq 0 \iff y^T x \geq 0 \iff y^T x \geq y^T 0 \iff (-y)^T x \leq (-y)^T 0$$

- Dual cone contains set of all  $y$  such that  $-y$  is the normal of the hyperplane that supports  $K$

# Convex Functions, Concave Functions

**Convex function:** A function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is **convex** if  $\text{dom } f$  is a convex set and if for all  $x, y \in \text{dom } f$ , and  $\theta$  with  $0 \leq \theta \leq 1$ , we have

$$f(\theta x + (1 - \theta)y) \leq \theta f(x) + (1 - \theta)f(y)$$

Figure 5: Convex function

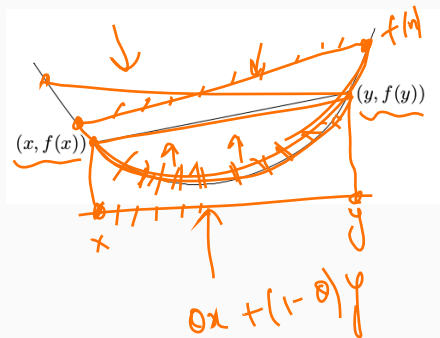
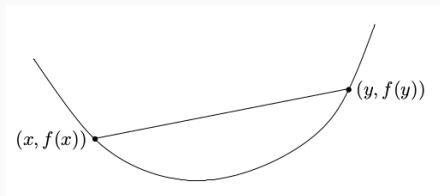


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**Geometrically:** The line segment joining points  $(x, f(x))$  and  $(y, f(y))$  lies **above** the graph of  $f$ .

# Convex Functions, Concave Functions

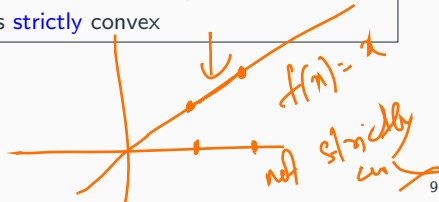
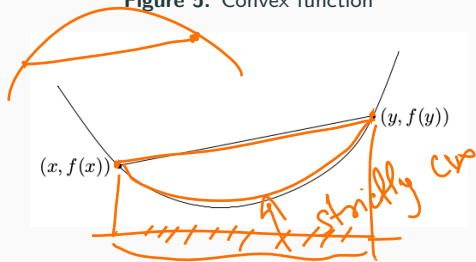
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**Geometrically:** The line segment joining points  $(x, f(x))$  and  $(y, f(y))$  lies **above** the graph of  $f$ .

**Strictly convex:** A function is **strictly convex** if **strict inequality** holds whenever  $x \neq y$  and  $0 < \theta < 1$ . We say  $f$  is **concave** if  $-f$  is convex, and **strictly concave** if  $-f$  is **strictly** convex

Figure 5: Convex function



## Examples of Convex Functions

$$g'(x) > 0$$

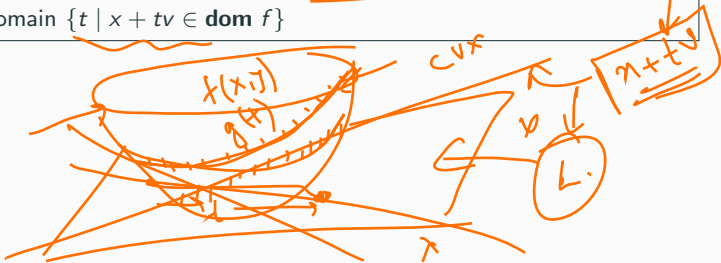
**Quiz:** Recall that an affine function is of the form  $f(x) = Ax - b$ . Is this a convex function? What about linear function  $f(x) = Ax$ ?

**Proof:** on chalkboard

**Fact:** A function is **convex** if and only if it is convex when **restricted** to any line that intersects its domain.

In other words, a function is **convex** if and only if for all  $x \in \text{dom } f$  and all  $v$ , the function  $g(t) = f(x + tv)$  is convex on its domain  $\{t \mid x + tv \in \text{dom } f\}$

**Proof:** On chalkboard.



## Scratch Space

→ Spec  $f$  is convex.

