

Topics in Applied Optimization

Optimization for ML and Data Sciences

Dr. Pawan Kumar

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IIIT, Hyderabad

Convex Optimization Problem: Local Optima = Global Optima

Fact: For a convex optimization problem, any local optima is a global optima

Ans: Proof on chalkboard!

Convex Optimization Problem: Optimality Criteria

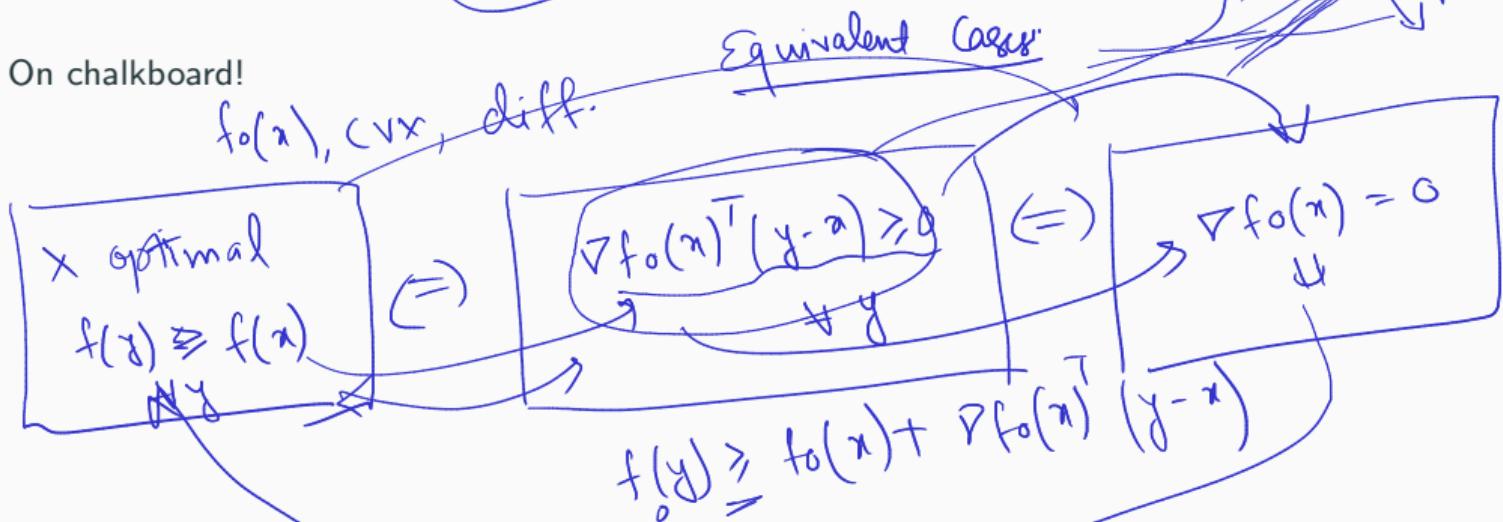
$$f(y) \geq f(x^*) + \nabla f(x^*)^T (y - x)$$

↗ left

Fact: If f_0 in a convex optimization problem is **differentiable**, then the point x is **optimal** if

$$\nabla f_0(x)^T (y - x) \geq 0 \quad \text{for all } y \in X$$

Proof: On chalkboard!



Convex Optimization Problem: Optimality for Unconstrained problems

Fact: For an unconstrained problem, ($m = p = 0$), the optimality condition

$$\nabla f_0(x)^T(y - x) \geq 0 \quad \text{for all } y \in X$$

reduces to the well known necessary and sufficient condition

$$\nabla f_0(x) = 0$$

Proof on chalkboard!

