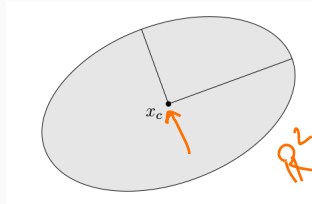


Example of convex set: Ellipsoid

Ellipsoid: $\{x \mid (x - x_c)^T P (x - x_c) \leq 1\}$

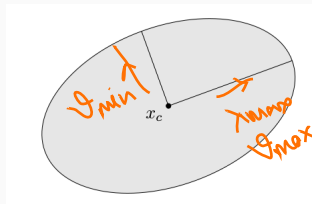
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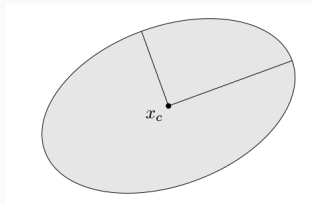
\mathbb{R}^2
 $P \in \mathbb{R}^{2 \times 2}$
 λ_{\max}
 λ_{\min}

- Matrix P determines how far the ellipsoid extends in every direction from center x_c

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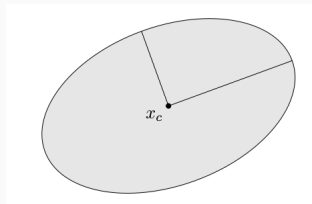


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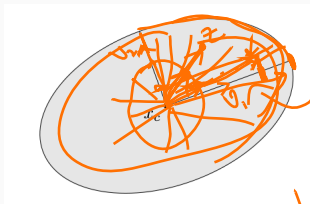


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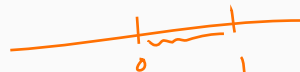
Example of convex set: Ellipsoid

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- P is symmetric positive definite



$$x^T P x - x_c^T P x + \underbrace{x_c^T P x_c}_{\text{constant}}$$



$(x - x_c)^T P (x - x_c) \geq 0$
We have a basis

- Matrix P determines how far the ellipsoid extends in every direction from center x_c
- The length of semi-axes of ellipsoid are given by $\sqrt{\lambda_i}$, where λ_i are eigenvalues of P
- A ball is an ellipsoid with $P = r^2 I$
- Another representation of Ellipsoid

$$\{x_c + Au \mid \|u\|_2 \leq 1\}, \quad A \text{ is SPD}$$

P is sym.
 $\Rightarrow P$ has n -Lin.
ind. eig. veds.

Example of Convex Set: Norm Cone

The norm cone associated with a norm $\|\cdot\|$ is the set

$$C = \{(x, t) \mid \|x\|_2 \leq t\} \subseteq \mathbb{R}^{n+1},$$

$(x, t) \in \mathbb{R}^{n+1}$
 $x \in \mathbb{R}^n, t \in \mathbb{R}$
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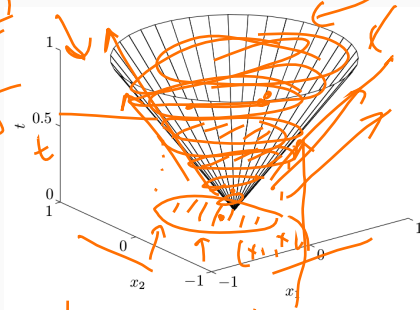
$$C = \{(x, t) \mid \|x\| \leq t\} \subseteq \mathbb{R}^{n+1}$$

Ex This is convex

(x, t)
 (y, t)

Norm Ball

$$B_2 = \{x \mid \|x\|_2 \leq 1\}$$



$n = 2$
 C in \mathbb{R}^3

(x_1, x_2, t)

$$\sqrt{x_1^2 + x_2^2} \leq t$$

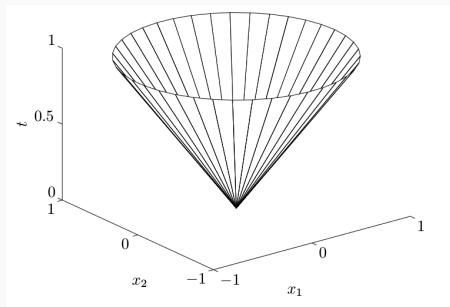
$$x_1^2 + x_2^2 \leq t^2$$

disc / circle with center (0,0)
radius = t

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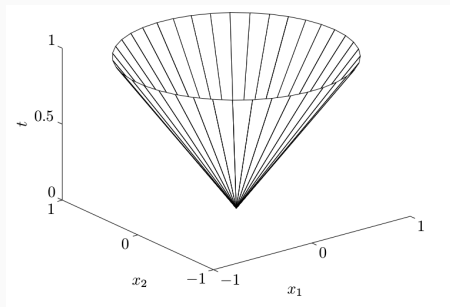