Claim:  $g(t)$  is convex

Let  $t_1, t_2 \in \mathbb{R}$ .

$$\rightarrow \theta g(t_1) + (1-\theta)g(t_2)$$

$$= \theta f(\underbrace{x+t_1 y}) + (1-\theta) f(\underbrace{x+t_2 y})$$

$$\stackrel{\textcircled{>}}{=} f\left(\theta(x+t_1 y) + (1-\theta)(x+t_2 y)\right) \quad \left(\text{because } f \text{ is convex}\right)$$

$$= f\left(x + \underbrace{(\theta t_1 + (1-\theta)t_2)}_{\text{}}\right) y = g(\underline{\underline{\theta t_1 + (1-\theta)t_2}}) \leftarrow$$

$\Rightarrow g$  is convex

## Scratch Space

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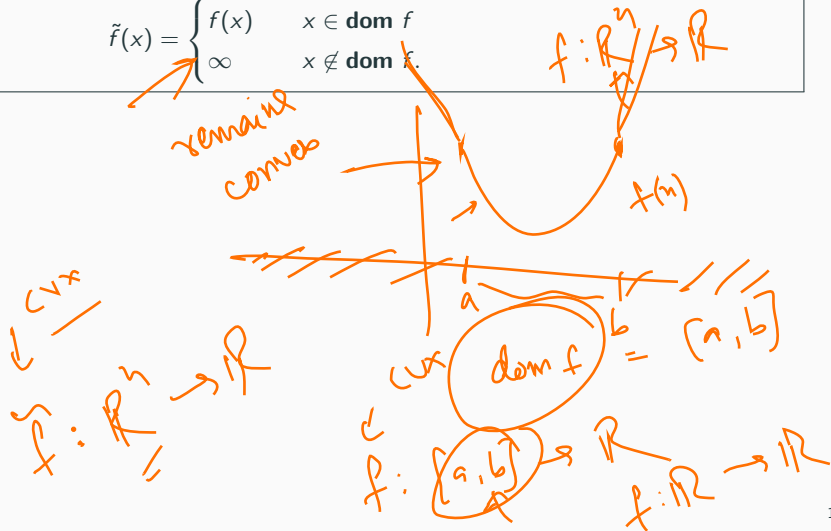




## Extended Value Extensions

**Extended value function:** If  $f$  is convex we define its extended value extension  $\tilde{f} : \mathbb{R}^n \rightarrow \mathbb{R} \cup \infty$  by

$$\tilde{f}(x) = \begin{cases} f(x) & x \in \text{dom } f \\ \infty & x \notin \text{dom } f. \end{cases}$$



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- If  $x, y$  are not in  $\mathbf{dom} f$ , then right hand side is  $\infty$

## Indicator Function and Extended Values

**Indicator Function:** Let  $C \subseteq \mathbb{R}^n$  be a convex set, and consider the function  $I_C$  with domain  $C$  and  $I_C(x) = 0$  for all  $x \in C$ . In other words, the function is **identically zero** on the set  $C$ . Its **extended** value extension is given by

$$\tilde{I}_C(x) = \begin{cases} 0 & x \in C \\ \infty & x \notin C \end{cases}$$

The convex function  $\tilde{I}_C$  is called the **indicator function** of the set  $C$



## Indicator Function and Extended Values

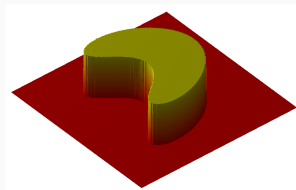
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The convex function  $\tilde{I}_C$  is called the **indicator function** of the set  $C$

- The problem of minimizing a function  $f$  on the set  $C$  is the **same** as minimizing the function  $f + \tilde{I}_C$  over all of  $\mathbb{R}^n$
- Proof on chalkboard!

**Figure 6:** Indicator Function



# Convexity of Indicator Function $\equiv$ Set is convex

Case-3  
 $x \notin C, y \notin C$

**Fact:** A set is **convex** if and only if the **indicator function** is a **convex** function

Proof on chalkboard  $\Rightarrow$

$C$  convex set  $\Rightarrow \tilde{I}_C$  convex fn

$x, y \in \mathbb{R}^n$

$$\theta \tilde{I}_C(x) + (1-\theta) \tilde{I}_C(y) \geq \tilde{I}_C(\theta x + (1-\theta)y)$$

