

25.09.2020

Digital Image Processing (CSE/ECE 478)

Lecture-13: Morphological Operations, Intro to Geometric Operations

Ravi Kiran



Announcements

- Projects
 - Form group(s) of ≥ 1 and ≤ 3
 - List will be announced at 9pm on 16th September
 - Read guidelines re: project preferences carefully

Binary Images

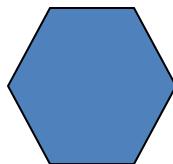
Structuring Elements

A **structuring element** = a shape mask

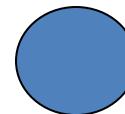
They can be any shape and size that is digitally representable, and each has an **origin**.



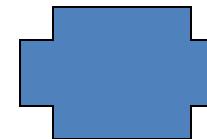
box



hexagon



disk



something

box(length,width)

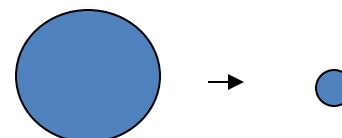
disk(diameter)

Erosion

Erosion **shrinks** the connected sets of 1s of a binary image.

It can be used for

1. shrinking features



2. Removing bridges, branches and small protrusions

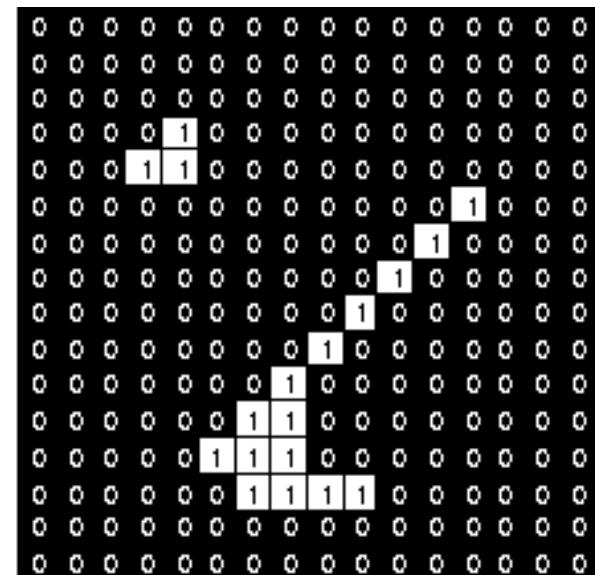
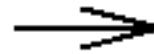
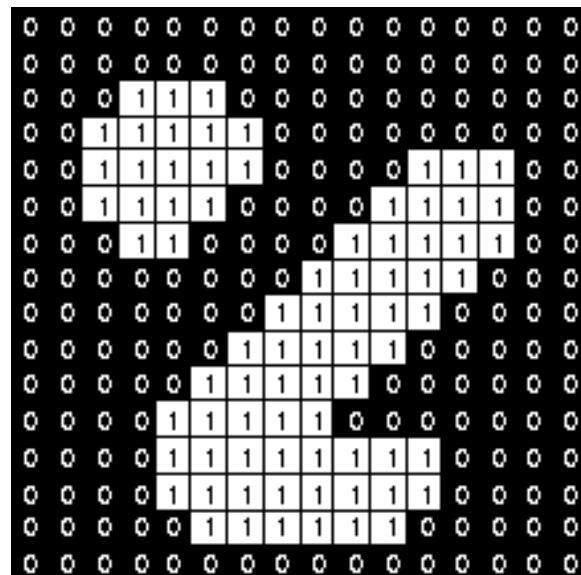


Erosion : Operation (min filter)

1	1	1
1	1	1
1	1	1

Set of coordinate points =

$$\{ (-1, -1), (0, -1), (1, -1), \\ (-1, 0), (0, 0), (1, 0), \\ (-1, 1), (0, 1), (1, 1) \}$$

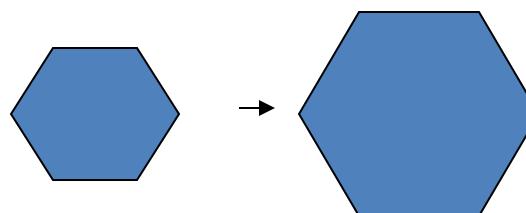


Dilation

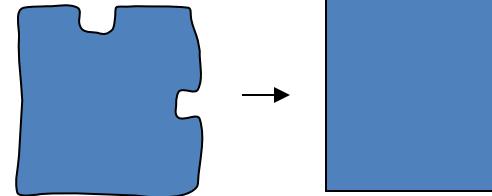
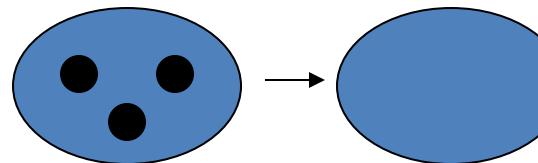
Dilation **expands** the connected sets of 1s of a binary image.

It can be used for

1. growing features



2. filling holes and gaps

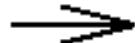


Dilation (max filter)

1	1	1
1	1	1
1	1	1

A 16x16 binary matrix representing an image. A 3x3 kernel of ones is applied across the entire matrix. The result is a 16x16 matrix where every element is 1. The original input values are 0.

0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	0	0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	1	0	0	0	0	1	1	1	0	0	0
0	0	1	1	1	1	1	0	0	0	0	1	1	1	1	0	0
0	0	0	1	1	1	1	0	0	0	0	1	1	1	1	0	0
0	0	0	1	1	1	1	0	0	0	0	1	1	1	1	0	0
0	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0	0
0	0	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
0	0	0	0	0	0	1	1	1	1	1	1	0	0	0	0	0
0	0	0	0	0	0	0	1	1	1	1	1	1	0	0	0	0
0	0	0	0	0	0	0	0	1	1	1	1	1	1	0	0	0
0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	0	0
0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	0
0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1
0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1

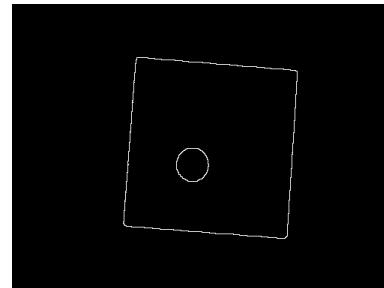
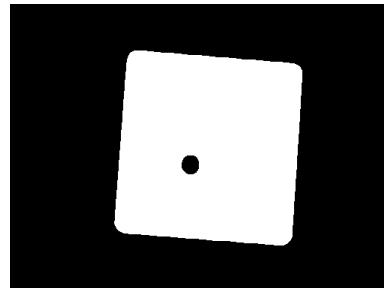
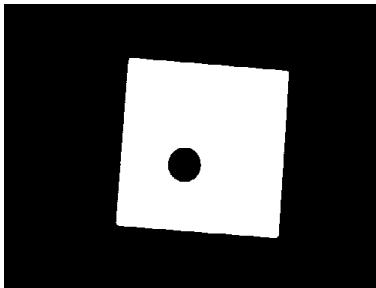


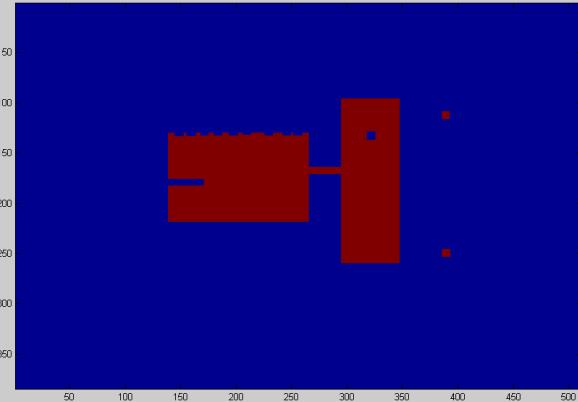
A 16x16 binary matrix representing the result of the dilation operation. Every element in the matrix is 1, indicating that the maximum value (1) was found in every 3x3 neighborhood of the input matrix.

0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0
0	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0
0	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0
0	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0
0	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0
0	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0
0	1	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1
0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1
0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1
0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1
0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1

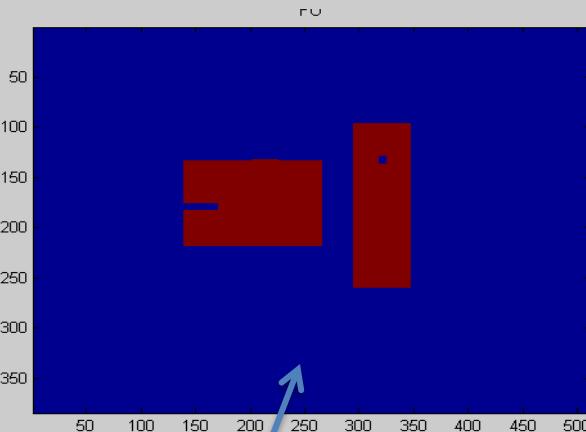
Boundary Detection

1. Dilate input image
2. Subtract input image from dilated image
3. Boundaries remain!

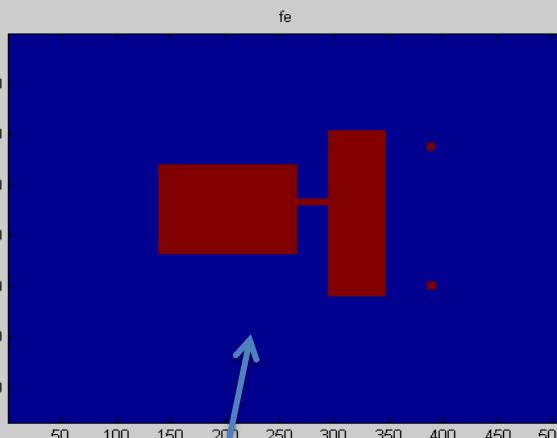




ORIGINAL



OPENING

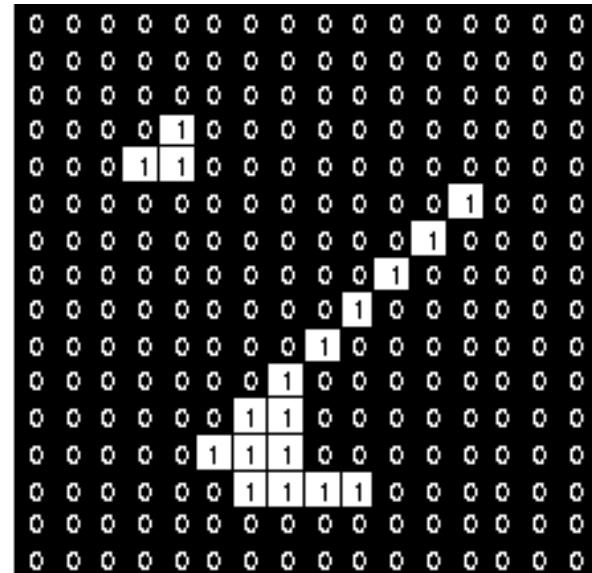
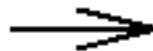
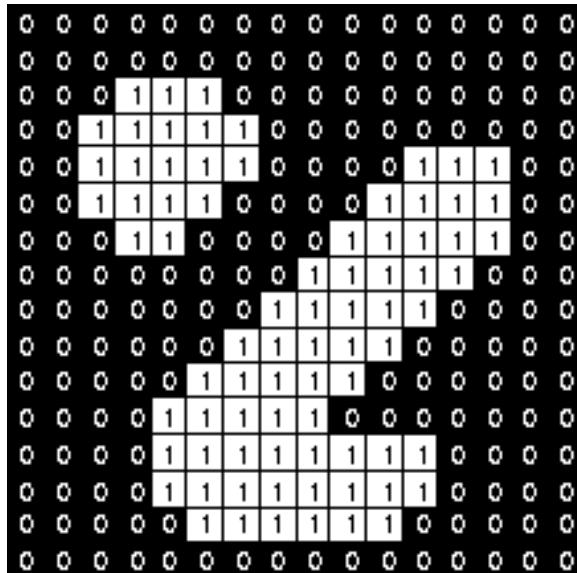


CLOSING

Erosion

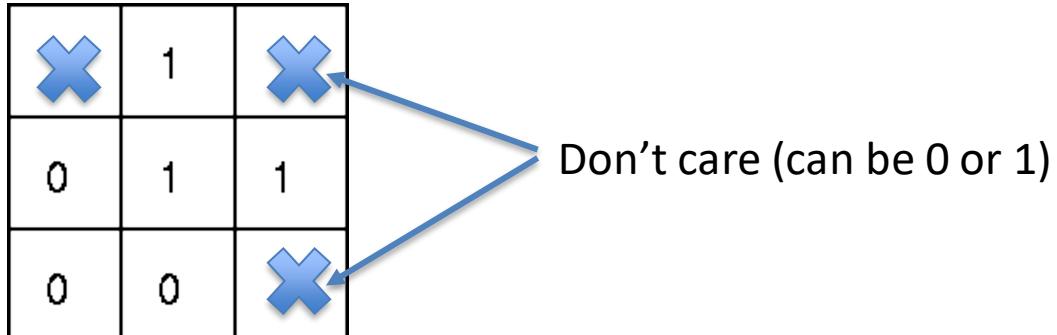
- Simple application of **pattern matching**
 - **Fixed template**

