

Learning

Deductive Reasoning

- **Deductive Reasoning** – A type of logic in which one goes from a general statement to a specific instance.
- The classic example
All men are mortal. (premise-I)
Socrates is a man. (premise-II)
Therefore, Socrates is mortal. (conclusion)

Inductive Reasoning

Inductive Reasoning, involves going from a series of specific cases to a general statement. The conclusion in an inductive argument is never guaranteed.

Example: What is the next number in the sequence 6, 13, 20, 27, ...
There is more than one correct answer.

Inductive Reasoning

- Here's the sequence again 6, 13, 20, 27, ...
- Look at the difference of each term.
- $13 - 6 = 7$, $20 - 13 = 7$, $27 - 20 = 7$
- Thus the next term is 34, because $34 - 27 = 7$.
- However what if the sequence represents the dates. Then the next number could be 3 (31 days in a month).
- The next number could be 4 (30 day month)
- Or it could be 5 (29 day month – Feb. Leap year)
- Or even 6 (28 day month – Feb.)

Two types of learning in AI

Deductive: Deduce rules/facts from already known rules/facts. (We have already dealt with this)

$$(A \Rightarrow B \Rightarrow C) \Rightarrow (A \Rightarrow C)$$

Inductive: Learn new rules/facts from a data set \mathcal{D} .

$$\mathcal{D} = \{\mathbf{x}(n), y(n)\}_{n=1 \dots N} \Rightarrow (A \Rightarrow C)$$

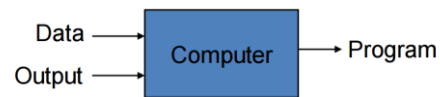
Motivation

- Learning is important for agents to deal with
 - Unknown environments (lacks omniscience)
 - Changes
- In many cases, it is more efficient to train an agent via examples, than to “manually” extract knowledge from the examples
- Agents capable of learning can improve their performance

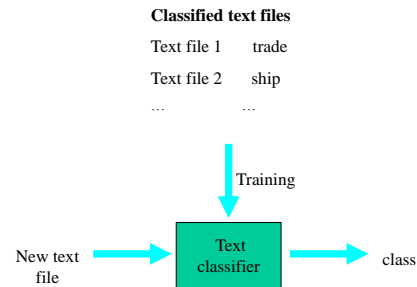
Traditional Programming



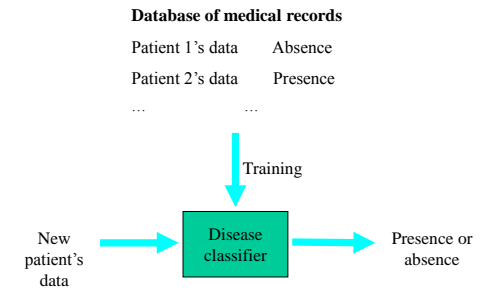
Machine Learning



Example 1: Text Classification



Example 2: Disease Diagnosis



Inductive Learning

- **Inductive learning** or “**Prediction**”:
 - **Given** examples of a function $(X, F(X))$
 - **Predict** function $F(X)$ for new examples X
- **Classification**: Learning categories
 $F(X)$ = Discrete
- **Regression**: Learning function values
 $F(X)$ = Continuous

Inductive learning

Simplest form: learn a function from examples

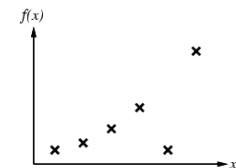
f is the **target function**

An **example** is a pair $(x, f(x))$

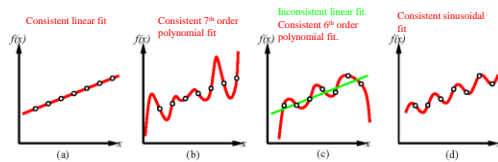
Problem: find a **hypothesis** h
 such that $h \approx f$
 given a **training set** of examples

Inductive learning method

- Construct/adjust h to agree with f on training set
- (h is **consistent** if it agrees with f on all examples)
- E.g., curve fitting:

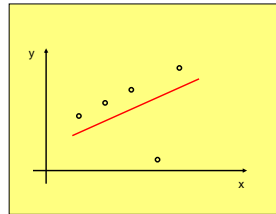


Inductive learning

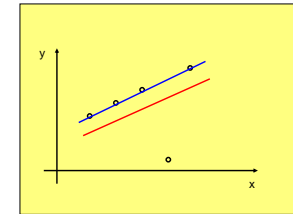


- Construct h so that it agrees with f .
- The hypothesis h is consistent if it agrees with f on all observations.
- How to achieve good generalization?