Case-1:  $x, y \in C$

$$\theta \cdot 0 + (1-\theta) \cdot 0 = 0 \geq 0$$

because  $C$  is convex  
 $\theta x + (1-\theta)y \in C$

$x \notin C, y \notin C$   
 $\infty \geq \infty$

Case-2:  $x \in C, y \notin C$

$$\theta \cdot 0 + (1-\theta) \cdot \infty \geq \infty$$

## Scratch Space

$$\tilde{I}_C \text{ cvx} \Rightarrow C \text{ is } \underline{\text{CVX}} \quad \checkmark$$
$$x_1, x_2 \in C \Rightarrow \underline{\tilde{I}_C(x_1) = \tilde{I}_C(x_2) = 0}$$

$$\underline{\theta x_1 + (1-\theta)x_2} \in C$$

Claim  $\tilde{I}_C(\theta x_1 + (1-\theta)x_2) = 0$

$$\Rightarrow \theta x_1 + (1-\theta)x_2 \in C$$

$$\theta \tilde{I}_C(x_1) + (1-\theta) \tilde{I}_C(x_2) \geq \tilde{I}_C(\theta x_1 + (1-\theta)x_2) = 0$$
$$\Rightarrow \tilde{I}_C(\theta x_1 + (1-\theta)x_2) \leq 0 \Rightarrow \tilde{I}_C(\theta x_1 + (1-\theta)x_2) = 0$$

## First Order Condition for Convexity

**First Order Condition:** Suppose  $f$  is differentiable. Then  $f$  is convex if and only if  $\text{dom } f$  is convex and

$$f(y) \geq f(x) + \nabla f(x)^T (y - x)$$

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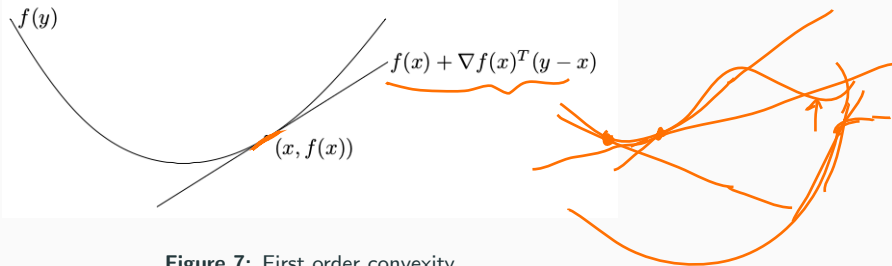


Figure 7: First order convexity

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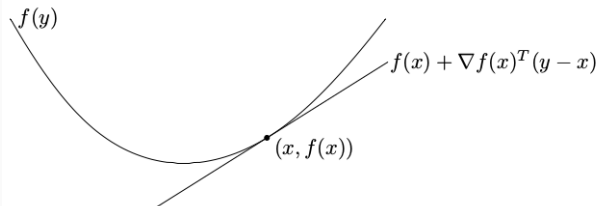


Figure 7: First order convexity

Let  $f(y) = mx + c$  be the line passing through  $(x, f(x))$ . Then  $c = f(x) - mx$ , where  $m = \nabla f(x)$ . Hence,  $f(y) = f(x) + \nabla f(x)(y - x)$  is the line that passes through  $(x, f(x))$

## Remarks on First Order Condition

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- The Taylor expansion of infinitely differentiable function  $f(x)$  at a point  $x = a$

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$$\begin{aligned} f(x) &= \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n \\ &= \underbrace{f(a)} + \frac{f^{(1)}(a)}{1!} (x-a) + \frac{f^{(2)}(a)}{2!} (x-a)^2 + \dots f^{(n)} \end{aligned}$$



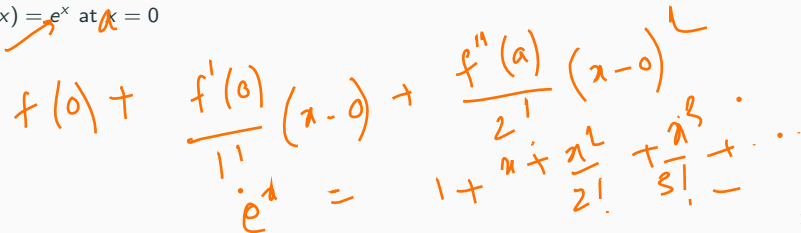
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- Exercise: Expand the following functions using Taylor series