1	1	1
1	1	1
1	1	1



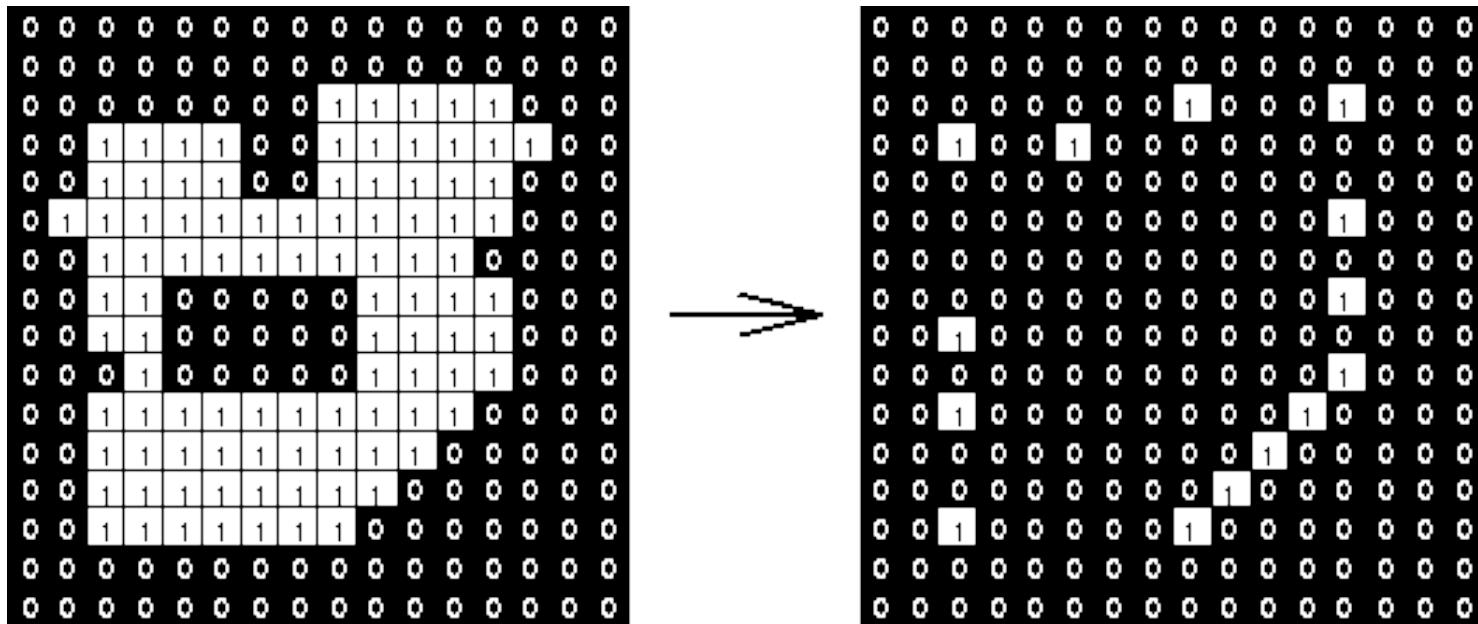
Hit-and-miss Transform

- Look for particular patterns of foreground and background pixels.



- If matched, set pixel = 1

Example: Find right-angled convex corners



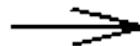
Example: Find right-angled convex corners

	1	
0	1	1
0	0	

	1	
1	1	0
	0	0

	0	0
1	1	0
	1	

0	0	
0	1	1
	1	



A 10x10 grid of binary digits (0s and 1s). The following cells are highlighted with black squares:

- (Row 1, Column 2)
- (Row 2, Column 1)
- (Row 2, Column 3)
- (Row 4, Column 1)
- (Row 4, Column 9)
- (Row 6, Column 1)
- (Row 6, Column 9)
- (Row 8, Column 1)
- (Row 8, Column 3)
- (Row 8, Column 5)
- (Row 8, Column 7)
- (Row 8, Column 9)
- (Row 10, Column 1)
- (Row 10, Column 3)
- (Row 10, Column 5)
- (Row 10, Column 7)
- (Row 10, Column 9)

Sample HAM transforms

1)

0	0	0
0	1	0
0	0	0

Locate isolated
points

Sample HAM transforms

1)

0	0	0
0	1	0
0	0	0

Locate isolated
points

2)

0	1	0
0	0	0

Locate end points
on thin lines

Sample HAM transforms

1)

0	0	0
0	1	0
0	0	0

Locate isolated points

2)

0	1	0
0	0	0

Locate end points
on thin/tapering structures

3a)

	1	
	1	
1		1

3b)

1		
	1	
1		1

Locate triple junctions

3c)

*	0	1
1	1	0
*	1	*

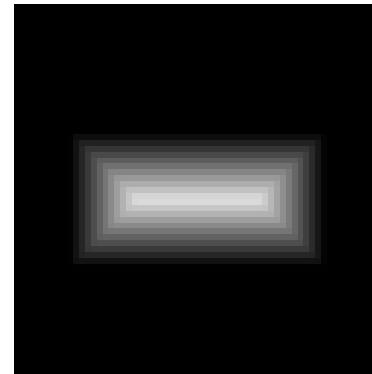
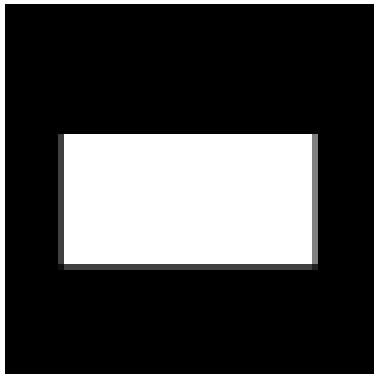
Distance Transform (with chessboard distance metric)

0	0	0	0	0	0	0
0	1	1	1	1	1	0
0	1	1	1	1	1	0
0	1	1	1	1	1	0
0	1	1	1	1	1	0
0	1	1	1	1	1	0
0	0	0	0	0	0	0

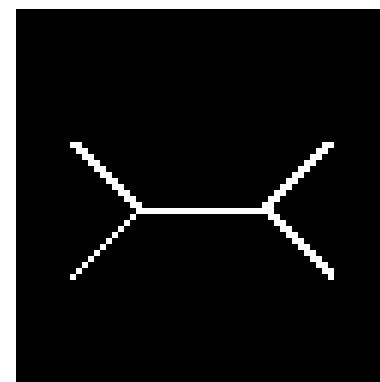
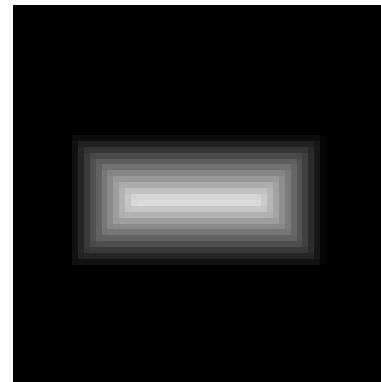
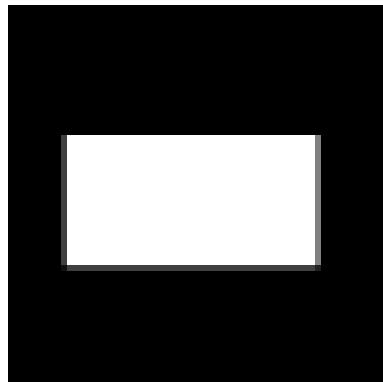
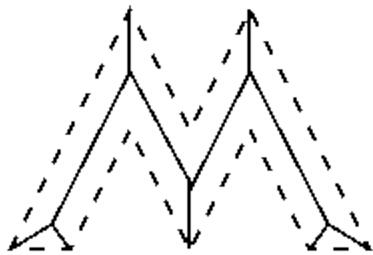
Binary Image

0	0	0	0	0	0	0
0	1	1	1	1	1	0
0	1	2	2	2	1	0
0	1	2	3	2	1	0
0	1	2	2	2	1	0
0	1	1	1	1	1	0
0	0	0	0	0	0	0

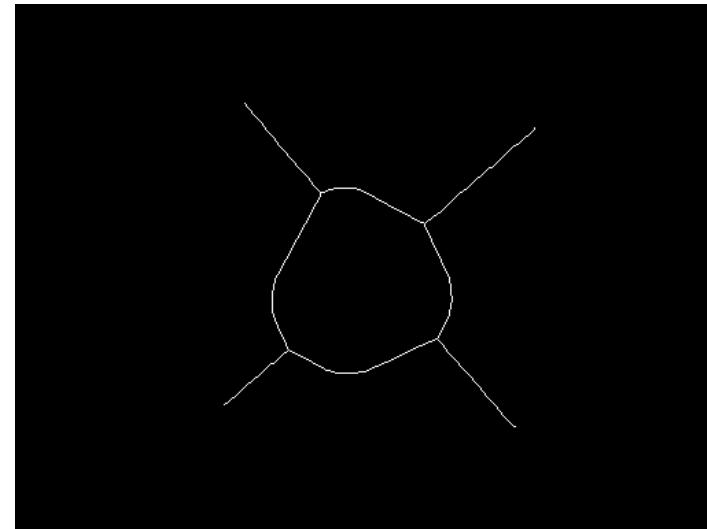
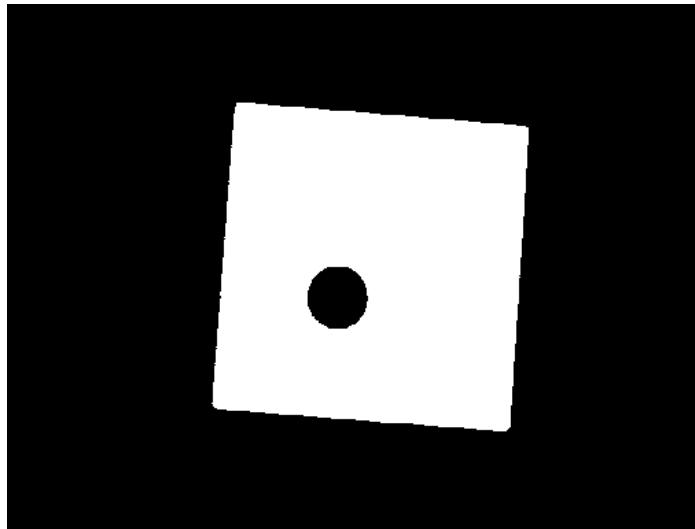
Distance transformation



Skeletonization



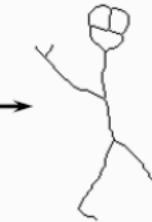
Skeletonization - Example



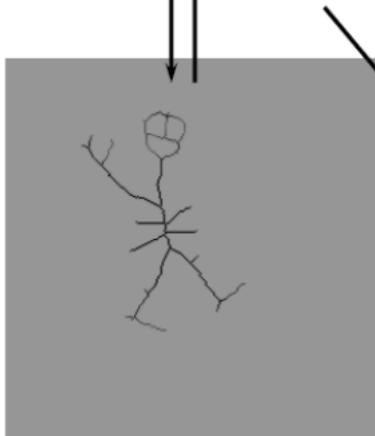
Skeleton



Skeleton

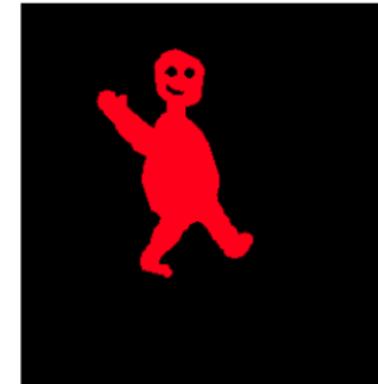
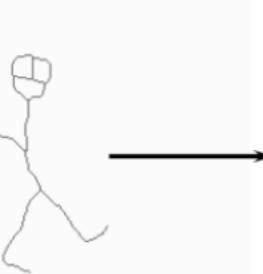


Skeletonisation based on
thinning (not reversible)

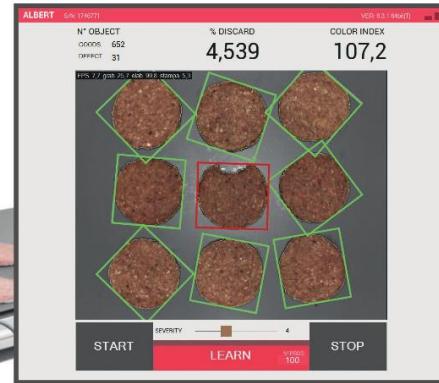
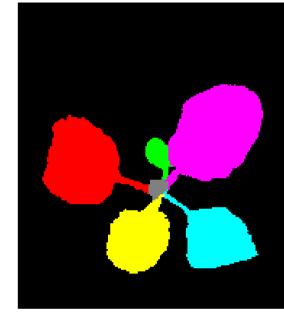
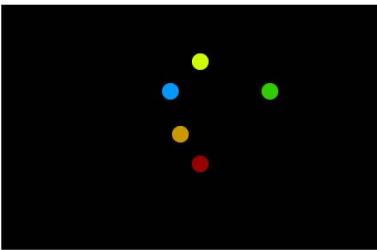
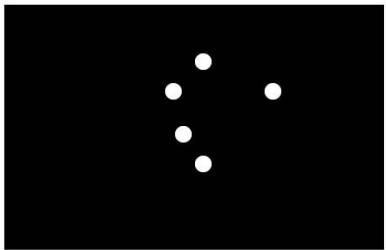