- **Second order cone:** Norm cone with $\|\cdot\|_2$ norm

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- **Second order cone:** Norm cone with $\|\cdot\|_2$ norm
- Other names of second order cone: **quadratic cone**, **Lorentz-cone**, **ice-cream cone**

Example of convex sets: Polyhedron

Polyhedron is defined as a set of finite number of equalities and inequalities:

$$P = \{x \mid a_j^T x \leq b_j, j = 1, \dots, m, \quad c^T x = d_j, j = 1, 2, \dots, p\}$$

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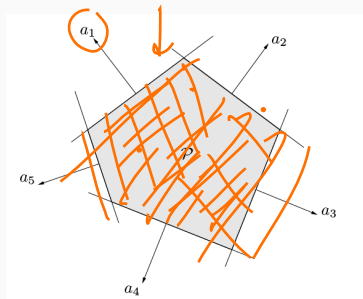
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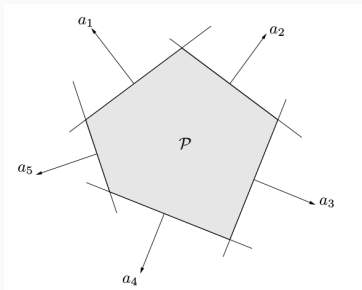
$$\left. \begin{array}{l} a_1^T x \leq b_1 \\ a_2^T x \leq b_2 \\ \vdots \\ a_m^T x \leq b_m \end{array} \right\}$$

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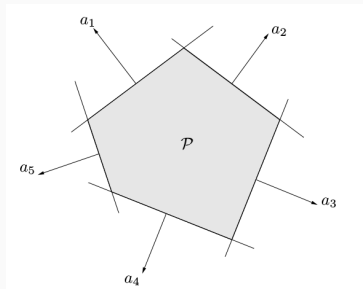


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Quiz Which of the following are **polyhedron**?

- hyperplanes, lines, half-spaces

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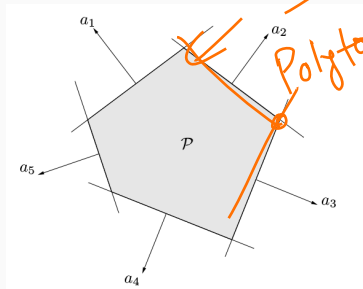
Polyhedron is defined as a set of finite number of equalities and inequalities:

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can't be circle

$$\begin{bmatrix} -a_1^T \\ -a_2^T \\ \vdots \\ -a_m^T \end{bmatrix} x \leq \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix} \quad A \quad b$$

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A bounded polyhedron is usually called polytope

Example of Convex Sets: Polyhedron

A **polyhedron** can be more compactly represented as

$$P = \{x \mid \underline{Ax \leq b}, \underline{Cx = d}\},$$

where

$$A = \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_m^T \end{bmatrix}, \quad C = \begin{bmatrix} c_1^T \\ c_2^T \\ \vdots \\ c_p^T \end{bmatrix}$$

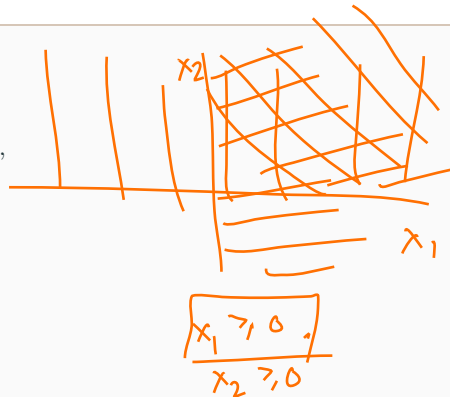
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Example: The **nonnegative orthant** is the set of points with **nonnegative** components.

$$\left\{ \mathbb{R}_+^n = \{x \in \mathbb{R}^n \mid x_i \geq 0, i = 1, 2, \dots, n\} = \{x \in \mathbb{R}^n \mid x \geq 0\} \right.$$

$x_n \geq 0$

Example of Convex set: Simplexes

Simplexes are another family of polyhedra.