- $f: \mathbb{R} \rightarrow \mathbb{R}$ , Expand  $f(x) = e^x$  at  $x = 0$



Handwritten Taylor expansion of  $e^x$  at  $x=0$ :

$$f(0) + \frac{f'(0)}{1!} (x-0) + \frac{f''(0)}{2!} (x-0)^2 + \dots$$

Below the general formula, the specific expansion for  $e^x$  is written:

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

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  - $f : \mathbb{R} \rightarrow \mathbb{R}$ , Expand  $f(x) = \sin x$  at  $x = \pi$

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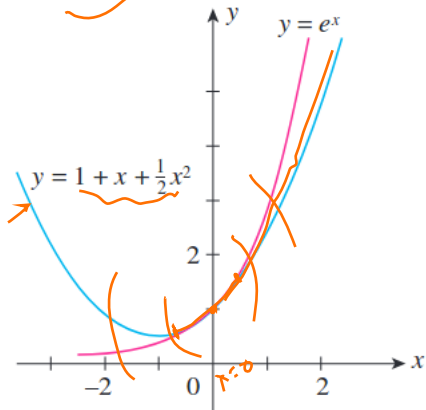
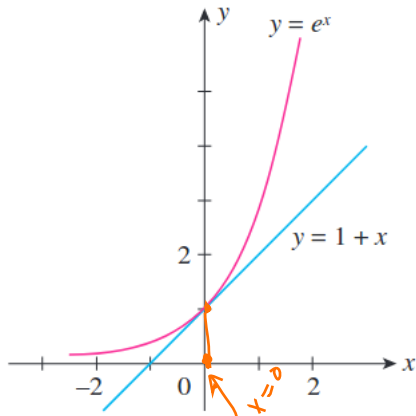
- $f : \mathbb{R} \rightarrow \mathbb{R}$ , Expand  $f(x) = e^x$  at  $x = 0$
- $f : \mathbb{R} \rightarrow \mathbb{R}$ , Expand  $f(x) = \sin x$  at  $x = \pi$
- $f : \mathbb{R} \setminus \{0\} \rightarrow \mathbb{R}$ , Expand  $f(x) = \frac{1}{1-x}$  at  $x = -1$



$f : \mathbb{R} \rightarrow \mathbb{R}$ , Expand  $f(x) = e^x$  at  $x = 0$

$f : \mathbb{R} \rightarrow \mathbb{R}$ , Expand  $f(x) = e^x$  at  $x = 0$

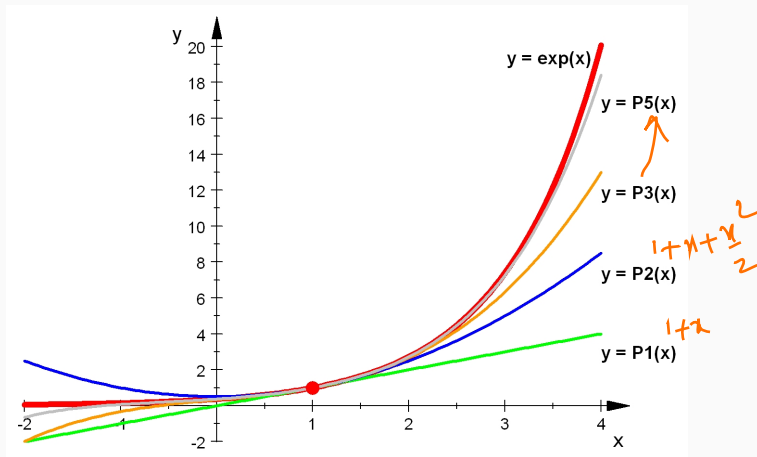
$$e^x = 1 + x + \frac{x^2}{2} + \frac{x^3}{3!} + \dots$$





$f : \mathbb{R} \rightarrow \mathbb{R}$ , Expand  $f(x) = e^x$  at  $x = 1$

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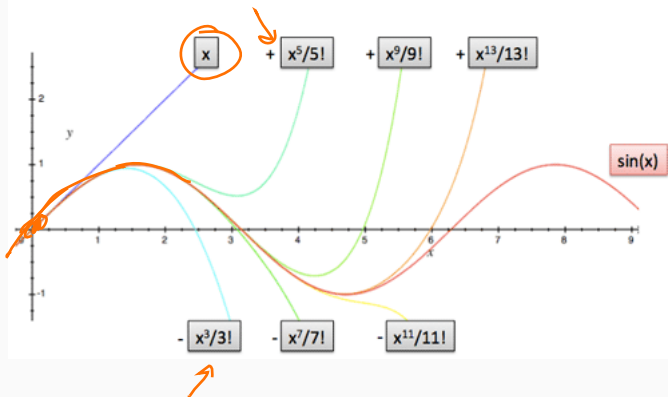