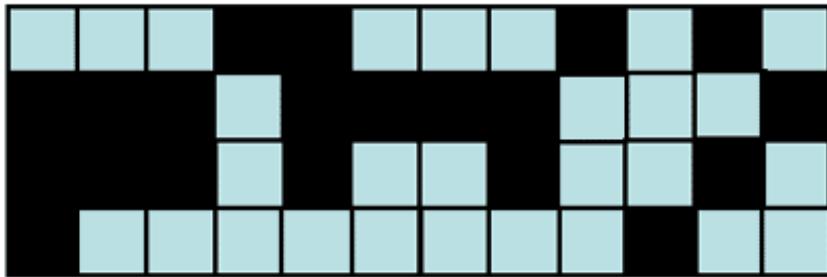
Skeleton using Chamfer(3,4) DT,
no pruning (fully reversible)

Skeleton using Chamfer(3,4) DT,
followed by pruning (not fully
reversible)

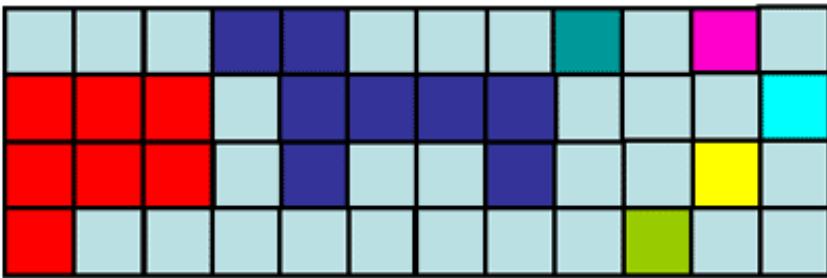


Components

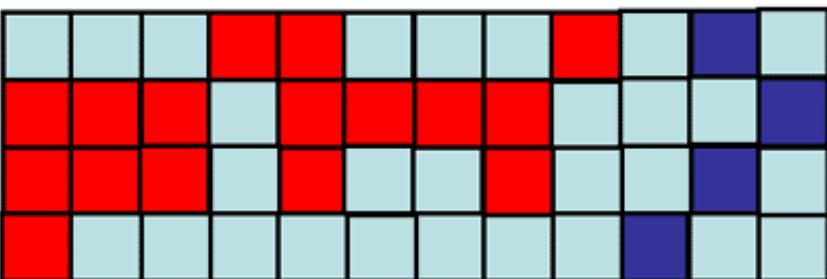




Binary image:
0 - objects;
1 - background

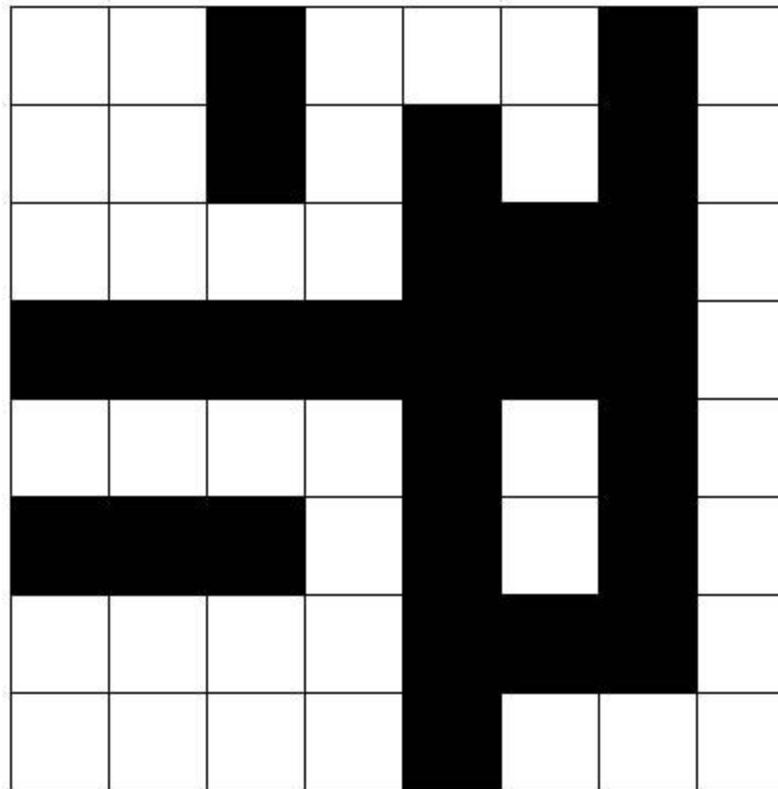


4-connected
objects +
8-connected
background

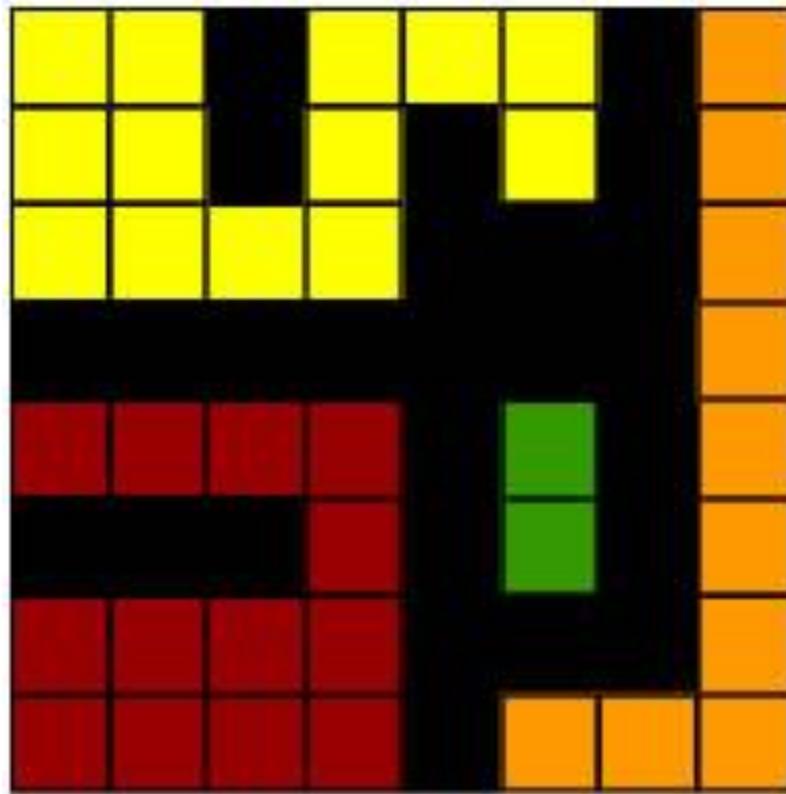


8-connected
objects +
8-connected
background

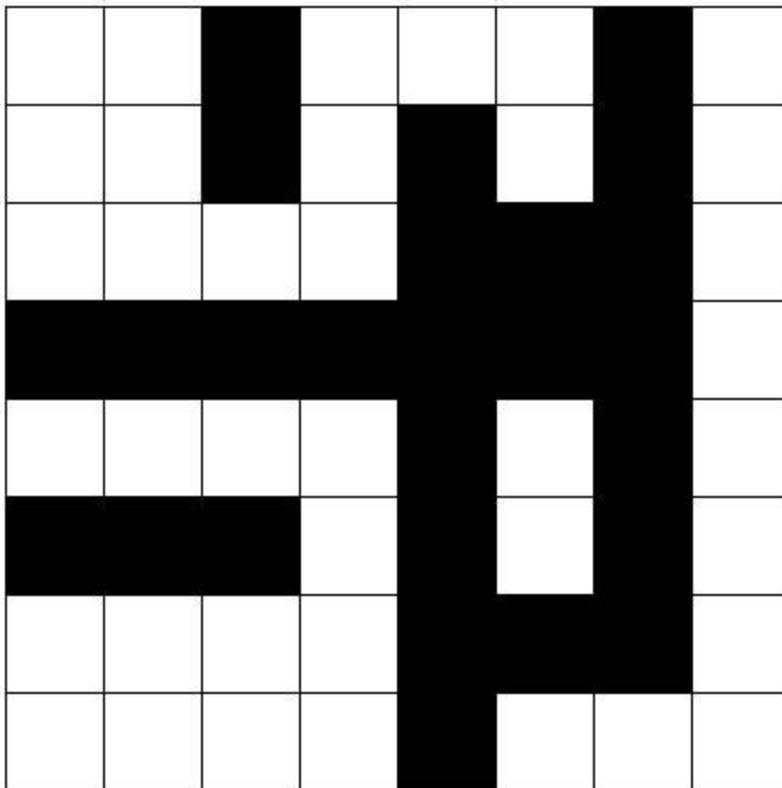
Two-Pass Algorithm for Connected Component Labelling



Two-Pass Algorithm for CCL

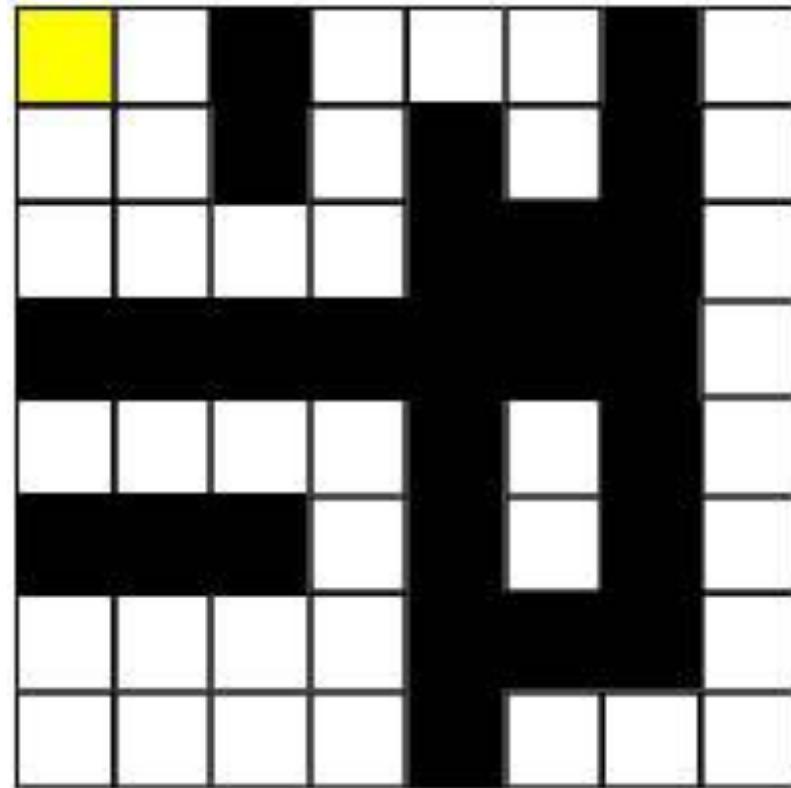
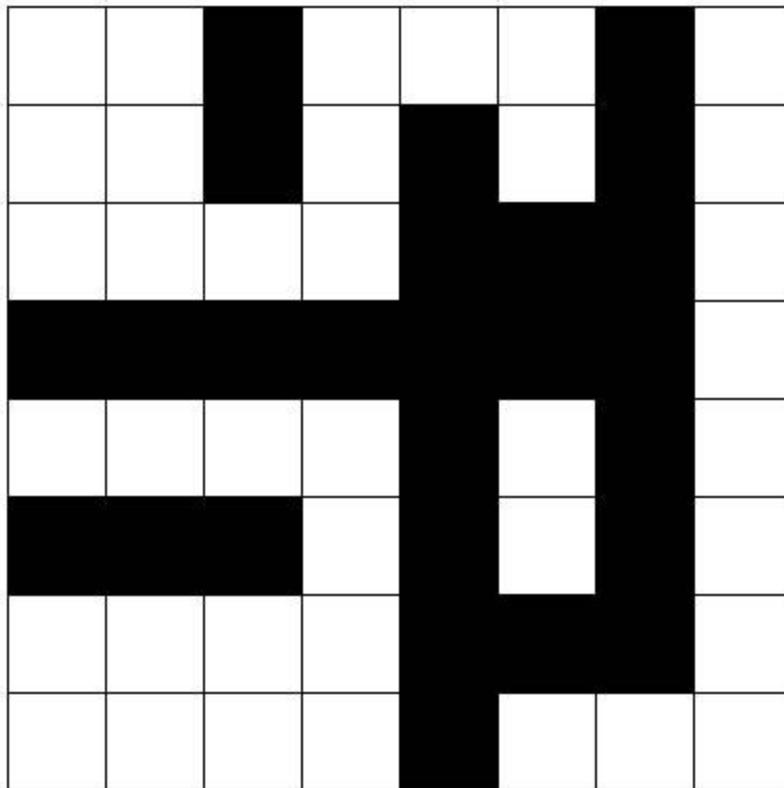