Suppose x is optimal $\Rightarrow x \in \text{dom } f_0$ f for all y we have

Scasible &

$$\nabla f_0(x)^T(y - x) \geq 0$$

~~to us take my~~

$$\begin{aligned} f(y) &\geq f(x) + \nabla f(x)^T(y - x) \\ \text{if } \nabla f(x) &= 0 \Rightarrow f_0(y) \geq f_0(x) \forall y \\ &\Rightarrow x^* \text{ is optimal} \end{aligned}$$

Scratch Space

So we prove that if $\exists x^* \text{ s.t } \boxed{\nabla f(x^*) = 0} \Rightarrow x^* \text{ is optimal}$

Again w/t $\Rightarrow \nabla f_0(x)^T(y-x) \geq 0$

Claim: Assume that $\nabla f_0(x)^T(y-x) > 0$ + say, then

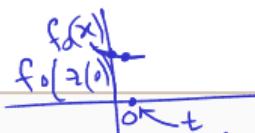
$$\begin{aligned} &\nabla f_0(x) \neq 0 \\ \Rightarrow f_0(y) &> f_0(x) + \underbrace{\nabla f_0(x)^T(y-x)}_{>0} \leftarrow (\text{Convexity}) \end{aligned}$$

$$\Rightarrow \boxed{f_0(y) > f_0(x)} \Rightarrow x \text{ is optimal}$$

Conversely: say x is optimal and on contrary assume that $\nabla f_0(x)^T(y-x) < 0 \rightarrow \star$

Scratch Space

Consider that point: $z(t) = ty + (1-t)x$, $t \in [0,1]$



$z(t)$ is on the line joining x & y & $x, y \in$ feasible set which is conv.

$\Rightarrow z(t) \in$ feasible set.

$$\frac{d}{dt} f_0(z(t)) \Big|_{t=0} = \nabla f_0(x)^T z'(t) \Big|_{t=0} = \nabla f_0(x)^T (y-x) < 0$$

$\Rightarrow f_0(z(t))$ decreases as t increases. $\Rightarrow \exists$ small positive t for which $f_0(z(t)) < f_0(z(0)) = f_0(x)$



a contradiction to the fact that x was optimal

$$\text{Take } y = x - t \nabla f_0(x). \text{ For small } t, \text{ point } y \text{ is feasible}$$

$$\nabla f_0(x)^T (y-x) = \nabla f_0(x)^T - t \nabla f_0(x)^T$$

$$(\nabla f_0(x) = 0) \Leftrightarrow = -t \|\nabla f_0(x)\|_2^2 > 0$$

Unconstrained Quadratic Optimization

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where $P \in S_+^n$.

Unconstrained Quadratic Optimization

Consider the problem of minimizing

$$f_0(x) = (1/2)x^T Px + q^T x + r,$$

where $P \in S_+^n$. The **necessary and sufficient** condition for x to be minimizer of f_0 is

$$\nabla f_0(x) = Px + q = 0. \quad (\text{Why?})$$

$\boxed{Px = -q}$ f_0 is CVX:

$\checkmark f_0$ is diff. ($\text{poly}^{(m^n)}$)
① is fo convexⁿ

$$\begin{aligned}\nabla f_0(x) &= Px + q \\ \nabla^2 f_0(x) &= P \geq 0\end{aligned}$$

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Several cases may occur:

1. If $q \notin R(P)$, then there is no solution. f_0 is unbounded below

$Px = -q$ ← can never be satisfied

$$\begin{bmatrix} p_1 & p_2 & \cdots & p_n \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = -q$$
$$= x_1 p_1 + x_2 p_2 + \cdots + x_n p_n = -q$$

$\Rightarrow q$ is a linear combination of p_i 's

$\Rightarrow q \in R(P)$

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Several cases may occur:

1. If $q \neq \mathcal{R}(P)$, then there is **no** solution. f_0 is unbounded below
2. If $\cancel{P} > 0$, then there is a **unique** minimizer, $x^* = \cancel{-P^{-1}q}$

$\Rightarrow P \in S_{++}^n$ + strictly P.D. \Rightarrow non-singularity.

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3. If P is **singular**, but $q \in \mathcal{R}(P)$.