$f : \mathbb{R} \rightarrow \mathbb{R}$ , Expand  $f(x) = \sin x$  at  $x = 0$

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$$x + \frac{x^3}{3!} + \frac{x^5}{5!} - \dots$$

## Better Models of Sine



# Multivariate Taylor Series

$$f: \mathbb{R} \rightarrow \mathbb{R},$$

The **Taylor expansion** of function  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$  near point  $(a, b)$  is given as follows:

$$f(x, y) = f(a, b) + \frac{\partial f}{\partial x}(a, b)(x - a) + \frac{\partial f}{\partial y}(a, b)(y - b) + \frac{1}{2}(A(x - a)^2 + 2B(x - a)(y - b) + C(y - b)^2),$$

where

plane

$$A = \frac{\partial^2 f}{\partial x^2}(a, b), \quad C = \frac{\partial^2 f}{\partial y^2}(a, b)$$

$$B = \frac{\partial^2 f}{\partial x \partial y}(a, b) = \frac{\partial^2 f}{\partial y \partial x}(a, b)$$









## Multivariate Taylor Series Using Gradient and Hessian...

The **Taylor expansion** of function  $f : \mathbb{R} \rightarrow \mathbb{R}$  near point  $(a, b)$  is given as follows:

$$f(x, y) = f(a, b) + \frac{\partial f}{\partial x}(a, b)(x - a) + \frac{\partial f}{\partial y}(a, b)(y - b) + \frac{1}{2}(A(x - a)^2 + 2B(x - a)(y - b) + C(y - b)^2),$$

where

$$A = \frac{\partial^2 f}{\partial x^2}(a, b), \quad C = \frac{\partial^2 f}{\partial y^2}(a, b)$$

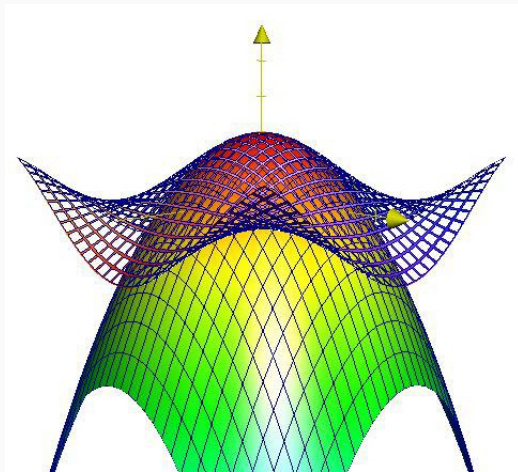
$$B = \frac{\partial^2 f}{\partial x \partial y}(a, b) = \frac{\partial^2 f}{\partial y \partial x}(a, b)$$

$$H = \begin{bmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{bmatrix}$$

$$= f(a, b) + \nabla f^T(a, b) \begin{bmatrix} x - a \\ y - b \end{bmatrix} + \frac{1}{2} \begin{bmatrix} x - a & y - b \end{bmatrix}^T H \begin{bmatrix} x - a \\ y - b \end{bmatrix}$$

$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x}(a, b) \\ \frac{\partial f}{\partial y}(a, b) \end{bmatrix}$





**Figure 1:** A second order Taylor approximation of the function

## Remarks on First Order Condition

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- The affine function of  $y$  given by  $f(x) + \nabla f(x)^T(y - x)$  is a first order Taylor approximation of  $f$  near  $x$ .

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- The inequality

$$f(y) \geq f(x) + \nabla f(x)^T (y - x)$$

states that for a convex function the first order **Taylor approximation** is in fact a **global underestimator** of the function

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- The inequality

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states that for a convex function the first order **Taylor approximation** is in fact a **global underestimator** of the function

- Conversely, if the first order Taylor approximation of a function is always a global underestimator of the function, then the function is convex
- **Quiz:** What does the inequality above say when  $\nabla f(x) = 0$ ?