Two-Pass Algorithm for Connected Component Labelling

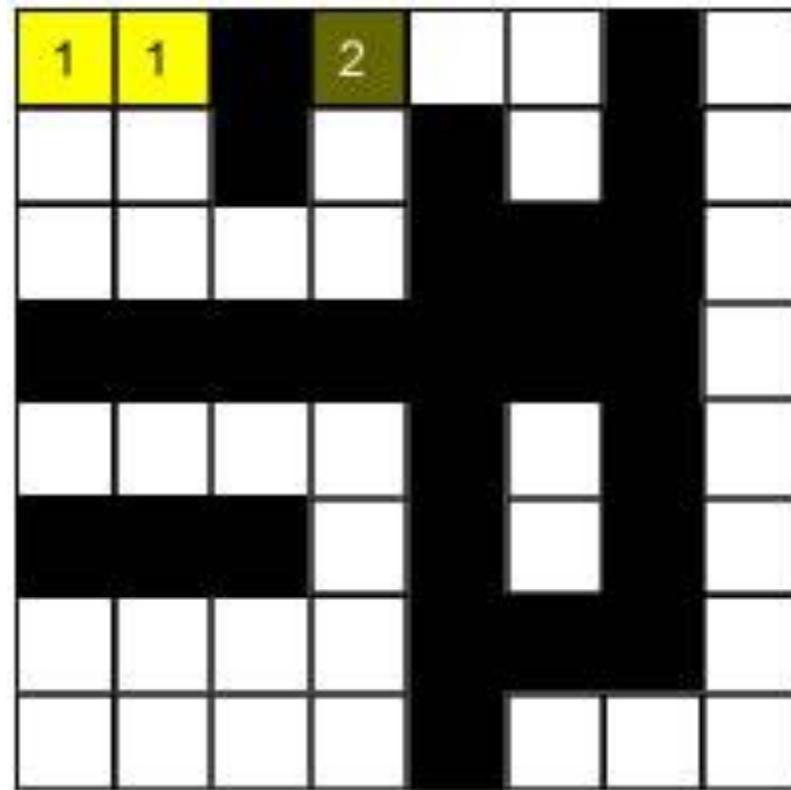
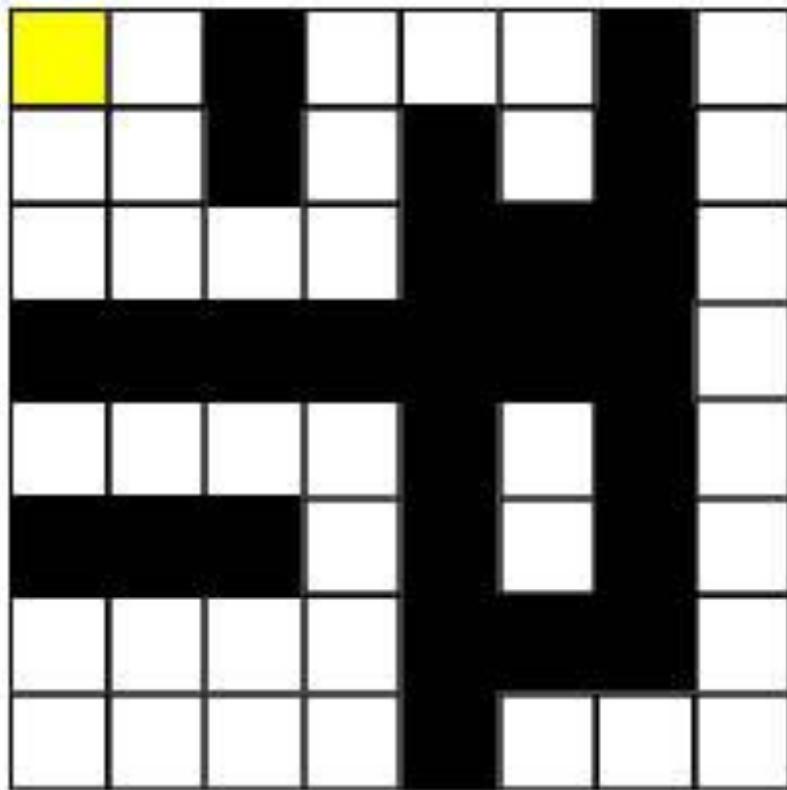


1	1	0	1	1	1	0	1
1	1	0	1	0	1	0	1
1	1	1	1	0	0	0	1
0	0	0	0	0	0	0	1
1	1	1	1	0	1	0	1
0	0	0	1	0	1	0	1
1	1	1	1	0	0	0	1
1	1	1	1	0	1	1	1

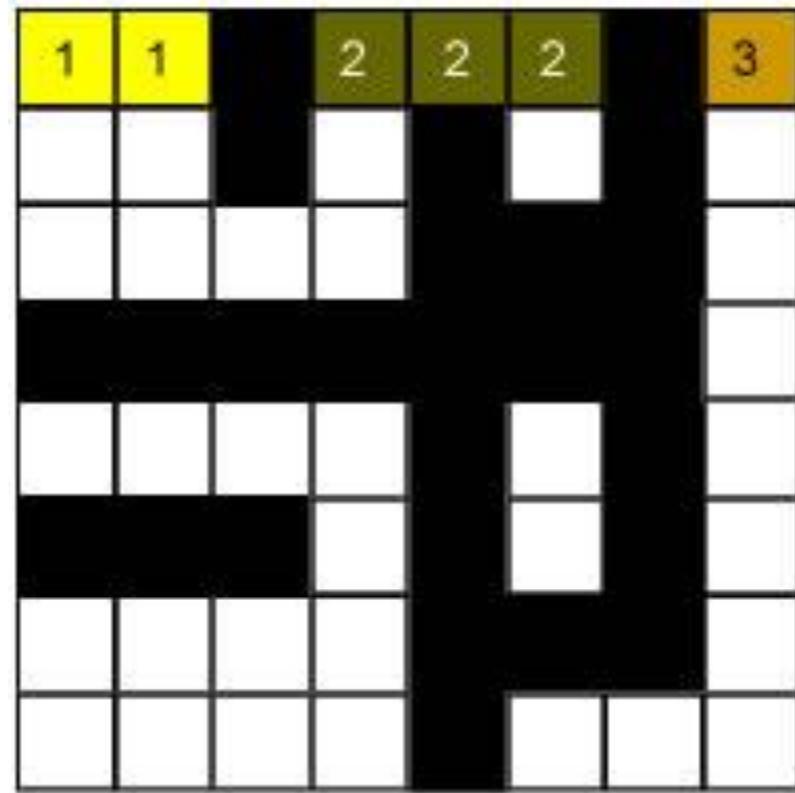
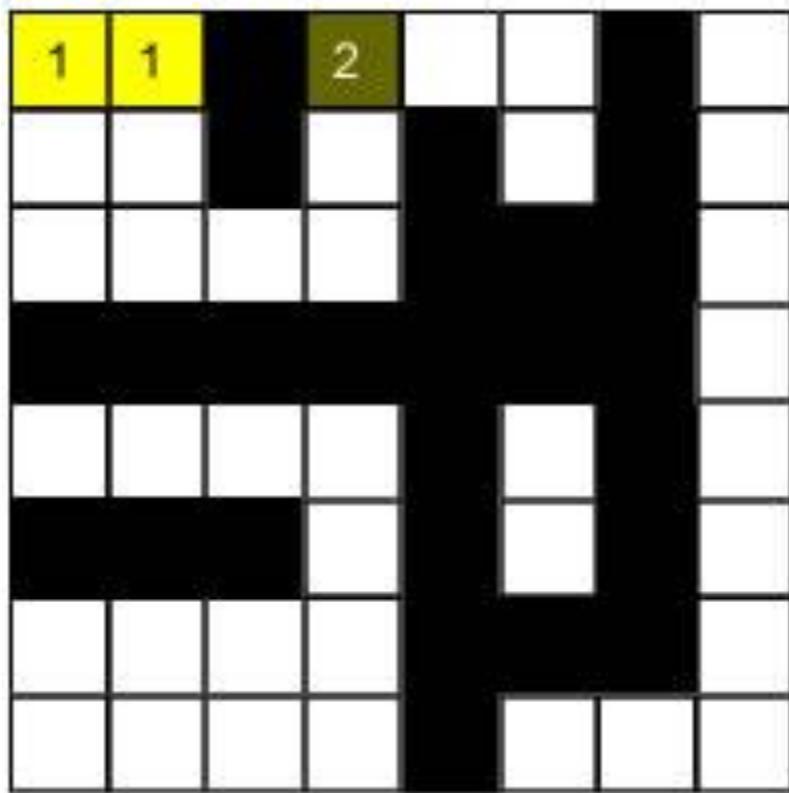
2PA: No top, left pixels → Create new label



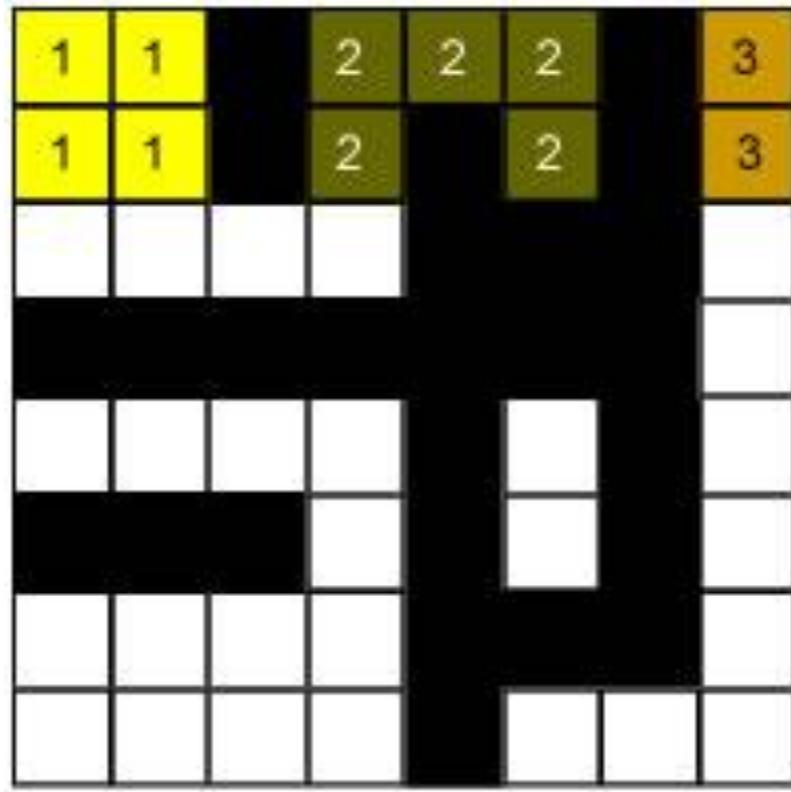
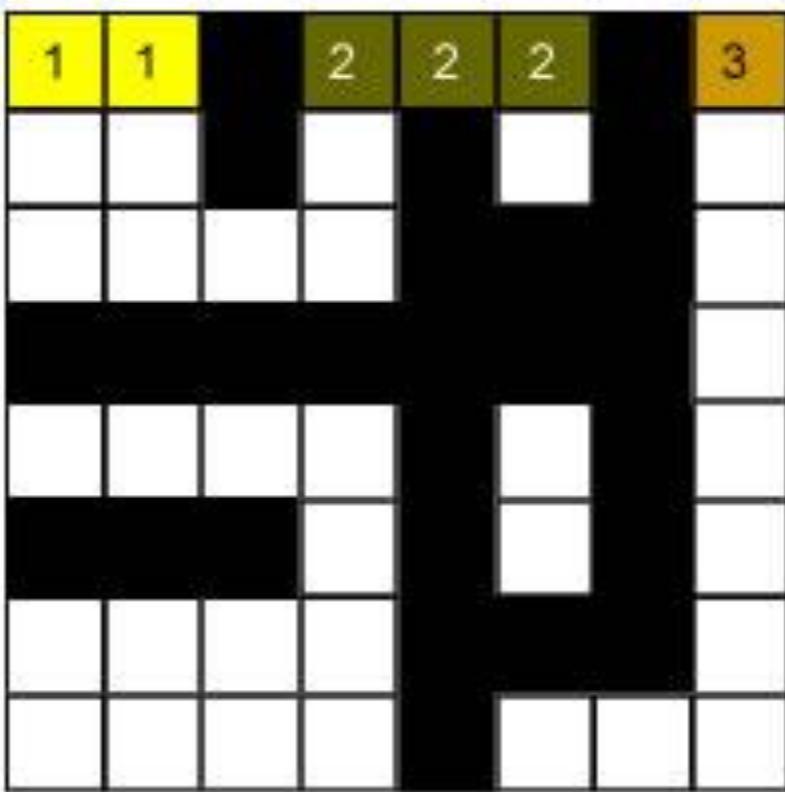
2PA: left pixel labeled → Copy label ; left pixel BG → new label