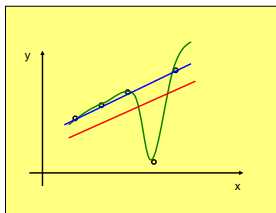
Inductive learning – example



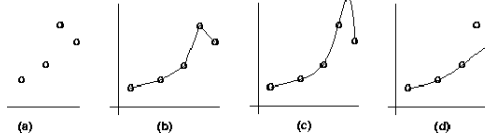
Inductive learning – example



Inductive learning – example



Inductive learning and bias

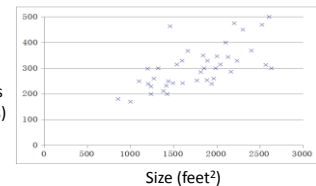


- Suppose that we want to learn a function h and we are given some sample $(x, f(x))$ pairs, as in figure (a)
- There are several hypotheses we could make about this function, e.g.: (b), (c) and (d)
- A preference for one over the others reveals the **bias** of our learning technique, e.g.:
 - prefer piece-wise functions
 - prefer a smooth function
 - prefer a simple function and treat outliers as noise

Linear Regression with one Variable

Housing Prices (Portland, OR)

Price
(in 1000s
of dollars)



Supervised Learning

Given the “right answer” for each example in the data.

Regression Problem

Predict real-valued output

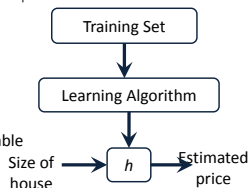
	Size in feet ² (x)	Price (\$) in 1000's (y)
Training set of housing prices	2104	460
	1416	232
	1534	315
	852	178

Notation:

m = Number of training examples

x's = "input" variable / features

y's = "output" variable / "target" variable



Question : How to describe **h**?

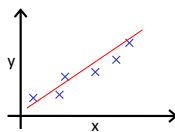
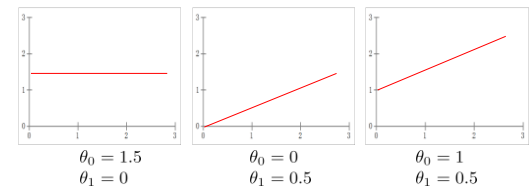
Training Set	Size in feet ² (x)	Price (\$) in 1000's (y)
	2104	460
	1416	232
	1534	315
	852	178

Hypothesis: $h_{\theta}(x) = \theta_0 + \theta_1 x$

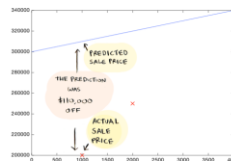
θ_i 's: Parameters

How to choose θ_i 's ?

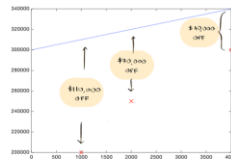
$$h_{\theta}(x) = \theta_0 + \theta_1 x$$



Idea: Choose θ_0, θ_1 so that $h_{\theta}(x)$ is close to y for our training examples (x, y)



Maybe a drunk person drew this line...it is \$110,000 dollars off the mark for that house. It is also far off all the other values:



On average, this line is \$73,333 off $(\$110,000 + \$70,000 + \$40,000 / 3)$.

Cost Function

Hypothesis:

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

Parameters:

$$\theta_0, \theta_1$$

Cost Function:

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

Goal: minimize $J(\theta_0, \theta_1)$

Simplified:

$$h_{\theta}(x) = \theta_1 x$$

$$\theta_1$$

$$J(\theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

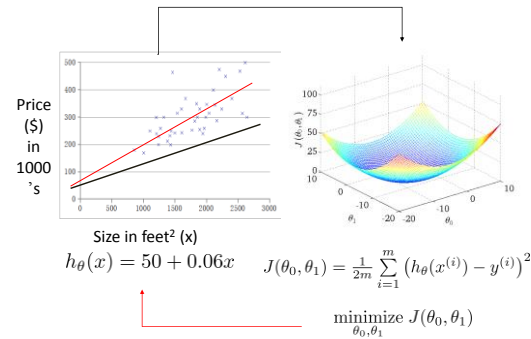
minimize $J(\theta_1)$

Cost Function

FOR A GIVEN θ_0 AND θ_1 ...