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3. If P is **singular**, but $q \in \mathcal{R}(P)$.
 - set of **optimal** points is $X_{\text{opt}} = -P^+q + \mathcal{N}(P)$, where P^+ denotes the pseudoinverse of P

$$\begin{aligned}
 & x_1^2 - 2x_1x_2 + x_2^2 \\
 & q = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 & r = 0
 \end{aligned}$$

$\left[\begin{array}{cc} x_1 & x_2 \end{array} \right] \left[\begin{array}{cc} 1 & -1 \\ -1 & 1 \end{array} \right] \left[\begin{array}{c} x_1 \\ x_2 \end{array} \right] = \underline{x}$
 $\underline{x}^T P \underline{x} \geq 0$
 $\Rightarrow P \in S_+^n$

$$+ + +$$

Problems with Equality Constraints

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Consider the following optimization problem with equality constraints only

$$\begin{aligned} & \text{minimize} && f_0(x) \\ & \text{subject to} && Ax = b \checkmark \end{aligned}$$

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$$\text{minimize } f_0(x)$$

$$\text{subject to } Ax = b$$



$$f(y) \geq f(x) + \dots$$

- Feasible set is **affine**, recall that x is **feasible** if it satisfies

$$\nabla f_0(x)^T(y - x) \geq 0, \quad \text{for all } y \text{ such that } Ay = b$$

$\nabla f_0(x)^T$
affine

$$Ay = b$$

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- Every **feasible** y has the form: $y = \underbrace{x + v}_{\downarrow \downarrow}, (\text{Why?})$ for some $v \in \underline{\mathcal{N}(A)}$

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$$\nabla f_0(x)^T \underbrace{v}_{\geq 0} \quad \text{for all } v \in \mathcal{N}(A)$$

Problems with Equality Constraints

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Consider the following optimization problem with equality constraints only

$$\text{minimize } f_0(x)$$

$$\text{subject to } Ax = b$$

$$g(v) = \nabla f_0(x)^T v + C$$

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$$\nabla f_0(x)^T (y - x) \geq 0, \quad \text{for all } y \text{ such that } Ay = b$$

- Every **feasible** y has the form: $y = x + v$, (**Why?**) for some $v \in N(A)$
- **Optimality condition** is

$$\nabla f_0(x)^T v \geq 0 \quad \text{for all } v \in N(A)$$

- $\nabla f_0(x)^T v$ is **linear** in v , and **nonnegative** on a subspace, hence

$$\begin{aligned} g(v) &= \nabla f_0(x)^T v + C \\ &\text{is linear in } v \\ &\text{and nonnegative on } N(A) \\ \Rightarrow g(-v) &= -g(v) \geq 0 \\ \Rightarrow g(v) &\leq 0 \rightarrow 0 \\ \Rightarrow g(v) &= 0 \end{aligned}$$

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 - $\nabla f_0(x)^T v = 0$ for all $v \in \mathcal{N}(A)$. (**Why?**)

Problems with Equality Constraints

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$$x \in S = \{ y \mid Ay = b \}$$

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$$\nabla f_0(x)^T(y - x) \geq 0 \quad \text{for all } y \text{ such that } Ay = b$$

$$\nabla f_0(x)^T v = 0 \quad \forall v \in N(A)$$

- Every **feasible** y has the form: $y = x + v$, (**Why?**) for some $v \in N(A)$ $\Rightarrow \nabla f_0(x) \perp N(A)$
- Optimality condition is

$$\nabla f_0(x)^T v \geq 0 \quad \text{for all } v \in N(A)$$

$$N(A) \oplus R(A^T)$$

$$x = v + v^T$$

- $\nabla f_0(x)^T v$ is **linear** in v , and **nonnegative** on a subspace, hence
 - $\nabla f_0(x)^T v = 0$ for all $v \in N(A)$. (**Why?**)
 - $\nabla f_0(x) \perp N(A) \Rightarrow \nabla f_0(x) \in R(A^T)$, (**Why?**) i.e., $\exists v$ such that

Problems with Equality Constraints

$$\alpha^T \beta + \gamma^T x = 0$$

$$P(A) \quad \begin{bmatrix} P \\ A \\ 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

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 - $\nabla f_0(x)^T v = 0$ for all $v \in \mathcal{N}(A)$. (**Why?**)
 - $\nabla f_0(x) \perp \mathcal{N}(A) \implies \nabla f_0(x) \in \mathcal{R}(A^T)$, (**Why?**) i.e., $\exists v$ such that $\nabla f_0(x) + A^T v = 0$

- The above together with $Ax = b$. Lagrange condition.