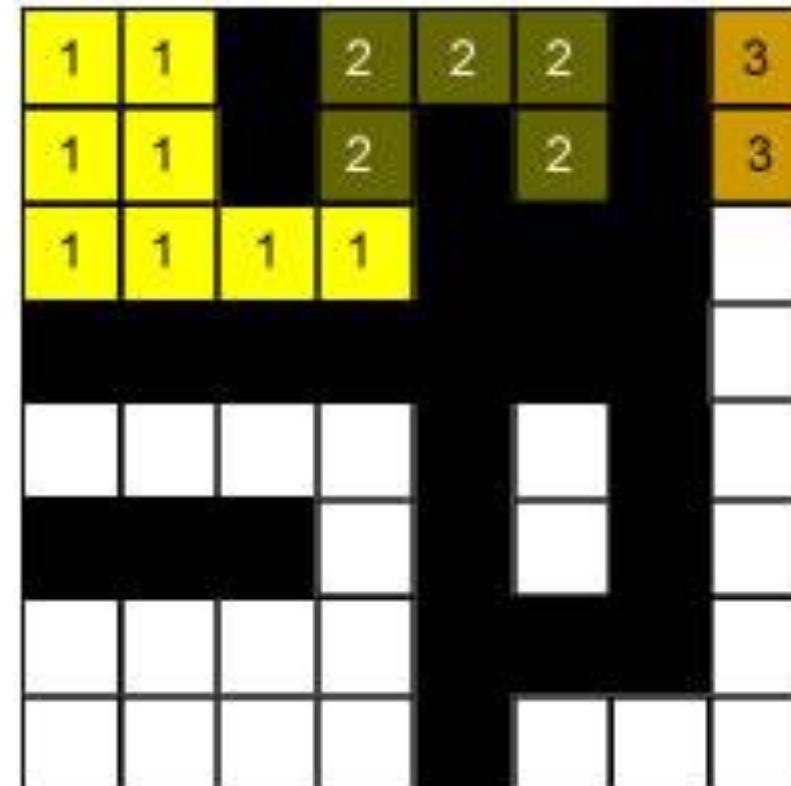
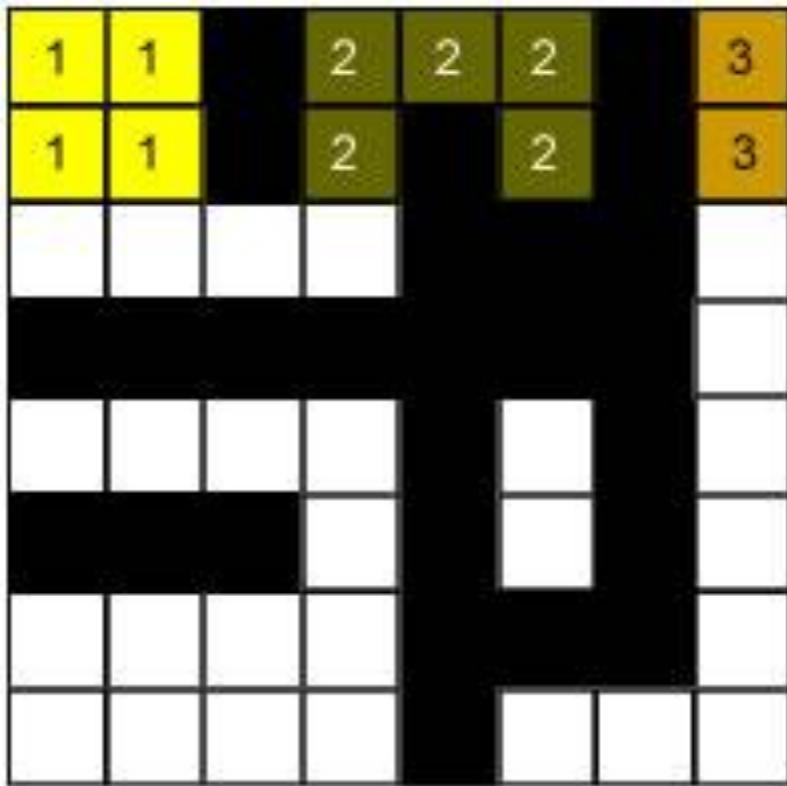
2PA: After row 1 is done



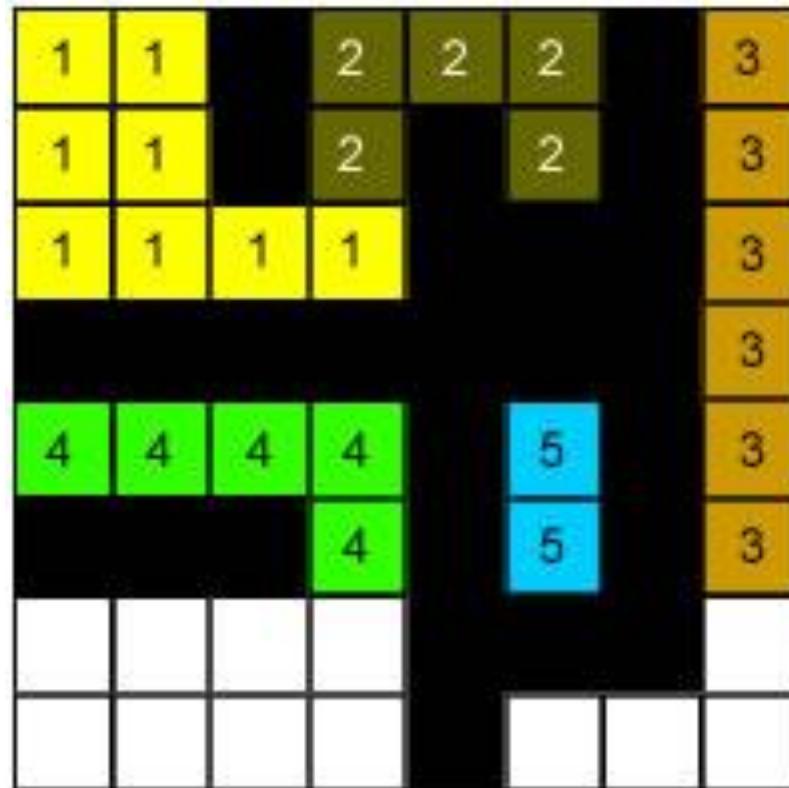
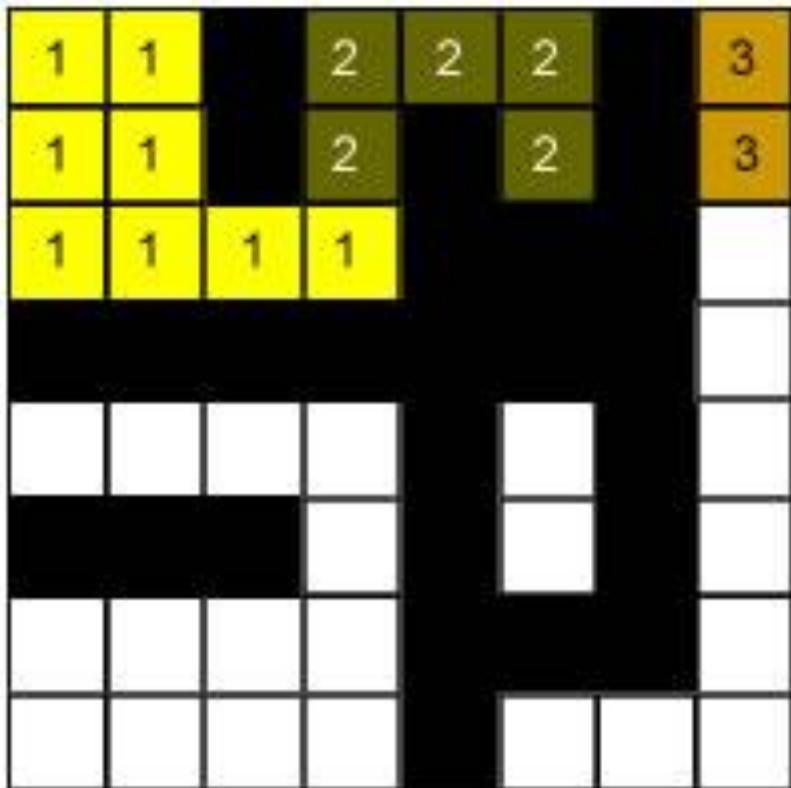
2PA: left/top pixel labeled → Copy label
(overrides) left pixel BG → new label



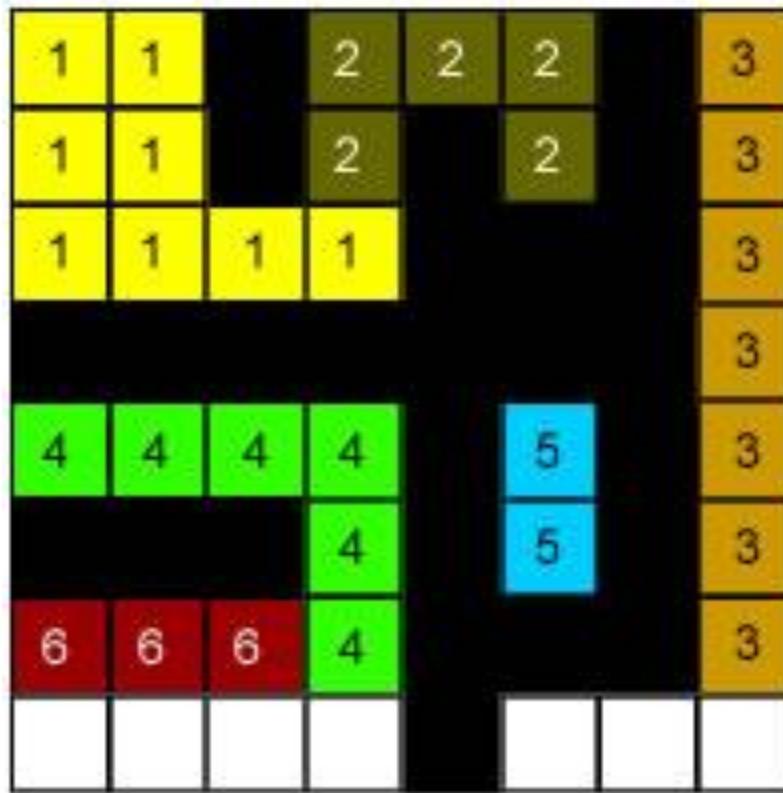
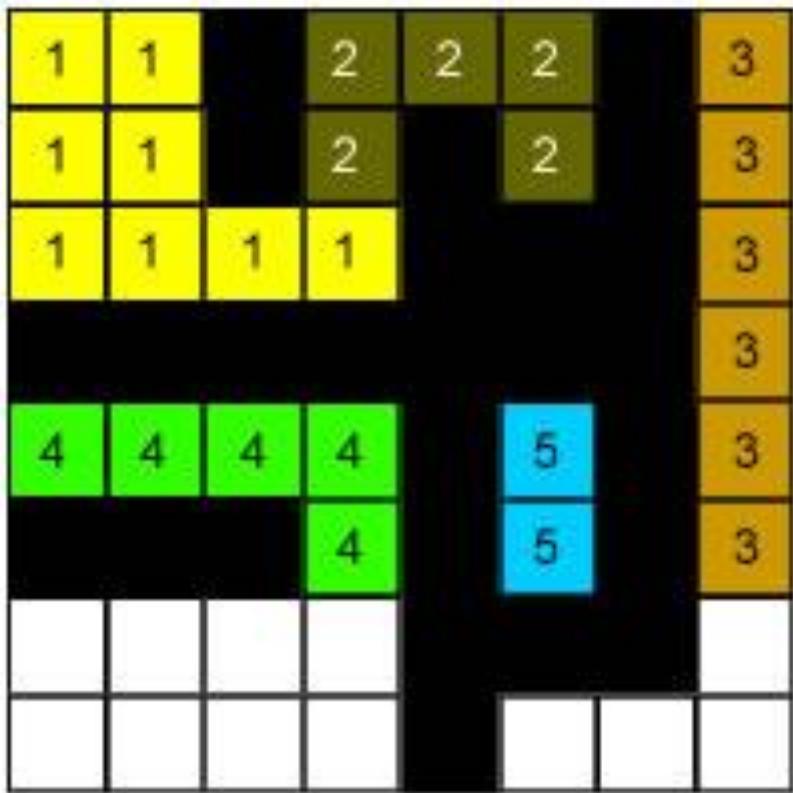
2PA: left/top pixel labeled, different labels → Copy smaller id label,
record the association



2PA: left/top pixel labeled, different labels → Copy smaller id label,
record the association