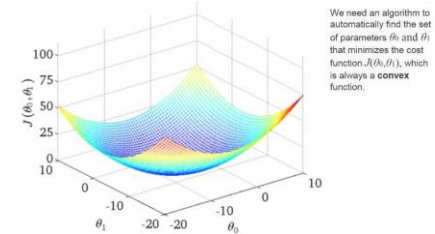
$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

1. THE PREDICTED VALUE
2. FIND THE DIFFERENCE BETWEEN THE PREDICTED AND ACTUAL VALUES
3. FIND ALL THE DIFFERENCES BETWEEN PREDICTED AND ACTUAL
4. FIND THE AVERAGE



Question: How to minimize J ?

The mean is halved as a convenience for the computation of the gradient descent, as the derivative term of the square function will cancel out the $(\cdot)^2$ term.



The cost function used for lecture is a convex function. In general don't necessarily have a convex cost function though we prefer to have one.

Gradient Descent

Have some function $J(\theta_0, \theta_1)$

Want $\min_{\theta_0, \theta_1} J(\theta_0, \theta_1)$

Outline:

- Start with some θ_0, θ_1
- Keep changing θ_0, θ_1 to reduce $J(\theta_0, \theta_1)$ until we hopefully end up at a minimum



Gradient descent algorithm

repeat until convergence {
 $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$ (for $j = 0$ and $j = 1$)
}

Correct: Simultaneous update

temp0 := $\theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$
temp1 := $\theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$
 $\theta_0 :=$ temp0
 $\theta_1 :=$ temp1

Incorrect:

temp0 := $\theta_0 - \alpha \frac{\partial}{\partial \theta_0} J(\theta_0, \theta_1)$
 $\theta_0 :=$ temp0
temp1 := $\theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_0, \theta_1)$
 $\theta_1 :=$ temp1

Gradient descent algorithm

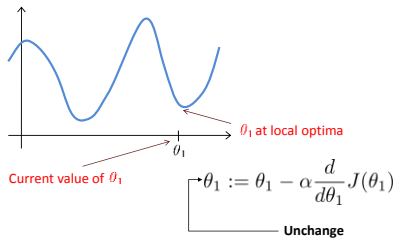
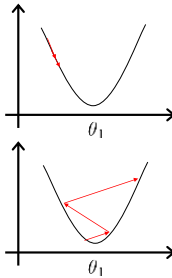
repeat until convergence {
 $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$ (simultaneously update $j = 0$ and $j = 1$)
}

α is the **learning rate**.

$$\theta_1 := \theta_1 - \alpha \frac{\partial}{\partial \theta_1} J(\theta_1)$$

If α is too small, gradient descent can be slow.

If α is too large, gradient descent can overshoot the minimum. It may fail to converge, or even diverge.



Gradient descent can converge to a local minimum, even with the learning rate α fixed.

Gradient Descent for Linear Regression

Gradient descent algorithm

repeat until convergence {
 $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \theta_1)$
 (for $j = 1$ and $j = 0$)
}

Linear Regression Model

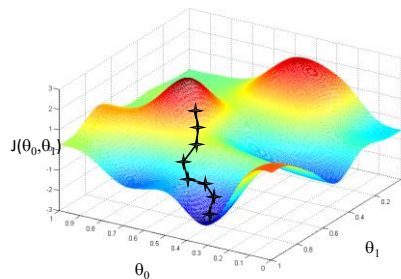
$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$J(\theta_0, \theta_1) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

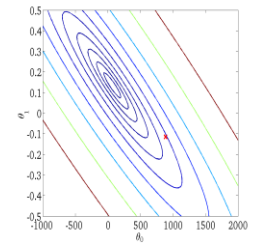
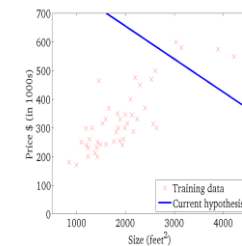
Gradient descent algorithm