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$$C = \text{conv}\{v_0, v_1, \dots, v_k\} = \{\theta_0 v_0 + \theta_1 v_1 + \dots + \theta_k v_k \mid \theta \geq 0, 1^T \theta = 1\}$$

$\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_k \end{bmatrix}$

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$$\{v_1 - v_0, v_2 - v_0\} \text{ L.I.}$$

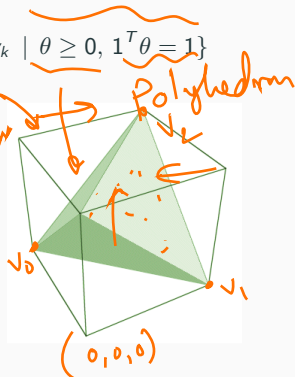


Figure 1: Tetrahedron

Other Examples of Simplexes

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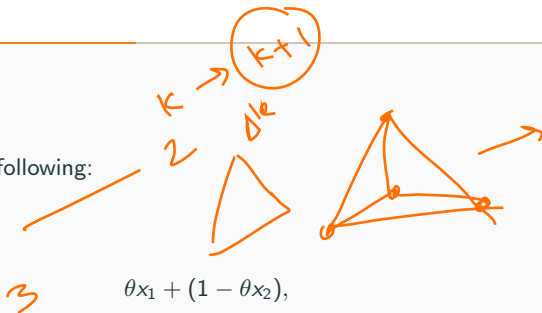
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2. 2D simplex = triangle: This simplex can be generated by considering affinely independent points x_1, x_2 , and x_3
3. 3D simplex = tetrahedron: This simplex is generated by considering affinely independent points x_1, x_2, x_3 , and x_4

Other simplexes

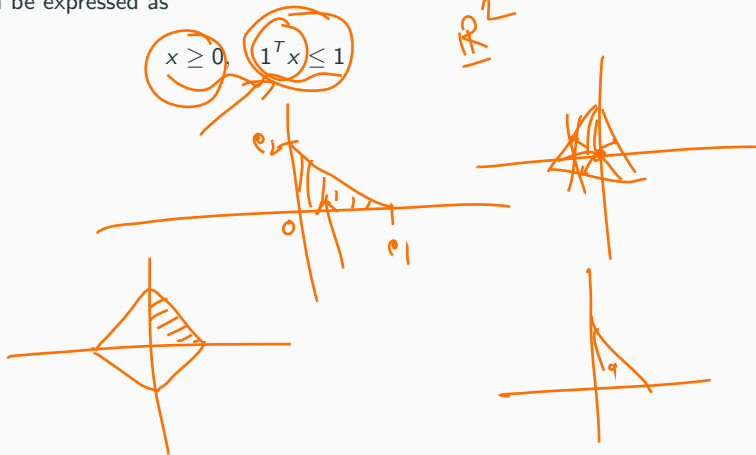
1. **Unit Simplex:** n -dimensional simplex determined by zero vector and the unit vectors, i.e., $0, e_1, \dots, e_n \in \mathbb{R}^n$. It can be expressed as

$$0, e_1, e_2$$

$$\|x\|_1 \leq 1$$

$$x \geq 0, \quad 1^T x \leq 1$$

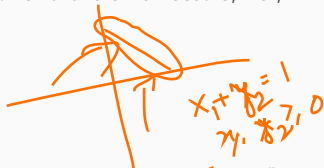
\mathbb{R}^2



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2. **Probability Simplex:** $n - 1$ dimensional simplex determined by the unit vectors $e_1, \dots, e_n \in \mathbb{R}^n$. It is the set of vectors that satisfy

$$x \geq 0, \quad 1^T x = 1$$

$$\begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \sum_{i=1}^n x_i = 1$$

- Vectors in probability simplex correspond to **probability distributions** on a set with n elements
- x_i interpreted as probability of the i th element

Cones, Convex Cones

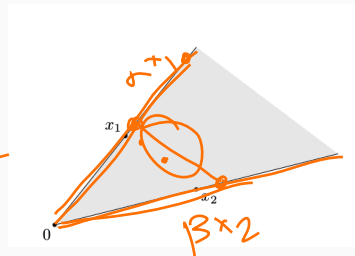
Cone: A set C is called a **cone** if for every $x \in C$, and $\theta \geq 0$, we have $\theta x \in C$.

$$C = \{ \alpha x_1 \} \cup \{ \beta x_2 \}$$

\uparrow is a cone.