2PA



1
↑
2

4
↑
6

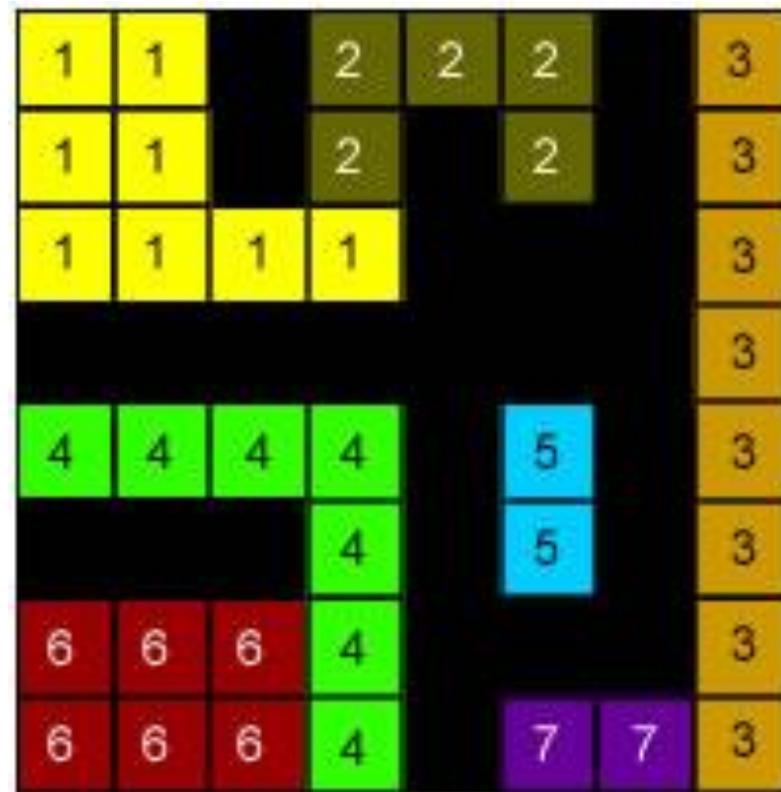
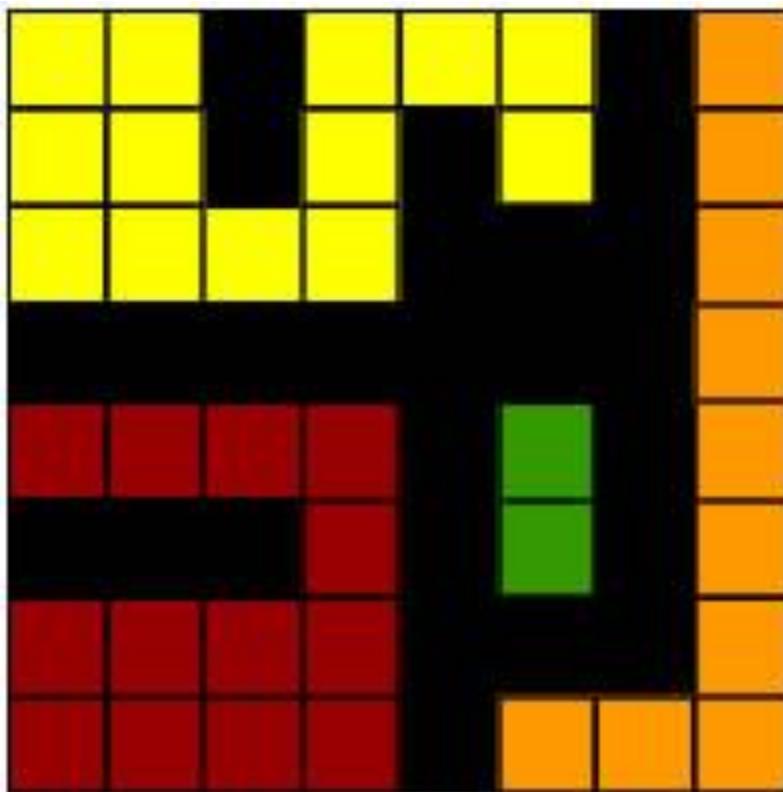
2PA: After first pass is complete

1	1		2	2	2	3
1	1		2	2		3
1	1	1	1			3
						3
4	4	4	4		5	3
					5	3
6	6	6	4			3
6	6	6	4			3

1	1		2	2	2	3
1	1		2	2		3
1	1	1	1			3
						3
4	4	4	4		5	3
					5	3
6	6	6	4			3
6	6	6	4			3
6	6	6	4		7	3
					7	3

1
2
4
6
3
7

2PA: After first pass is complete



1 ↑
2 ↑
4 ↑
6 ↑
3 ↑
7 ↑

2PA: Second pass: Replace child label with root label.

Union-Find data structure ensures ‘find’-ing root is O(1).

1	1		2	2	2		3
1	1		2		2		3
1	1	1	1				3
							3
4	4	4	4		5		3
					5		3
6	6	6	4				3
6	6	6	4		7	7	3

1	1		1	2	2		3
1	1		2		2		3
1	1	1	1	1			3
							3
4	4	4	4		5		3
					5		3
6	6	6	4				3
6	6	6	4		7	7	3

1
↑
2
4
↑
6
3
↑
7

2PA: Second pass: Replace child label with root label.

Union-Find data structure ensures ‘find’-ing root is O(1).

1	1		1	2	2		3
1	1		2		2		3
1	1	1	1				3
							3
4	4	4	4		5		3
				4			3
6	6	6	4				3
6	6	6	4		7	7	3

1	1		1	1	1		3
1	1		1	1	1		3
1	1	1	1				3
							3
4	4	4	4		5		3
				4			3
6	6	6	4				3
6	6	6	4		7	7	3

1
↑
2
4
↑
6
3
↑
7

2PA: Second pass: Replace child label with root label.

Union-Find data structure ensures ‘find’-ing root is O(1).

1	1		1	1	1		3
1	1		1		1		3
1	1	1	1				3
							3
4	4	4	4		5		3
				4		5	3
6	6	6	4				3
6	6	6	4		7	7	3

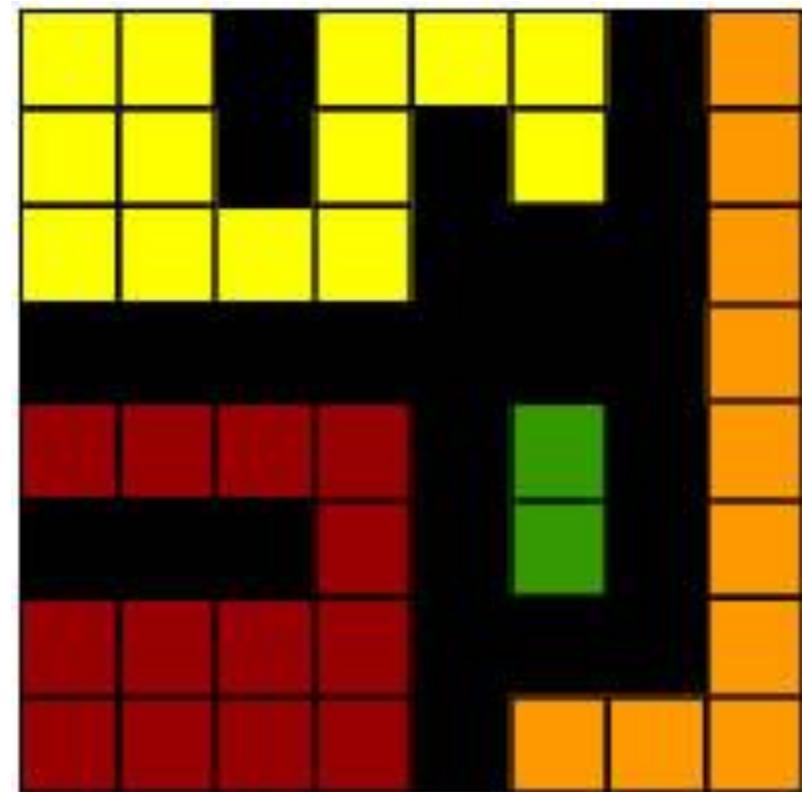
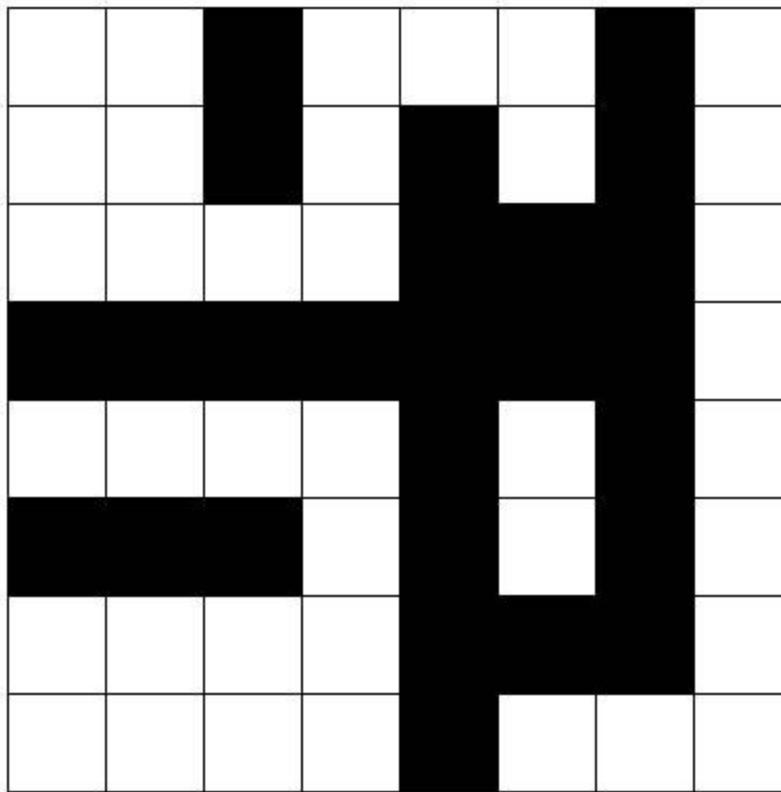
1	1		1	1	1		3
1	1		1		1		3
1	1	1	1				3
							3
4	4	4	4		5		3
				4		5	3
4	4	4	4				3
4	4	4	4		3	3	3

1
↑
2

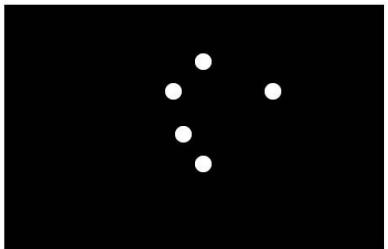
4
↑
6

3
↑
7

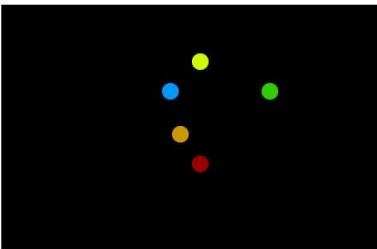
2PA-CCL (Rosenfeld&PFaltz 1968): Requires only two rows of image at a time



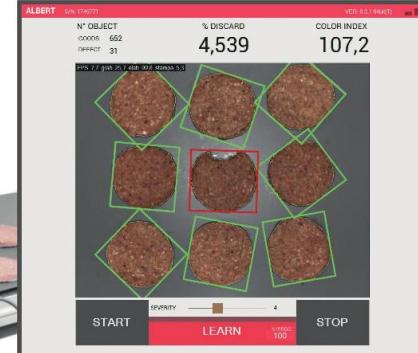
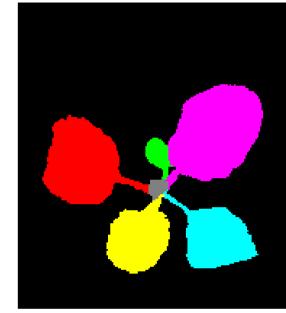
Connected Component Labeling

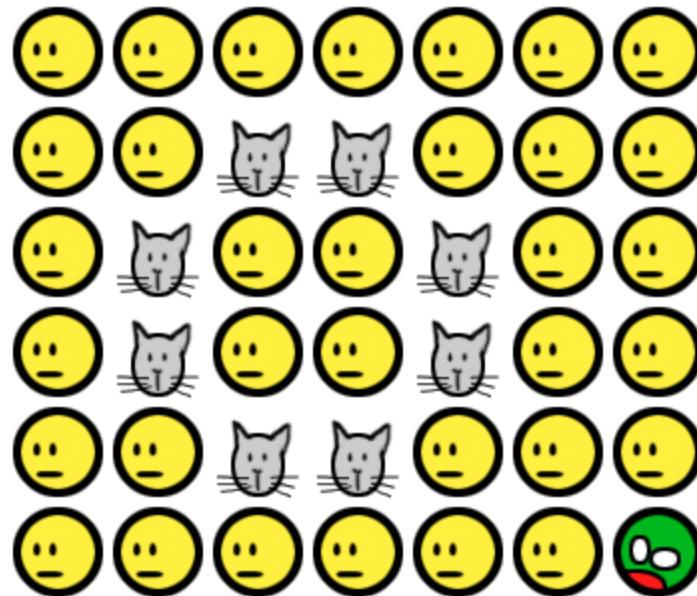
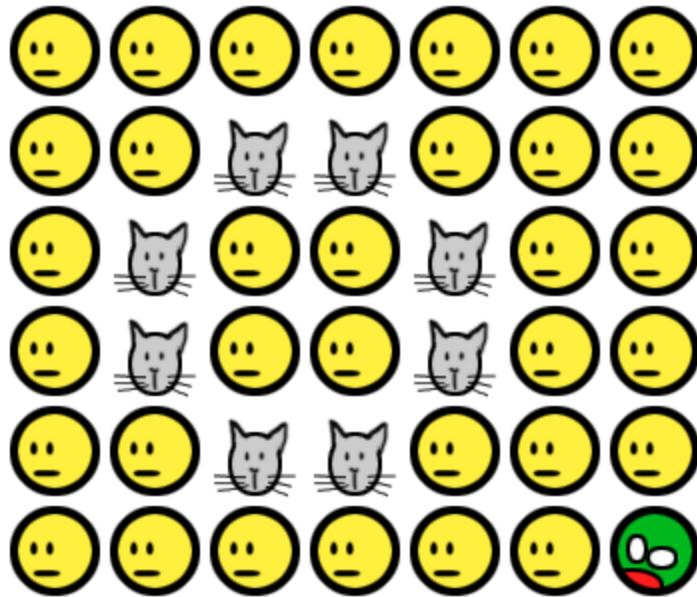