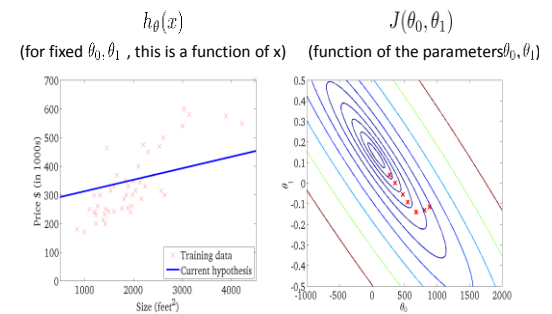
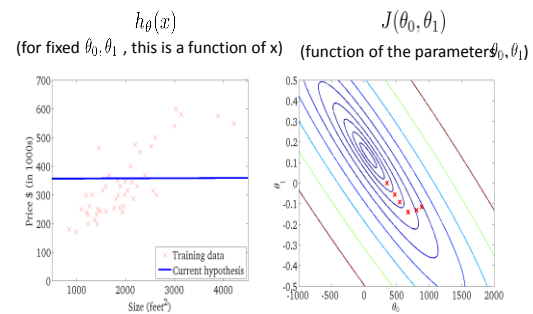
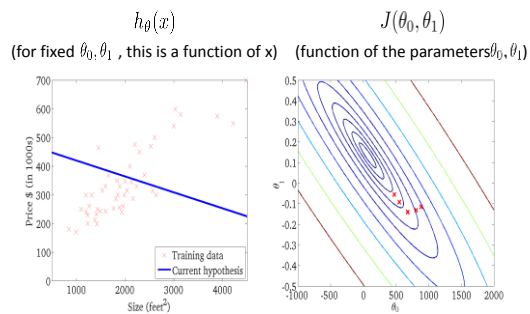
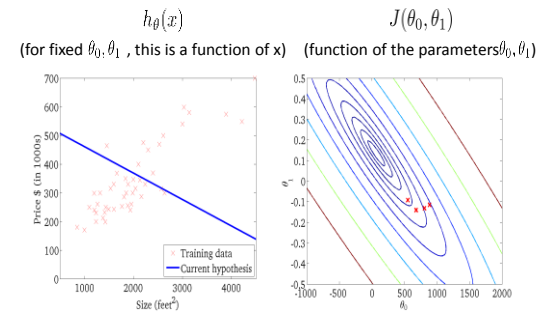
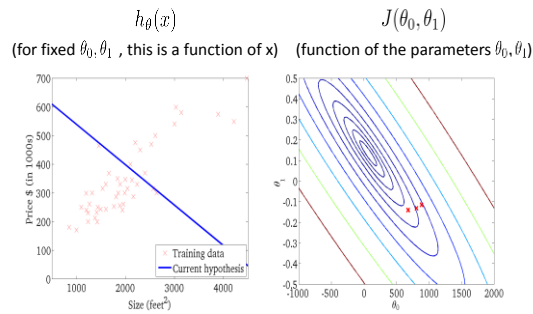
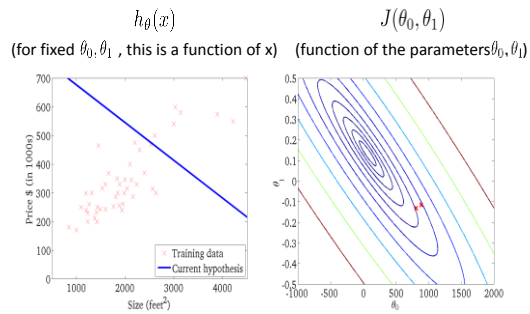
repeat until convergence {
 $\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})$
 $\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) \cdot x^{(i)}$
} }
 update θ_0 and θ_1 simultaneously