Figure 2: Cone



Let $y \in C$
 $\Rightarrow y \in \{ \alpha x_1 \}$
 $y = \alpha x_1 \in C$

Cone is not necessarily convex.

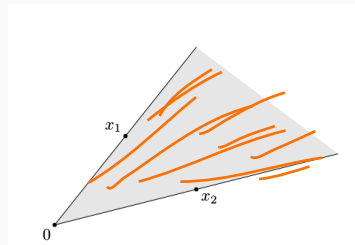
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Convex Cone: A set C is called convex cone if it is convex and a cone, i.e.,

$$\theta_1 x_1 + \theta_2 x_2 \in C, \quad x_1, x_2 \in C, \theta_1, \theta_2 \geq 0$$

Figure 2: Cone



Conic Combination and Conic Hull

$$\cancel{X^T \theta = 1}$$

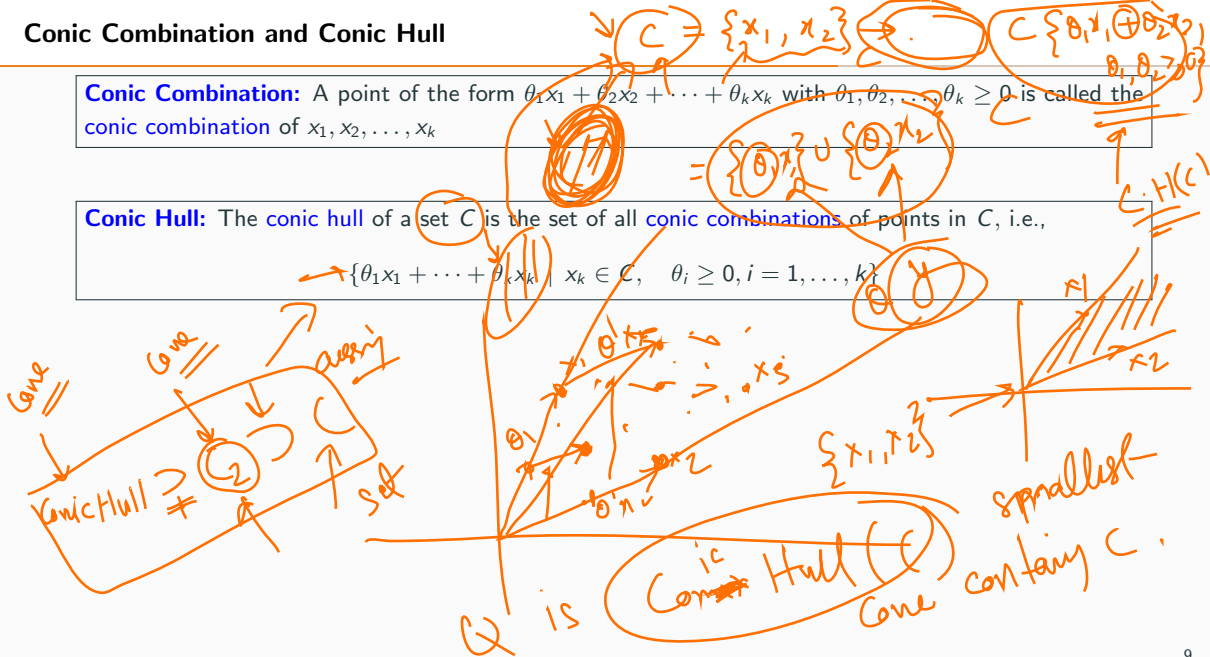
Conic Combination: A point of the form $\theta_1 x_1 + \theta_2 x_2 + \cdots + \theta_k x_k$ with $\theta_1, \theta_2, \dots, \theta_k \geq 0$ is called the **conic combination** of x_1, x_2, \dots, x_k

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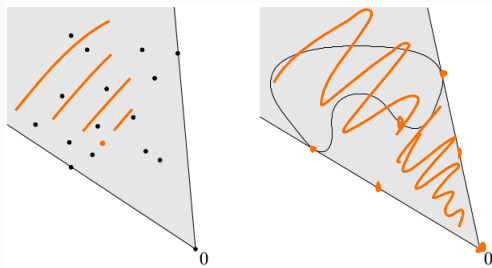


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Positive Semi-definite Cone

Let S^n denote set of **symmetric** $n \times n$ matrices

$$S^n = \{X \in \mathbb{R}^n \mid X = X^T\}$$