`bwlabel`

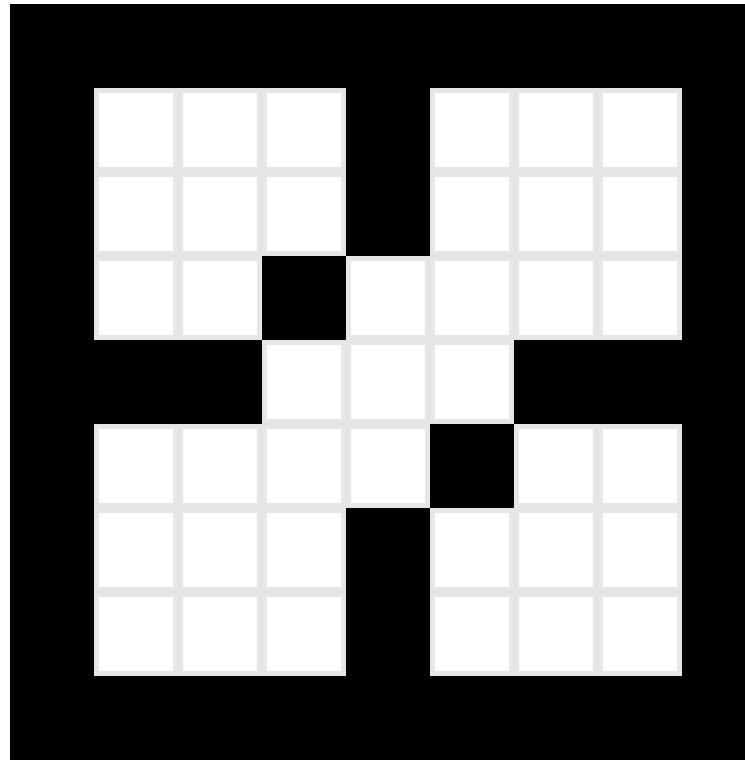


`label2rgb`





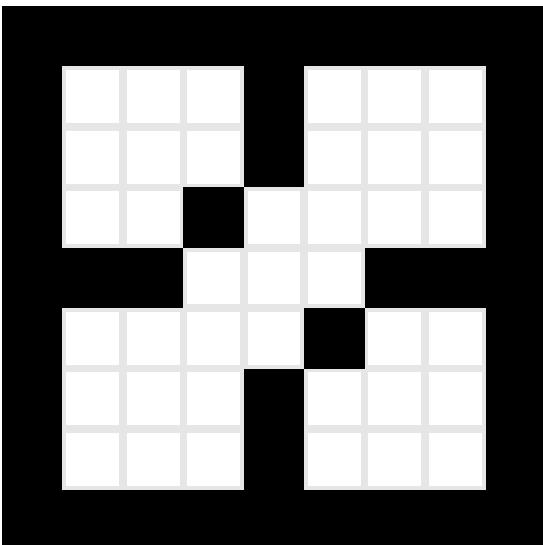
Flood-Fill



https://upload.wikimedia.org/wikipedia/commons/7/7e/Recursive_Flood_Fill_4_%28aka%29.gif

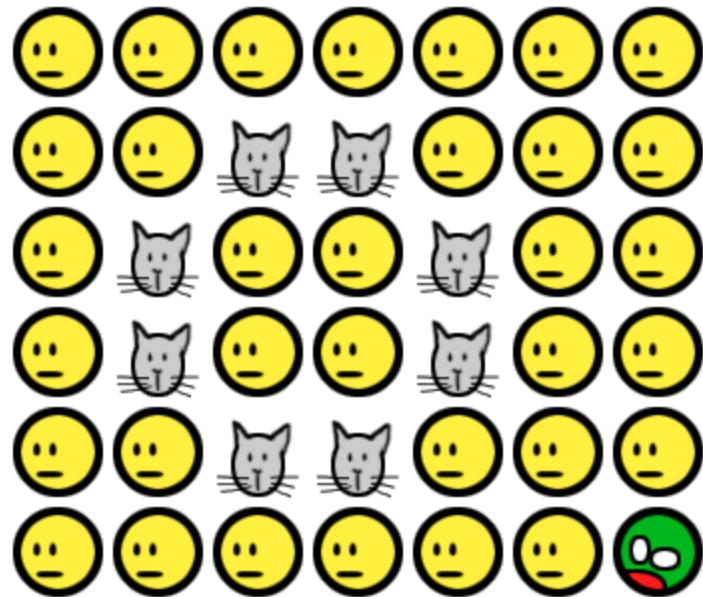
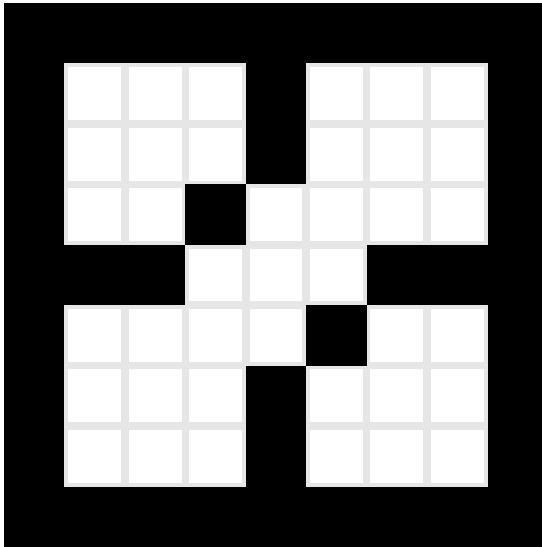
Flood-Fill Algorithm (4-conn)

```
void floodFill(int x, int y, int fill, int old)
{
    if ((x < 0) || (x >= width)) return;
    if ((y < 0) || (y >= height)) return;
    if (getPixel(x, y) == old) {
        setPixel(fill, x, y);
        floodFill(x+1, y, fill, old);
        floodFill(x, y+1, fill, old);
        floodFill(x-1, y, fill, old);
        floodFill(x, y-1, fill, old);
    }
}
```



Many/More efficient versions exist !

If 8-conn, all white pixels filled
(all humans eventually become zombie !)



Summary of Morphological Filtering

Operation	Equation	Comments (The Roman numerals refer to the structuring elements shown in Fig. 9.26.)
Translation	$(A)_z = \{w w = a + z, \text{ for } a \in A\}$	Translates the origin of A to point z .
Reflection	$\hat{B} = \{w w = -b, \text{ for } b \in B\}$	Reflects all elements of B about the origin of this set.
Complement	$A^c = \{w w \notin A\}$	Set of points not in A .
Difference	$A - B = \{w w \in A, w \notin B\} = A \cap B^c$	Set of points that belong to A but not to B .
Dilation	$A \oplus B = \{z (\hat{B})_z \cap A \neq \emptyset\}$	“Expands” the boundary of A . (I)
Erosion	$A \ominus B = \{z (B)_z \subseteq A\}$	“Contracts” the boundary of A . (I)
Opening	$A \circ B = (A \ominus B) \oplus B$	Smooths contours, breaks narrow isthmuses, and eliminates small islands and sharp peaks. (I)
Closing	$A \bullet B = (A \oplus B) \ominus B$	Smooths contours, fuses narrow breaks and long thin gulfs, and eliminates small holes. (I)

MATLAB codes

`circshift(A,z)`

`fliplr(flipud(B))`

`~A` or `1-A`

`A &~B`

`imdilate(A,B)`

`imerode(A,B)`

`imopen(A,B)`

`imclose(A,B)`

Summary (Con'd)

Hit-or-miss transform	$\begin{aligned} A \oplus B &= (A \ominus B_1) \cap (A^c \ominus B_2) \\ &= (A \ominus B_1) - (A \oplus \hat{B}_2) \end{aligned}$	The set of points (coordinates) at which, simultaneously, B_1 found a match ("hit") in A and B_2 found a match in A^c .	bwhitmiss(A,B)
Boundary extraction	$\beta(A) = A - (A \ominus B)$	Set of points on the boundary of set A . (I)	$A \& \sim(\text{imerode}(A,B))$
Region filling	$X_k = (X_{k-1} \oplus B) \cap A^c; X_0 = p$ and $k = 1, 2, 3, \dots$	Fills a region in A , given a point p in the region. (II)	region_fill.m
Thinning	$\begin{aligned} A \otimes B &= A - (A \oplus B) \\ &= A \cap (A \oplus B)^c \end{aligned}$	Thins set A . The first two equations give the basic definition of thinning. The last two equations denote thinning by a sequence of structuring elements. This method is normally used in practice. (IV)	$\text{bwmorph}(A, \text{'thin'})$
	$\begin{aligned} A \otimes \{B\} &= \\ &\left(\left(\dots \left((A \otimes B^1) \otimes B^2 \right) \dots \right) \otimes B^n \right) \\ \{B\} &= \{B^1, B^2, B^3, \dots, B^n\} \end{aligned}$		

Morphological Filtering using MATLAB

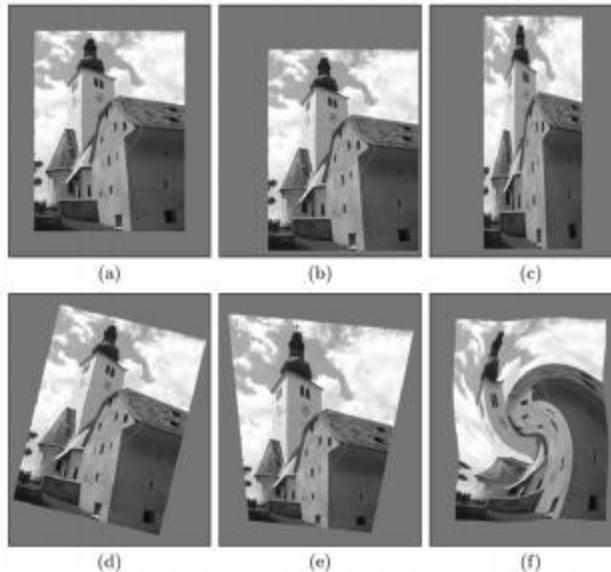
- <https://in.mathworks.com/help/images/morphological-filtering.html>

GEOMETRIC OPERATIONS

Geometric Operations

- Filters, point operations change intensity
- Pixel position (and geometry) unchanged
- Geometric operations: change image geometry
- **Examples:** translating, rotating, scaling an image

Examples of
Geometric
operations



Geometric Operations

- Example applications of geometric operations:
 - Zooming images, windows to arbitrary size
 - Computer graphics: deform textures and map to arbitrary surfaces
- **Definition:** Geometric operation transforms image I to new image I' by modifying **coordinates of image pixels**

$$I(x, y) \rightarrow I'(x', y')$$

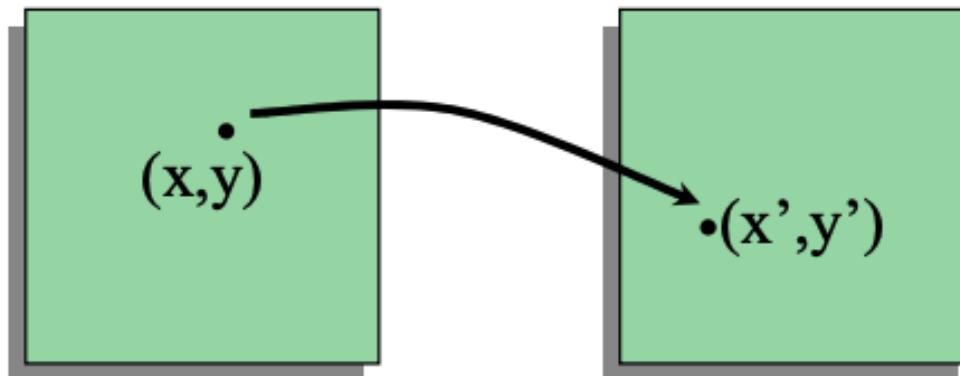
- Intensity value originally at (x, y) moved to new position (x', y')



$$x \rightarrow f_x(x, y) = x'$$

$$y \rightarrow f_y(x, y) = y'$$

$$I(x, y) = I'(f_x(x, y), f_y(x, y))$$



$I(x, y)$

$I'(x', y')$

Common Geometric Operations



- **Scale** - change image content size



- **Rotate** - change image content orientation



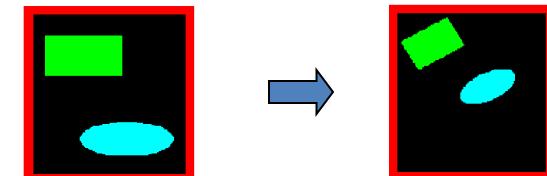
- **Reflect** - flip over image contents



- **Translate** - change image content position



- **Affine Transformation**
 - general image content linear geometric transformation



Simple Mappings

- **Translation:** (shift) by a vector (d_x, d_y)

$$\begin{aligned} T_x : x' &= x + d_x & \text{or} & \\ T_y : y' &= y + d_y & \left(\begin{matrix} x' \\ y' \end{matrix} \right) &= \left(\begin{matrix} x \\ y \end{matrix} \right) + \left(\begin{matrix} d_x \\ d_y \end{matrix} \right) \end{aligned}$$



Simple Mappings

- **Translation:** (shift) by a vector (d_x, d_y)

$$\begin{aligned}T_x : x' &= x + d_x \\T_y : y' &= y + d_y\end{aligned}\quad \text{or} \quad \begin{pmatrix}x' \\ y'\end{pmatrix} = \begin{pmatrix}x \\ y\end{pmatrix} + \begin{pmatrix}d_x \\ d_y\end{pmatrix}$$