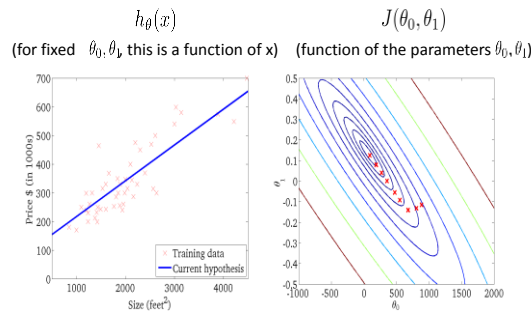
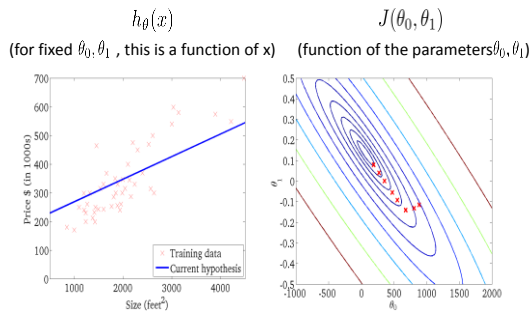
This method looks at each example in the entire training set on every step, and is called batch gradient descent.



$h_{\theta}(x)$ (for fixed θ_0, θ_1 , this is a function of x) $J(\theta_0, \theta_1)$ (function of the parameters θ_0, θ_1)







Linear Regression with multiple variables

Hypothesis: $h_{\theta}(x) = \theta^T x = \theta_0 x_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$

Parameters: $\theta_0, \theta_1, \dots, \theta_n$

Cost function:

$$J(\theta_0, \theta_1, \dots, \theta_n) = \frac{1}{2m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

Gradient descent:

Repeat {
 $\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_j} J(\theta_0, \dots, \theta_n)$
 } (simultaneously update for every $j = 0, \dots, n$)

Gradient Descent

Previously (n=1):

Repeat {
 $\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})$
 $\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_1^{(i)}$
 }
 (simultaneously update θ_0, θ_1)

New algorithm ($n \geq 1$):

Repeat {
 $\theta_j := \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_j^{(i)}$
 }
 (simultaneously update θ_j for $j = 0, \dots, n$)

 $\theta_0 := \theta_0 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)})$
 $\theta_1 := \theta_1 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_1^{(i)}$
 $\theta_2 := \theta_2 - \alpha \frac{1}{m} \sum_{i=1}^m (h_{\theta}(x^{(i)}) - y^{(i)}) x_2^{(i)}$

Speeding up Gradient Descent

- We can speed it up by having each of our input values roughly in the same range. This is because θ will descend quickly on small ranges than on large ranges, and hence will oscillate inefficiently down to the optimum when the variables are very uneven.

- Two ways:
 - Feature scaling
 - Mean Normalization

Feature Scaling

- It involves dividing the input values by the range of the input variables, resulting in the new range of just 1.

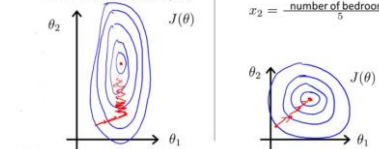
Idea: Make sure features are on a similar scale.

E.g. $x_1 = \text{size (0-2000 feet}^2\text{)}$

$x_2 = \text{number of bedrooms (1-5)}$

$x_1 = \frac{\text{size (feet}^2\text{)}}{2000}$

$x_2 = \frac{\text{number of bedrooms}}{5}$



Mean Normalization

Replace x_i with $x_i - \mu_i$ to make features have approximately zero mean
(Do not apply to $x_0 = 1$).

E.g. $x_1 = \frac{\text{size} - 1000}{2000}$ mean
 $x_2 = \frac{\text{\#bedrooms} - 2}{5}$ Range (max-min)

House Price Prediction Example

- Let the hypothesis be:

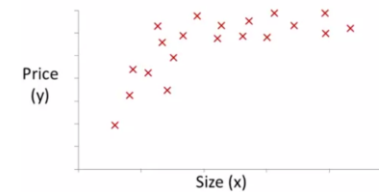
$$h_{\theta}(x) = \theta_0 + \theta_1 \times \text{frontage} + \theta_2 \times \text{depth}$$

- But, its not necessary to use the features provided as it is.
We can form new features like
area= frontage * depth
and refine the hypothesis
- Model might work better

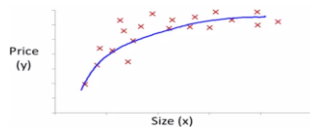


Polynomial Regression

- The idea close to defining new features is called polynomial regression
- Eg:



The idea of fitting a line does not seem promising, so we might try
To fit a quadratic function like the one given below:



$$\theta_0 + \theta_1 x + \theta_2 x^2$$

We might try a cubic function and others.