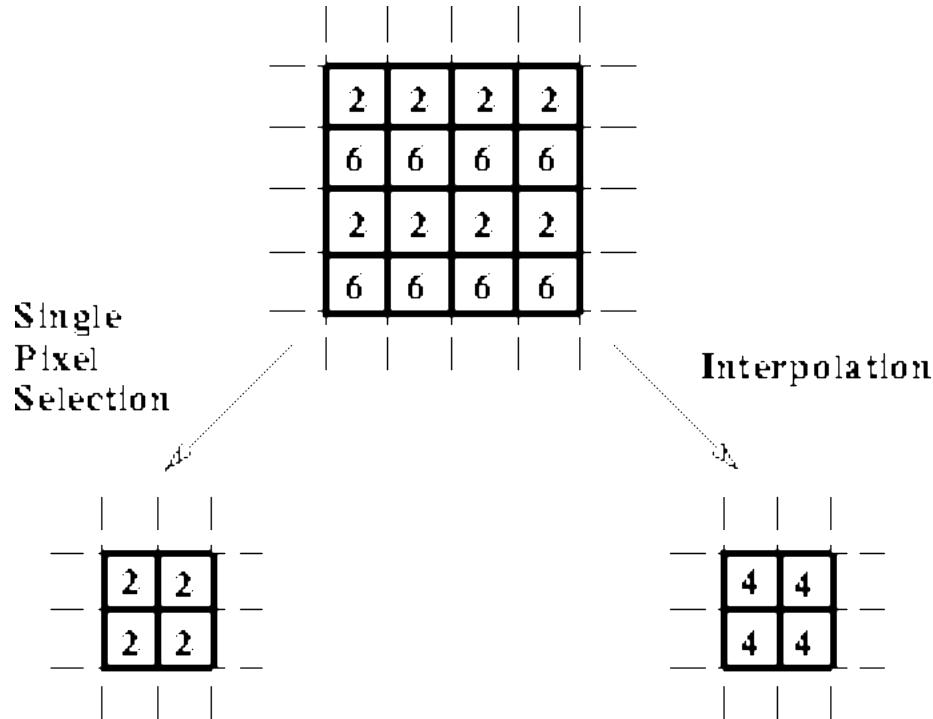
- **Scaling:** (contracting or stretching) along x or y axis by a factor

s_x or s_y

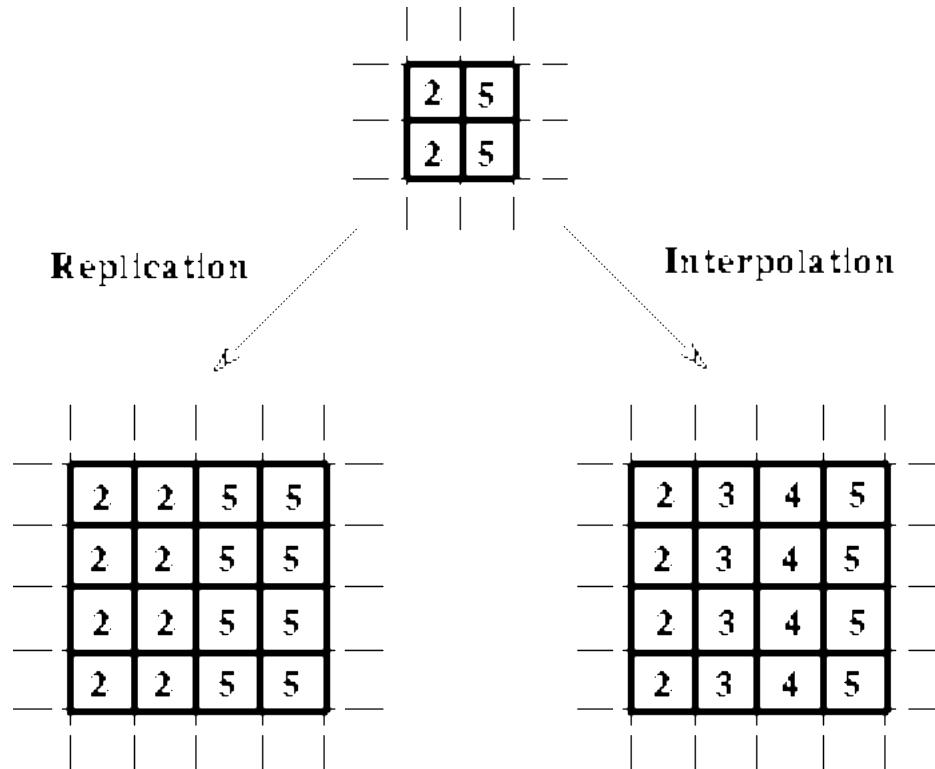
$$\begin{aligned}T_x : x' &= s_x \cdot x \\T_y : y' &= s_y \cdot y\end{aligned}\quad \text{or} \quad \begin{pmatrix}x' \\ y'\end{pmatrix} = \begin{pmatrix}s_x & 0 \\ 0 & s_y\end{pmatrix} \cdot \begin{pmatrix}x \\ y\end{pmatrix}$$



Scaling (Shrink)



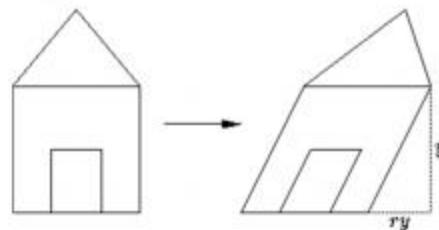
Scaling (Stretch)



Simple Mappings

- **Shearing:** along x and y axis by factor b_x and b_y

$$T_x : x' = x + b_x \cdot y \quad \text{or} \quad \begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} 1 & b_x \\ b_y & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$



- **Rotation:** the image by an angle α

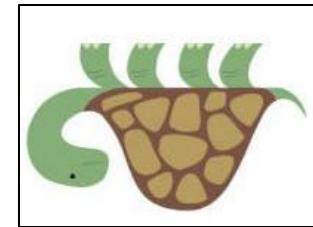
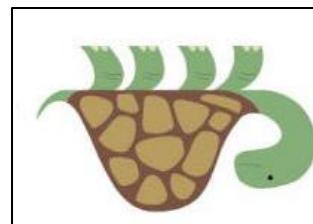
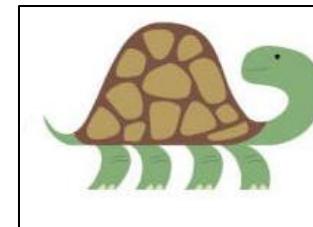
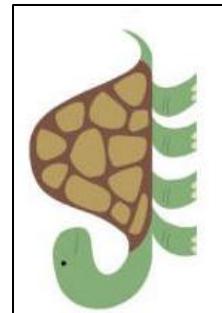
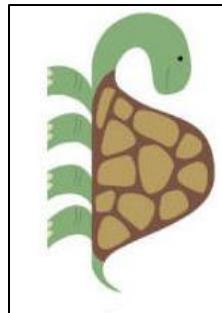
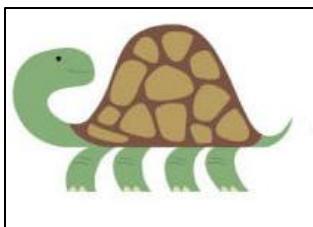
$$T_x : x' = x \cdot \cos \alpha - y \cdot \sin \alpha$$

$$T_y : y' = x \cdot \sin \alpha + y \cdot \cos \alpha$$

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix}$$

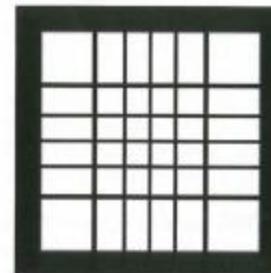
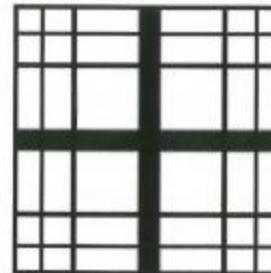


90, 180 rotations , Flipping



- **Image warping:** we can use a function to select which pixel somewhere else in the image to look up
- For example: apply function on both texel coordinates (x, y)

$$x' = x + y * \sin(\pi * x)$$



Homogeneous Coordinates

- Notation useful for converting scaling, translation, rotating into point-matrix multiplication
- To convert ordinary coordinates into homogeneous coordinates

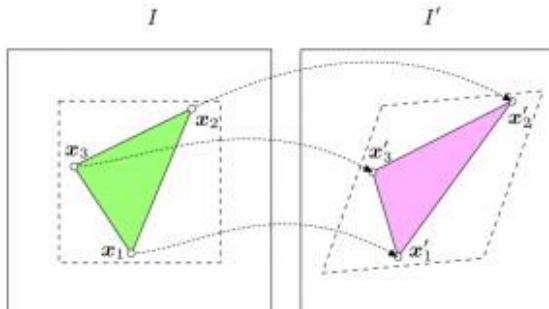
$$\mathbf{x} = \begin{pmatrix} x \\ y \end{pmatrix} \quad \text{converts to} \quad \hat{\mathbf{x}} = \begin{pmatrix} \hat{x} \\ \hat{y} \\ h \end{pmatrix} = \begin{pmatrix} h \ x \\ h \ y \\ h \end{pmatrix}$$

Affine (3-Point) Mapping

- Can use homogeneous coordinates to rewrite translation, rotation, scaling, etc as vector-matrix multiplication

$$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

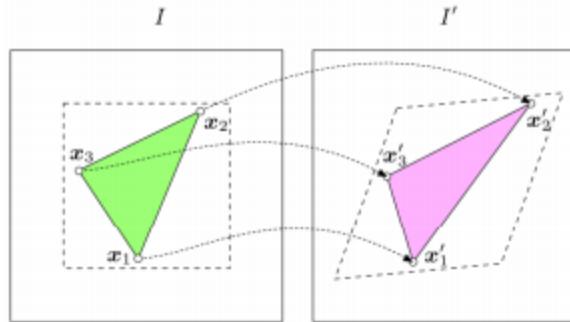
- **Affine mapping:** Can then derive values of matrix that achieve desired transformation (or combination of transformations)



- Inverse of transform matrix is **inverse mapping**

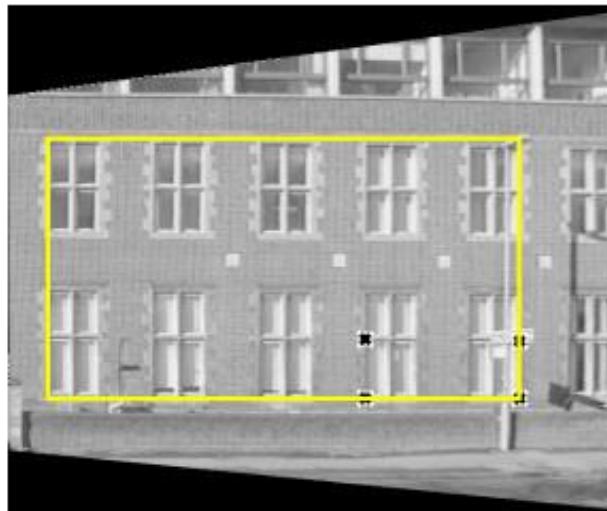
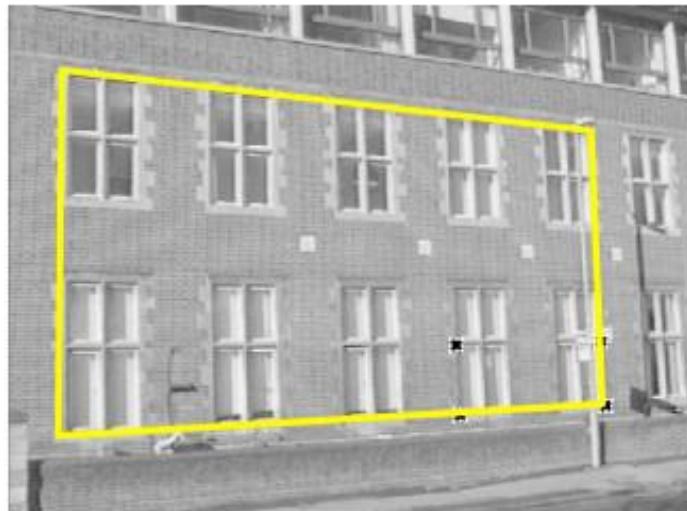
Affine (3-Point) Mapping

- What's so special about affine mapping?



- Maps
 - straight lines \rightarrow straight lines,
 - triangles \rightarrow triangles
 - rectangles \rightarrow parallelograms
 - Parallel lines \rightarrow parallel lines
- Distance ratio on lines do not change

Homography



from Hartley & Zisserman

$$\begin{pmatrix} x'_1 \\ x'_2 \\ x'_3 \end{pmatrix} = \begin{bmatrix} h_{11} & h_{12} & h_{13} \\ h_{21} & h_{22} & h_{23} \\ h_{31} & h_{32} & h_{33} \end{bmatrix} \times \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

References

- G&W, 3rd Ed., 9.1-9.3, 9.6
- Grayscale Morphology:

<http://people.ciirc.cvut.cz/~hlavac/TeachPresEn/11ImageProc/71-06MatMorfolGrayEn.pdf>

Scribe List

2018102018
2018102019
2018102022
2018102027
2018102028
2018102031