A cubic function seems to be a better fit and we might use
techniques of multivariate regression to solve it.

$$\begin{aligned} h_{\theta}(x) &= \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 \\ &= \theta_0 + \theta_1(\text{size}) + \theta_2(\text{size})^2 + \theta_3(\text{size})^3 \\ x_1 &= (\text{size}) \\ x_2 &= (\text{size})^2 \\ x_3 &= (\text{size})^3 \end{aligned}$$

Linear Regression Model

Relationship Between Variables Is a Linear Function

$$Y_i = \beta_0 + \beta_1 X_i + \epsilon_i$$

Population Y-Intercept Population Slope Random Error

Dependent (Response) Variable Independent (Explanatory) Variable

Fit the regression line $y = \beta_0 + \beta_1 x$ to the data

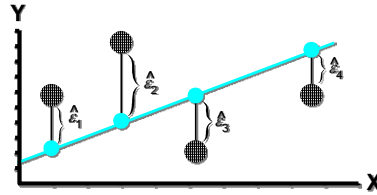
$$(x_1, y_1), \dots, (x_n, y_n)$$

by finding the “best” match between the line and the data. The “best” choice of β_0, β_1 will be chosen to minimize

$$Q = \sum_{i=1}^n (y_i - (\beta_0 + \beta_1 x_i))^2 = \sum_{i=1}^n \varepsilon_i^2.$$

Least Squares Graphically

$$\text{LS minimizes } \sum_{i=1}^n \hat{\varepsilon}_i^2 = \hat{\varepsilon}_1^2 + \hat{\varepsilon}_2^2 + \hat{\varepsilon}_3^2 + \hat{\varepsilon}_4^2$$



This is called the least square fit. Let's solve...

$$\frac{\partial Q}{\partial \beta_0} = -2 \sum (y_i - (\beta_0 + \beta_1 x_i)) = 0$$

$$\frac{\partial Q}{\partial \beta_1} = -2 \sum x_i (y_i - (\beta_0 + \beta_1 x_i)) = 0$$

$$\Leftrightarrow \sum y_i = n\beta_0 + \beta_1 \sum x_i$$

$$-2 \sum x_i (y_i - (\beta_0 + \beta_1 x_i)) = 0$$

After a little algebra, get

$$\hat{\beta}_1 = \frac{n \sum x_i y_i - (\sum x_i)(\sum y_i)}{n \sum x_i^2 - (\sum x_i)^2}$$

$$\hat{\beta}_0 = \bar{y} - \hat{\beta}_1 \bar{x}, \text{ where } \bar{y} \equiv \frac{1}{n} \sum y_i \text{ and } \bar{x} \equiv \frac{1}{n} \sum x_i.$$

Let's introduce some more notation:

$$S_{xx} = \sum (x_i - \bar{x})^2 = \sum x_i^2 - n\bar{x}^2$$

$$= \sum x_i^2 - \frac{(\sum x_i)^2}{n}$$

$$S_{xy} = \sum (x_i - \bar{x})(y_i - \bar{y}) = \sum x_i y_i - n\bar{x}\bar{y}$$

$$= \sum x_i y_i - \frac{(\sum x_i)(\sum y_i)}{n}$$

These are called “sums of squares.”

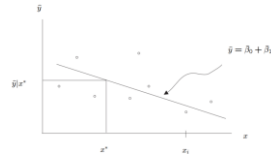
Then, after a little more algebra, we can write

$$\hat{\beta}_1 = \frac{S_{xy}}{S_{xx}}$$

the fitted regression line is:

$$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x.$$

Fix a specific value of the explanatory variable x^* , the equation gives a fitted value $\hat{y}|x^* = \hat{\beta}_0 + \hat{\beta}_1 x^*$ for the dependent variable y .



For actual data points x_i , the fitted values are $\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$.

observed values : $y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$

fitted values : $\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$

Let's estimate the error variation σ^2 by considering the deviations between y_i and \hat{y}_i .

$$SSE = \sum (y_i - \hat{y}_i)^2 = \sum (y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i))^2$$

$$= \sum y_i^2 - \hat{\beta}_0 \sum y_i - \hat{\beta}_1 \sum x_i y_i.$$